Operating Guide
Safe Torque Off

VLT® Frequency Converters
1 Introduction

1.1 Purpose of the Manual

This manual provides information for use of Danfoss VLT® frequency converters in functional safety applications. The manual includes information about functional safety standards, Danfoss VLT® frequency converter Safe Torque Off (STO) function, and the related installation and commissioning as well as service and maintenance for STO.

VLT® is a registered trademark.

1.2 Additional Resources

This manual is targeted at users already familiar with the VLT® frequency converters. It is intended as a supplement to the manuals and instructions available for download at drives.danfoss.com/knowledge-center/technical-documentation/. Read the instructions shipped with the frequency converter and/or frequency converter option before installing the unit, and observe the instructions for safe installation.

1.3 Functional Overview

1.3.1 Introduction

The Safe Torque Off (STO) function is a component in a safety control system. STO prevents the unit from generating the voltage required to rotate the motor.

**NOTICE**

Select and apply the components in the safety control system appropriately to achieve the desired level of operational safety. Before integrating and using STO in an installation, carry out a thorough risk analysis on the installation to determine whether the STO functionality and safety levels are appropriate and sufficient.

The VLT® frequency converter is available with:
- Safe Torque Off (STO), as defined by EN IEC 61800-5-2.
- Stop Category 0, as defined in EN 60204-1.

The frequency converter integrates the STO functionality via control terminal 37.

The VLT® frequency converter with STO functionality is designed and approved suitable for the requirements of:
- Category 3 in EN ISO 13849-1.
- Performance Level "d" in EN ISO 13849-1.
- SIL 2 in IEC 61508 and EN 61800-5-2.
- SILCL 2 in EN 62061.

1.3.2 Products Covered and Identification

The STO function is available for the following types of frequency converters:
- VLT® HVAC Drive FC 102
- VLT® Refrigeration Drive FC 103
- VLT® AQUA Drive FC 202
- VLT® AutomationDrive FC 301 enclosure size A1
- VLT® AutomationDrive FC 302
- VLT® Decentral Drive FCD 302

**Identification**
- Confirm that the frequency converter is configured with STO function by checking the unit typecode on the nameplate (see Table 1.1).

<table>
<thead>
<tr>
<th>Product</th>
<th>Typecode</th>
</tr>
</thead>
<tbody>
<tr>
<td>VLT® HVAC Drive FC 102</td>
<td>T or U at digit 18 of the typecode</td>
</tr>
<tr>
<td>VLT® Refrigeration Drive FC 103</td>
<td>T at digit 18 of the typecode</td>
</tr>
<tr>
<td>VLT® AQUA Drive FC 202</td>
<td>T or U at digit 18 of the typecode</td>
</tr>
<tr>
<td>VLT® AutomationDrive FC 301 enclosure size A1</td>
<td>T at digit 18 of the typecode</td>
</tr>
<tr>
<td>VLT® AutomationDrive FC 302</td>
<td>X, B, or R at digit 18 of the typecode</td>
</tr>
<tr>
<td>VLT® Decentral Drive FCD 302</td>
<td>X, B, or R at digit 18 of the typecode</td>
</tr>
</tbody>
</table>

Table 1.1 Typecode Identification

1.4 Approvals and Certifications

More approvals and certifications are available. Contact a local Danfoss partner.
Applied standards and compliance
Use of STO on terminal 37 requires that the user fulfills all provisions for safety including relevant laws, regulations, and guidelines.

The integrated STO function complies with the following standards:

- EN 60204-1: 2006 Stop category 0 – uncontrolled stop
- IEC/EN 61508: 2010 SIL2
- IEC/EN 62061: 2005 SIL CL2
- EN ISO 13849-1: 2008 Category 3 PL d

1.5 Symbols, Abbreviations, and Conventions

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Reference</th>
<th>Description</th>
</tr>
</thead>
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<tr>
<td>Cat.</td>
<td>EN ISO 13849-1</td>
<td>Category, level “B, 1–4”</td>
</tr>
<tr>
<td>DC</td>
<td></td>
<td>Diagnostic coverage</td>
</tr>
<tr>
<td>FIT</td>
<td></td>
<td>Failure in time: 1E-9/hour</td>
</tr>
<tr>
<td>HFT</td>
<td>EN IEC 61508</td>
<td>Hardware fault tolerance: HFT = n means that n+1 faults could cause a loss of the safety function</td>
</tr>
<tr>
<td>MTTF(_d)</td>
<td>EN ISO 13849-1</td>
<td>Mean time to failure - dangerous. Unit: Years</td>
</tr>
<tr>
<td>PFH</td>
<td>EN IEC 61508</td>
<td>Probability of dangerous failures per hour. Consider this value if the safety device is operated in high demand or continuous mode of operation, where the frequency of demands for operation made on a safety-related system is greater than one per year.</td>
</tr>
<tr>
<td>PFD</td>
<td>EN ISO 13849-1</td>
<td>Average probability of failure on demand, value used for low demand operation.</td>
</tr>
<tr>
<td>PL</td>
<td>EN ISO 13849-1</td>
<td>Discrete level used to specify the ability of safety-related parts of control systems to perform a safety function under foreseeable conditions. Levels a-e.</td>
</tr>
<tr>
<td>SIL</td>
<td>EN IEC 61508</td>
<td>Safety integrity level</td>
</tr>
<tr>
<td>SI</td>
<td>EN IEC 61800-5-2</td>
<td>Safe Torque Off</td>
</tr>
<tr>
<td>SS1</td>
<td>EN IEC 61800-5-2</td>
<td>Safe Stop 1</td>
</tr>
<tr>
<td>SRECS</td>
<td>EN IEC 62061</td>
<td>Safety related electrical control system</td>
</tr>
<tr>
<td>SRP/CS</td>
<td>EN ISO 13849-1</td>
<td>Safety related parts of control systems</td>
</tr>
<tr>
<td>PDS/SR</td>
<td>EN IEC 61800-5-2</td>
<td>Power drive system (safety-related)</td>
</tr>
</tbody>
</table>

Table 1.2 Abbreviations Related to Functional Safety

Conventions
Numbered lists indicate procedures.
Bullet lists indicate other information and description of illustrations.

Italicized text indicates:
- Cross-reference.
- Link.
- Parameter name.
- Footnote.
- Parameter group.
- Parameter option.
- Alarms/warnings.

All dimensions in drawings are given in both, metric and imperial units (in brackets), for example: mm (in).
An asterisk (*) indicates the default setting of a parameter.
2 Safety

2.1 Safety Symbols

The following symbols are used in this guide:

**WARNING**
Indicates a potentially hazardous situation that could result in death or serious injury.

**CAUTION**
Indicates a potentially hazardous situation that could result in minor or moderate injury. It can also be used to alert against unsafe practices.

**NOTICE**
Indicates important information, including situations that can result in damage to equipment or property.

2.2 Qualified Personnel

Only persons with proven skills are allowed to assemble, install, program, commission, maintain, and decommission the products. Persons with proven skills

- Are qualified electrical engineers, or persons who have received training from qualified electrical engineers and are suitably experienced to operate devices, systems, plant, and machinery in accordance with the general standards and guidelines for safety technology.
- Are familiar with the basic regulations concerning health and safety/accident prevention.
- Have read and understood the safety guidelines given in this manual and also the instructions given in the operating instructions of the frequency converter.
- Have a good knowledge of the generic and specialist standards applicable to the specific application.

Users of Power Drive Systems (Safety Related) (PDS(SR)) are responsible for:

- Hazard and risk analysis of the application.
- Identifying safety functions required and allocating SIL or PLr to each of the functions.
- Other subsystems and the validity of signals and commands from them.
- Designing appropriate safety-related control systems (hardware, software, parameterization, and so on).

**Protective measures**

- Only qualified and skilled personnel is allowed to install and commission safety engineering systems.
- Install the frequency converter in an IP54 cabinet as per IEC 60529 or in an equivalent environment. In special applications, a higher IP degree may be necessary.
- Ensure short-circuit protection of the cable between the safety option and the external safety device according to ISO 13849-2 table D.4. When external forces influence the motor axis (for example suspended loads), extra measures (for example a safety holding brake) are required to eliminate hazards.

2.3 Safety Precautions

See the Safety chapter in the relevant operating instructions/guides for general safety precautions.

**CAUTION**
After installation of STO, perform a commissioning test as specified in chapter 4.5 STO Commissioning Test. A passed commissioning test is mandatory after first installation and after each change to the safety installation.

**WARNING**
**RISK OF DEATH AND SERIOUS INJURY**
If external forces act on the motor, for example in case of vertical axis (suspended loads), and an unwanted movement, for example caused by gravity, could cause a hazard, the motor must be equipped with extra measures for fall protection. For example, install extra mechanical brakes.

**WARNING**
**RISK OF DEATH AND SERIOUS INJURY**
STO (that is, removal of 24 V DC voltage supply to terminal 37) does not provide electrical safety. The STO function itself is not sufficient to implement the Emergency-Off function as defined by EN 60204-1. Emergency-Off requires measures of electrical isolation, for example, by switching off mains via an additional contactor.
**WARNING**

**RISK OF ELECTRICAL SHOCK**

The STO function does NOT isolate mains voltage to the frequency converter or auxiliary circuits. Perform work on electrical parts of the frequency converter or the motor only after isolating the mains voltage supply and waiting for the discharge time to elapse, as specified in the Safety chapter in the relevant operating instructions/guides. Failure to isolate the mains voltage supply from the unit and waiting the time specified could result in death or serious injury.

- Do not stop the frequency converter by using the STO function. If a running frequency converter is stopped by using the function, the unit trips and stops by coasting. If this limitation is not acceptable, for example, because it causes danger, use the appropriate stopping mode to stop the frequency converter and machinery before using the STO function. Depending on the application, a mechanical brake may be required.
- STO is suitable for performing mechanical work on the frequency converter system or affected area of a machine only. It does not provide electrical safety. STO must not be used as a control for starting and/or stopping the frequency converter.

**CAUTION**

**AUTOMATIC RESTART**

Automatic restart behavior is only allowed in 1 of the 2 situations:

- The unintended restart prevention is implemented by other parts of the STO installation.
- A presence in the dangerous zone can be physically excluded when STO is not activated. In particular, paragraph 6.3.3.2.5 of ISO 12100:2010 must be observed.

**WARNING**

**RISK OF DEATH AND SERIOUS INJURY**

The STO function can be used for asynchronous, synchronous, and permanent magnet motors. 2 faults can occur in the power semiconductor of the frequency converter. When using synchronous or permanent magnet motors, a residual rotation can result from the faults. The rotation can be calculated to angle = 360/(number of poles). The application using synchronous or permanent magnet motors must take this residual rotation into consideration and ensure that it does not pose a safety risk. This situation is not relevant for asynchronous motors.

**NOTICE**

Perform a risk assessment for each stop function to determine the selection of a stop category in accordance with EN 60204-1:

- Stop Category 0 is achieved with immediate removal of power to the actuator, resulting in an uncontrolled coast to stop. STO according to EN 61800-5-2 accomplishes a Stop Category 0 stop.
- Stop Category 1 is achieved with power available to the machine actuators to achieve the stop. Power is removed from the actuators when the stop is achieved according to EN 61800-5-2 Safe Stop 1 (SS1).
- Stop Category 2 is a controlled stop with power available to the machine actuators. The stop is followed by a holding position under power.

**NOTICE**

When designing the machine application, timing and distance must be considered for a coast to stop (Stop Category 0 or STO). For more information regarding stop categories, refer to EN 60204-1.
3 Installation

3.1 Safety Instructions

**CAUTION**

**ELECTRICAL HAZARD**

The operator or electrical installer is responsible for proper grounding and compliance with all applicable national and local safety regulations.

See chapter 2 Safety and the relevant frequency converter operating instructions/guides. Also, always observe the instructions provided by the motor manufacturer.

3.2 STO Installation

For motor connection, AC mains connection, and control wiring, follow the instructions for safe installation in the operating instructions/guides of the frequency converter.

For installation with the Ex-certified VLT® PTC Thermistor Card MCB 112, see chapter 3.3 Installation in Combination with VLT® PTC Thermistor Card MCB 112.

Enable the integrated STO as follows:

1. Remove the jumper wire between control terminals 37 and 12 or 13. Cutting or breaking the jumper is not sufficient to avoid short-circuiting. (See jumper on Illustration 3.1)

Illustration 3.1 Jumper between terminal 12/13 (24 V) and 37 (all Frequency Converters except of FCD 302)

Illustration 3.2 Jumper between terminal 13 (24 V) and 37 (FCD 302)
2. Connect an external safety monitoring relay via a NO safety function to terminal 37 (STO) and either terminal 12 or 13 (24 V DC). Follow the installation instructions for the safety monitoring relay, and ensure that the safety monitoring relay complies with Category 3 /PL “d” (ISO 13849-1) or SIL 2 (EN 62061 and IEC 61508).

3. Complete wiring according to the instructions given in the operating instructions/guides of the frequency converter.

3.3 Installation in Combination with VLT® PTC Thermistor Card MCB 112

**NOTICE**
Combination of VLT® PTC Thermistor Card MCB 112 and STO function is only available for VLT® HVAC Drive FC 102, VLT® AQUA Drive FC 202, VLT® AutomationDrive FC 302, and VLT® AutomationDrive FC 301 enclosure size A1.

VLT® PTC Thermistor Card MCB 112 uses terminal 37 as its safety-related switch-off channel.

- Ensure that the output X44/12 of MCB 112 is AND-ed with the safety-related sensor (such as, for example, emergency stop button, and safetyguard switch), that activates STO. This means that the output to STO terminal 37 is HIGH (24 V) only if both the signal from MCB 112 output X44/12 and the signal from the safety-related sensor are HIGH. If at least 1 of the 2 signals is LOW, then the output to terminal 37 must be LOW too.
- Ensure that the safety device with AND-logic complies with the needed safety level.
- Short-circuit protect the connection from the output of the safety device with safe AND-logic to the STO terminal 37, see Illustration 3.4.
Illustration 3.4 shows a restart input for the external safety device. This means that in this installation, parameter 5-19 Terminal 37 Safe Stop can be set to value [7] PTC 1 & Relay W or [8] PTC 1 & Relay A/W. Refer to VLT® PTC Thermistor Card MCB 112 Operating Instructions for further details.
4 Commissioning

4.1 Safety Instructions

**CAUTION**

**ELECTRICAL HAZARD**

The operator or electrical installer is responsible for proper grounding and compliance with all applicable national and local safety regulations.

See chapter 2 Safety and the relevant frequency converter operating instructions/guides. Also, always observe the instructions provided by the motor manufacturer.

4.2 Activation of STO

The STO function is activated by removing the voltage at terminal 37 of the frequency converter. By connecting the frequency converter to external safety devices providing a safe delay, an installation for a Safe Stop 1 can be obtained. External safety devices must fulfill Cat./PL or SIL when connected to terminal 37. The STO function can be used for asynchronous, synchronous, and permanent magnet motors.

When the STO function (terminal 37) is activated, the frequency converter issues an alarm, trips the unit, and coasts the motor to a stop. Manual restart is required. Use the STO function to stop the frequency converter in emergency stop situations. In normal operating mode when STO is not required, use the standard stop function instead. Ensure that requirements according to ISO 12100 paragraph 6.3.3.2.5 are fulfilled before using the automatic restart function.

4.3 Parameter Settings for STO in Combination with VLT® PTC Thermistor Card MCB 112

When MCB 112 is connected, additional selections are available for parameter 5-19 Terminal 37 Safe Stop ([4] PTC 1 Alarm to [9] PTC 1 & Relay W/A).

- Selections [1]* Safe Stop Alarm and [3] Safe Stop Warning are still available, but are for installations without MCB 112 or any external safety devices. If [1]* Safe Stop Alarm or [3] Safe Stop Warning are selected and MCB 112 is triggered, the frequency converter reacts with alarm 72, Dangerous Failure and coasts the motor safely, without automatic restart.
- Do not select [4] PTC 1 Alarm and [5] PTC 1 Warning when an external safety device is used. Those selections are for when only MCB 112 uses the STO.

If selection [4] PTC 1 Alarm or [5] PTC 1 Warning is selected and the external safety device triggers STO, the frequency converter issues alarm 72, Dangerous Failure and coasts the motor safely, without automatic restart.


**CAUTION**

**AUTOMATIC RESTART**

Selections allow for automatic restart when the external safety device is de-activated.

Before selecting [7] PTC 1 & Relay W or [8] PTC 1 & Relay A/W, ensure that:

- The unintended restart prevention is implemented by other parts of the STO installation, or
- A presence in the dangerous zone can be physically excluded when STO is not activated. In particular, paragraph 6.3.3.2.5 of ISO 12100:2010 must be observed.

See VLT® PTC Thermistor Card MCB 112 Operating Instructions for further information.

4.4 Automatic/Manual Restart Behavior

By default, the STO function is set to unintended restart prevention behavior. To terminate STO and resume normal operation:

1. Reapply 24 V DC supply to terminal 37.
2. Give a reset signal (via bus, digital I/O, or [Reset] key).

Set the STO function to automatic restart by setting the value of parameter 5-19 Terminal 37 Safe Stop from default value [1]* Safe Stop Alarm to value [3] Safe Stop Warning. Automatic restart means that STO is terminated, and normal operation is resumed, when the 24 V DC is applied to terminal 37. No reset signal is required.

4.5 STO Commissioning Test

After installation and before first operation, perform a commissioning test of the installation, using STO. Perform the test again after each modification of the installation or application involving the STO.
A successful commissioning test of the STO function is required after the initial installation, and after each subsequent change to the installation.

To perform a commissioning test:
- Follow the instructions in chapter 4.5.1 Restart Prevention for STO Application for applications without automatic restart after a safe stop, or
- Follow the instructions in chapter 4.5.2 Automatic Restart of STO Application for applications with automatic restart after a safe stop

### 4.5.1 Restart Prevention for STO Application

Application where parameter 5-19 Terminal 37 Safe Stop is set to default value [1]* Safe Stop Alarm or combined STO and MCB 112 where parameter 5-19 Terminal 37 Safe Stop is set to [6] PTC 1 & Relay A or [9] PTC 1 & Relay W/A:

1. Remove the 24 V DC voltage supply to terminal 37 using the interrupt device while the frequency converter drives the motor (that is mains supply is not interrupted).
2. Check that:
   - 2a The motor coasts.
   - 2b The mechanical brake activates (if connected).
   - 2c If the local control panel (LCP) is mounted, it shows alarm 68, Safe Stop.
3. Reapply 24 V DC to terminal 37.
4. Ensure that the motor remains in the coasted state, and the mechanical brake (if connected) remains activated.
5. Send reset signal (via bus, digital I/O, or [Reset] key).
6. Ensure that the motor becomes operational again.

The commissioning test is successfully completed when all the given steps are passed.

### 4.5.2 Automatic Restart of STO Application

Application where parameter 5-19 Terminal 37 Safe Stop is set to [3] Safe Stop Warning or combined Safe Torque Off and MCB 112 where parameter 5-19 Terminal 37 Safe Stop is set to [7] PTC 1 & Relay W or [8] PTC 1 & Relay A/W:

1. Remove the 24 V DC voltage supply to terminal 37 by the interrupt device while the frequency converter drives the motor (that is mains supply is not interrupted).
2. Check that:
   - 2a The motor coasts.
   - 2b The mechanical brake activates (if connected).
   - 2c If the local control panel (LCP) is mounted, it shows warning 68, Safe Stop.
3. Reapply 24 V DC to terminal 37.
4. Ensure that the motor becomes operational again.

The commissioning test is successfully completed when all the given steps are passed.
5 STO Technical Data

**NOTICE**
For technical specifications and operating conditions for the frequency converter, refer to the relevant operating instructions/guides of the frequency converter.

**NOTICE**
The STO signal must be SELV or PELV supplied.

<table>
<thead>
<tr>
<th>European directives</th>
<th>Machinery Directive (2006/42/EC)</th>
<th>EN ISO 13849-1</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>EMC Directive (2014/30/EU)</td>
<td>EN 50011</td>
</tr>
<tr>
<td></td>
<td>Low Voltage Directive (2014/35/EU)</td>
<td>EN 50178</td>
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</tbody>
</table>

<table>
<thead>
<tr>
<th>Safety standards</th>
<th>Safety of Machinery</th>
<th>EN ISO 13849-1, IEC 62061, IEC 60204-1</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>Functional Safety</td>
<td>IEC 61508-1 to -7, IEC 61800-5-2</td>
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<table>
<thead>
<tr>
<th>Safety function</th>
<th>ISO 13849-1</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Cat 3</td>
</tr>
<tr>
<td></td>
<td>DC: 90% (Medium)</td>
</tr>
<tr>
<td></td>
<td>Mean Time to Dangerous Failure MTTF, 14000 years (High)</td>
</tr>
<tr>
<td></td>
<td>Performance Level PL d</td>
</tr>
<tr>
<td></td>
<td>IEC 61508/IEC 62061</td>
</tr>
<tr>
<td></td>
<td>Safety Integrity Level SIL 2, SIL CL2</td>
</tr>
<tr>
<td></td>
<td>Probability of Dangerous Failure per Hour PFH, 1E-10/h; 1E-8/h for specific variants (High Demand Mode)</td>
</tr>
<tr>
<td></td>
<td>Probability of Dangerous Failure on Demand PFD, 1E-10; 1E-4 for specific variants (Low Demand Mode)</td>
</tr>
<tr>
<td></td>
<td>Hardware Fault Tolerance HFT: 0 (1oo1)</td>
</tr>
<tr>
<td></td>
<td>Proof Test Interval T1 20 Years</td>
</tr>
<tr>
<td></td>
<td>Mission time TM 20 Years</td>
</tr>
</tbody>
</table>

| Reaction time        | Input to output response time Maximum 20 ms, 60 ms for specific variants |

Table 5.1 Technical Data

1) VLT® HVAC Drive, VLT® AQUA Drive, and VLT® AutomationDrive High Power Drives with enclosure size F:

- 400 V: 450/500 kW (600/650 hp) – 800/1000 kW (1075/1350 hp) (High Overload/Normal Overload).

**SISTEMA data**
Functional safety data are available from a data library for use with the SISTEMA calculation tool from the IFA (Institute for Occupational Safety and Health of the German Social Accident Insurance), and data for manual calculation. SISTEMA is available for download at www.drives.danfoss.com/services/pc-tools/.
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