

## Marine Application Software Change Note APFIFF09

**Application:** APFIFF09  
**Application Name:** Marine application  
**Application Manual:** DPD01667

**Update Note 1:** This application parameters are not kept backwards compatible if new features or improvements would be difficult to implement by doing so. Read this change note and chapter "Compatibility issues in parameters between versions" from manual before updating the application.

**Update Note 2:** It's recommended to use compare function for parameter changes when updating application, especially in cases when version number change is considerably high. Application is constantly developed; this includes changing parameter default values, and if parameters are directly downloaded to drive improved default values may be lost.

There is APFIQ181V001 Double Marine based on APFIFF09V168, configured as a 2<sup>nd</sup> application in drive memory.

There is APFIQ181V002 Double Marine based on APFIFF09V197, configured as a 2<sup>nd</sup> application in drive memory.

## APFIFF09V232

**Replaced Application:** APFIFF09V231  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added two Klixon inputs, F66 Klixon.
  - P2.4.2.44 Klixon In 1 ID780
  - P2.4.2.45 Klixon In 2 ID781
  - P2.12.1.9 Klixon Response ID782
- Added input switch monitoring, F55 Input Switch.
  - P2.4.2.46 Input Switch ID1209
  - P2.12.1.11 Input Switch Respond ID785
- Added Ambien temperature monitoring, F88 Ambien Temp.
  - P2.4.2.47 Ambien Temp ID783
  - P2.12.1.10 Ambien Temp Respond ID784

## APFIFF09V231

**Replaced Application:** APFIFF09V230  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added Ramp Scale ID function, select a input value to be used to scale ramp times.
  - P 2.3.13.1 RampScaleFunc. ID3650
  - P 2.3.13.2 Input Value ID ID3651
  - P 2.3.13.3 Input Minimum ID3652
  - P 2.3.13.4 Input Maximum ID3653
  - P 2.3.13.5 Inverted ID3656
  - P 2.3.13.6 MinRampScale ID3654
  - P 2.3.13.7 MaxRampScale ID3655
- Added P2.3.12.5 Freq Ramp Gap ID537

## APFIFF09V230

**Replaced Application:** APFIFF09V229  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added digital output inversion B04 and B05
  - B00 = +1 = Invert Common Alarm
  - B04 = +16 = Invert Ready signal
  - B05 = +32 = Invert Run signal

## APFIFF09V229

**Replaced Application:** APFIFF09V228  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.12.1.7 Quick Stop Indication.
- Added P2.12.1.8 Run Enable Indication.
- Added P2.16.12 Mot.Stall Tries
- Added P2.13.45 FBStartNotReset,
  - Possible select that Ready signal will not reset FB Start command.

## APFIFF09V228

**Replaced Application:** APFIFF09V227  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- VNXC-1784 - Implement: CBM Vibration and Load envelope disabled in insulation supervision freeze zone
  - o Stator winding frozen area is different variable than in vibration and load monitoring's.

## **APFIFF09V227**

**Replaced Application:** APFIFF09V225  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P3.8-10 MM ID1-3. Select multi-monitoring items by ID number.
- Added P2.12.8.3 Earth fault warning limit

## APFIFF09V225

<b>Replaced Application:</b>	APFIFF09V224
<b>Used Firmware version:</b>	NXP4.99
<b>System Software requirement:</b>	NXPV202
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- IO Start function Rising pulse to start and rising pulse to stop was not reset when control place changed, fixed.



## APFIFF09V224

**Replaced Application:** APFIFF09V223  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- VNXC-1413 - NXP: Condition based monitoring Stator windings detection more applications
  - o Added Baseline run and Condition Based Monitoring features
  - o Added password to all CBM functions
  - o Added encrypted library
  - o Added licence to activate CBM. CBM POUs are only executed if license is activated
- VNXC-1239 - NXP: Vibration & Load Envelope Condition based monitoring features to NXP
  - o Added vibration and load monitoring

## APFIFF09V223

**Replaced Application:** APFIFF09V221  
**Used Firmware version:** NXP4.99  
**System Software requirement:** NXPV202  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Firmware updated to FW4.99
  - Requires system software V202
- Added P2.8.6.26 FlxSaturRatio d ID683
- Added P2.8.6.27 FlxSaturRatio qID684
- Added P2.8.6.28 LdqSatIDRun ID677
- Added P2.8.6.29 LdqIDWithAngle ID678

## APFIFF09V221

**Replaced Application:** APFIFF09V219  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.6.3.4 PullOutSlipLimit.
- OPT-BH was giving short circuit warning before reading from option board has stabilized on 24 Vdc power up, fixed.

## APFIFF09V220

**Replaced Application:** APFIFF09V219  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- LsVoltageDrop maximum changed from 3000 to 32000.
- Master Follower modes 1, 2, 3 and 4 will set OPT-D2 TX1 jumper on software side. Hardware jumpers can be left to TX2. Note OPT-D2 needs to be J version or newer.

## APFIFF09V219

<b>Replaced Application:</b>	APFIFF09V218
<b>Used Firmware version:</b>	NXP4.91
<b>System Software requirement:</b>	NXPV200
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Added Control Options 1 B00; Show Drive output power with one decimal regardless of unit size.

## APFIFF09V218

**Replaced Application:** APFIFF09V217  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.8.8.21 FlyStartPhs1Time ID1718
- Added P2.12.12.5 EncPulseFaultMaxCount ID778
- Datalogger reset function rewritten.

## APFIFF09V217

**Replaced Application:** APFIFF09V215  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- If unsupported P2.9.36 Control Slot Select was requested system load may have increased. Now selection is set internally only once to avoid system load increase.

## APFIFF09V215

**Replaced Application:** APFIFF09V213  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Stop Torque Release Time limited from 0 to 500 ms.
- Compatibility note
  - Stop Torque Release Time ID number changed from ID1848 to ID1858.



## APFIFF09V213

**Replaced Application:** APFIFF09V209  
**Used Firmware version:** NXP4.91  
**System Software requirement:** NXPV200  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added monitoring variables NonReadyCauses and PreventMCReady.
- Added new functionality ID.bit ID Control
  - G2.14.8 ID Contrl ID.Bit
- Added several monitoring signals from Functional Safety
- If motor type is other than Induction motor, then old DTC identification mode is use.
  - Identification mode 7 / DTC Identification update.
    - Requires system software NXPV201
    - Older system software version uses earlier mode.
- If SCTorqueChainSel +96 has been set, it will not be reset when other ID runs are made.
- Start Angle Identification Automatic will work also motor type 4.
- Follower will show VSE\_SafeQuickStop\_Request i.e. Quick Stop.
- Automatic parameter backup to panel disabled.

## APFIFF09V209

<b>Replaced Application:</b>	APFIFF09V208
<b>Used Firmware version:</b>	NXP4.90
<b>System Software requirement:</b>	NXPV201
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Identification mode 7 / DTC Identification update.
  - Requires system software NXPV201
  - Older system software version uses earlier mode.

## **APFIFF09V208**

<b>Replaced Application:</b>	APFIFF09V207
<b>Used Firmware version:</b>	NXP4.90
<b>System Software requirement:</b>	NXPV196
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Over Speed Protection was giving unnecessary trigger in power-up, fixed.

## APFIFF09V207

**Replaced Application:** APFIFF09V205  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.8.6.23 Start Angle Offset.
- Added P2.15.13.4 RollBack Kp 2
- FB Actual scale will follow FB Custom Min/Max when PB mode is 2.
- Some parameters were missing parameter lock, added.

## APFIFF09V205

**Replaced Application:** APFIFF09V203  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.10.10 Advanced Options 7
- Quick stop was not reset if external force was keeping shaft rotating in closed loop control, fixed.
- Added Over Speed Protection. Hysteresis 5 Hz from Pos and Neg Frequency limits. Default response warning.

## APFIFF09V203

**Replaced Application:** APFIFF09V202  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Parameter Set Change was causing fieldbus fault, fixed.
- Fault in DriveSynch Master was making also F75 DS Follower fault in master drive, fixed.

## APFIFF09V202

**Replaced Application:** APFIFF09V201  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added parameter P2.3.12.4 ExtntZeroSpedTime to extend zero speed time until speed is zero.
- Application level Fieldbus fault is disabled until fieldbus communication is established first time after power up.

## APFIFF09V201

**Replaced Application:** APFIFF09V199  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added P2.8.8.18 Generator Torque Scale
- Internal temperature compensation is not activated automatically for synchronous motors.
- Added Response parameter for SQS.
- Added Response parameter for SS1.
- Added Response parameter for SS2.



## APFIFF09V199

**Replaced Application:** APFIFF09V197  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added parameter lock for Encoder Supervision, this parameter can't be changed to 3 / Warn; To OL while drive is modulating.

## **APFIFF09V198**

<b>Replaced Application:</b>	APFIFF09V197
<b>Used Firmware version:</b>	NXP4.90
<b>System Software requirement:</b>	NXPV196
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Motor Type 4 will use same ID run options as Motor Type's 1 & 2.

## **APFIFF09V197**

<b>Replaced Application:</b>	APFIFF09V194
<b>Used Firmware version:</b>	NXP4.90
<b>System Software requirement:</b>	NXPV196
<b>Released to field:</b>	29.8.2018
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Added monitoring value for 32 Bit absolute position.
- Added monitoring value for High Word absolute position.
- Added Identified Shaft Position High Word.

## APFIFF09V194

**Replaced Application:** APFIFF09V191  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- F32 Fan Cooling triggering behaved different than Simulation signal, fixed.
- Possible to select how Fault and Warning indication to fieldbus and DO behaves. P2.12.1.6 FaultWarnindicat
  - Static signal, as long as warning or fault is active
  - New fault or warning toggles signal for one second.
  - Signal toggles in new fault or warning and status needs to be reset to get signal down.

## APFIFF09V191

**Replaced Application:** APFIFF09V190  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Fault Word 1 B14 was showing Fault 11, fixed.
- F81 External fault added to Fault Word 2 B6
- F32 Fan Cooling added to Fault Word 2 B11
- F32 Fan Cooling fault response follows F60 Cooling Fault response and delay.
- F32 Simulation added to Simulation Word B10

## APFIFF09V190

**Replaced Application:** APFIFF09V188  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Current Follower without Drive Synch option will allow standard unit maximum switching frequency.
- F74, Follower fault was always costing, fixed.
- AuxStatusWord B10 was not showing torque control state when TorqueSelect was 1, fixed.

## APFIFF09V188

**Replaced Application:** APFIFF09V187  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added Response parameter for second fieldbus board.
- Added Encoder Warning to Warning Word 1 B6

## APFIFF09V187

**Replaced Application:** APFIFF09V184  
**Used Firmware version:** NXP4.90  
**System Software requirement:** NXPV196  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Extended support for Process Data In and Out variables from 8 to 16.
  - PD 9-16 are available if a fieldbus option board with 16 PD support is inserted to option board slots D or E.
  - The use of PD variables 9-16 is enabled with the Fieldbus parameter P2.13.37 Control Slot Selector.
- Datalogger defaults updates.



## APFIFF09V184

<b>Replaced Application:</b>	APFIFF09V183
<b>Used Firmware version:</b>	NXP4.83 (V192)
<b>System Software requirement:</b>	NXPV195 (Recommendation)
<b>Released to field:</b>	-
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Some situation OPT-AF status was not indicating correctly, fixed.
- DTC identification added to PMSM when Ident all is selected.

## APFIFF09V183

<b>Replaced Application:</b>	APFIFF09V177
<b>Used Firmware version:</b>	NXP4.83 (V192)
<b>System Software requirement:</b>	NXPV195 (Recommendation)
<b>Released to field:</b>	15.2.2018
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Added sensorless control
- Added Encoder Response Warn; To OL
- Ident All for IM will include also DTC Identification
- Identification warning gives a sub code, Ident Fail number

## APFIFF09V182

**Replaced Application:** APFIFF09V177  
**Used Firmware version:** NXP4.83 (V192)  
**System Software requirement:** NXPV195 (Recommendation)  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added MotorPower\_kW for monitoring ID79
- New selections for 4 mA and fieldbus fault responses.
- Added motor selection SRM
- Parameter Group U/f Settings changed to Open Loop
  - Added I/f start to Open Loop Group. Implemented also for induction motor NXP00002V195.
- F14 Unit temperature in Fault Word was not from Fault block, was not visible when making simulated fault, fixed.
- Safe Torque Off added to warning Word 1.B5.
- Added F42/W42 Brake Resistor fault to Fault Word 1.B9
- Added F12/W12 Brake Chopperto Fault Word 2.B7
- Control Options B14 do not disable Drive Synch if drive is not in Current Follower mode.

## **APFIFF09V177**

**Replaced Application:** APFIFF09V174  
**Used Firmware version:** NXP4.83  
**System Software requirement:** NXPV192  
**Released to field:** -  
**Used in production:** -  
**Changes in new application:**

- Added parameter to select encoder fault mode.
- Added parameter Over Load Minimum input.
- Added two new identification modes.

## **APFIFF09V174**

<b>Replaced Application:</b>	APFIFF09V173
<b>Used Firmware version:</b>	NXP4.83
<b>System Software requirement:</b>	NXPV192
<b>Released to field:</b>	8.6.2017
<b>Used in production:</b>	-
<b>Changes in new application:</b>	

- Added Closed Loop mode status to Status Word 2 B1

## **APFIFF09V173**

**Replaced Application:** APFIFF09V172  
**Used Firmware version:** NXP4.83  
**System Software requirement:** NXPV192  
**Released to field:** 8.6.2017  
**Used in production:** -  
**Changes in new application:**

- Added Identification Fail information for monitoring (ID98).
- Brake control waited Follower brake status after certain sequences while operating as a single drive, fixed.

## APFIFF09V172

**Replaced Application:** APFIFF09V171

**Used Firmware version:** NXP4.83

**System Software requirement:** NXPV192

**Released to field:** 27.3.2017

**Used in production:** -

**Changes in new application:**

- Start location B run enable did not work for start logic 2 and 7, fixed.
- Added P2.15.14.1 Stop Torque Release Time
- Datalogger signals changed depending on motor type and control mode.
- Added P2.12.14 Reset Datalogger

## **APFIFF09V171**

**Replaced Application:** APFIFF09V170  
**Used Firmware version:** NXP4.83  
**System Software requirement:** NXPV192  
**Released to field:** 16.3.2017  
**Used in production:** -  
**Changes in new application:**

- Control Options B14 disables Drive Synch, needed to activate in some cases when current follower function is used.



## **APFIFF09V170**

**Replaced Application:** APFIFF09V169

**Used Firmware version:** NXP4.83

**System Software requirement:** NXPV192

**Released to field:** 26.1.2017

**Used in production:** -

**Changes in new application:**

- Firmware interface updated to NXP4.83.
- AuxStatusWord.B10 shows also if torque control mode is selected in open loop control.

## APFIFF09V169

**Replaced Application:** APFIFF09V168  
**Used Firmware version:** NXP4.81  
**System Software requirement:** NXPV192  
**Released to field:** 26.10.2016  
**Used in production:** 26.10.2016  
**Changes in new application:**

- Power reference speed direction automatic update function added to Control Options 2.B01 when starting to rotating motor is done in power control (torque control) mode.
  - When torque select is "RampOutput" and shaft was rotating opposite direction compared to reference direction, actual speed was going back to zero when ramp output was going through zero.
- Software F1 Over Current was making ramping stop in certain cases, fixed.

## APFIFF09V168

**Replaced Application:** APFIFF09V165  
**Used Firmware version:** NXP4.81  
**System Software requirement:** NXPV192  
**Released to field:** 1.7.2016  
**Used in production:** -  
**Changes in new application:**

- MotPot function has new selection "StopReg;Fout". This makes a DigiPot functionality.
- Firmware interface update.
- Added "P2.8.8.12 FlyStAccFreqLim"
- Added "P2.12.5.11 OverCurrTripLim"
- Added "P2.8.6.21 EncIdRunMode"
- Added "P2.8.9.28 ID Run Curr. Kp"

## APFIFF09V165

**Replaced Application:** APFIFF09V164  
**Used Firmware version:** NXP4.76  
**System Software requirement:** NXPV189  
**Released to field:** 15.2.2016  
**Used in production:** 15.2.2015  
**Changes in new application:**

- Added Voltage Margin parameter
- Added Voltage Drop parameter
- Limited user possibility to change parameters in certain cases.

## APFIFF09V164

**Replaced Application:** APFIFF09V163  
**Used Firmware version:** NXP4.76  
**System Software requirement:** NXPV189  
**Released to field:**  
**Used in production:**  
**Changes in new application:**

- Rotor Flux as monitoring value.
- Added ABS values for torque supervision.

## APFIFF09V163

**Replaced Application:** APFIFF09V160

**Used Firmware version:** NXP4.76

**System Software requirement:** NXPV189

**Released to field:**

**Used in production:**

**Changes in new application:**

- P2.5.6.6 and P2.5.7.6 have the same text, fixed.
- Generator side torque follower was using limit from motoring side in some cases, fixed.
- Torque follower separated from torque limit ramp function, both can be used separately.
- Giving negative value to torque limit ramp rate will remove ramping.
  - Torque Ramp rate default -1 %.
- Giving negative value to power limit ramp rate will remove ramping.
  - Power ramp rate default -1 %.
- Added Status Word 2
  - B00 = Value Control SR state.
- Activating power limit ramp rate caused to power limit ramp from zero, fixed.
- In fieldbus board ByPass mode actual speed was always positive, fixed.

## **APFIFF09V160**

**Replaced Application:** APFIFF09V159  
**Used Firmware version:** NXP4.76  
**System Software requirement:** NXPV189  
**Released to field:** 9.9.2015  
**Used in production:** 9.9.2015  
**Changes in new application:**

- Flying Start tuning parameters added.

## **APFIFF09V159**

**Replaced Application:** APFIFF09V157  
**Used Firmware version:** NXP4.76  
**System Software requirement:** NXPV189  
**Released to field:** 9.6.2015  
**Used in production:** 9.6.2015  
**Changes in new application:**

- Torque limit follower has new option to follow generator side.
- In master follower system follower did not start if drive was not a Ramp follower and start stop mode was "As Master", fixed. Bug present since V147.



## APFIFF09V157

**Replaced Application:** APFIFF09V156

**Used Firmware version:** NXP4.76

**System Software requirement:** NXPV189

**Released to field:** 13.5.2015

**Used in production:** 13.5.2015

**Changes in new application:**

- Motor nominal speed minimum changed to 5 rpm
- Torque reference chain interpolator changed automatically based on reference location.
- V155 changes removed to allow further changes with released system softwares.

## **APFIFF09V156**

**Replaced Application:** APFIFF09V155  
**Used Firmware version:** NXP4.81  
**System Software requirement:** NXPV192 (Note)  
**Released to field:** 21.4.2015  
**Used in production:**  
**Changes in new application:**

- Added software level over current trip function F1 A4
- Added parameter for minimum flying start frequency.

## **APFIFF09V155**

**Replaced Application:** APFIFF09V152

**Used Firmware version:** NXP4.75

**System Software requirement:** NXPV188

**Released to field:**

**Used in production:**

**Changes in new application:**

- Added section for Fieldbus fault to activate quick stop.
- In DriveSynch operation some follower faults triggered master fault on fault reset even if follower was mend to stay in fault and other drives to stay operational.
- Changes in Datalogger default settings.

## **APFIFF09V152**

**Replaced Application:** APFIFF09V151

**Used Firmware version:** NXP4.75

**System Software requirement:** NXPV188

**Released to field:**

**Used in production:**

**Changes in new application:**

- Several changes to monitoring value limits, helps NCDrive use.
- Internal motor temperature compensation is not activated automatically if drive is in DriveSynch operation.
- Operation Hours added.
- W14 Unit Temperature simulation signal did not active DO indication, fixed.

## APFIFF09V151

**Replaced Application:** APFIFF09V148

**Used Firmware version:** NXP4.74

**System Software requirement:** NXPV188

**Released to field:**

**Used in production:**

**Changes in new application:**

- Updated monitoring groups and signals (SIA-II compatibility).
- Source Code converter to Vacon Programming.
- Several code improvements due better compiler.
- Updates to parameters grouping, some parameters are doubled in parameter three for usability.
- More accurate information in application level Status Word.
  - Signals taken from more informative place.
- Encoder 2 frequency as monitoring value ID53

## **APFIFF09V148**

**Replaced Application:** APFIFF09V147

**Used Firmware version:** NXP4.74

**System Software requirement:** NXPV188

**Released to field:**

**Used in production:**

**Changes in new application:**

- Added RR Enable digital input
- 4 mA fault and warning were not visible in Fault Word 1 nor in Warning Word 1
- Added Roll-Back Control parameters

## APFIFF09V147

**Replaced Application:** APFIFF09V146  
**Used Firmware version:** NXP4.74  
**System Software requirement:** NXPV187  
**Released to field:** March 14, 2014  
**Used in production:**  
**Changes in new application:**

- Continuing FBD to ST work
- PMSM selection will set:
  - Switching Frequency to 3,6 kHz if higher.
  - Modulator type to 1 if 0.
- Brake Chopper Active in Status Word B10.
- Quick Stop: RAMP, did not make ramp stop if normal stop function was Coasting, fixed.
- State Machine: Profidrive:
  - FB Control Word B0 will make ramp stop.
  - FB Control B1 will make always coasting stop.
- FBActualSpeed selection by default changed to 1.
  - 0 / Calculated to 1 / Actual.
    - 0 / Ramp Controller Output
    - 1 / OL: Calculated Speed. CL: Measured Speed.
- FB Actual Speed calculation uses now frequency [Hz] instead of speed [rpm], this is more accurate in high pole number motors.
- FBActualSpeedMode by default 1

## **APFIFF09V146**

**Replaced Application:** APFIFF09V144  
**Used Firmware version:** NXP4.74  
**System Software requirement:** NXPV187  
**Released to field:** January 22, 2014  
**Used in production:**  
**Changes in new application:**

- Added own ramp time for Quick Stop function.
- Start-Up Wizard disabled.



## APFIFF09V144

**Replaced Application:** APFIFF09V138  
**Used Firmware version:** NXP4.74  
**System Software requirement:** NXPV187  
**Released to field:** December 10, 2013  
**Used in production:** January 8, 2014  
**Changes in new application:**

- Improvements to identification handling on application level.
- Added filtering parameters for AI1 and AI2 signals, existing ones are for frequency reference chain only.
- Default switching frequency limited to 3,6 kHz.
- When magnetization current was given before identification run, U/f curve were supposed to set accordingly. This was not happening, Magnetization current were replaced with estimated magnetization current, fixed.

## **APFIFF09V138**

**Replaced Application:** APFIFF09V137  
**System Software requirement:** NXPV185  
**Used in production:** September, 2013  
**Changes in new application:**

- Added V: Shaft Frequency, previously V: Enc 1 Frequency, this is the frequency used by system software in closed loop control.
- Changed V: Enc 1 Frequency, to be direct monitoring from encoder board. No need of changes on PLC if already used.

## **APFIFF09V137**

**Replaced Application:** APFIFF09V135

**System Software requirement:** NXPV185

**Used in production:** August, 2013

**Changes in new application:**

- Status Word was not using final brake open command status, fixed. Fieldbus control was missing from status.
- Brake speed limit was reset from Drive Run Status; this caused error in speed release function in some cases. Brake speed release function uses now actual brake control status.

## **APFIFF09V135**

**Replaced Application:** APFIFF09V134

**System Software requirement:** NXPV185

**Used in production:** -

**Changes in new application:**

- Added status of active parameter set to Status Word B9. High when Set 2 is active.

## **APFIFF09V134**

**Replaced Application:** APFIFF09V131

**System Software requirement:** NXPV185

**Used in production:** April. 2013

**Changes in new application:**

- Joystick reference was not limited correctly by Pos and Neg frequency limits, fixed.
- Added PT100 fault and warning bits to FW10 and WW10.
- Added Frequency Delta as monitoring value.

## **APFIFF09V131**

**Replaced Application:** APFIFF09V130

**System Software requirement:** NXPV185

**Used in production:** Feb. 2013

**Changes in new application:**

- Changes to default operation:
  - By default ramp generator is updated when in closed loop control change from torque control to speed control is made.
  - By default follow encoder frequency in limiting situation is active.
- Analogue output did not have function 20 / Drive Output Power. Function was available for AO2, AO3 and AO4.

## APFIFF09V130

**Replaced Application:** APFIFF09V129

**System Software requirement:** NXPV185

**Used in production:**

**Changes in new application:**

- This version uses NXP3 V185 system software processor load reduction feature.
- More selection in Cooling Fault Response parameter.
  - 0= Stop State: No Action, Run State: Warning
  - 1= Stop State: Warning, Run State: Warning
  - 2= Stop State: Warning, Run State: Fault
  - 3= Stop State: No Action, Run State: Fault
- Cooling fault is not stored to fault history when drive is in stop state or no Run Request has been given.
- Cooling fault delay is started from zero when drive start or start command is received. Before fault was generated immediately if cooling input was low on stop state and start command was issued.

## **APFIFF09V129**

**Replaced Application:** APFIFF09V128

**System Software requirement:** NXPV184

**Used in production:**

**Changes in new application:**

- Added inversion bits for Generator Torque Lim and Motoring Torque Lim digital inputs to P2.4.7.1 INV Commands.



## APFIFF09V128

**Replaced Application:** APFIFF09V127

**System Software requirement:** NXPV184

**Used in production:**

**Changes in new application:**

- On V108 during minor code clean up: One line of code were removed that caused drive to lose Ready status if follower drive was not ramp follower and Follower stop function was 2 "As Master", fixed.
- Master – Follower brake control improvements.
  - **Compatibility Issue:** Earlier version, when operating in Ramp Follower mode, follower brake control closed the brake after master drive was in stop state. Now brake is closed in this mode at the same time as master drive is closing the brake.
  - Drive Synch follower brake control will use master drive brake control status.
  - Added parameter P2.11.5 MF Brake Logic to select brake functionality in follower drive. Also if selection 2 is made in master, drive will wait follower brake status before sending speed release command to follower drive.

## **APFIFF09V127**

**Replaced Application:** APFIFF09V126

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added MONO timer to Free DIN Delay function.
- Added over load function where input signal can be selected between Current, Torque and Power.
- Added function to detect if no motor is connected.
  - Current < 10 % of motor nominal at FreqOut > 10 Hz

## **APFIFF09V126**

**Replaced Application:** APFIFF09V125

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added function that enables to add delay function to any digital input function.

## **APFIFF09V125**

**Replaced Application:** APFIFF09V124

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added three digital inputs.
  - Start Place A/B
  - Start Signal 1B
  - Start Signal 2B

## **APFIFF09V124**

**Replaced Application:** APFIFF09V123

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added Earth Fault Warning bit to warning world

## APFIFF09V123

**Replaced Application:** APFIFF09V120

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added more comments to NCDrive help function. Select parameter text and press "F1"
- **Compatibility Issue** - Speed error monitoring status bits are moved from Fault Word 2 to Fault Word 10 B0 and from Warning Word 1 to Warning Word 10 B0.

## **APFIFF09V121**

**Replaced Application:** APFIFF09V120

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added Speed Error fault and warning bits to fault and warning words.

## APFIFF09V120

**Replaced Application:** APFIFF09V119

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added over temperature warning and fault to fault simulation word B7 & B8 (F14). Warning bit needs to be active that fault will come in simulation. If fault bit is left active drive will go fault state at warning limit when drive temperature will rise to warning level.
- **Compatibility Issue** - Temperature measurement board 2 has own response parameter.



## **APFIFF09V119**

**Replaced Application:** APFIFF09V118

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- It took few start attempts before 4 mA fault was reset permanently, fixed.
- Analogue input 2 4 mA monitoring was given faster than analogue input 1, fixed to same time.
- Added F8 System Fault to Fault Word 2 B13
- Added Power On and Energy counter for monitoring for fieldbus, not as keypad monitoring signals.

## **APFIFF09V118**

**Replaced Application:** APFIFF09V115

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- 4 mA bit in warning word was not functioning, fixed.
- Flux off delay function was not disabled when Quick stop with ramp was done, fixed.
- Motor Regulator Status as monitoring signal ID77
- Separate warning and fault limits for PT100 channels, activated when warning limit is different than zero.
- Added tuning parameters for encoder fault detection.

## **APFIFF09V115**

**Replaced Application:** APFIFF09V114

**System Software requirement:** NXPV183

**Used in production:**

**Changes in new application:**

- Added support for OPT-BH heat measurement board.
- Temperature measurement now monitors short-cut and broken cable. Gives sub code A2 and A3 respectively; these will be only warnings.
- Added a new digital input which saves active parameter set. Note that function will work only if parameter set selection is A.1 or higher.

## **APFIFF09V114**

**Replaced Application:** APFIFF09V113  
**System Software requirement:** NXPV183  
**Used in production:** February, 2012 (17.2)  
**Changes in new application:**

- Added analogue output function 20 / Drive output power, scaled with Motor Nom Power parameter.
- Delayed outputs has possibility to select ID.Bit to DO, Selection 28 / ID.Bit
- Added encoder fault information to Fault Word Bit 2
- Added ID Control DO2

## **APFIFF09V113**

<b>Replaced Application:</b>	APFIFF09V112
<b>System Software requirement:</b>	NXPV183
<b>Used in production:</b>	January, 2012 (23.1)
<b>Changes in new application:</b>	
• Added PIC Control function.	
• Added Fault Simulation Word.	

## **APFIFF09V112**

**Replaced Application:** APFIFF09V111  
**System Software requirement:** NXPV183  
**Used in production:** November, 2011 (16.11)  
**Changes in new application:**

- When fast profibus mode is used B15 is not updated in fixed control word, added logic that will disable process data locking if fast profibus mode is used.
- Restart delay minimum limit is set to 1 ms so that there will be no problem with init task, if set to zero value will be taken from firmware on power up.
- Added Flux Stab Coeff

## APFIFF09V111

**Replaced Application:** APFIFF09V110  
**System Software requirement:** NXPV183  
**Used in production:** October, 2011 (07.10)  
**Changes in new application:**

- Added current follower function
- Application data sending is disabled to master if SBLastId is higher than four.
- Added FW1.B0 Output Phase supervision
- Added OL under voltage reference selection
- Added OL under voltage reference value
- Added CL under voltage reference

## **APFIFF09V110**

**Replaced Application:** APFIFF09V109  
**System Software requirement:** NXPV183  
**Used in production:** Aug 12, 2011 (12.08)  
**Changes in new application:**

- Joystick function changed for frequency reference so that it will support 4-20 mA.
- Dead zone function for torque was subtracted from final reference when input was at maximum, fixed.
- AI dead zone do not affect anymore to torque reference. Use dead zone parameter in Torque Control group.



## **APFIFF09V109**

**Replaced Application:** APFIFF09V108  
**System Software requirement:** NXPV182  
**Used in production:** June 28, 2011 (28.06)  
**Changes in new application:**

- Added master control word for monitoring
- Resettable warning will go low for 1 s if different warning becomes active.
- Added separate fault numbers for External Fault 1 and external fault 2
- Inversion for external fault added to Inversion control
- Added start mode where start and stop are both rising pulses.

## **APFIFF09V108**

**Replaced Application:** APFIFF09V107

**Used Firmware version:**

**System Software requirement:** NXPV181

**Released to field:** June 14, 2011

**Used in production:**

**Changes in new application:**

- Added possibility to connect Value control function to AO, selection 19.
- Added two more DIN ID Control functions.
- Minor code clean up.

## APFIFF09V107

**Replaced Application:** APFIFF09V106  
**Used Firmware version:**  
**System Software requirement:** NXPV180  
**Released to field:** Feb 18, 2011  
**Used in production:** Feb 18, 2011  
**Changes in new application:**

- PMSM Identification encoder ID run changed to only encoder identification.
- SB Last ID added also to application level, value copied also to option board and other way round when changed.

## **APFIFF09V106**

**Replaced Application:** APFIFF09V105  
**Used Firmware version:**  
**System Software requirement:** NXPV180  
**Released to field:** Dec 14, 2010  
**Used in production:**  
**Changes in new application:**

- Fixed issue of limiting switching frequency when drive synch is activated.
- Added motoring and generator torque limit for DIN control.

## APFIFF09V105

**Replaced Application:** APFIFF09V104  
**Used Firmware version:**  
**System Software requirement:** NXPV179  
**Released to field:** Nov 2, 2010  
**Used in production:**  
**Changes in new application:**

- Thermistor warning added to warning word B1
- Load drooping removal function 2 did not work correctly, fixed.
- Added scaling for fieldbus reference.
- Added emergency stop function.
- MCStatus Word had wrong ID, fixed 68 -> 64, P2.13.19 GSW ID default changed to 64.
- Added profibus Status word ID 65
- Added ProfiDrive profile in application level, activated by Profibus Mode 2/ProfiDrive
- Added interpolator function, automatically set to 1 ms internally if ramp follower function is used.

## APFIFF09V104

**Replaced Application:** APFIFF09V103  
**Used Firmware version:**  
**System Software requirement:** NXPV179  
**Released to field:** Oct 6, 2010  
**Used in production:**  
**Changes in new application:**

- Default torque limit and power limit ramp rate increased 10000 %/s
- MotorCurrent D1 shows always own power unit current value and works also in single drive operation.

## APFIFF09V103

**Replaced Application:** APFIFF09V102  
**Used Firmware version:**  
**System Software requirement:** NXPV178  
**Released to field:** May 6, 2010  
**Used in production:** June 28, 2010  
**Changes in new application:**

- Monitoring value "MotorCurrent D1" is updated also when drive is operating in standard master follower mode.
- Open Loop Torque/Power limit function did not take minimum from P2.6.3.2 Motoring Torque Limit, only minimum from P2.6.2.3 MotoringPowerLimit and P2.6.3.1 Torque limit. This malfunction did not affect closed loop control.

## APFIFF09V102

**Replaced Application:** APFIFF09V101  
**Used Firmware version:**  
**System Software requirement:** NXPV178  
**Released to field:** April 20, 2010  
**Used in production:**  
**Changes in new application:**

- Minimum limit for closed loop under voltage controller lowered to 83 %.



## **APFIFF09V101**

**Replaced Application:** APFIFF09V100  
**Used Firmware version:**  
**System Software requirement:** NXPV178  
**Released to field:** March 29, 2010  
**Used in production:**  
**Changes in new application:**

- New application, based on PreMarine application APFIF129V096.