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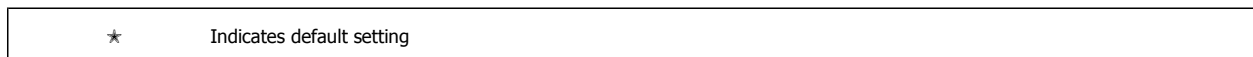
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1 Safety

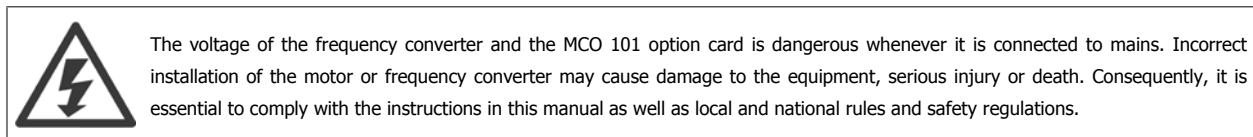
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1.1.1 Symbols

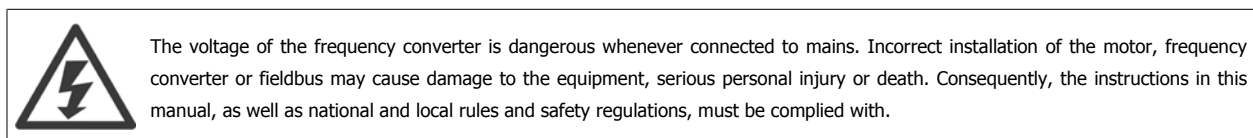
Symbols used in this manual:



1.1.2 High voltage warning



1.1.3 Safety note



Safety Regulations

1. The frequency converter must be disconnected from mains if repair work is to be carried out. Check that the mains supply has been disconnected and that the necessary time has passed before removing motor and mains plugs.
2. The [STOP/RESET] key on the LCP of the frequency converter does not disconnect the equipment from mains and is thus not to be used as a safety switch.
3. Correct protective earthing of the equipment must be established, the user must be protected against supply voltage, and the motor must be protected against overload in accordance with applicable national and local regulations.
4. The earth leakage currents are higher than 3.5 mA.
5. Protection against motor overload is set by par.1-90 *Motor Thermal Protection*. If this function is desired, set par.1-90 *Motor Thermal Protection* to data value [ETR trip] (default value) or data value [ETR warning]. Note: The function is initialised at 1.16 x rated motor current and rated motor frequency. For the North American market: The ETR functions provide class 20 motor overload protection in accordance with NEC.

1

6. Do not remove the plugs for the motor and mains supply while the frequency converter is connected to mains. Check that the mains supply has been disconnected and that the necessary time has passed before removing motor and mains plugs.
7. Please note that the frequency converter has more voltage inputs than L1, L2 and L3, when load sharing (linking of DC intermediate circuit) and external 24 V DC have been installed. Check that all voltage inputs have been disconnected and that the necessary time has passed before commencing repair work.

Installation at High Altitudes

Installation at high altitude:
 380 - 500 V, enclosure A, B and C: At altitudes above 2 km, please contact Danfoss regarding PELV.
 380 - 500 V, enclosure D, E and F: At altitudes above 3 km, please contact Danfoss regarding PELV.
 525 - 690 V: At altitudes above 2 km, please contact Danfoss regarding PELV.

Warning against Unintended Start

1. The motor can be brought to a stop by means of digital commands, bus commands, references or a local stop, while the frequency converter is connected to mains. If personal safety considerations make it necessary to ensure that no unintended start occurs, these stop functions are not sufficient.
2. While parameters are being changed, the motor may start. Consequently, the stop key [STOP/RESET] must always be activated; following which data can be modified.
3. A motor that has been stopped may start if faults occur in the electronics of the frequency converter, or if a temporary overload or a fault in the supply mains or the motor connection ceases.

Warning:
 Touching the electrical parts may be fatal - even after the equipment has been disconnected from mains.

Also make sure that other voltage inputs have been disconnected, such as external 24 V DC, load sharing (linkage of DC intermediate circuit), as well as the motor connection for kinetic back up. Refer to the Operating Instructions for further safety guidelines.

1.1.4 Caution

The frequency converter DC link capacitors remain charged after power has been disconnected. To avoid an electrical shock hazard, disconnect the frequency converter from the mains before carrying out maintenance. Wait at least as follows before doing service on the frequency converter:

| Voltage (V) | Min. Waiting Time (Minutes) | | | | |
|-------------|-----------------------------|-------------|--------------|---------------|---------------|
| | 4 | 15 | 20 | 30 | 40 |
| 200 - 240 | 1.1 - 3.7 kW | 5.5 - 45 kW | | | |
| 380 - 480 | 1.1 - 7.5 kW | 11 - 90 kW | 110 - 250 kW | | 315 - 1000 kW |
| 525-600 | 1.1 - 7.5 kW | 11 - 90 kW | | | |
| 525-690 | | 11 - 90 kW | 45 - 400 kW | 450 - 1200 kW | |

Be aware that there may be high voltage on the DC link even when the LEDs are turned off.

1.1.5 Before commencing repair work

1. Disconnect the frequency converter from mains
2. Disconnect DC bus terminals 88 and 89
3. Wait at least the time mentioned in section General Warning above
4. Remove motor cable

1.1.6 Special conditions

Electrical ratings:

The rating indicated on the nameplate of the frequency converter is based on a typical 3-phase mains power supply, within the specified voltage, current and temperature range, which is expected to be used in most applications.

The frequency converters also support other special applications, which affect the electrical ratings of the frequency converter. Special conditions which affect the electrical ratings might be:

- Single phase applications
- High temperature applications which require de-rating of the electrical ratings
- Marine applications with more severe environmental conditions.

Other applications might also affect the electrical ratings.

Consult the relevant sections in this manual and in the *VLT HVAC Drive Design Guide, MG.11.BX.YY* for information about the electrical ratings.

Installation requirements:

The overall electrical safety of the frequency converter requires special installation considerations regarding:

- Fuses and circuit breakers for over-current and short-circuit protection
- Selection of power cables (mains, motor, brake, loadsharing and relay)
- Grid configuration (IT, TN, grounded leg, etc.)
- Safety of low-voltage ports (PELV conditions).

Consult the relevant clauses in these instructions and in the *VLT HVAC Drive Design Guide* for information about the installation requirements.

1.1.7 Installation at high altitudes (PELV)



By altitudes above 2 km, please contact Danfoss regarding PELV.

1.1.8 Avoid unintended start

While the frequency converter is connected to mains, the motor can be started/stopped using digital commands, bus commands, references or via the Local Control Panel.

- Disconnect the frequency converter from mains whenever personal safety considerations make it necessary to avoid unintended start.
- To avoid unintended start, always activate the [OFF] key before changing parameters.
- Unless terminal 37 is turned off, an electronic fault, temporary overload, a fault in the mains supply, or lost motor connection may cause a stopped motor to start.

1.1.9 Safe Stop of the frequency converter

For versions fitted with a Safe Stop terminal 37 input, the frequency converter can perform the safety function *Safe Torque Off* (As defined by draft CD IEC 61800-5-2) or *Stop Category 0* (as defined in EN 60204-1).

It is designed and approved suitable for the requirements of Safety Category 3 in EN 954-1. This functionality is called Safe Stop. Prior to integration and use of Safe Stop in an installation, a thorough risk analysis on the installation must be carried out in order to determine whether the Safe Stop functionality and safety category are appropriate and sufficient. In order to install and use the Safe Stop function in accordance with the requirements of Safety

Category 3 in EN 954-1, the related information and instructions of the *VLT HVAC Drive Design Guide* must be followed! The information and instructions of the Operating Instructions are not sufficient for a correct and safe use of the Safe Stop functionality!

1

| | | |
|--|--|--|
| Prüf- und Zertifizierungsstelle im BG-PRÜFZERT |  | BGIA Berufsgenossenschaftliches Institut für Arbeitsschutz Hauptverband der gewerblichen Berufsgenossenschaften |
| Type Test Certificate | | 05 06004 |
| <u>Translation</u> In any case, the German original shall prevail. | | No. of certificate |
| Name and address of the holder of the certificate: (customer) | Danfoss Drives A/S, Ulnaes 1 DK-6300 Graasten, Dänemark | |
| Name and address of the manufacturer: | Danfoss Drives A/S, Ulnaes 1 DK-6300 Graasten, Dänemark | |
| Ref. of customer: | Ref. of Test and Certification Body: Apf/Köh VE-Nr. 2003 23220 | Date of Issue: 13.04.2005 |
| Product designation: | Frequency converter with integrated safety functions | |
| Type: | VLT® Automation Drive FC 302 | |
| Intended purpose: | Implementation of safety function „Safe Stop“ | |
| Testing based on: | EN 954-1, 1997-03, DKE AK 226.03, 1998-06, EN ISO 13849-2; 2003-12, EN 61800-3, 2001-02, EN 61800-5-1, 2003-09, | |
| Test certificate: | No.: 2003 23220 from 13.04.2005 | |
| Remarks: | The presented types of the frequency converter FC 302 meet the requirements laid down in the test bases. With correct wiring a category 3 according to DIN EN 954-1 is reached for the safety function. | |
| <hr/> The type tested complies with the provisions laid down in the directive 98/37/EC (Machinery). | | |
| Further conditions are laid down in the Rules of Procedure for Testing and Certification of April 2004. | | |
| Head of certification body  (Prof. Dr. rer. nat. Dietmar Reinert) | Certification officer  (Dipl.-Ing. R. Apfeld) | |
| PZB10E 01.05 |  | Postal address: 53754 Sankt Augustin |
| | | Office: Alte Heerstraße 111 53757 Sankt Augustin |
| | | Phone: 0 22 41/2 31-02 Fax: 0 22 41/2 31-22 34 130BA491 |

This certificate also covers FC 102 and FC 202!

1.1.10 IT mains

**IT Mains**

Do not connect frequency converters with RFI-filters to mains supplies with a voltage between phase and earth of more than 440 V for 400 V converters and 760 V for 690 V converters.

For 400 V IT mains and delta earth (grounded leg), mains voltage may exceed 440 V between phase and earth.

For 690 V IT mains and delta earth (grounded leg), mains voltage may exceed 760 V between phase and earth.

1

par. 14-50 *RFI Filter* can be used to disconnect the internal RFI capacitors from the RFI filter to ground.

1.1.11 Software version and approvals: VLT HVAC Drive

VLT HVAC Drive
Software version: 3.1.x



This manual can be used with all VLT HVAC Drive frequency converters with software version 3.1.x.
The software version number can be seen from par. 15-43 *Software Version*.

1.1.12 Disposal instruction



Equipment containing electrical components must not be disposed of together with domestic waste.
It must be separately collected with electrical and electronic waste according to local and currently valid legislation.

2

2 Introduction

2.1 Introduction

2.1.1 Available literature for VLT HVAC Drive

2

- Operating Instructions MG.11.Ax.yy provide the necessary information for getting the frequency converter up and running.
- Operating Instructions VLT HVAC Drive High Power, MG.11.Fx.yy
- Design Guide MG.11.Bx.yy entails all technical information about the frequency converter and customer design and applications.
- Programming Guide MG.11.Cx.yy provides information on how to programme and includes complete parameter descriptions.
- Mounting Instruction, Analog I/O Option MCB109, MI.38.Bx.yy
- Application Note, Temperature Derating Guide, MN.11.Ax.yy
- PC-based Configuration Tool MCT 10, MG.10.Ax.yy enables the user to configure the frequency converter from a Windows™ based PC environment.
- Danfoss VLT® Energy Box software at www.danfoss.com/BusinessAreas/DrivesSolutions then choose PC Software Download
- VLT® VLT HVAC Drive Drive Applications, MG.11.Tx.yy
- Operating Instructions VLT HVAC Drive Profibus, MG.33.Cx.yy.
- Operating Instructions VLT HVAC Drive Device Net, MG.33.Dx.yy
- Operating Instructions VLT HVAC Drive BACnet, MG.11.Dx.yy
- Operating Instructions VLT HVAC Drive LonWorks, MG.11.Ex.yy
- Operating Instructions VLT HVAC Drive Metasys, MG.11.Gx.yy
- Operating Instructions VLT HVAC Drive FLN, MG.11.Zx.yy
- Output Filter Design Guide, MG.90.Nx.yy
- Brake Resistor Design Guide, MG.90.Ox.yy

x = Revision number

yy = Language code

Danfoss technical literature is available in print from your local Danfoss Sales Office or online at:
www.danfoss.com/BusinessAreas/DrivesSolutions/Documentations/Technical+Documentation.htm

2.1.2 Abbreviations and Standards

2

| Abbreviations: | Terms: | SI-units: | I-P units: |
|------------------|-------------------------------|-----------------------|-----------------------|
| a | Acceleration | m/s ² | ft/s ² |
| AWG | American wire gauge | | |
| Auto Tune | Automatic Motor Tuning | | |
| °C | Celsius | | |
| I | Current | A | Amp |
| I _{LIM} | Current limit | | |
| Joule | Energy | J = N•m | ft-lb, Btu |
| °F | Fahrenheit | | |
| FC | Frequency Converter | | |
| f | Frequency | Hz | Hz |
| kHz | Kilohertz | kHz | kHz |
| LCP | Local Control Panel | | |
| mA | Milliampere | | |
| ms | Millisecond | | |
| min | Minute | | |
| MCT | Motion Control Tool | | |
| M-TYPE | Motor Type Dependent | | |
| Nm | Newton Metres | | in-lbs |
| I _{M,N} | Nominal motor current | | |
| f _{M,N} | Nominal motor frequency | | |
| P _{M,N} | Nominal motor power | | |
| U _{M,N} | Nominal motor voltage | | |
| par. | Parameter | | |
| PELV | Protective Extra Low Voltage | | |
| Watt | Power | W | Btu/hr, hp |
| Pascal | Pressure | Pa = N/m ² | psi, psf, ft of water |
| I _{INV} | Rated Inverter Output Current | | |
| RPM | Revolutions Per Minute | | |
| SR | Size Related | | |
| T | Temperature | C | F |
| t | Time | s | s,hr |
| T _{LIM} | Torque limit | | |
| U | Voltage | V | V |

Table 2.1: Abbreviation and Standards table .

2.1.3 Frequency Converter Identification

Below is an example of an identification label. This label is situated on the frequency converter and shows the type and options fitted to the unit. See below for details of how to read the Type code string (T/C).



Illustration 2.1: This example shows an identification label.



NB!

Please have T/C (type code) number and serial number ready before contacting Danfoss.

2.1.4 Type Code String Low and Medium Power

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------------|---|---|---|---|---|---|---|---|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|--|---|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | | |
| FC- | | | | 0 | P | | | | T | | | | | | | | | | | | | | X | S | X | X | X | X | A | | B | | C | | | | | | | D |
| 130BA052.15 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

| Description | Pos | Possible choice |
|---------------------------|-------|---|
| Product group & FC Series | 1-6 | FC 102 |
| Power rating | 8-10 | 1.1 - 90 kW (P1K1 - P90K) |
| Number of phases | 11 | Three phases (T) |
| Mains voltage | 11-12 | T 2: 200-240 VAC T 4: 380-480 VAC T 6: 525-600 VAC |
| Enclosure | 13-15 | E20: IP20 E21: IP 21/NEMA Type 1 E55: IP 55/NEMA Type 12 E66: IP66 P21: IP21/NEMA Type 1 w/backplate P55: IP55/NEMA Type 12 w/backplate |
| RFI filter | 16-17 | H1: RFI filter class A1/B H2: RFI filter class A2 H3: RFI filter class A1/B (reduced cable length) Hx: No RFI filter |
| Brake | 18 | X: No brake chopper included B: Brake chopper included T: Safe Stop U: Safe + brake |
| Display | 19 | G: Graphical Local Control Panel (GLCP) N: Numeric Local Control Panel (NLCP) X: No Local Control Panel |
| Coating PCB | 20 | X: No coated PCB C: Coated PCB |
| Mains option | 21 | X: No Mains disconnect switch and Load Sharing 1: With Mains disconnect switch (IP55 only) 8: Mains disconnect and Load Sharing D: Load Sharing See Chapter 8 for max. cable sizes. |
| Adaptation | 22 | X: Standard 0: European metric thread in cable entries. |
| Adaptation | 23 | Reserved |
| Software release | 24-27 | Actual software |
| Software language | 28 | |
| A options | 29-30 | AX: No options A0: MCA 101 Profibus DP V1 A4: MCA 104 DeviceNet AG: MCA 108 Lonworks AJ: MCA 109 BACnet gateway |
| B options | 31-32 | BX: No option BK: MCB 101 General purpose I/O option BP: MCB 105 Relay option BO: MCB 109 Analog I/O option |
| C0 options MCO | 33-34 | CX: No options |
| C1 options | 35 | X: No options |
| C option software | 36-37 | XX: Standard software |
| D options | 38-39 | DX: No option D0: DC back-up |

Table 2.2: Type code description.

The various Options and Accessories are described further in the *VLT HVAC Drive Design Guide, MG.11.BX.YY.*

3

3 Mechanical Installation

3.1 Before starting

3.1.1 Checklist

When unpacking the frequency converter, ensure that the unit is undamaged and complete. Use the following table to identify the packaging:

3

| Enclosure type: | A2 (IP 20-21) | A3 (IP 20-21) | A5 (IP 55-66) | B1/B3 (IP 20-21-55-66) | B2/B4 (IP 20-21-55-66) | C1/C3 (IP 20-21-55-66) | C2*/C4 (IP 20-21-55-66) |
|------------------------|------------------|------------------|------------------|---------------------------|---------------------------|---------------------------|----------------------------|
| | | | | | | | |
| Unit size (kW): | | | | | | | |
| 200-240 V | 1.1-3.0 | 3.7 | 1.1-3.7 | 5.5-11/ 5.5-11 | 15/ 15-18.5 | 18.5-30/ 22-30 | 37-45/ 37-45 |
| 380-480 V | 1.1-4.0 | 5.5-7.5 | 1.1-7.5 | 11-18.5/ 11-18.5 | 22-30/ 22-37 | 37-55/ 45-55 | 75-90/ 75-90 |
| 525-600 V | | 1.1-7.5 | 1.1-7.5 | 11-18.5/ 11-18.5 | 22-30/ 22-37 | 37-55/ 45-55 | 75-90/ 75-90 |

Table 3.1: Unpacking table

Please note that a selection of screwdrivers (Phillips or cross-thread screwdriver and Torx), a side-cutter, drill and knife is also recommended to have handy for unpacking and mounting the frequency converter. The packaging for these enclosures contains, as shown: Accessories bag(s), documentation and the unit. Depending on options fitted there may be one or two bags and one or more booklets.

3.2.2 Mechanical Dimensions

| Frame size (kW): | Mechanical dimensions | | | | | | | | | | | |
|-------------------------------|-----------------------|---------|---------|-----------|-----------|---------|---------|-----------|-----------|---------|---------|--|
| | A2 | A3 | A5 | B1 | B2 | B3 | B4 | C1 | C2 | C3 | C4 | |
| 200-240 V | 1.1-3.0 | 3.7 | 1.1-3.7 | 5.5-11 | 15 | 5.5-11 | 15-18.5 | 18.5-30 | 37-45 | 22-30 | 37-45 | |
| 380-480 V | 1.1-4.0 | 5.5-7.5 | 1.1-7.5 | 11-18.5 | 22-30 | 11-18.5 | 22-37 | 37-55 | 75-90 | 45-55 | 75-90 | |
| 525-600 V | - | 1.1-7.5 | 1.1-7.5 | 11-18.5 | 22-30 | 11-18.5 | 22-37 | 37-55 | 75-90 | 45-55 | 75-90 | |
| IP | 20 | 21 | 55/66 | 21/ 55/66 | 21/ 55/66 | 20 | 20 | 21/ 55/66 | 21/ 55/66 | 20 | 20 | |
| NEMA | Chassis | Type 1 | Type 12 | Type 1/12 | Type 1/12 | Chassis | Chassis | Type 1/12 | Type 1/12 | Chassis | Chassis | |
| Height (mm) | | | | | | | | | | | | |
| Enclosure | A** | 246 | 372 | 420 | 480 | 350 | 460 | 680 | 770 | 490 | 600 | |
| .with de-coupling plate | A2 | 374 | - | - | - | 419 | 595 | - | - | 630 | 800 | |
| Back plate | A1 | 268 | 375 | 420 | 480 | 399 | 520 | 680 | 770 | 550 | 660 | |
| Distance between mount. holes | a | 257 | 350 | 402 | 454 | 380 | 495 | 648 | 739 | 521 | 631 | |
| Width (mm) | | | | | | | | | | | | |
| Enclosure | B | 90 | 130 | 242 | 242 | 165 | 231 | 308 | 370 | 308 | 370 | |
| With one C option | B | 130 | 170 | 242 | 242 | 205 | 231 | 308 | 370 | 308 | 370 | |
| Back plate | B | 90 | 130 | 242 | 242 | 165 | 231 | 308 | 370 | 308 | 370 | |
| Distance between mount. holes | b | 70 | 110 | 215 | 210 | 140 | 200 | 272 | 334 | 270 | 330 | |
| Depth (mm) | | | | | | | | | | | | |
| Without option A/B | C | 205 | 205 | 200 | 260 | 248 | 242 | 310 | 335 | 333 | 333 | |
| With option A/B | C* | 220 | 220 | 200 | 260 | 262 | 242 | 310 | 335 | 333 | 333 | |
| Screw holes (mm) | | | | | | | | | | | | |
| c | 8.0 | 8.0 | 8.0 | 8.2 | 12 | 8 | - | 12 | 12 | - | - | |
| d | 11 | 11 | 11 | 12 | 19 | 12 | - | 19 | 19 | - | - | |
| e | 5.5 | 5.5 | 5.5 | 6.5 | 9 | 6.8 | 8.5 | 9.0 | 9.0 | 8.5 | 8.5 | |
| f | 9 | 9 | 9 | 9 | 9 | 7.9 | 15 | 9.8 | 9.8 | 17 | 17 | |
| Max weight (kg) | 4.9 | 5.3 | 6.6 | 7.0 | 23 | 12 | 23.5 | 45 | 65 | 35 | 50 | |

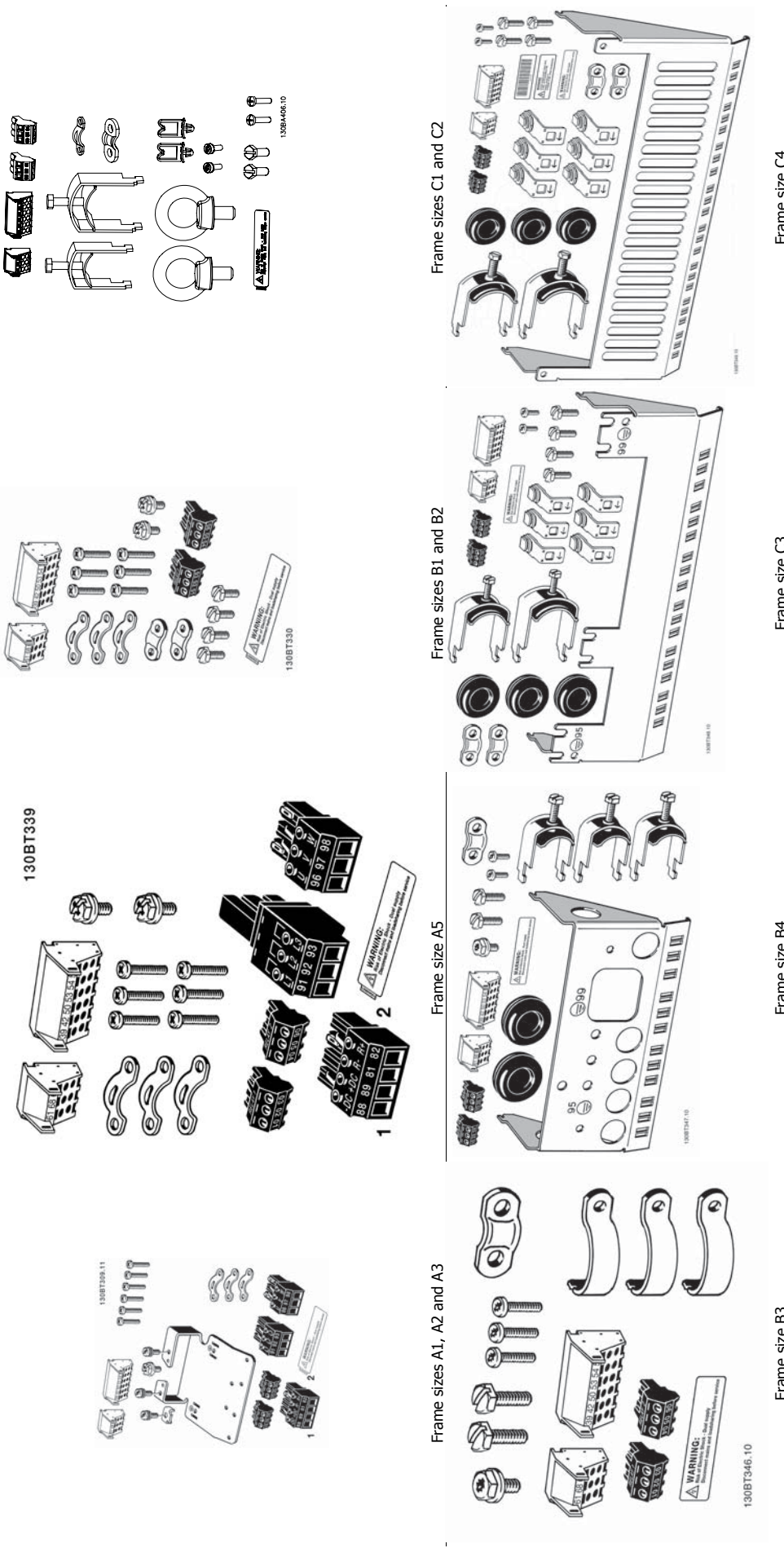
* Depth of enclosure will vary with different options installed.

** The free space requirements are above and below the bare enclosure height measurement A. See section 3.2.3 for further information.

3

3.2.3 Accessory Bags

Accessory Bags: Find the following parts included in the frequency converter accessory bags



1 + 2 only available in units with brake chopper. For DC link connection (Load sharing) the connector 1 can be ordered separately (Code no. 130B1064)
An eight pole connector is included in accessory bag for FC 102 without Safe Stop.

3.2.4 Mechanical mounting

All IP20 enclosure sizes as well as IP21/ IP55 enclosure sizes except A2 and A3 allow side-by-side installation.

If the IP 21 Enclosure kit (130B1122 or 130B1123) is used on enclosure A2 or A3, there must be a clearance between the drives of min. 50 mm.

For optimal cooling conditions allow a free air passage above and below the frequency converter. See table below.

Air passage for different enclosures

| Enclosure: | A2 | A3 | A5 | B1 | B2 | B3 | B4 | C1 | C2 | C3 | C4 |
|------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| a (mm): | 100 | 100 | 100 | 200 | 200 | 200 | 200 | 200 | 225 | 200 | 225 |
| b (mm): | 100 | 100 | 100 | 200 | 200 | 200 | 200 | 200 | 225 | 200 | 225 |

1. Drill holes in accordance with the measurements given.
2. You must provide screws suitable for the surface on which you want to mount the frequency converter. Re-tighten all four screws.

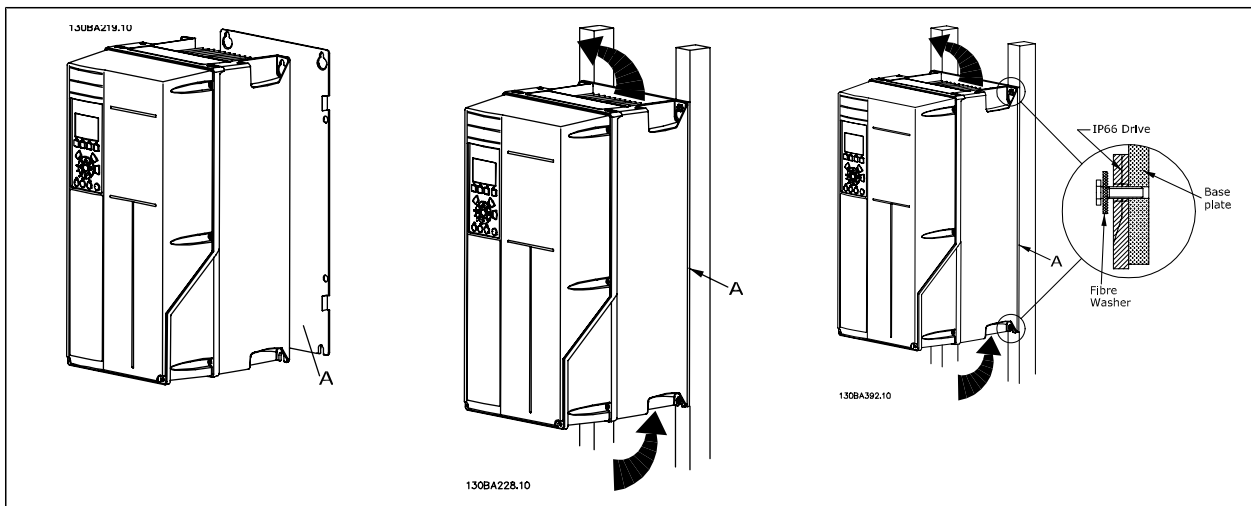


Table 3.2: Mounting frame sizes A5, B1, B2, B3, B4, C1, C2, C3 and C4 on a non-solid back wall, the drive must be provided with a back plate A due to insufficient cooling air over the heat sink.

With heavier drives (B4, C3, C4) use a lift. First wall-mount the 2 lower bolts - then lift the drive onto the lower bolts - finally fasten the drive against the wall with the 2 top bolts.

3.2.5 Safety Requirements of Mechanical Installation

Pay attention to the requirements that apply to integration and field mounting kit. Observe the information in the list to avoid serious damage or injury, especially when installing large units.

The frequency converter is cooled by means of air circulation.

To protect the unit from overheating, it must be ensured that the ambient temperature *does not exceed the maximum temperature stated for the frequency converter* and that the 24-hour average temperature *is not exceeded*. Locate the maximum temperature and 24-hour average in the paragraph *Derating for Ambient Temperature*.

If the ambient temperature is in the range of 45 °C - 55 °C, derating of the frequency converter will become relevant, see *Derating for Ambient Temperature*.

The service life of the frequency converter is reduced if derating for ambient temperature is not taken into account.

3.2.6 Field Mounting

For field mounting the IP 21/IP 4X top/TYPE 1 kits or IP 54/55 units are recommended.

3

3.2.7 Panel Through Mounting

A Panel Through Mount Kit is available for frequency converter series VLT HVAC Drive, VLT Aqua Drive and.

In order to increase heatsink cooling and reduce panel depth, the frequency converter may be mounted in a through panel. Furthermore the in-built fan can then be removed.

The kit is available for enclosures A5 through C2.



NB!

This kit cannot be used with cast front covers. No cover or IP21 plastic cover must be used instead.

Information on ordering numbers is found in the *Design Guide*, section *Ordering Numbers*.

More detailed information is available in the *Panel Through Mount Kit instruction*, *MI.33.H1.YY*, where yy=language code.

4 Electrical Installation

4.1 How to connect

4.1.1 Cables General


NB!

For the VLT HVAC Drive High Power series mains and motor connections, please see VLT HVAC Drive *High Power Operating Instructions MG.11.FX.YY*.


NB!
Cables General

All cabling must comply with national and local regulations on cable cross-sections and ambient temperature. Copper (60/75 °C) conductors are recommended.

4

Details of terminal tightening torques.

| Enclosure | Power (kW) | | | Torque (Nm) | | | | | |
|---------------------|------------|-----------|-----------|---------------------|---------------------|---------------|-------|-------|-------|
| | 200-240 V | 380-480 V | 525-600 V | Mains | Motor | DC connection | Brake | Earth | Relay |
| A2 | 1.1 - 3.0 | 1.1 - 4.0 | 1.1 - 4.0 | 1.8 | 1.8 | 1.8 | 1.8 | 3 | 0.6 |
| A3 | 3.7 | 5.5 - 7.5 | 5.5 - 7.5 | 1.8 | 1.8 | 1.8 | 1.8 | 3 | 0.6 |
| A5 | 1.1 - 3.7 | 1.1 - 7.5 | 1.1 - 7.5 | 1.8 | 1.8 | 1.8 | 1.8 | 3 | 0.6 |
| B1 | 5.5 - 11 | 11 - 18.5 | - | 1.8 | 1.8 | 1.5 | 1.5 | 3 | 0.6 |
| B2 | - | 22 | - | 4.5 | 4.5 | 3.7 | 3.7 | 3 | 0.6 |
| | 15 | 30 | - | 4.5 ²⁾ | 4.5 ²⁾ | 3.7 | 3.7 | 3 | 0.6 |
| B3 | 5.5 - 11 | 11 - 18.5 | 11 - 18.5 | 1.8 | 1.8 | 1.8 | 1.8 | 3 | 0.6 |
| B4 | 11 - 18.5 | 18.5 - 37 | 18.5 - 37 | 4.5 | 4.5 | 4.5 | 4.5 | 3 | 0.6 |
| C1 | 18.5 - 30 | 37 - 55 | - | 10 | 10 | 10 | 10 | 3 | 0.6 |
| C2 | 37 - 45 | 75 - 90 | - | 14/24 ¹⁾ | 14/24 ¹⁾ | 14 | 14 | 3 | 0.6 |
| C3 | 18.5 - 30 | 37 - 55 | 37 - 55 | 10 | 10 | 10 | 10 | 3 | 0.6 |
| C4 | 30 - 45 | 55 - 90 | 55 - 90 | 14/24 ¹⁾ | 14/24 ¹⁾ | 14 | 14 | 3 | 0.6 |
| High Power | | | | | | | | | |
| Enclosure | 525-690 V | | | Mains | Motor | DC connection | Brake | Earth | Relay |
| D1/D3 | 45-160 | | | 19 | 19 | 9.6 | 9.6 | 19 | 0.6 |
| D2/D4 | 200-400 | | | 19 | 19 | 9.6 | 9.6 | 19 | 0.6 |
| E1/E2 | 450-630 | | | 19 | 19 | 19 | 9.6 | 19 | 0.6 |
| F1-F3 ³⁾ | 710-900 | | | 19 | 19 | 19 | 9.6 | 19 | 0.6 |
| F2-F4 ³⁾ | 1000-1200 | | | 19 | 19 | 19 | 9.6 | 19 | 0.6 |

Table 4.1: Tightening of terminals

- 1) For different cable dimensions x/y, where $x \leq 95 \text{ mm}^2$ and $y \geq 95 \text{ mm}^2$
- 2) Cable dimensions above 18.5 kW $\geq 35 \text{ mm}^2$ and below 22 kW $\leq 10 \text{ mm}^2$
- 3) For data on the F-series please consult VLT® HVAC Drive High Power Operating Instructions, MG.11.F1.02

4.1.2 Electrical Installation and Control Cables

4

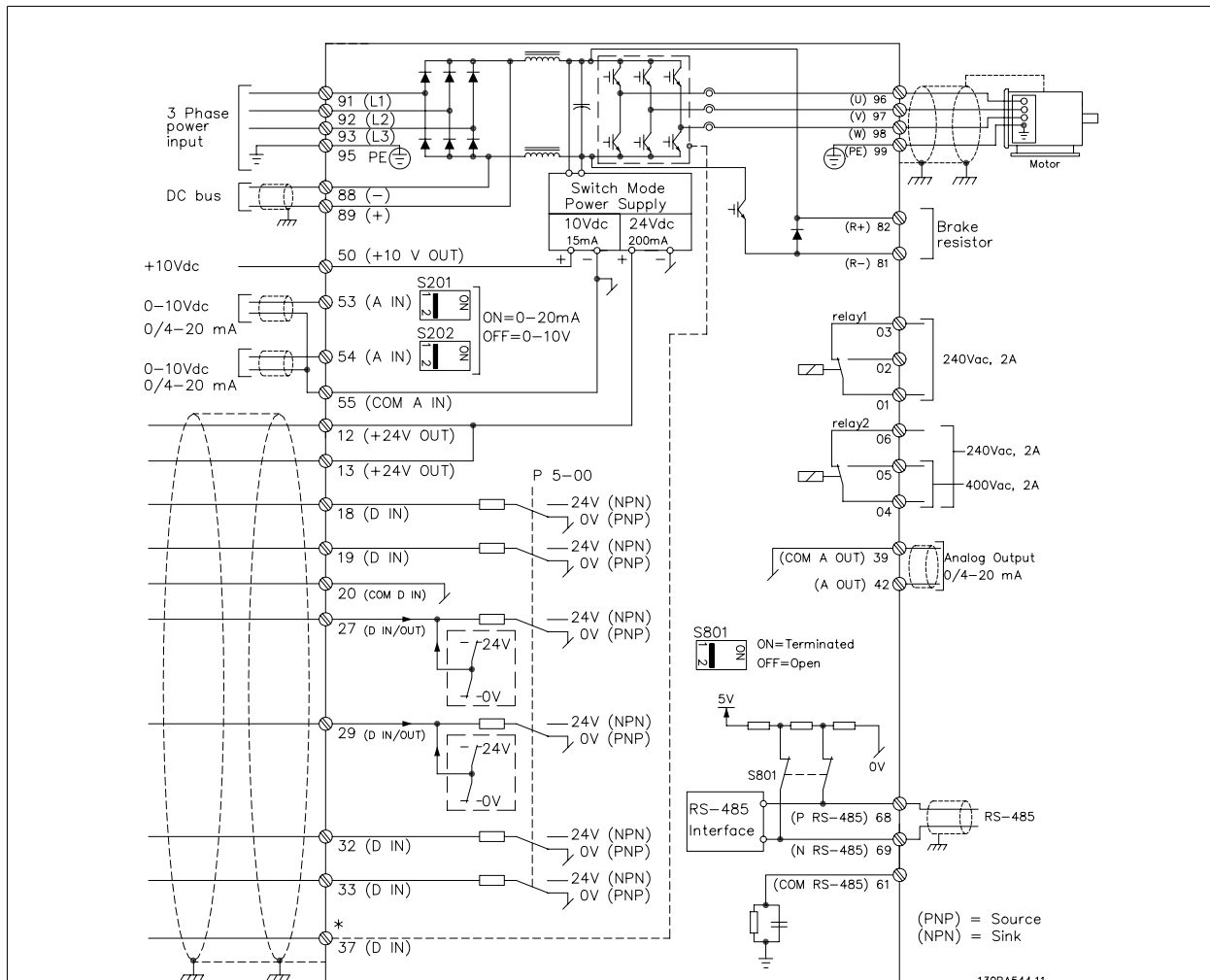


Illustration 4.1: Diagram showing all electrical terminals. (Terminal 37 present for units with Safe Stop Function only.)

| Terminal number | Terminal description | Parameter number | Factory default |
|-----------------|----------------------------------|------------------|-----------------|
| 1+2+3 | Terminal 1+2+3-Relay1 | 5-40 | No operation |
| 4+5+6 | Terminal 4+5+6-Relay2 | 5-40 | No operation |
| 12 | Terminal 12 Supply | - | +24 VDC |
| 13 | Terminal 13 Supply | - | +24 VDC |
| 18 | Terminal 18 Digital Input | 5-10 | Start |
| 19 | Terminal 19 Digital Input | 5-11 | No operation |
| 20 | Terminal 20 | - | Common |
| 27 | Terminal 27 Digital Input/Output | 5-12/5-30 | Coast inverse |
| 29 | Terminal 29 Digital Input/Output | 5-13/5-31 | Jog |
| 32 | Terminal 32 Digital Input | 5-14 | No operation |
| 33 | Terminal 33 Digital Input | 5-15 | No operation |
| 37 | Terminal 37 Digital Input | - | Safe Stop |
| 42 | Terminal 42 Analog Output | 6-50 | Speed 0-HighLim |
| 53 | Terminal 53 Analog Input | 3-15/6-1*/20-0* | Reference |
| 54 | Terminal 54 Analog Input | 3-15/6-2*/20-0* | Feedback |

Table 4.2: Terminal connections

Very long control cables and analog signals may, in rare cases and depending on installation, result in 50/60 Hz earth loops due to noise from mains supply cables.

If this occurs, break the screen or insert a 100 nF capacitor between screen and chassis.

**NB!**

The common of digital / analog inputs and outputs should be connected to separate common terminals 20, 39, and 55. This will avoid ground current interference among groups. For example, it avoids switching on digital inputs disturbing analog inputs.

**NB!**

Control cables must be screened/armoured.

4.1.3 Fuses

Branch circuit protection

In order to protect the installation against electrical and fire hazard, all branch circuits in an installation, switch gear, machines etc., must be short-circuit and over-current protected according to the national/international regulations.

Short circuit protection

The frequency converter must be protected against short-circuit to avoid electrical or fire hazard. Danfoss recommends using the fuses mentioned below to protect service personnel or other equipment in case of an internal failure in the unit. The frequency converter provides full short circuit protection in case of a short-circuit on the motor output.

Over-current protection

Provide overload protection to avoid fire hazard due to overheating of the cables in the installation. Over current protection must always be carried out according to national regulations. The frequency converter is equipped with an internal over current protection that can be used for upstream overload protection (UL-applications excluded). See par. 4-18 *Current Limit* in the *VLT HVAC Drive Programming Guide*. Fuses must be designed for protection in a circuit capable of supplying a maximum of 100,000 A_{rms} (symmetrical), 500 V/600 V maximum.

Non UL compliance

If UL/cUL is not to be complied with, Danfoss recommends using the fuses mentioned in the table below, which will ensure compliance with EN50178. In case of malfunction, not following the recommendation may result in unnecessary damage to the frequency converter.

Non UL compliance

| Frequency converter | Max. fuse size | Voltage | Type |
|---|-------------------|-----------|---------|
| 200-240 V - T2 | | | |
| 1K1-1K5 | 16A ¹ | 200-240 V | type gG |
| 2K2 | 25A ¹ | 200-240 V | type gG |
| 3K0 | 25A ¹ | 200-240 V | type gG |
| 3K7 | 35A ¹ | 200-240 V | type gG |
| 5K5 | 50A ¹ | 200-240 V | type gG |
| 7K5 | 63A ¹ | 200-240 V | type gG |
| 11K | 63A ¹ | 200-240 V | type gG |
| 15K | 80A ¹ | 200-240 V | type gG |
| 18K5 | 125A ¹ | 200-240 V | type gG |
| 22K | 125A ¹ | 200-240 V | type gG |
| | 160A ¹ | 200-240 V | type gG |
| 37K | 200A ¹ | 200-240 V | type aR |
| 45K | 250A ¹ | 200-240 V | type aR |
| 380-480 V - T4 | | | |
| 1K1-1K5 | 10A ¹ | 380-500 V | type gG |
| 2K2-3K0 | 16A ¹ | 380-500 V | type gG |
| 4K0-5K5 | 25A ¹ | 380-500 V | type gG |
| 7K5 | 35A ¹ | 380-500 V | type gG |
| 11K-15K | 63A ¹ | 380-500 V | type gG |
| 18K | 63A ¹ | 380-500 V | type gG |
| 22K | 63A ¹ | 380-500 V | type gG |
| 30K | 80A ¹ | 380-500 V | type gG |
| 37K | 100A ¹ | 380-500 V | type gG |
| 45K | 125A ¹ | 380-500 V | type gG |
| 55K | 160A ¹ | 380-500 V | type gG |
| 75K | 250A ¹ | 380-500 V | type aR |
| 90K | 250A ¹ | 380-500 V | type aR |
| 1) Max. fuses - see national/international regulations for selecting an applicable fuse size. | | | |

Table 4.3: Non UL fuses 200 V to 480 V

| Size/Type | Rating plug catalog # | Amps |
|-----------|-----------------------|------|
| P110 | SRPK800A300 | 300 |
| P132 | SRPK800A350 | 350 |
| P160 | SRPK800A400 | 400 |
| P200 | SRPK800A500 | 500 |
| P250 | SRPK800A600 | 600 |

Table 4.4: D enclosures, 380-480 V

| Size/Type | Bussmann PN* | Rating | Ferraz | Siba |
|-----------|--------------|--------------|------------------|---------------|
| P250 | 170M4017 | 700 A, 700 V | 6.9URD31D08A0700 | 20 610 32.700 |
| P315 | 170M6013 | 900 A, 700 V | 6.9URD33D08A0900 | 20 630 32.900 |
| P355 | 170M6013 | 900 A, 700 V | 6.9URD33D08A0900 | 20 630 32.900 |
| P400 | 170M6013 | 900 A, 700 V | 6.9URD33D08A0900 | 20 630 32.900 |

Table 4.5: E enclosures, 380-480 V

| Danfoss PN | Bussmann | Ferraz | Siba |
|------------|----------|------------------|---------------|
| 20220 | 170M4017 | 6.9URD31D08A0700 | 20 610 32.700 |
| 20221 | 170M6013 | 6.9URD33D08A0900 | 20 630 32.900 |

Table 4.6: Additional Fuses for Non-UL Applications, E enclosures, 380-480 V

| Size/Type | Bussmann PN* | Danfoss PN | Rating | Losses (W) |
|-----------|----------------------|------------|--------------|------------|
| P355 | 170M4017 170M5013 | 20220 | 700 A, 700 V | 85 |
| P400 | 170M4017 170M5013 | 20220 | 700 A, 700 V | 85 |
| P500 | 170M6013 | 20221 | 900 A, 700 V | 120 |
| P560 | 170M6013 | 20221 | 900 A, 700 V | 120 |

Table 4.7: E enclosures, 525-600 V

*170M fuses from Bussmann shown use the -/80 visual indicator, -TN/80 Type T, -/110 or TN/110 Type T indicator fuses of the same size and amperage may be substituted for external use.

| Danfoss PN | Bussmann | Ferraz | Siba |
|------------|----------|------------------|---------------|
| 20220 | 170M4017 | 6.9URD31D08A0700 | 20 610 32.700 |
| 20221 | 170M6013 | 6.9URD33D08A0900 | 20 630 32.900 |

Table 4.8: Additional Fuses for Non-UL Applications E enclosures, 525-600 V

Suitable for use on a circuit capable of delivering not more than 100 000 rms symmetrical amperes, 500/600/690 Volts maximum when protected by the above fuses.

If UL/cUL is not to be complied with, we recommend using the following fuses, which will ensure compliance with EN50178:

In case of malfunction, not following the recommendation may result in unnecessary damage to the frequency converter.

| | | |
|-------------|-------------|---------|
| P110 - P200 | 380 - 500 V | type gG |
| P250 - P450 | 380 - 500 V | type gR |

Table 4.9: Additional High Power Non UL compliance

UL Compliance

| Frequency converter | Bussmann | Bussmann | Bussmann | SIBA | Littel fuse | Ferraz-Shawmut | Ferraz-Shawmut |
|---------------------|----------|----------|----------|-------------|-------------|----------------|----------------|
| 200-240 V | | | | | | | |
| kW | Type RK1 | Type J | Type T | Type RK1 | Type RK1 | Type CC | Type RK1 |
| K25-K37 | KTN-R05 | JKS-05 | JJN-05 | 5017906-005 | KLN-R005 | ATM-R05 | A2K-05R |
| K55-1K1 | KTN-R10 | JKS-10 | JJN-10 | 5017906-010 | KLN-R10 | ATM-R10 | A2K-10R |
| 1K5 | KTN-R15 | JKS-15 | JJN-15 | 5017906-015 | KLN-R15 | ATM-R15 | A2K-15R |
| 2K2 | KTN-R20 | JKS-20 | JJN-20 | 5012406-020 | KLN-R20 | ATM-R20 | A2K-20R |
| 3K0 | KTN-R25 | JKS-25 | JJN-25 | 5012406-025 | KLN-R25 | ATM-R25 | A2K-25R |
| 3K7 | KTN-R30 | JKS-30 | JJN-30 | 5012406-030 | KLN-R30 | ATM-R30 | A2K-30R |
| 5K5 | KTN-R50 | JKS-50 | JJN-50 | 5012406-050 | KLN-R50 | - | A2K-50R |
| 7K5 | KTN-R50 | JKS-60 | JJN-60 | 5012406-050 | KLN-R60 | - | A2K-50R |
| 11K | KTN-R60 | JKS-60 | JJN-60 | 5014006-063 | KLN-R60 | A2K-60R | A2K-60R |
| 15K | KTN-R80 | JKS-80 | JJN-80 | 5014006-080 | KLN-R80 | A2K-80R | A2K-80R |
| 18K5 | KTN-R125 | JKS-150 | JJN-125 | 2028220-125 | KLN-R125 | A2K-125R | A2K-125R |
| 22K | KTN-R125 | JKS-150 | JJN-125 | 2028220-125 | KLN-R125 | A2K-125R | A2K-125R |
| 30K | FWX-150 | - | - | 2028220-150 | L25S-150 | A25X-150 | A25X-150 |
| 37K | FWX-200 | - | - | 2028220-200 | L25S-200 | A25X-200 | A25X-200 |
| 45K | FWX-250 | - | - | 2028220-250 | L25S-250 | A25X-250 | A25X-250 |

Table 4.10: UL fuses, 200 - 240 V

| Frequency converter | Bussmann | Bussmann | Bussmann | SIBA | Littel fuse | Ferraz-Shawmut | Ferraz-Shawmut |
|-----------------------------|----------|----------|----------|-------------|-------------|----------------|----------------|
| 380-480 V, 525-600 V | | | | | | | |
| kW | Type RK1 | Type J | Type T | Type RK1 | Type RK1 | Type CC | Type RK1 |
| K37-1K1 | KTS-R6 | JKS-6 | JJS-6 | 5017906-006 | KLS-R6 | ATM-R6 | A6K-6R |
| 1K5-2K2 | KTS-R10 | JKS-10 | JJS-10 | 5017906-010 | KLS-R10 | ATM-R10 | A6K-10R |
| 3K0 | KTS-R15 | JKS-15 | JJS-15 | 5017906-016 | KLS-R16 | ATM-R16 | A6K-16R |
| 4K0 | KTS-R20 | JKS-20 | JJS-20 | 5017906-020 | KLS-R20 | ATM-R20 | A6K-20R |
| 5K5 | KTS-R25 | JKS-25 | JJS-25 | 5017906-025 | KLS-R25 | ATM-R25 | A6K-25R |
| 7K5 | KTS-R30 | JKS-30 | JJS-30 | 5012406-032 | KLS-R30 | ATM-R30 | A6K-30R |
| 11K | KTS-R40 | JKS-40 | JJS-40 | 5014006-040 | KLS-R40 | - | A6K-40R |
| 15K | KTS-R40 | JKS-40 | JJS-40 | 5014006-040 | KLS-R40 | - | A6K-40R |
| 18K | KTS-R50 | JKS-50 | JJS-50 | 5014006-050 | KLS-R50 | - | A6K-50R |
| 22K | KTS-R60 | JKS-60 | JJS-60 | 5014006-063 | KLS-R60 | - | A6K-60R |
| 30K | KTS-R80 | JKS-80 | JJS-80 | 2028220-100 | KLS-R80 | - | A6K-80R |
| 37K | KTS-R100 | JKS-100 | JJS-100 | 2028220-125 | KLS-R100 | - | A6K-100R |
| 45K | KTS-R125 | JKS-150 | JJS-150 | 2028220-125 | KLS-R125 | - | A6K-125R |
| 55K | KTS-R150 | JKS-150 | JJS-150 | 2028220-160 | KLS-R150 | - | A6K-150R |
| 75K | FWH-220 | - | - | 2028220-200 | L50S-225 | - | A50-P225 |
| 90K | FWH-250 | - | - | 2028220-250 | L50S-250 | - | A50-P250 |

Table 4.11: UL fuses, 380 - 600 V

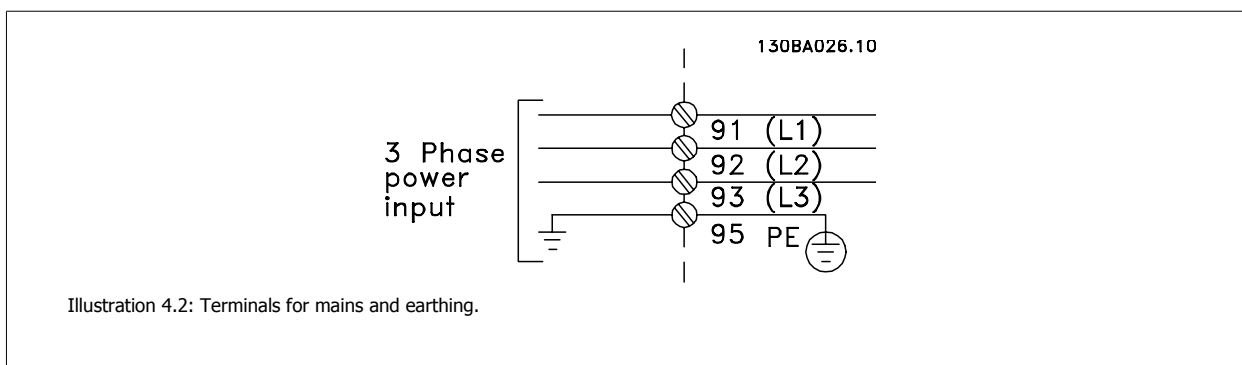
- KTS-fuses from Bussmann may substitute KTN for 240 V frequency converters.
- FWH-fuses from Bussmann may substitute FWX for 240 V frequency converters.
- KLSR fuses from LITTEL FUSE may substitute KLNK fuses for 240 V frequency converters.
- L50S fuses from LITTEL FUSE may substitute L50S fuses for 240 V frequency converters.
- A6KR fuses from FERRAZ SHAWMUT may substitute A2KR for 240 V frequency converters.
- A50X fuses from FERRAZ SHAWMUT may substitute A25X for 240 V frequency converters.

4.1.4 Earthing and IT mains

The earth connection cable cross section must be at least 10 mm² or 2 rated mains wires terminated separately according to *EN 50178* or *IEC 61800-5-1* unless national regulations specify differently. Always comply with national and local regulations on cable cross-sections.

The mains is connected to the main disconnect switch if this is included.

NB!
Check that mains voltage corresponds to the mains voltage of the frequency converter name plate.



**IT Mains**

Do not connect 400 V frequency converters with RFI-filters to mains supplies with a voltage between phase and earth of more than 440 V.

For IT mains and delta earth (grounded leg), mains voltage may exceed 440 V between phase and earth.

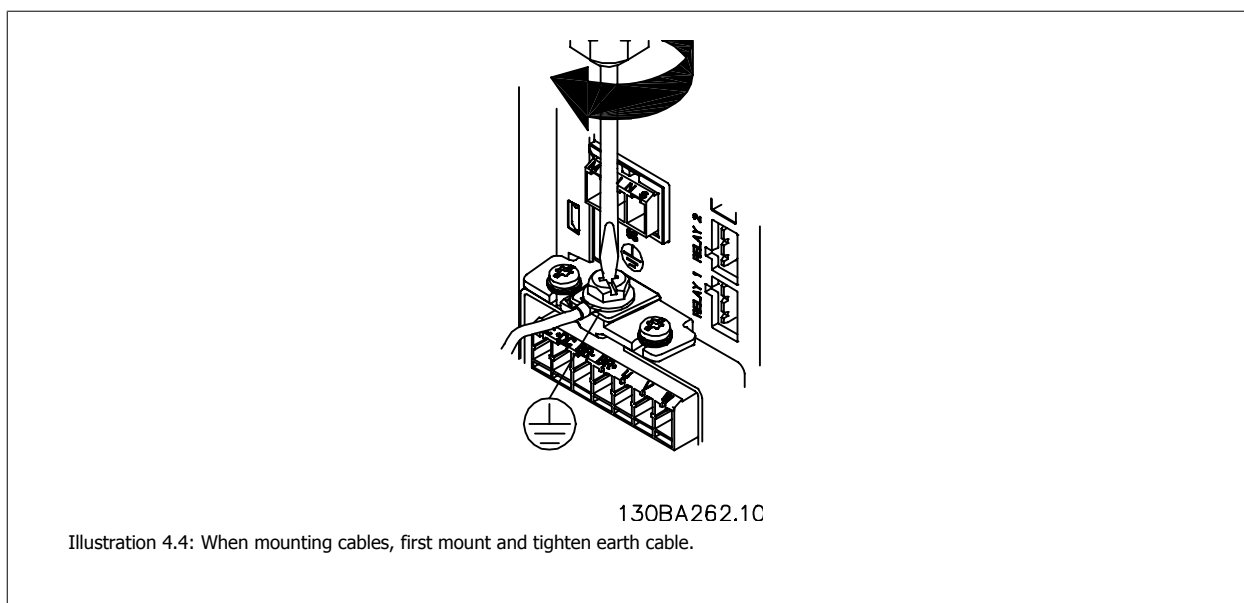
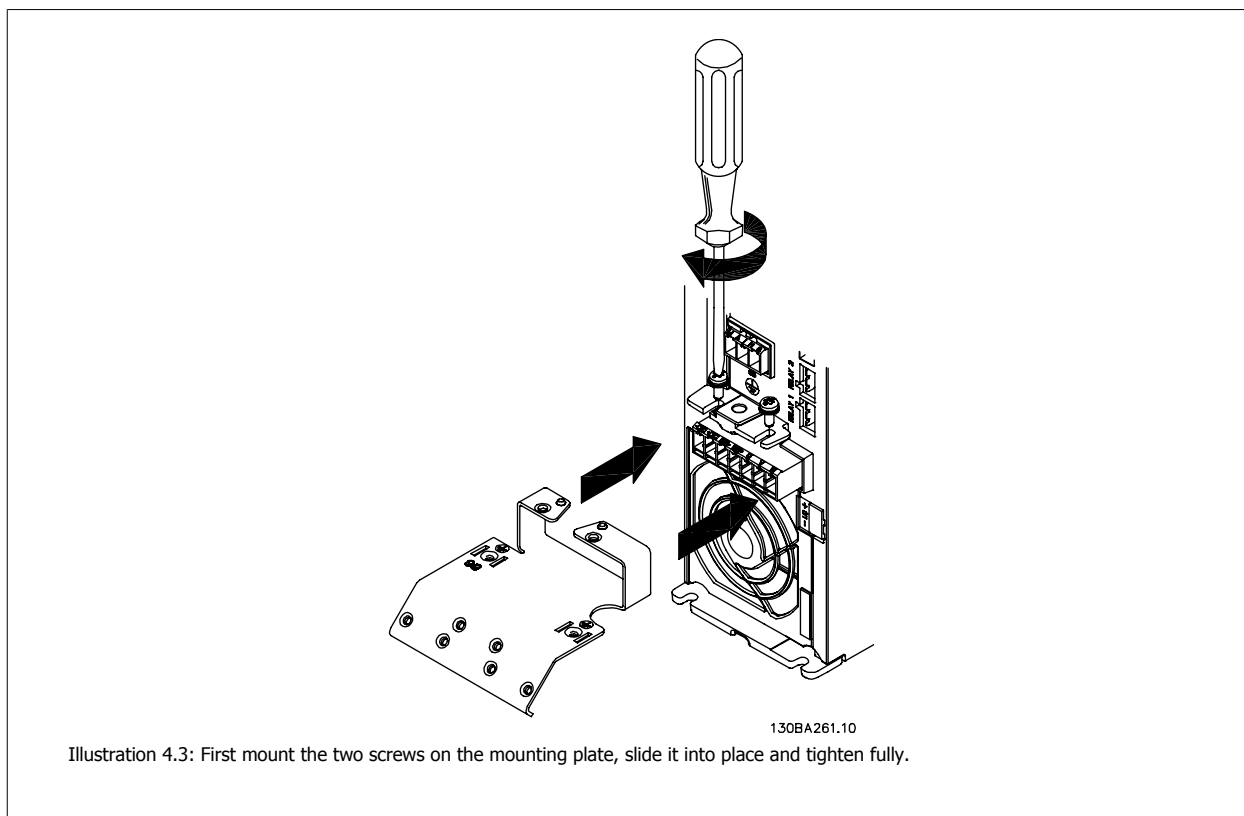
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4.1.5 Mains wiring overview

| Enclosure: | A2 (IP 20/IP 21) | A3 (IP 20/IP 21) | A5 (IP 55/IP 66) | B1 (IP 21/IP 55/IP 66) | B2 (IP 21/IP 55/IP 66) | B3 (IP 20) | B4 (IP 20) | C1 (IP 21/IP 55/66) | C2 (IP 21/IP 55/66) | C3 (IP 20) | C4 (IP20) |
|--------------------|---------------------|---------------------|---------------------|---------------------------|---------------------------|---------------|---------------|------------------------|------------------------|---------------|--------------|
| Motor size: | | | | | | | | | | | |
| 200-240 V | 1.1-3.0 kW | 3.7 kW | 1.1-3.7 kW | 5.5-11 kW | 15 kW | 5.5-11 kW | 15-18.5 kW | 18.5-30 kW | 37-45 kW | 22-30 kW | 37-45 kW |
| 380-480 V | 1.1-4.0 kW | 5.5-7.5 kW | 1.1-7.5 kW | 11-18.5 kW | 22-30 kW | 11-18.5 kW | 22-37 kW | 37-55 kW | 75-90 kW | 45-55 kW | 75-90 kW |
| 525-600 V | | 1.1-7.5 kW | 1.1-7.5 kW | 11-18.5 kW | 22-30 kW | 11-18.5 kW | 22-37 kW | 37-55 kW | 75-90 kW | 45-55 kW | 75-90 kW |
| Goto: | 4.1.5 | | 4.1.6 | 4.1.7 | | 4.1.8 | | 4.1.9 | | | |

Table 4.12: Mains wiring table.

4.1.6 Mains connection for A2 and A3



The earth connection cable cross section must be at least 10 mm² or 2 rated mains wires terminated separately according to *EN 50178/IEC 61800-5-1*.

4

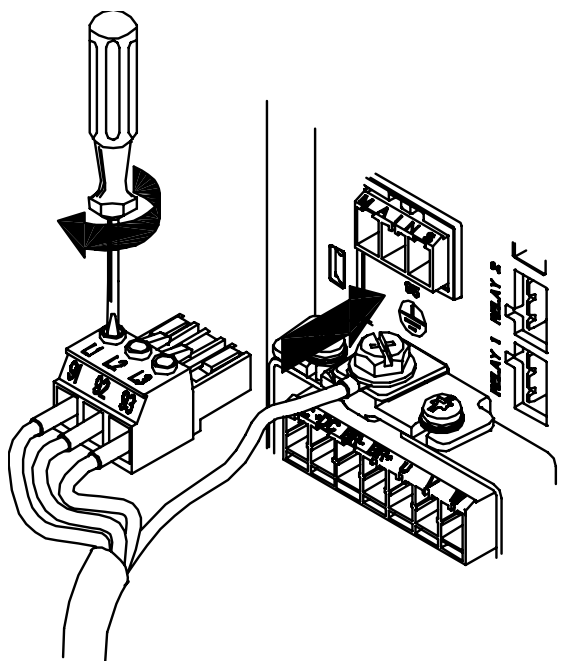


Illustration 4.5: Then mount mains plug and tighten wires.

130BA263.10

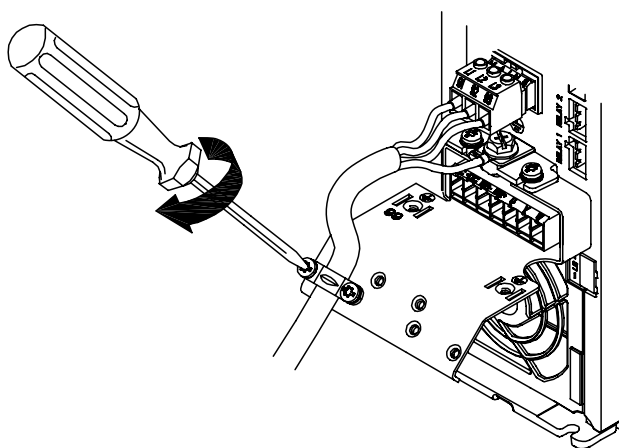


Illustration 4.6: Finally tighten support bracket on mains wires.

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NB!

With single phase A3 use L1 and L2 terminals.

4.1.7 Mains connection for A5

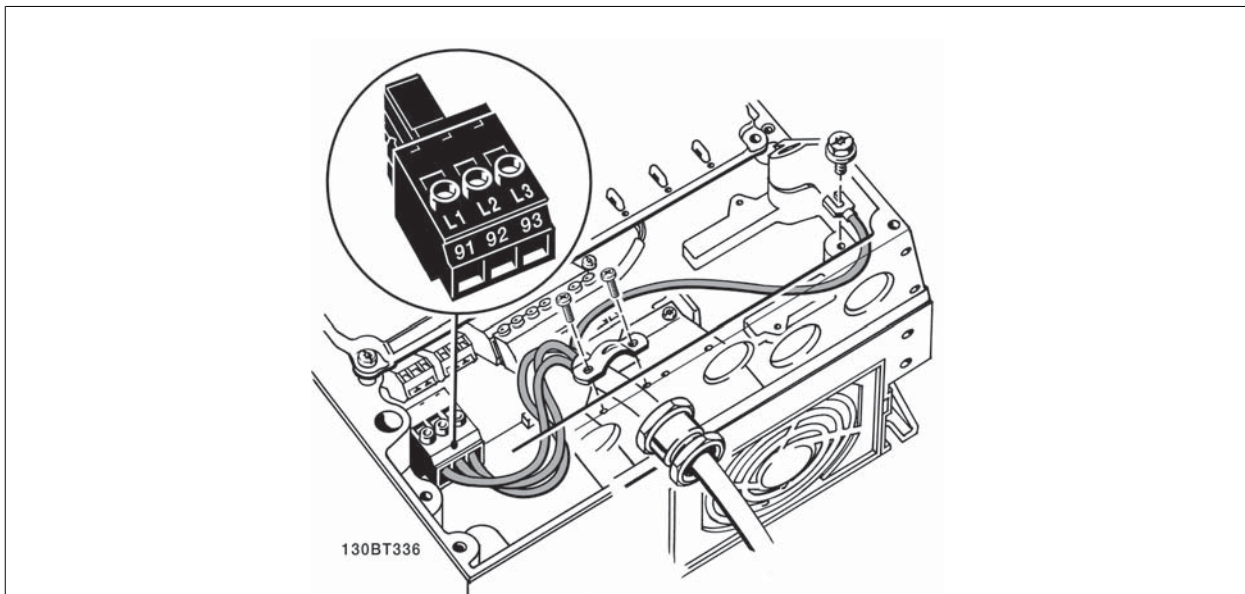


Illustration 4.7: How to connect to mains and earthing without mains disconnect switch. Note that a cable clamp is used.

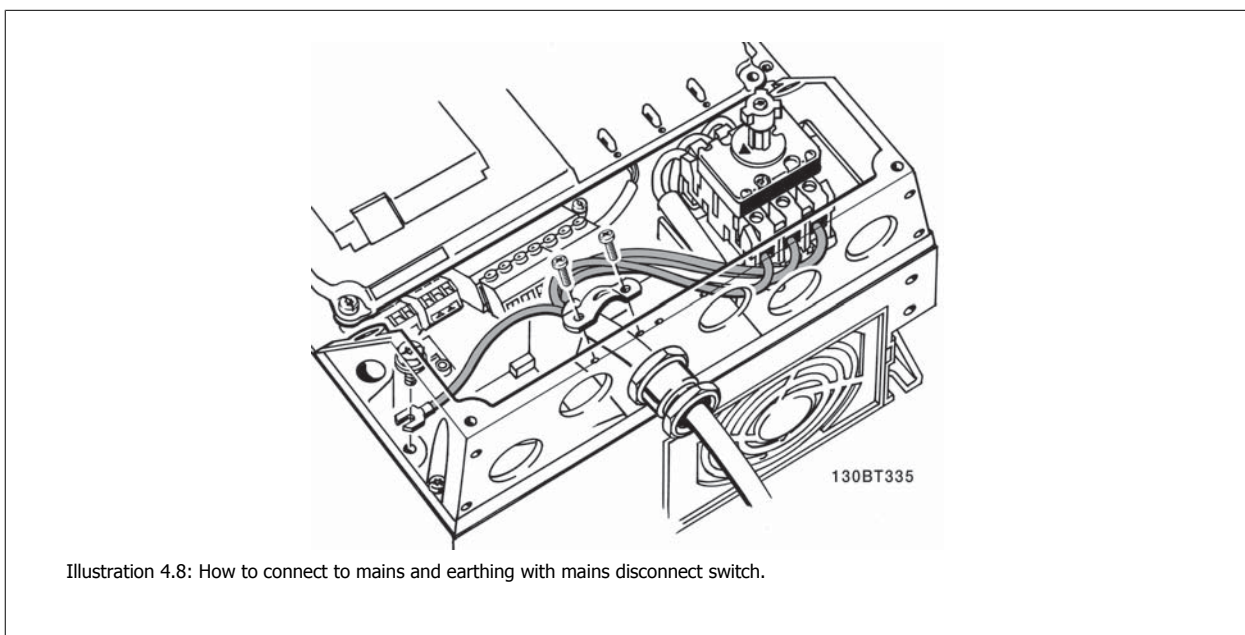


Illustration 4.8: How to connect to mains and earthing with mains disconnect switch.

NB!
With single phase A5 use L1 and L2 terminals.

4.1.8 Mains connection for B1, B2 and B3

4

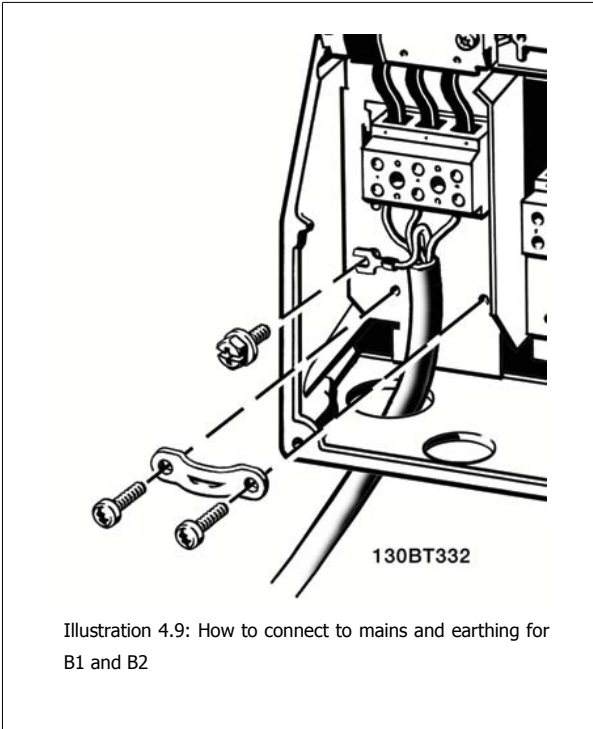


Illustration 4.9: How to connect to mains and earthing for B1 and B2

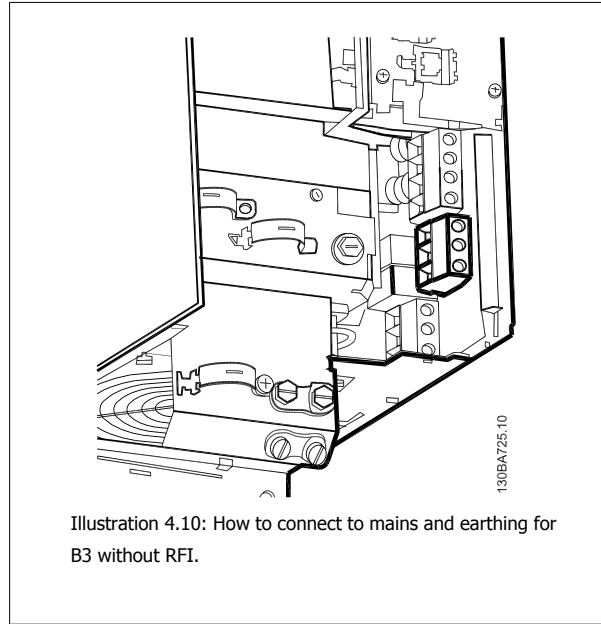


Illustration 4.10: How to connect to mains and earthing for B3 without RFI.

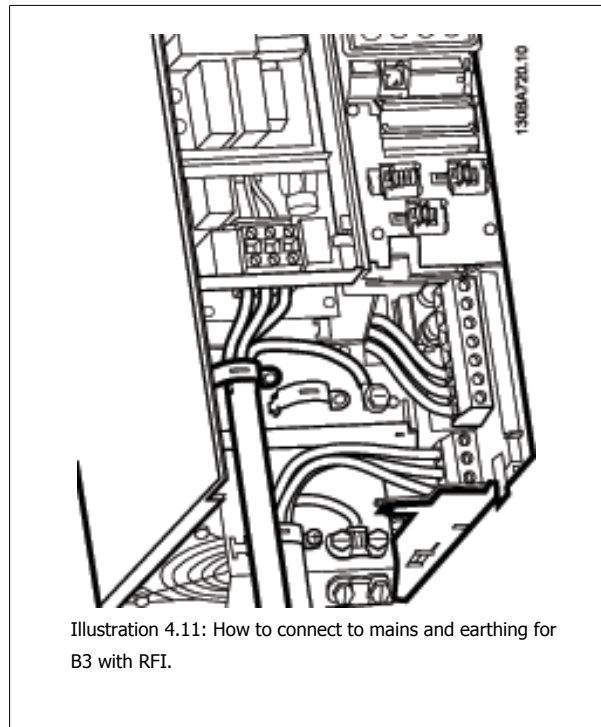


Illustration 4.11: How to connect to mains and earthing for B3 with RFI.

NB!

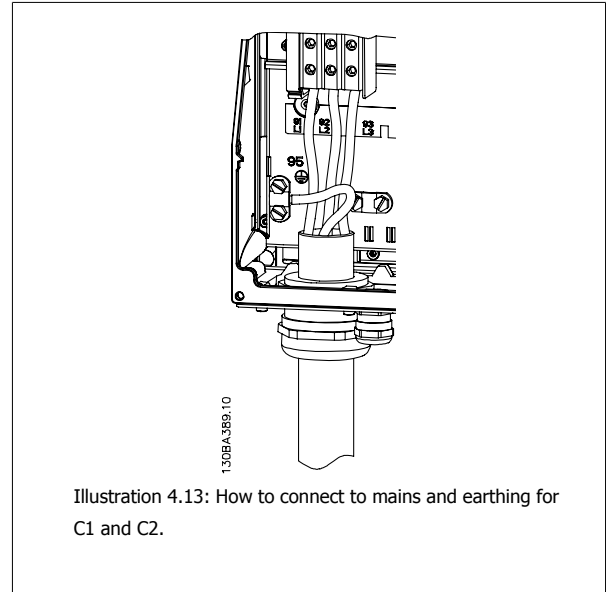
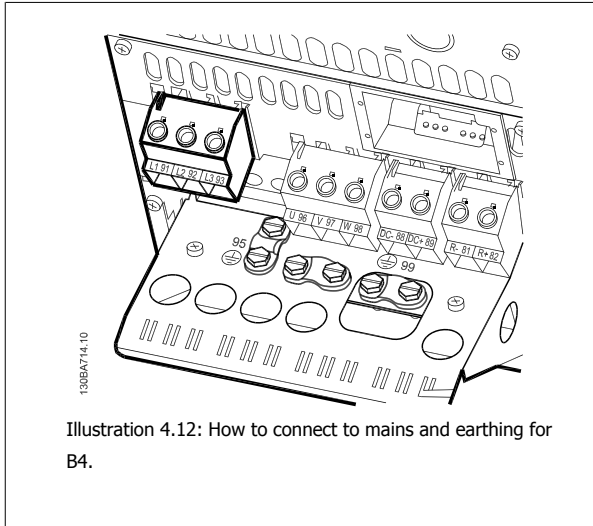
With single phase B1 use L1 and L2 terminals.



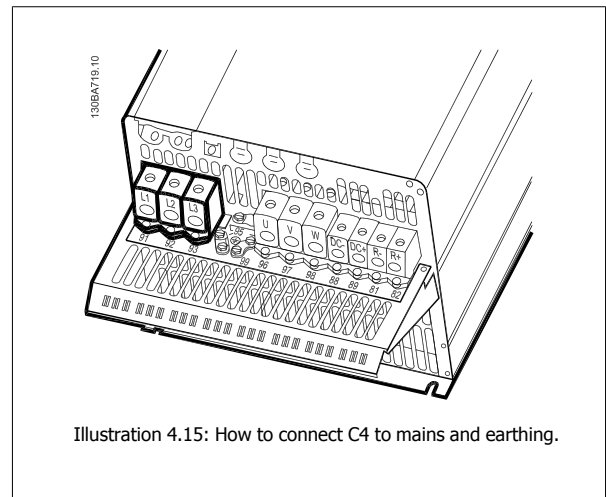
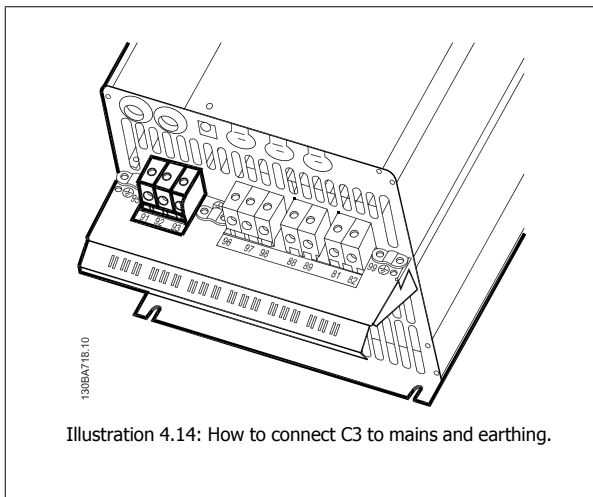
NB!

For correct cable dimensions please see the section General Specifications at the back of this manual.

4.1.9 Mains connection for B4, C1 and C2



4.1.10 Mains connection for C3 and C4



4.1.11 How to connect motor - foreword

See section *General Specifications* for correct dimensioning of motor cable cross-section and length.

- Use a screened/armoured motor cable to comply with EMC emission specifications (or install the cable in metal conduit).
- Keep the motor cable as short as possible to reduce the noise level and leakage currents.
- Connect the motor cable screen/armour to both the decoupling plate of the frequency converter and to the metal of the motor. (Same applies to both ends of metal conduit if used instead of screen.)
- Make the screen connections with the largest possible surface area (cable clamp or by using an EMC cable gland). This is done by using the supplied installation devices in the frequency converter.
- Avoid terminating the screen by twisting the ends (pigtails), as this will spoil high frequency screening effects.
- If it is necessary to break the continuity of the screen to install a motor isolator or motor relay, the continuity must be maintained with the lowest possible HF impedance.

4

Cable length and cross-section

The frequency converter has been tested with a given length of cable and a given cross-section of that cable. If the cross-section is increased, the cable capacitance - and thus the leakage current - may increase, and the cable length must be reduced correspondingly.

Switching frequency

When frequency converters are used together with sine wave filters to reduce the acoustic noise from a motor, the switching frequency must be set according to the sine wave filter instruction in par.14-01 *Switching Frequency*.

Precautions while using Aluminium conductors

Aluminium conductors are not recommended for cable cross sections below 35 mm². Terminals can accept aluminium conductors but the conductor surface has to be clean and the oxidation must be removed and sealed by neutral acid free Vaseline grease before the conductor is connected.

Furthermore, the terminal screw must be retightened after two days due to the softness of the aluminium. It is crucial to ensure the connection makes a gas tight joint, otherwise the aluminium surface will oxidize again.

All types of three-phase asynchronous standard motors can be connected to the frequency converter. Normally, small motors are star-connected (230/400 V, D/Y). Large motors are delta-connected (400/690 V, D/Y). Refer to the motor name plate for correct connection mode and voltage.

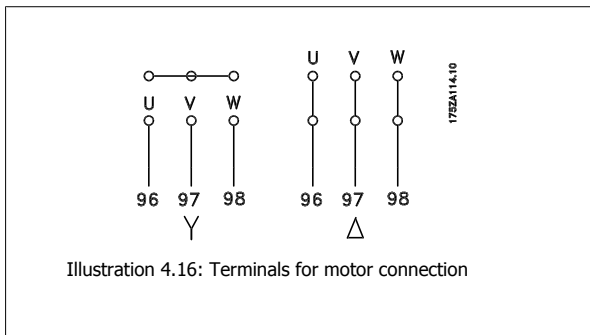


Illustration 4.16: Terminals for motor connection



NB!

In motors without phase insulation paper or other insulation reinforcement suitable for operation with voltage supply (such as a frequency converter), fit a sine-wave filter on the output of the frequency converter. (Motors that comply with IEC 60034-17 do not require an Sine-wave filter).

| | | | | |
|-----|----|----|----|--|
| No. | 96 | 97 | 98 | Motor voltage 0-100% of mains voltage. |
| | U | V | W | 3 cables out of motor |
| | U1 | V1 | W1 | 6 cables out of motor, Delta-connected |
| | W2 | U2 | V2 | |
| | U1 | V1 | W1 | 6 cables out of motor, Star-connected |
| | | | | U2, V2, W2 to be interconnected separately (optional terminal block) |
| No. | 99 | | | Earth connection |
| | PE | | | |

Table 4.13: 3 and 6 cable motor connection.

4.1.12 Motor wiring overview












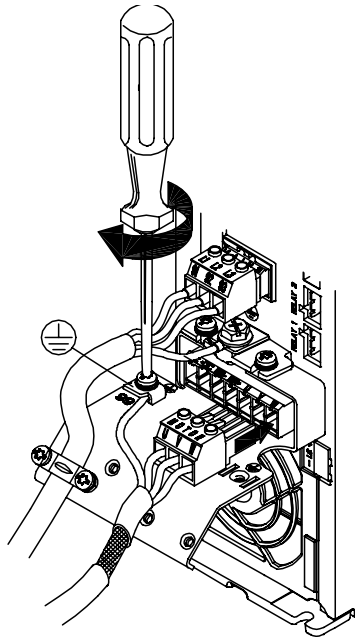
| Enclosure: | A2 (IP 20/IP 21) | A3 (IP 20/IP 21) | A5 (IP 55/IP 66) | B1 (IP 21/IP 55/ IP 66) | B2 (IP 21/IP 55/ IP 66) | B3 (IP 20) | B4 (IP 20) | C1 (IP 21/IP 55/66) | C2 (IP 21/IP 55/66) | C3 (IP 20) | C4 (IP 20) |
|--------------------|---|---|---|---|---|--|---|---|---|---|---|
| |  |  |  |  |  |  |  |  |  |  |  |
| Motor size: | | | | | | | | | | | |
| 200-240 V | 1.1-3.0 kW | 3.7 kW | 1.1-3.7 kW | 5.5-11 kW | 15 kW | 5.5-11 kW | 15-18.5 kW | 18.5-30 kW | 37-45 kW | 22-30 kW | 37-45 kW |
| 380-480 V | 1.1-4.0 kW | 5.5-7.5 kW | 1.1-7.5 kW | 11-18.5 kW | 22-30 kW | 11-18.5 kW | 22-37 kW | 37-55 kW | 75-90 kW | 45-55 kW | 75-90 kW |
| 525-600 V | | 1.1-7.5 kW | 1.1-7.5 kW | 11-18.5 kW | 22-30 kW | 11-18.5 kW | 22-37 kW | 37-55 kW | 75-90 kW | 45-55 kW | 75-90 kW |
| Goto: | 4.1.12 | | 4.1.13 | 4.1.14 | | 4.1.15 | | 4.1.16 | | 4.1.17 | |

Table 4.14: Motor wiring table.

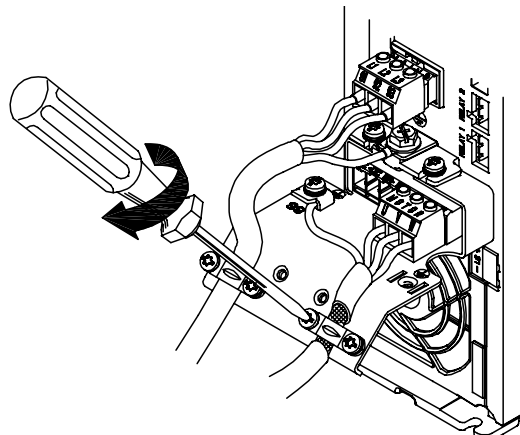
4.1.13 Motor connection for A2 and A3

Follow these drawings step by step for connecting the motor to the frequency converter.

4

130BA265.10

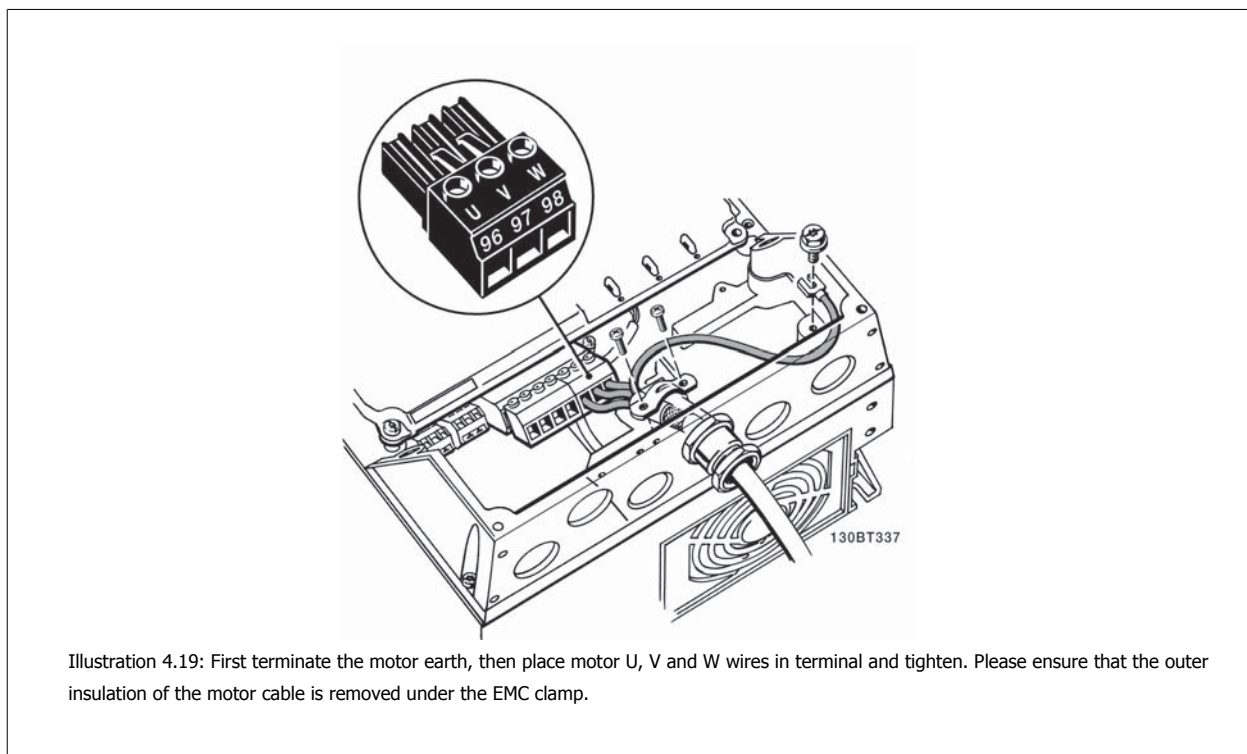
Illustration 4.17: First terminate the motor earth, then place motor U, V and W wires in plug and tighten.



130BA266.10

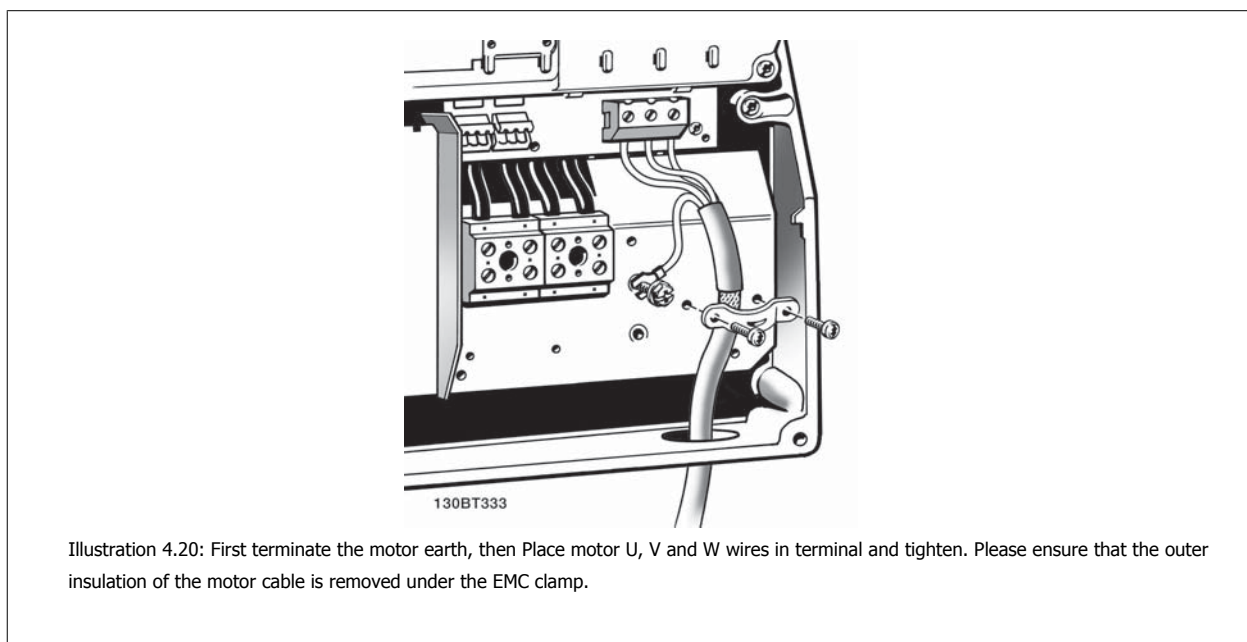
Illustration 4.18: Mount cable clamp to ensure 360 degree connection between chassis and screen, note the outer insulation of the motor cable is removed under the clamp.

4.1.14 Motor connection for A5



4

4.1.15 Motor connection for B1 and B2



4

4.1.16 Motor connection for B3 and B4

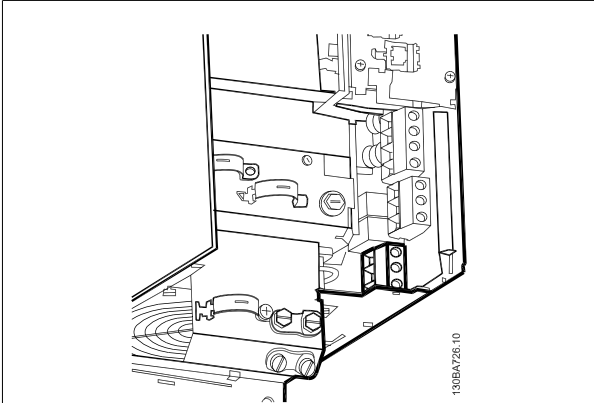


Illustration 4.21: First terminate the motor earth, then Place motor U, V and W wires in terminal and tighten. Please ensure that the outer insulation of the motor cable is removed under the EMC clamp.

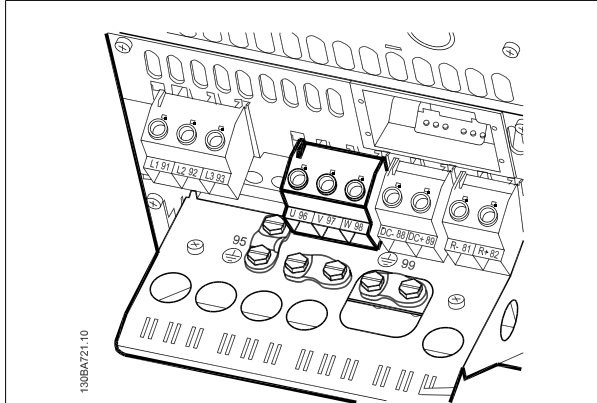


Illustration 4.22: First terminate the motor earth, then Place motor U, V and W wires in terminal and tighten. Please ensure that the outer insulation of the motor cable is removed under the EMC clamp.

4.1.17 Motor connection for C1 and C2

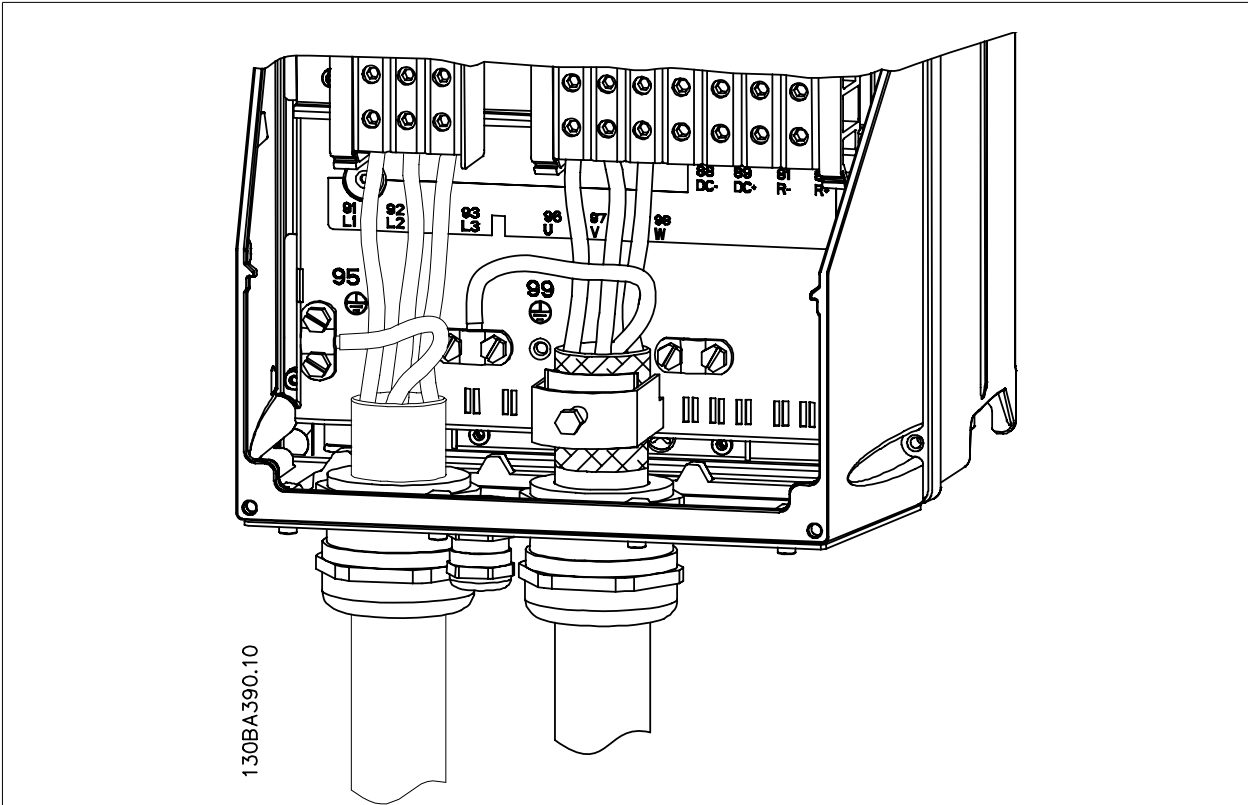
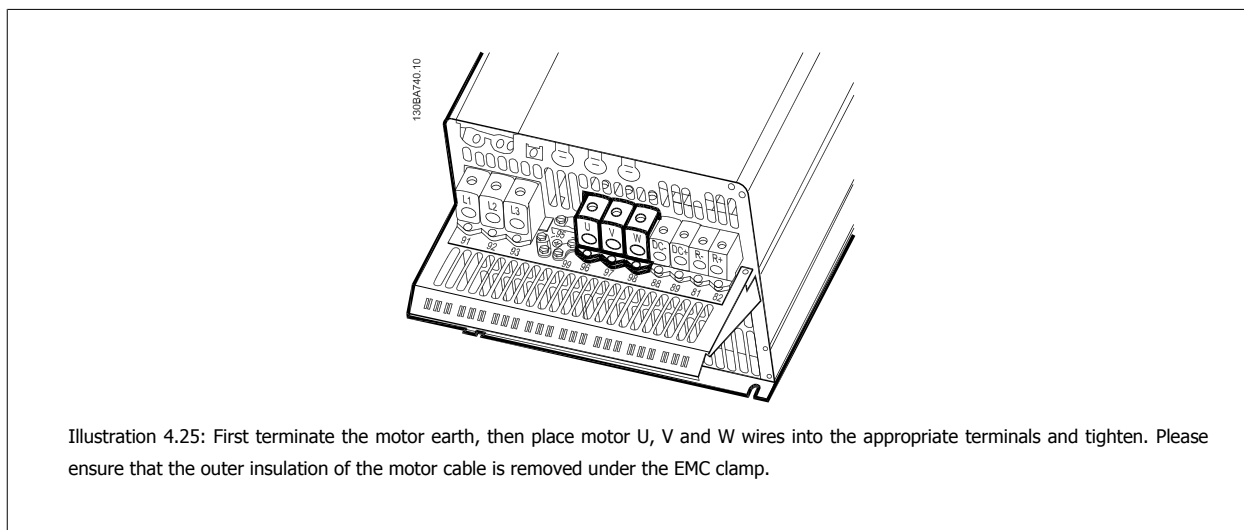
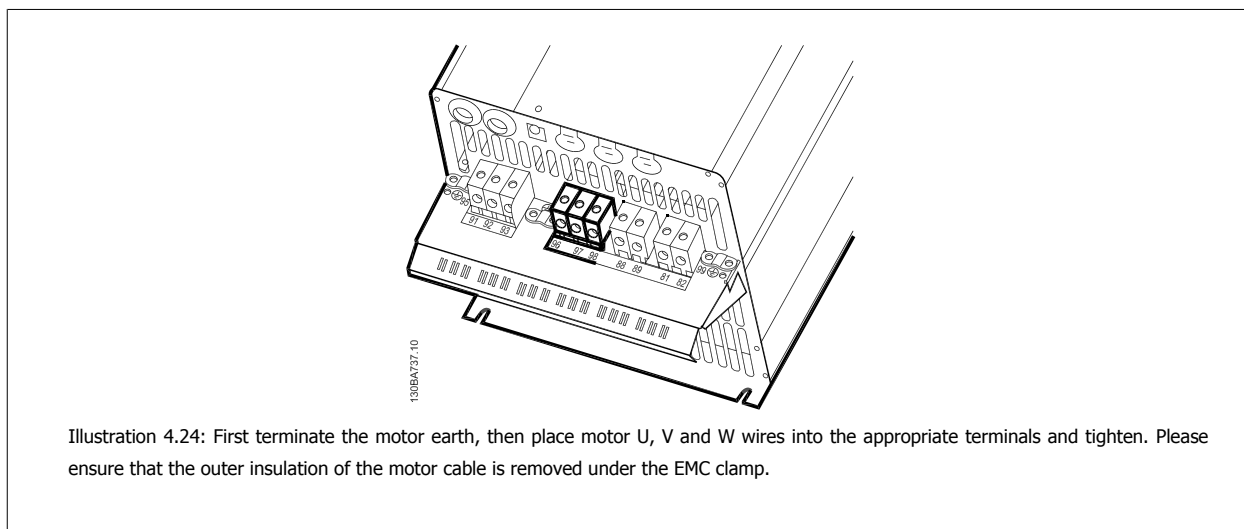


Illustration 4.23: First terminate the motor earth, then Place motor U, V and W wires in terminal and tighten. Please ensure that the outer insulation of the motor cable is removed under the EMC clamp.

4.1.18 Motor connection for C3 and C4



4.1.19 Wiring Example and Testing

The following section describes how to terminate control wires and how to access them. For an explanation of the function, programming and wiring of the control terminals, please see chapter, *How to programme the frequency converter*.

4.1.20 DC bus connection

The DC bus terminal is used for DC back-up, with the intermediate circuit being supplied from an external source.

Terminal numbers used: 88, 89

4

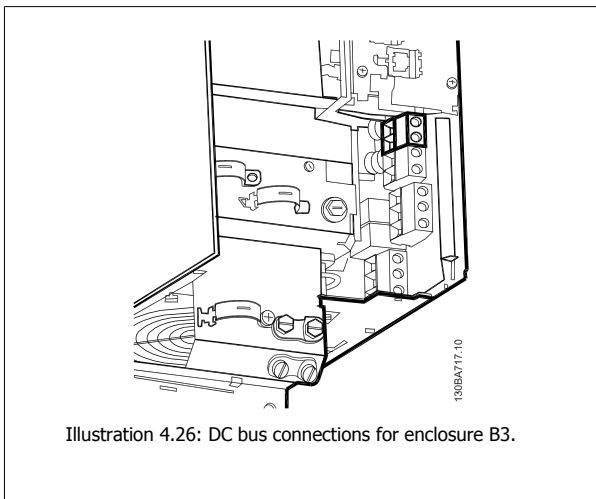


Illustration 4.26: DC bus connections for enclosure B3.

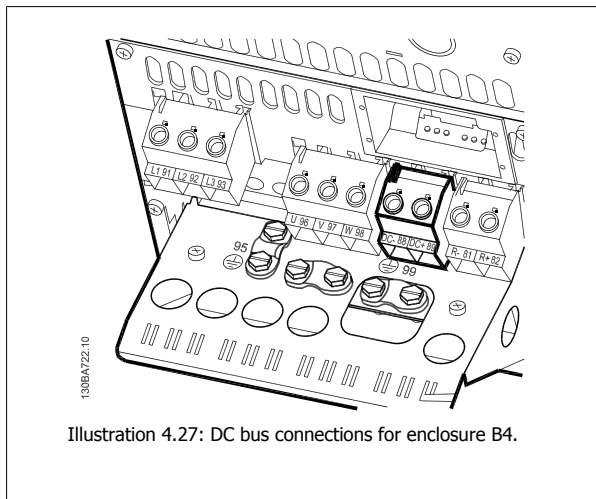


Illustration 4.27: DC bus connections for enclosure B4.

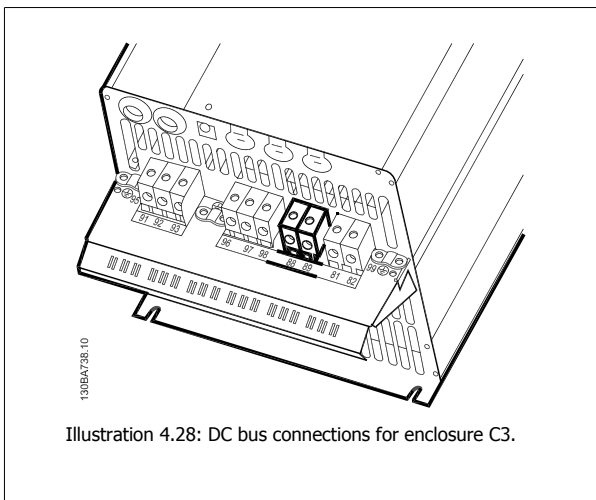


Illustration 4.28: DC bus connections for enclosure C3.

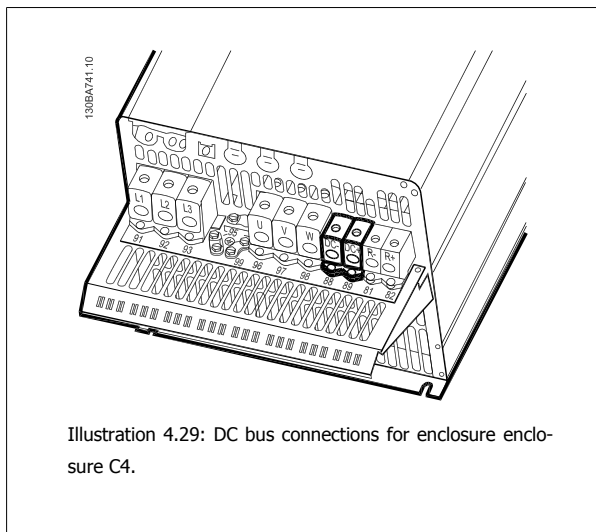


Illustration 4.29: DC bus connections for enclosure enclosure C4.

Please contact Danfoss if you require further information.

4.1.21 Brake Connection Option

The connection cable to the brake resistor must be screened/armoured.

| Brake resistor | | |
|-----------------|----|----|
| Terminal number | 81 | 82 |
| Terminals | R- | R+ |

NB!
Dynamic brake calls for extra equipment and safety considerations. For further information, please contact Danfoss.

1. Use cable clamps to connect the screen to the metal cabinet of the frequency converter and to the decoupling plate of the brake resistor.
2. Dimension the cross-section of the brake cable to match the brake current.

NB!
Voltages up to 975 V DC (@ 600 V AC) may occur between the terminals.

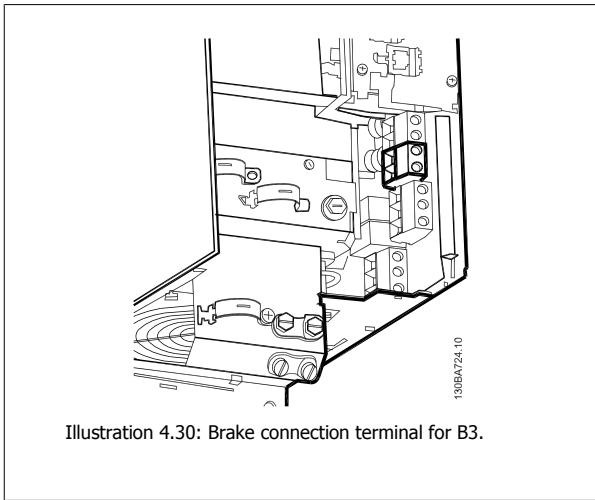


Illustration 4.30: Brake connection terminal for B3.

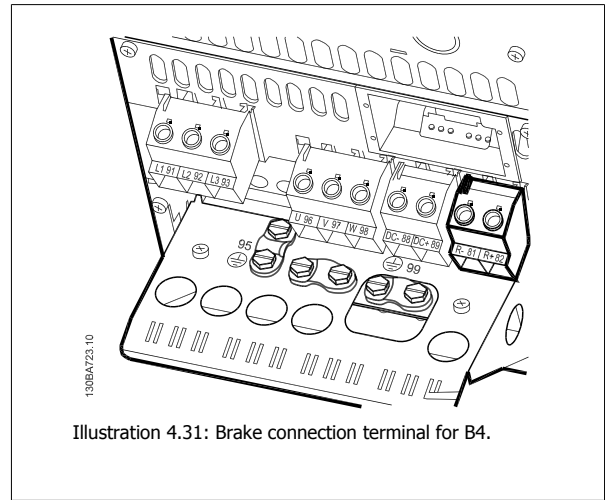


Illustration 4.31: Brake connection terminal for B4.

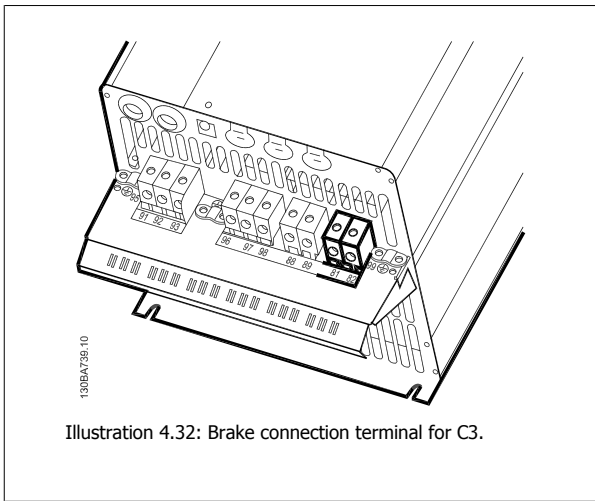


Illustration 4.32: Brake connection terminal for C3.

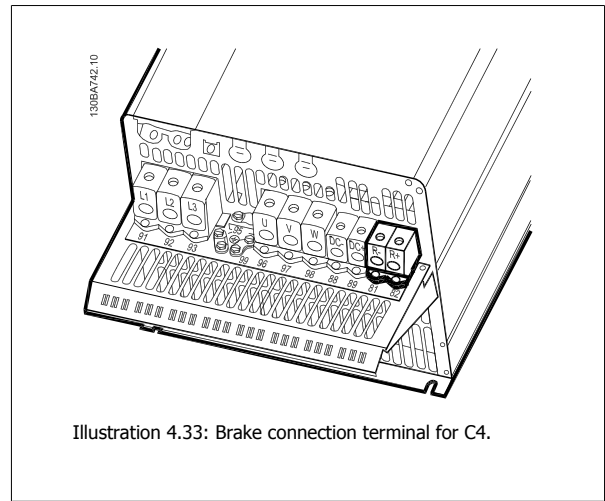


Illustration 4.33: Brake connection terminal for C4.

NB!
 If a short circuit in the brake IGBT occurs, prevent power dissipation in the brake resistor by using a mains switch or contactor to disconnect the mains for the frequency converter. Only the frequency converter shall control the contactor.

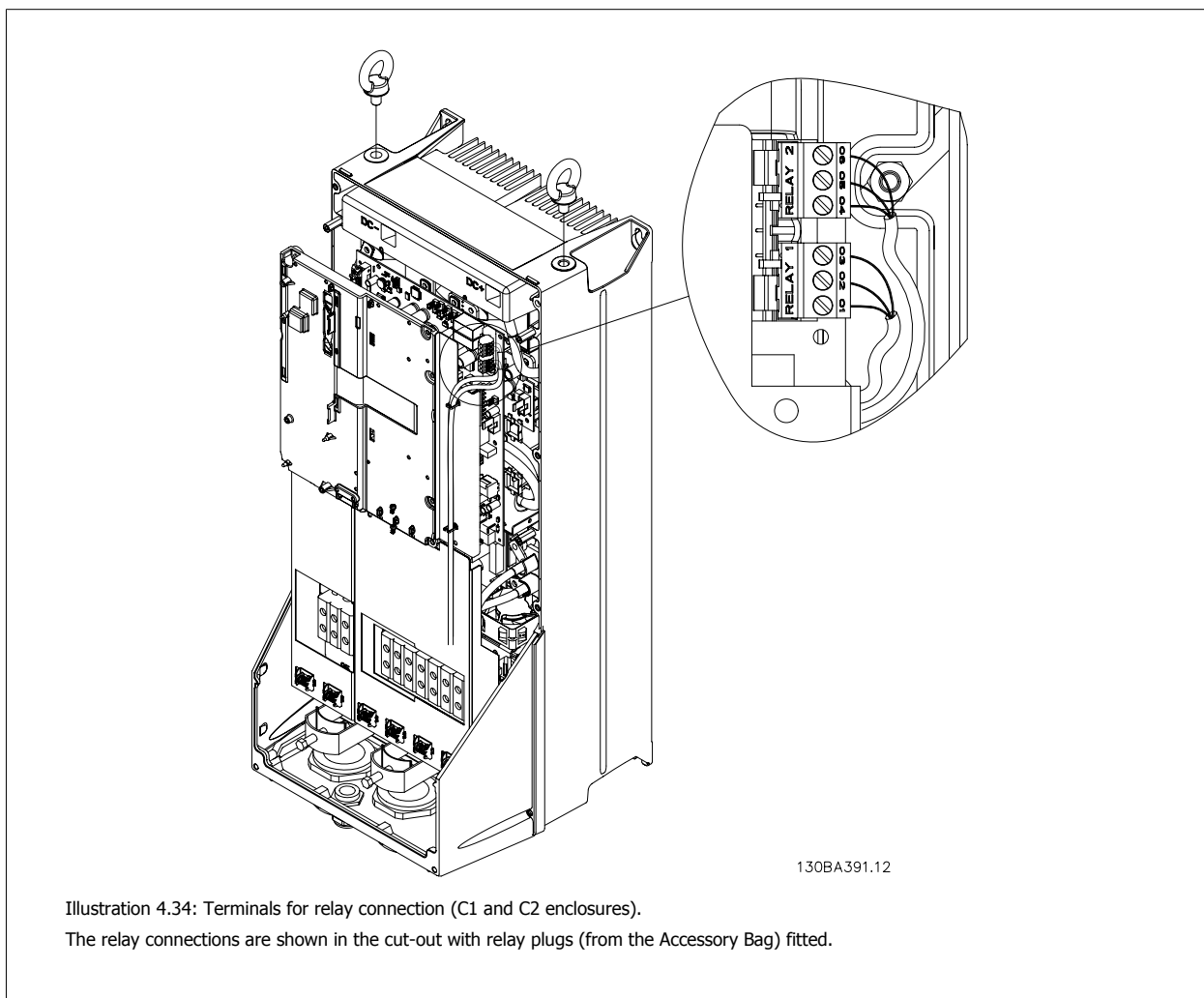
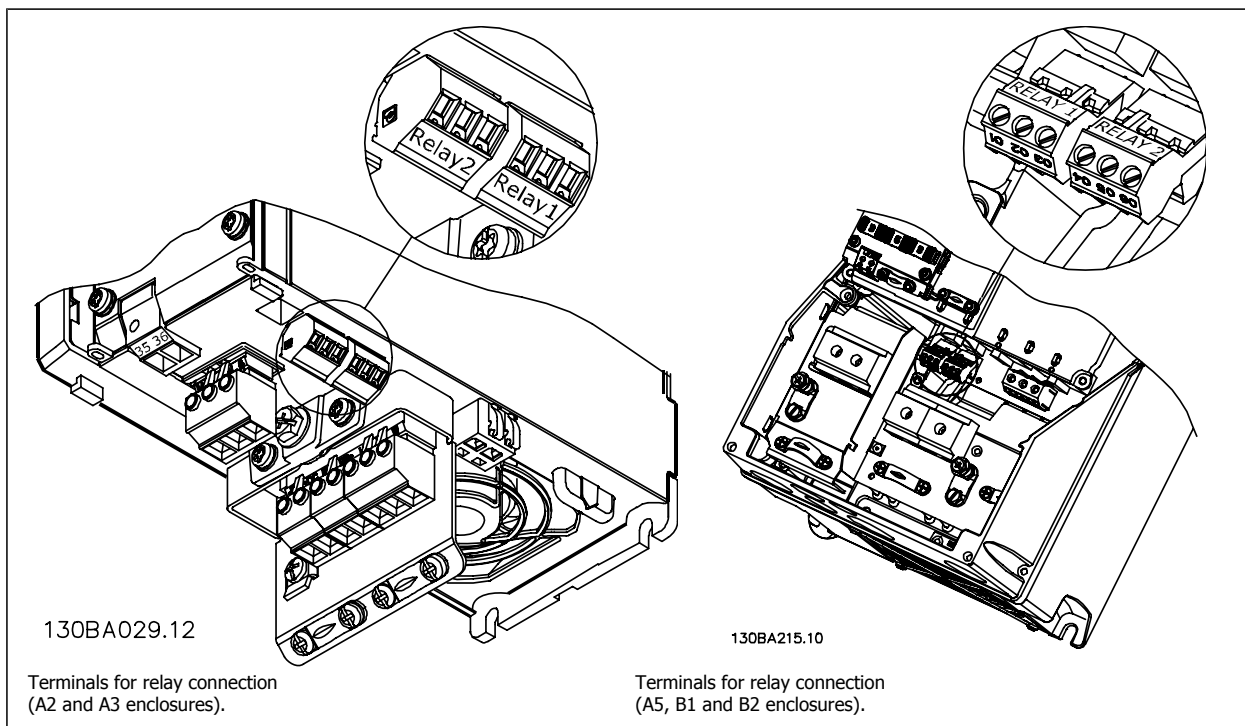
NB!
 Place the brake resistor in an environment free of fire risk and ensure that no external objects can fall into the brake resistor through ventilation slots.
 Do not cover ventilation slots and grids.

4.1.22 Relay Connection

To set relay output, see par. group 5-4* Relays.

| | | |
|-----|---------|-------------------------|
| No. | 01 - 02 | make (normally open) |
| | 01 - 03 | break (normally closed) |
| | 04 - 05 | make (normally open) |
| | 04 - 06 | break (normally closed) |

4



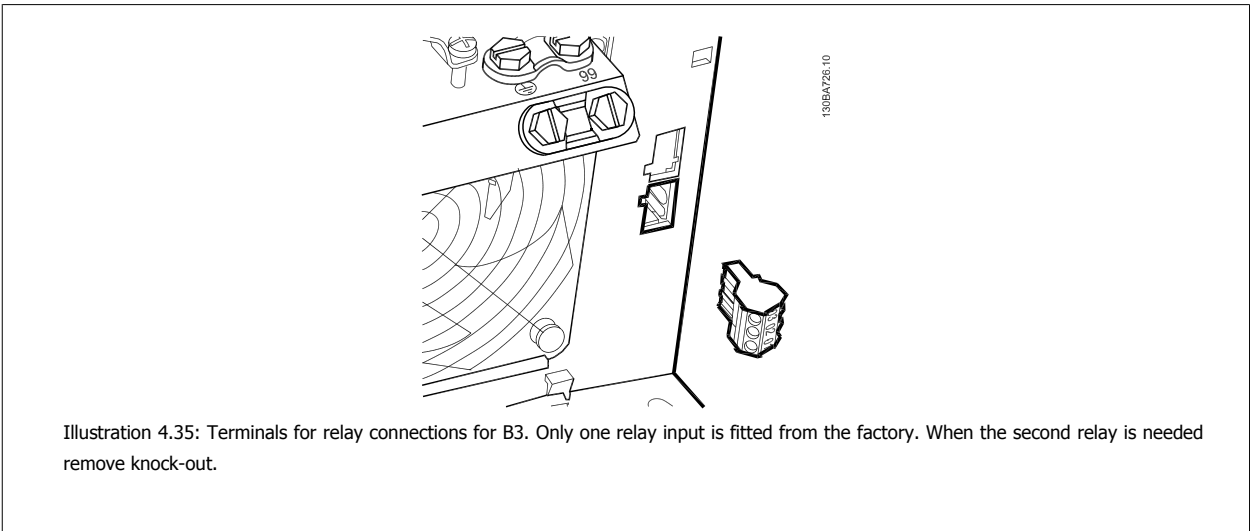


Illustration 4.35: Terminals for relay connections for B3. Only one relay input is fitted from the factory. When the second relay is needed remove knock-out.

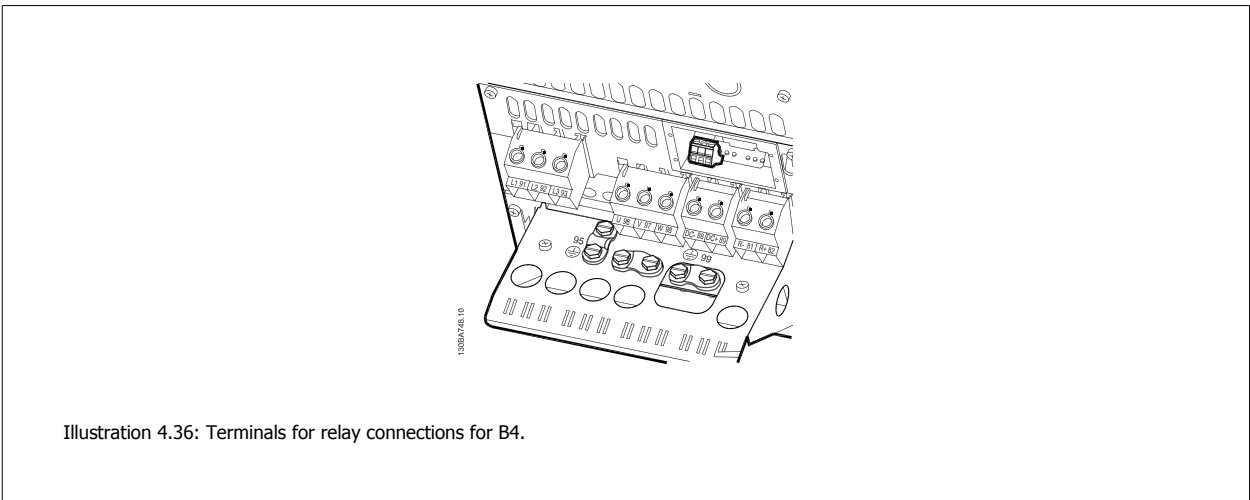


Illustration 4.36: Terminals for relay connections for B4.

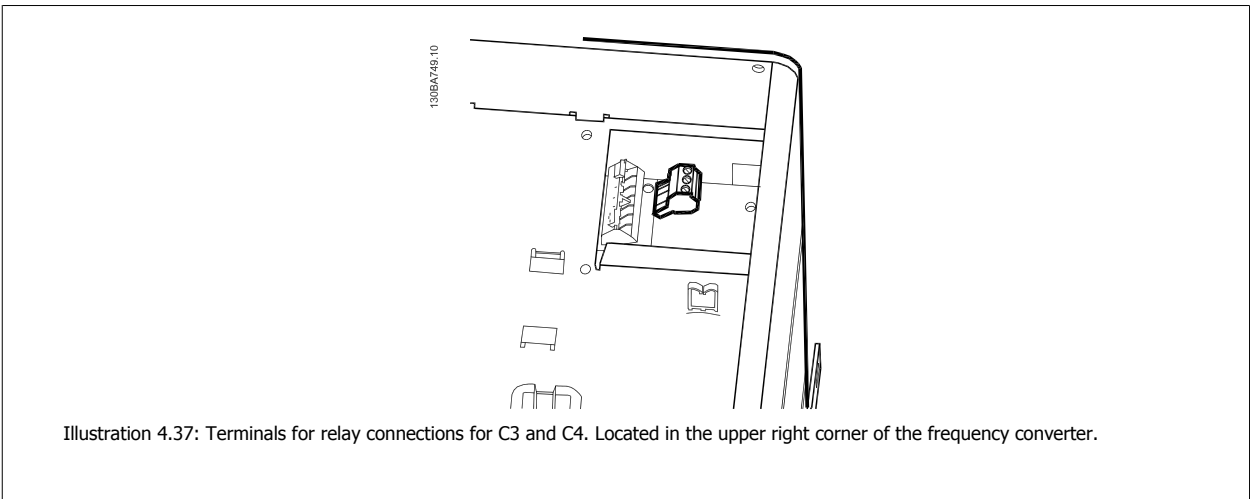


Illustration 4.37: Terminals for relay connections for C3 and C4. Located in the upper right corner of the frequency converter.

4.1.23 Relay Output

Relay 1

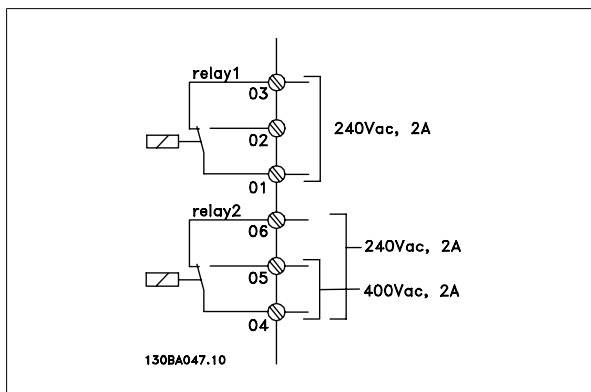
- Terminal 01: common
- Terminal 02: normal open 240 V AC
- Terminal 03: normal closed 240 V AC

Relay 2

- Terminal 04: common
- Terminal 05: normal open 400 V AC
- Terminal 06: normal closed 240 V AC

Relay 1 and relay 2 are programmed in par.5-40 *Function Relay*, par. 5-41 *On Delay, Relay*, and par. 5-42 *Off Delay, Relay*.

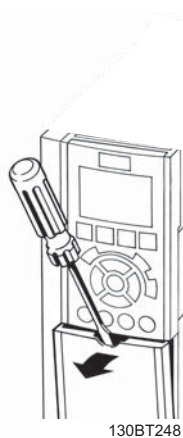
Additional relay outputs by using option module MCB 105.



4

4.1.24 Access to Control Terminals

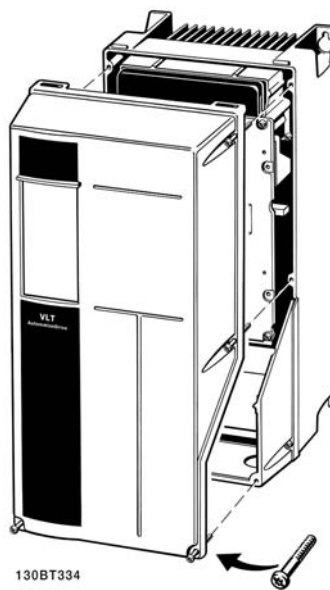
All terminals to the control cables are located underneath the terminal cover on the front of the frequency converter. Remove the terminal cover with a screwdriver.



130BT248

Illustration 4.38: Access to control terminals for A2, A3, B3, B4, C3 and C4 enclosures

Remove front-cover to access control terminals. When replacing the front-cover, please ensure proper fastening by applying a torque of 2 Nm.



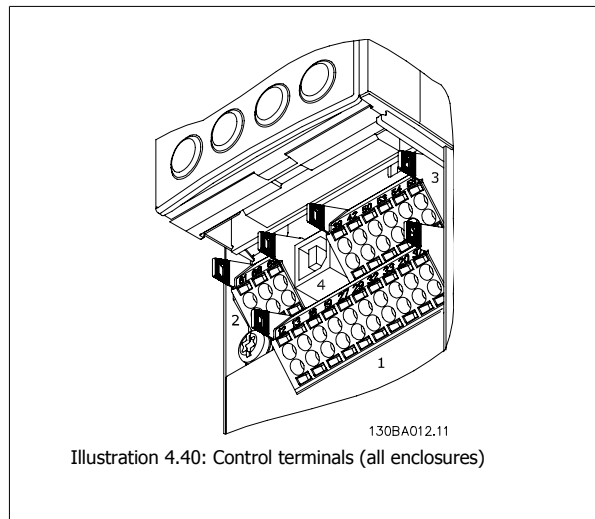
130BT334

Illustration 4.39: Access to control terminals for A5, B1, B2, C1 and C2 enclosures

4.1.25 Control Terminals

Drawing reference numbers:

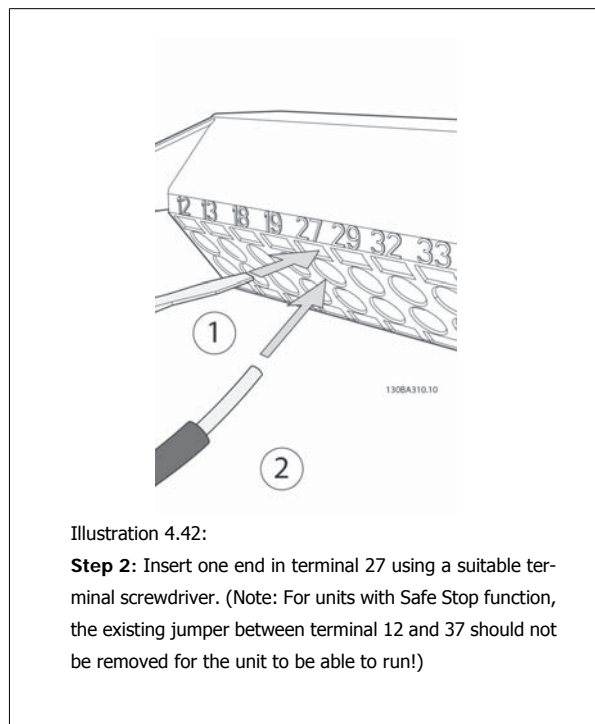
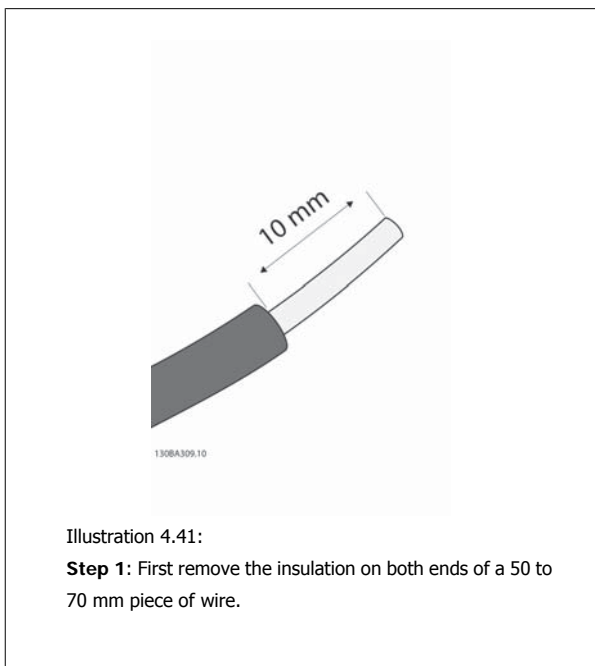
1. 10 pole plug digital I/O.
2. 3 pole plug RS-485 Bus.
3. 6 pole analog I/O.
4. USB connection.



4.1.26 How to Test Motor and Direction of Rotation.

Note that unintended motor start can occur, ensure no personnel or equipment is in danger!

Please follow these steps to test the motor connection and direction of rotation. Start with no power to the unit.



4

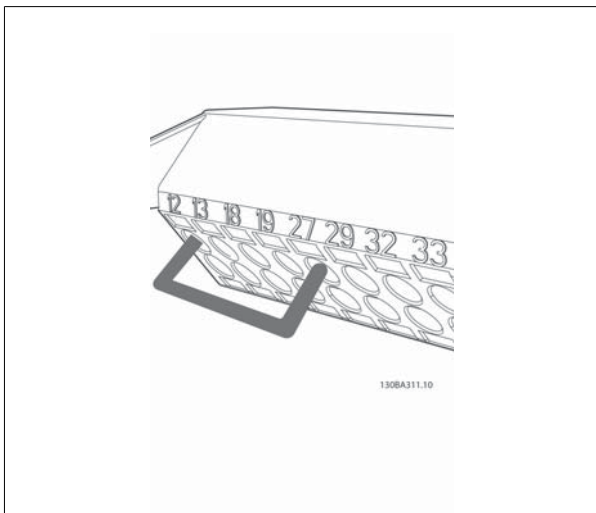


Illustration 4.43:
Step 3: Insert the other end in terminal 12 or 13. (Note: For units with Safe Stop function, the existing jumper between terminal 12 and 37 should not be removed for the unit to be able to run!)

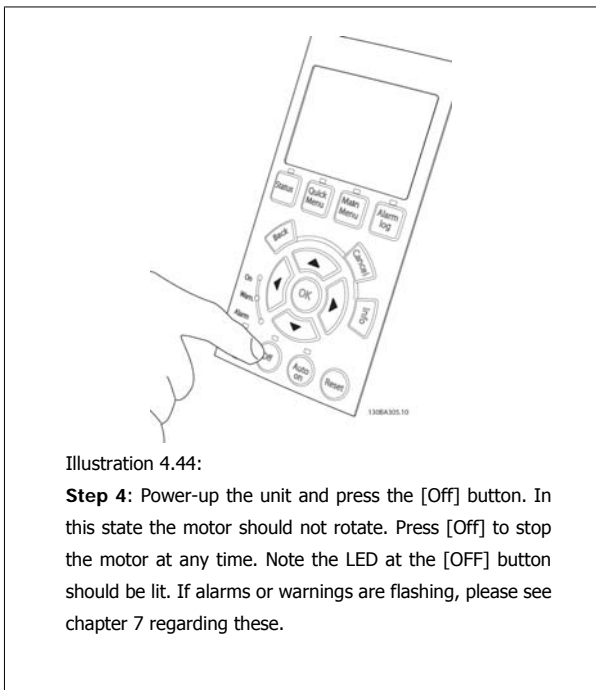


Illustration 4.44:
Step 4: Power-up the unit and press the [Off] button. In this state the motor should not rotate. Press [Off] to stop the motor at any time. Note the LED at the [OFF] button should be lit. If alarms or warnings are flashing, please see chapter 7 regarding these.



Illustration 4.45:
Step 5: By pressing the [Hand on] button, the LED above the button should be lit and the motor may rotate.



Illustration 4.46:
Step 6: The speed of the motor can be seen in the LCP. It can be adjusted by pushing the up ▲ and down ▼ arrow buttons.



Illustration 4.47:
Step 7: To move the cursor, use the left ◀ and right ▶ arrow buttons. This enables changing the speed in larger increments.



Illustration 4.48:
Step 8: Press the [Off] button to stop the motor again.

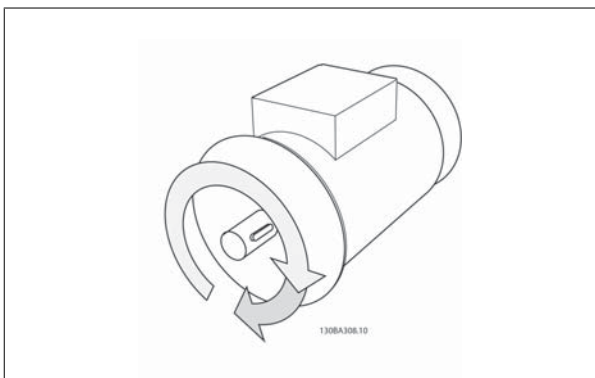



Illustration 4.49:
Step 9: Change two motor wires if the desired rotation of direction is not achieved.



Remove mains power from the frequency converter before changing motor wires.

4.1.27 Switches S201, S202, and S801

Switches S201 (AI 53) and S202 (AI 54) are used to select a current (0-20 mA) or a voltage (0 to 10 V) configuration of the analog input terminals 53 and 54 respectively.

Switch S801 (BUS TER.) can be used to enable termination on the RS-485 port (terminals 68 and 69).

Please note that the switches may be covered by an option, if fitted.

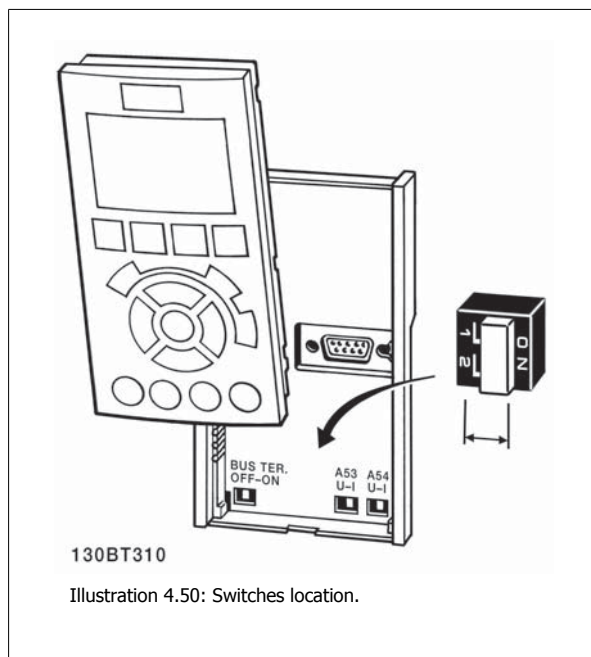
4

Default setting:

S201 (AI 53) = OFF (voltage input)

S202 (AI 54) = OFF (voltage input)

S801 (Bus termination) = OFF



4.2 Final Optimization and Test

To optimize motor shaft performance and optimize the frequency converter for the connected motor and installation, please follow these steps. Ensure that frequency converter and motor are connected and that power is applied to frequency converter.



NB!

Before power up ensure that connected equipment is ready for use.

Step 1. Locate motor name plate



NB!

The motor is either star- (Y) or delta- connected (Δ). This information is located on the motor name plate data.

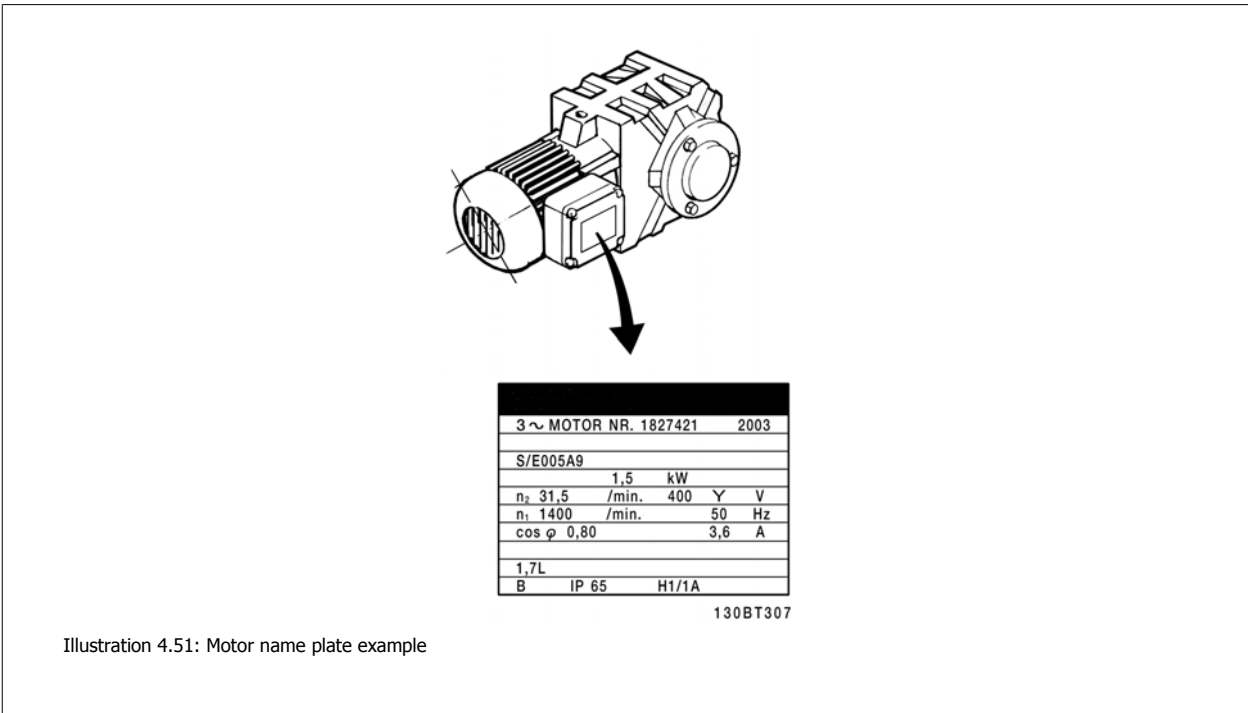


Illustration 4.51: Motor name plate example

Step 2. Enter motor name plate data in following parameter list

To access list first press [QUICK MENU] key then select "Q2 Quick Setup".

| | |
|----|------------------------------|
| 1. | par.1-20 Motor Power [kW] |
| | par.1-21 Motor Power [HP] |
| 2. | par.1-22 Motor Voltage |
| 3. | par.1-23 Motor Frequency |
| 4. | par.1-24 Motor Current |
| 5. | par.1-25 Motor Nominal Speed |

Table 4.15: Motor related parameters

Step 3. Activate Automatic Motor Adaptation (AMA) Activate Auto Tune

Performing AMA ensures best possible performance. AMA automatically takes measurements from the specific motor connected and compensates for installation variances.

1. Connect terminal 27 to terminal 12 or use [QUICK MENU] and "Q2 Quick Setup" and set Terminal 27 par. 5-12 Terminal 27 Digital Input Terminal 27 Digital Input to *No function [0]*
2. Press [QUICK MENU], select "Q3 Function Setups", select "Q3-1 General Settings", select "Q3-10 Adv. Motor Settings" and scroll down to par. 1-29 Automatic Motor Adaptation (AMA) Automatic Motor Adaption.
3. Press [OK] to activate the AMA par.1-29 Automatic Motor Adaptation (AMA).
4. Choose between complete or reduced AMA. If sine wave filter is mounted, run only reduced AMA, or remove sine wave filter during AMA procedure.
5. Press [OK] key. Display should show "Press [Hand on] to start".
6. Press [Hand on] key. A progress bar indicates if AMA is in progress.

Stop the AMA during operation

1. Press the [OFF] key - the frequency converter enters into alarm mode and the display shows that the AMA was terminated by the user.


Successful AMA

1. The display shows "Press [OK] to finish AMA".
2. Press the [OK] key to exit the AMA state.

Unsuccessful AMA

1. The frequency converter enters into alarm mode. A description of the alarm can be found in the *Troubleshooting* section.

- 2. "Report Value" in the [Alarm Log] shows the last measuring sequence carried out by the AMA, before the frequency converter entered alarm mode. This number along with the description of the alarm will assist troubleshooting. If contacting Danfoss Service, make sure to mention number and alarm description.



NB!
 Unsuccessful AMA is often caused by incorrectly entered motor name plate data or too big difference between the motor power size and the frequency converter power size.

Step 4. Set speed limit and ramp time

4

Set up the desired limits for speed and ramp time.

par.3-02 *Minimum Reference*
 par.3-03 *Maximum Reference*

par.4-11 *Motor Speed Low Limit [RPM]* or par.4-12 *Motor Speed Low Limit [Hz]*
 par.4-13 *Motor Speed High Limit [RPM]* or par.4-14 *Motor Speed High Limit [Hz]*

par.3-41 *Ramp 1 Ramp Up Time* Ramp-up Time 1 [s]
 par.3-42 *Ramp 1 Ramp Down Time* Ramp-down Time 1 [s]

See the section *How to programme the frequency converter, Quick Menu Mode* for an easy set-up of these parameters.

5 How to Operate the Frequency Converter

5.1.1 Three ways of operating

The frequency converter can be operated in 3 ways:

1. Graphical Local Control Panel (GLCP), see 5.1.2
2. Numeric Local Control Panel (NLCP), see 5.1.3
3. RS-485 serial communication or USB, both for PC connection, see 5.1.4

If the frequency converter is fitted with fieldbus option, please refer to relevant documentation.

5.1.2 How to operate graphical LCP (GLCP)

The following instructions are valid for the GLCP (LCP 102).

The GLCP is divided into four functional groups:

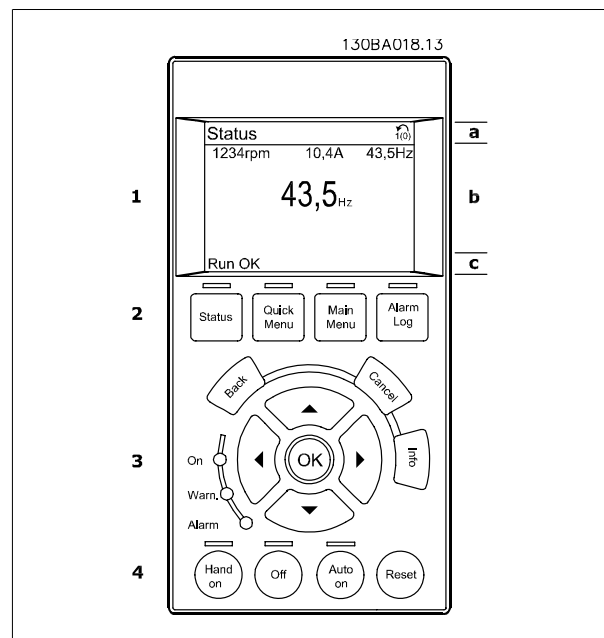
1. Graphical display with Status lines.
2. Menu keys and indicator lights (LED's) - selecting mode, changing parameters and switching between display functions.
3. Navigation keys and indicator lights (LEDs).
4. Operation keys and indicator lights (LEDs).

Graphical display:

The LCD-display is back-lit with a total of 6 alpha-numeric lines. All data is displayed on the LCP which can show up to five operating variables while in [Status] mode.

Display lines:

- a. **Status line:** Status messages displaying icons and graphics.
- b. **Line 1-2:** Operator data lines displaying data and variables defined or chosen by the user. By pressing the [Status] key, up to one extra line can be added.
- c. **Status line:** Status messages displaying text.



The display is divided into 3 sections:

Top section (a) shows the status when in status mode or up to 2 variables when not in status mode and in the case of Alarm/Warning.

The number of the Active Set-up (selected as the Active Set-up in par. 0-10 *Active Set-up*) is shown. When programming in another Set-up than the Active Set-up, the number of the Set-up being programmed appears to the right in brackets.

The **Middle section** (b) shows up to 5 variables with related unit, regardless of status. In case of alarm/warning, the warning is shown instead of the variables.

The **Bottom section** (c) always shows the state of the frequency converter in Status mode.

It is possible to toggle between three status read-out displays by pressing the [Status] key. Operating variables with different formatting are shown in each status screen - see below.

5

Several values or measurements can be linked to each of the displayed operating variables. The values / measurements to be displayed can be defined via par.0-20 *Display Line 1.1 Small*, par. 0-21 *Display Line 1.2 Small*, par. 0-22 *Display Line 1.3 Small*, par. 0-23 *Display Line 2 Large* and par. 0-24 *Display Line 3 Large*, which can be accessed via [QUICK MENU], "Q3 Function Setups", "Q3-1 General Settings", "Q3-13 Display Settings".

Each value / measurement readout parameter selected in par.0-20 *Display Line 1.1 Small* to par. 0-24 *Display Line 3 Large* has its own scale and number of digits after a possible decimal point. Larger numeric values are displayed with few digits after the decimal point.

Ex.: Current readout

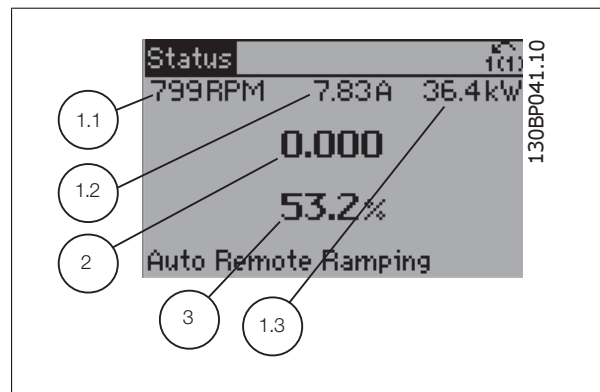
5.25 A; 15.2 A 105 A.

Status display I:

This read-out state is standard after start-up or initialization.

Use [INFO] to obtain information about the value/measurement linked to the displayed operating variables (1.1, 1.2, 1.3, 2, and 3).

See the operating variables shown in the display in this illustration. 1.1, 1.2 and 1.3 are shown in small size. 2 and 3 are shown in medium size.

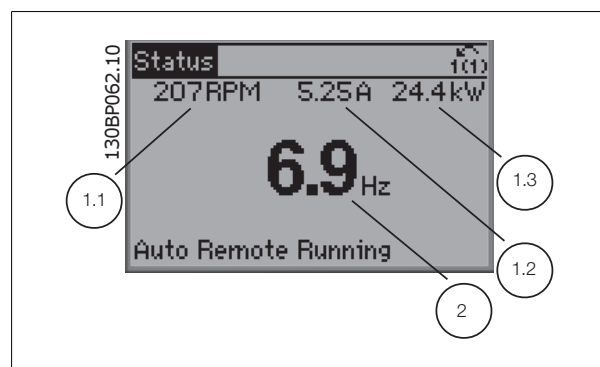


Status display II:

See the operating variables (1.1, 1.2, 1.3, and 2) shown in the display in this illustration.

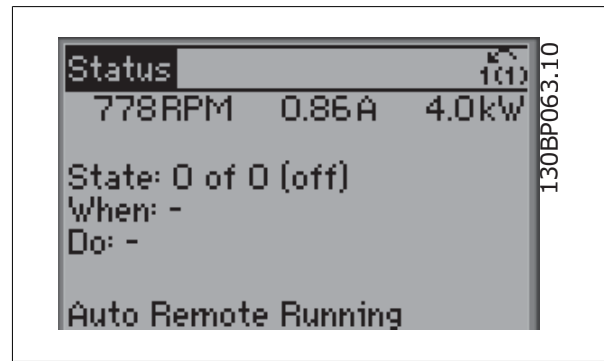
In the example, Speed, Motor current, Motor power and Frequency are selected as variables in the first and second lines.

1.1, 1.2 and 1.3 are shown in small size. 2 is shown in large size.



Status display III:

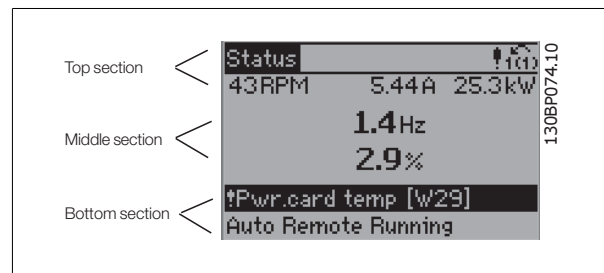
This state displays the event and action of the Smart Logic Control. For further information, see section *Smart Logic Control*.



Display Contrast Adjustment

Press [status] and [▲] for darker display

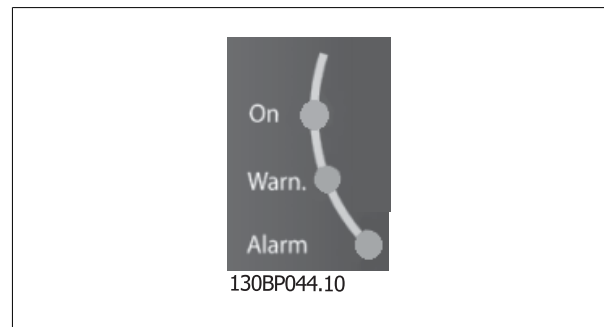
Press [status] and [▼] for brighter display



Indicator lights (LEDs):

If certain threshold values are exceeded, the alarm and/or warning LED lights up. A status and alarm text appear on the control panel. The On LED is activated when the frequency converter receives power from mains voltage, a DC bus terminal, or an external 24 V supply. At the same time, the back light is on.

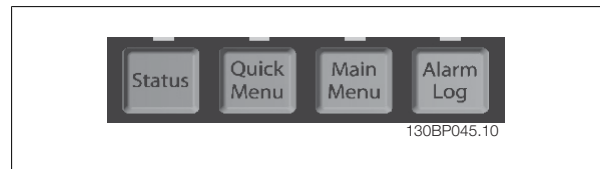
- Green LED/On: Control section is working.
- Yellow LED/Warn.: Indicates a warning.
- Flashing Red LED/Alarm: Indicates an alarm.



GLCP keys

Menu keys

The menu keys are divided into functions. The keys below the display and indicator lamps are used for parameter set-up, including choice of display indication during normal operation.



[Status]

indicates the status of the frequency converter and/or the motor. 3 different readouts can be chosen by pressing the [Status] key: 5 line readouts, 4 line readouts or Smart Logic Control.

Use [Status] for selecting the mode of display or for changing back to Display mode from either the Quick Menu mode, the Main Menu mode or Alarm mode. Also use the [Status] key to toggle single or double read-out mode.

[Quick Menu]

allows quick set-up of the frequency converter. **The most common VLT HVAC Drive functions can be programmed here.**

The [Quick Menu] consists of:

- My Personal Menu
- Quick Set-up
- Function Set-up
- Changes Made
- Loggings

The Function set-up provides quick and easy access to all parameters required for the majority of VLT HVAC Drive applications including most VAV and CAV supply and return fans, cooling tower fans, Primary, Secondary and Condenser Water Pumps and other pump, fan and compressor applications. Amongst other features it also includes parameters for selecting which variables to display on the LCP, digital preset speeds, scaling of analog references, closed loop single zone and multi-zone applications and specific functions related to Fans, Pumps and Compressors.

The Quick Menu parameters can be accessed immediately unless a password has been created via par. 0-60 *Main Menu Password*, par. 0-61 *Access to Main Menu w/o Password*, par. 0-65 *Personal Menu Password* or par. 0-66 *Access to Personal Menu w/o Password*.

It is possible to switch directly between Quick Menu mode and Main Menu mode.

[Main Menu]

is used for programming all parameters. The Main Menu parameters can be accessed immediately unless a password has been created via par. 0-60 *Main Menu Password*, par. 0-61 *Access to Main Menu w/o Password*, par. 0-65 *Personal Menu Password* or par. 0-66 *Access to Personal Menu w/o Password*. For the majority of VLT HVAC Drive applications it is not necessary to access the Main Menu parameters but instead the Quick Menu, Quick Set-up and Function Set-up provides the simplest and quickest access to the typical required parameters.

It is possible to switch directly between Main Menu mode and Quick Menu mode.

Parameter shortcut can be carried out by pressing down the [Main Menu] key for 3 seconds. The parameter shortcut allows direct access to any parameter.

[Alarm Log]

displays an Alarm list of the five latest alarms (numbered A1-A5). To obtain additional details about an alarm, use the arrow keys to manoeuvre to the alarm number and press [OK]. Information is displayed about the condition of the frequency converter before it enters the alarm mode.

The Alarm log button on the LCP allows access to both Alarm log and Maintenance log.

[Back]

reverts to the previous step or layer in the navigation structure.

[Cancel]

last change or command will be cancelled as long as the display has not been changed.

[Info]

displays information about a command, parameter, or function in any display window. [Info] provides detailed information when needed.

Exit Info mode by pressing either [Info], [Back], or [Cancel].



Navigation Keys

The four navigation arrows are used to navigate between the different choices available in [Quick Menu], [Main Menu] and [Alarm Log]. Use the keys to move the cursor.

[OK] is used for choosing a parameter marked by the cursor and for enabling the change of a parameter.



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Operation Keys for local control are found at the bottom of the control panel.



[Hand On]

enables control of the frequency converter via the GLCP. [Hand On] also starts the motor, and it is now possible to enter the motor speed data by means of the arrow keys. The key can be selected as *Enable* [1] or *Disable* [0] via par. 0-40 [Hand on] Key on LCP.

The following control signals will still be active when [Hand On] is activated:

- [Hand On] - [Off] - [Auto on]
- Reset
- Coasting stop inverse
- Reversing
- Set-up select lsb - Set-up select msb
- Stop command from serial communication
- Quick stop
- DC brake

NB!
External stop signals activated by means of control signals or a serial bus will override a "start" command via the LCP.

[Off]

stops the connected motor. The key can be selected as *Enable* [1] or *Disable* [0] via par. 0-41 [Off] Key on LCP. If no external stop function is selected and the [Off] key is inactive the motor can only be stopped by disconnecting the mains supply.

[Auto on]

enables the frequency converter to be controlled via the control terminals and/or serial communication. When a start signal is applied on the control terminals and/or the bus, the frequency converter will start. The key can be selected as Enable [1] or Disable [0] via par. 0-42 *[Auto on] Key on LCP*.

**NB!**

An active HAND-OFF-AUTO signal via the digital inputs has higher priority than the control keys [Hand on] – [Auto on].

[Reset]

is used for resetting the frequency converter after an alarm (trip). It can be selected as *Enable* [1] or *Disable* [0] via par. 0-43 *[Reset] Key on LCP*.

The parameter shortcut can be carried out by holding down the [Main Menu] key for 3 seconds. The parameter shortcut allows direct access to any parameter.

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5.1.3 How to operate numeric LCP (NLCP)

The following instructions are valid for the NLCP (LCP 101).

The control panel is divided into four functional groups:

1. Numeric display.
2. Menu key and indicator lights (LEDs) - changing parameters and switching between display functions.
3. Navigation keys and indicator lights (LEDs).
4. Operation keys and indicator lights (LEDs).

**NB!**

Parameter copy is not possible with Numeric Local Control Panel (LCP101).

Select one of the following modes:

Status Mode: Displays the status of the frequency converter or the motor.

If an alarm occurs, the NLCP automatically switches to status mode. A number of alarms can be displayed.

Quick Setup or Main Menu Mode: Display parameters and parameter settings.

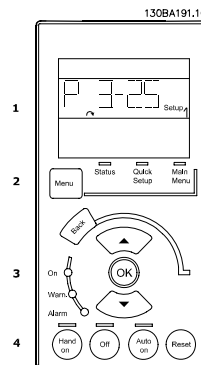


Illustration 5.1: Numerical LCP (NLCP)

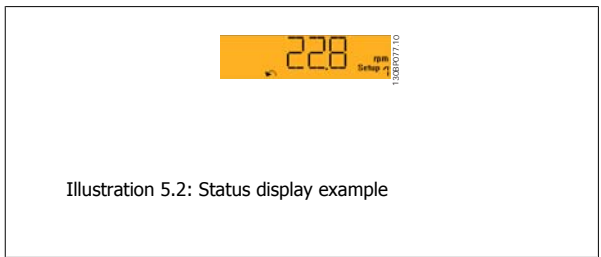


Illustration 5.2: Status display example

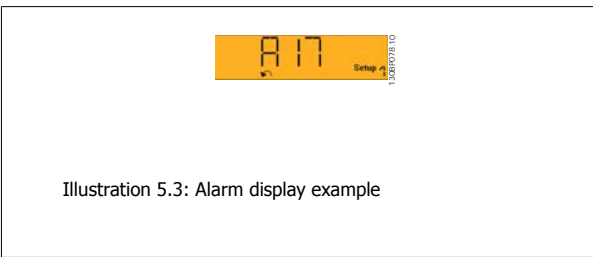


Illustration 5.3: Alarm display example

Indicator lights (LEDs):

- Green LED/On: Indicates if control section is on.
- Yellow LED/Wrn.: Indicates a warning.
- Flashing red LED/Alarm: Indicates an alarm.

Menu key

[Menu] Select one of the following modes:

- Status
- Quick Setup
- Main Menu

Main Menu

is used for programming all parameters.

The parameters can be accessed immediately unless a password has been created via par. 0-60 *Main Menu Password*, par. 0-61 *Access to Main Menu w/o Password*, par. 0-65 *Personal Menu Password* or par. 0-66 *Access to Personal Menu w/o Password*.

Quick Setup is used to set up the frequency converter using only the most essential parameters.

The parameter values can be changed using the up/down arrows when the value is flashing.

Select Main Menu by pressing the [Menu] key a number of times until the Main Menu LED is lit.

Select the parameter group [xx-__] and press [OK]

Select the parameter [__-xx] and press [OK]

If the parameter is an array parameter select the array number and press [OK]

Select the wanted data value and press [OK]

Navigation Keys

[Back]

for stepping backwards

Arrow [▲] [▼]

keys are used for manoeuvring between parameter groups, parameters and within parameters

[OK]

is used for choosing a parameter marked by the cursor and for enabling the change of a parameter.

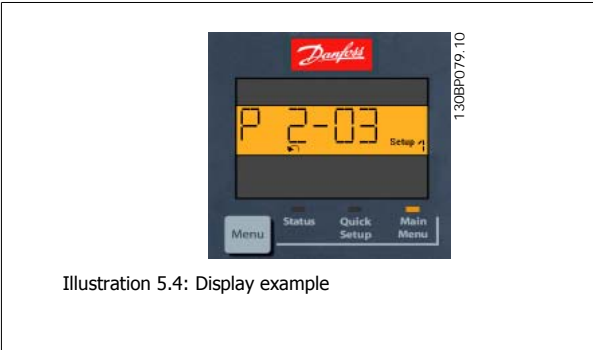


Illustration 5.4: Display example

Operation Keys

Keys for local control are found at the bottom of the control panel.

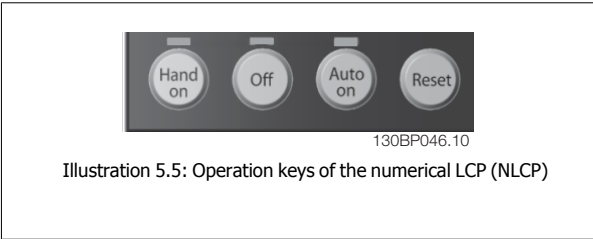


Illustration 5.5: Operation keys of the numerical LCP (NLCP)

[Hand on]

enables control of the frequency converter via the LCP. [Hand on] also starts the motor and it is now possible to enter the motor speed data by means of the arrow keys. The key can be *Enabled* [1] or *Disabled* [0] via par. 0-40 *[Hand on] Key on LCP*.

External stop signals activated by means of control signals or a serial bus will override a 'start' command via the LCP.

The following control signals will still be active when [Hand on] is activated:

- [Hand on] - [Off] - [Auto on]
- Reset
- Coasting stop inverse
- Reversing
- Set-up select lsb - Set-up select msb
- Stop command from serial communication
- Quick stop
- DC brake

[Off]

stops the connected motor. The key can be *Enabled* [1] or *Disabled* [0] via par. 0-41 [Off] Key on LCP.

If no external stop function is selected and the [Off] key is inactive the motor can be stopped by disconnecting the mains supply.

[Auto on]

enables the frequency converter to be controlled via the control terminals and/or serial communication. When a start signal is applied on the control terminals and/or the bus, the frequency converter will start. The key can be *Enabled* [1] or *Disabled* [0] via par. 0-42 [Auto on] Key on LCP.



NB!

An active HAND-OFF-AUTO signal via the digital inputs has higher priority than the control keys [Hand on] [Auto on].

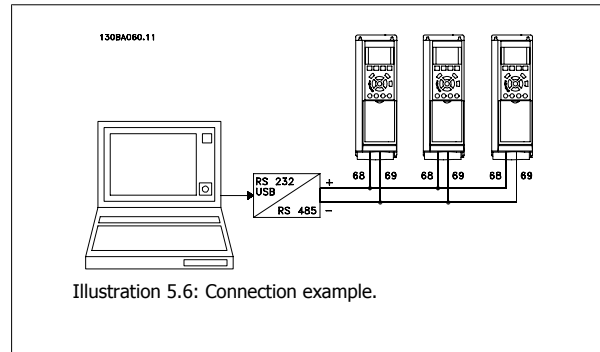
[Reset]

is used for resetting the frequency converter after an alarm (trip). The key can be *Enabled* [1] or *Disabled* [0] via par. 0-43 [Reset] Key on LCP.

5.1.4 RS-485 Bus Connection

One or more frequency converters can be connected to a controller (or master) using the RS-485 standard interface. Terminal 68 is connected to the P signal (TX+, RX+), while terminal 69 is connected to the N signal (TX-, RX-).

If more than one frequency converter is connected to a master, use parallel connections.



In order to avoid potential equalizing currents in the screen, earth the cable screen via terminal 61, which is connected to the frame via an RC-link.

Bus termination

The RS-485 bus must be terminated by a resistor network at both ends. If the drive is the first or the last device in the RS-485 loop, set the switch S801 on the control card for ON.

For more information, see the paragraph *Switches S201, S202, and S801*.

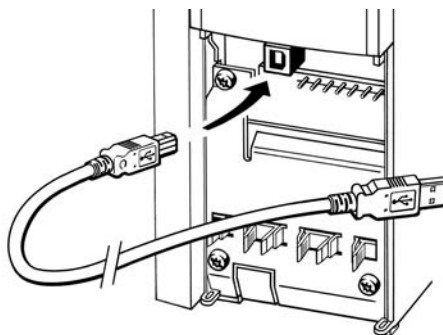
5.1.5 How to Connect a PC to the frequency converter

To control or program the frequency converter from a PC, install the PC-based Configuration Tool MCT 10.

The PC is connected via a standard (host/device) USB cable, or via the RS-485 interface as shown in the VLT HVAC Drive *Design Guide, chapter How to Install > Installation of misc. connections*.

**NB!**

The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals. The USB connection is connected to protection earth on the frequency converter. Use only isolated laptop as PC connection to the USB connector on the frequency converter.



130BT308

Illustration 5.7: For control cable connections, see section on *Control Terminals*.

5.1.6 PC Software tools

PC-based Configuration Tool MCT 10

All Frequency converters are equipped with a serial communication port. Danfoss provides a PC tool for communication between PC and frequency converter, PC-based Configuration Tool MCT 10. Please check the section on *Available Literature* for detailed information on this tool.

MCT 10 Set-up Software

MCT 10 has been designed as an easy to use interactive tool for setting parameters in our frequency converters. The software can be downloaded from the Danfoss internet site <http://www.Danfoss.com/BusinessAreas/DrivesSolutions/SoftwareDownload/DDPC+Software+Program.htm>.

The xMCT 10 Set-up software will be useful for:

- Planning a communication network off-line. MCT 10 contains a complete frequency converter database
- Commissioning frequency converters on line
- Saving settings for all frequency converters
- Replacing a frequency converter in a network
- Simple and accurate documentation of frequency converter settings after commissioning.
- Expanding an existing network
- Future developed frequency converters will be supported

MCT 10 set-up software supports Profibus DP-V1 via a Master class 2 connection. It makes it possible to on line read/write parameters in a frequency converter via the Profibus network. This will eliminate the need for an extra communication network.

Save Frequency Converter Settings:

1. Connect a PC to the unit via USB com port. (Note: Use a PC, which is isolated from the mains, in conjunction with the USB port. Failure to do so may damage equipment.)
2. Open MCT 10 Set-up Software
3. Choose "Read from drive"
4. Choose "Save as"

All parameters are now stored in the PC.

Load Frequency Converter Settings:

1. Connect a PC to the frequency converter via USB com port
2. Open MCT 10 Set-up software
3. Choose "Open" – stored files will be shown
4. Open the appropriate file
5. Choose "Write to drive"

All parameter settings are now transferred to the frequency converter.

A separate manual for MCT 10 Set-up Software is available: *MG.10.Rx.yy*.

The MCT 10 Set-up Software Modules

The following modules are included in the software package:

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| | |
|--|--|
| | MCT Set-up 10 Software Setting parameters Copy to and from frequency converters Documentation and print out of parameter settings incl. diagrams |
| | Ext. User Interface Preventive Maintenance Schedule Clock settings Timed Action Programming Smart Logic Controller Set-up |

Ordering number:

Please order the CD containing MCT 10 Set-up Software using code number 130B1000.

MCT 10 can also be downloaded from the Danfoss Internet: WWW.DANFOSS.COM, Business Area: Motion Controls.

5.1.7 Tips and tricks

| | |
|---|--|
| * | For the majority of HVAC applications the Quick Menu, Quick Set-up and Function Set-up provides the simplest and quickest access to all the typical parameters required. |
| * | Whenever possible, performing an AMA, will ensure best shaft performance |
| * | Contrast of the display can be adjusted by pressing [Status] and [▲] for darker display or by pressing [Status] and [▼] for brighter display |
| * | Under [Quick Menu] and [Changes Made] all parameters that have been changed from factory settings are displayed |
| * | Press and hold [Main Menu] key for 3 seconds for access to any parameter |
| * | For service purposes it is recommended to copy all parameters to the LCP, see par. 0-50 <i>LCP Copy</i> for further information |

Table 5.1: Tips and tricks

5.1.8 Quick Transfer of Parameter Settings when using GLCP

Once the set-up of a frequency converter is complete, it is recommended to store (backup) the parameter settings in the GLCP or on a PC via MCT 10 Set-up Software Tool.

**NB!**

Stop the motor before performing any of these operations.

Data storage in LCP:

1. Go to par. 0-50 *LCP Copy*
2. Press the [OK] key
3. Select "All to LCP"
4. Press the [OK] key

All parameter settings are now stored in the GLCP indicated by the progress bar. When 100% is reached, press [OK].

The GLCP can now be connected to another frequency converter and the parameter settings copied to this frequency converter.

Data transfer from LCP to Frequency converter:

1. Go to par. 0-50 *LCP Copy*
2. Press the [OK] key
3. Select "All from LCP"
4. Press the [OK] key

The parameter settings stored in the GLCP are now transferred to the frequency converter indicated by the progress bar. When 100% is reached, press [OK].

5.1.9 Initialisation to Default Settings

There are two ways to initialise the frequency converter to default: Recommended initialisation and manual initialisation.

Please be aware that they have different impact according to the below description.

Recommended initialisation (via par. 14-22 *Operation Mode*)

1. Select par. 14-22 *Operation Mode*
2. Press [OK]
3. Select "Initialisation" (for NLCP select "2")
4. Press [OK]
5. Remove power to unit and wait for display to turn off.
6. Reconnect power and the frequency converter is reset. Note that first start-up takes a few more seconds.
7. Press [Reset]

par. 14-22 *Operation Mode* initialises all except:

- par. 14-50 *RFI Filter*
- par. 8-30 *Protocol*
- par. 8-31 *Address*
- par. 8-32 *Baud Rate*
- par. 8-35 *Minimum Response Delay*
- par. 8-36 *Max Response Delay*
- par. 8-37 *Maximum Inter-Char Delay*
- par. 15-00 *Operating Hours* to par. 15-05 *Over Volt's*
- par. 15-20 *Historic Log: Event* to par. 15-22 *Historic Log: Time*
- par. 15-30 *Alarm Log: Error Code* to par. 15-32 *Alarm Log: Time*

**NB!**

Parameters selected in par. 0-25 *My Personal Menu*, will stay present, with default factory setting.

Manual initialisation**NB!**

When carrying out manual initialisation, serial communication, RFI filter settings and fault log settings are reset.
Removes parameters selected in par. 0-25 *My Personal Menu*

1. Disconnect from mains and wait until the display turns off.
- 2a. Press [Status] - [Main Menu] - [OK] at the same time while power up for Graphical LCP (GLCP).
- 2b. Press [Menu] while power up for LCP 101, Numerical Display
3. Release the keys after 5 s.
4. The frequency converter is now programmed according to default settings.

This parameter initialises all except:

- par. 15-00 *Operating Hours*
- par. 15-03 *Power Up's*
- par. 15-04 *Over Temp's*
- par. 15-05 *Over Volt's*

6

6 How to Programme the Frequency Converter

6.1 How to programme

6.1.1 Quick Menu Mode

Parameter Data

The graphical display (GLCP) provides access to all parameters listed under the Quick Menus. The numeric display (NLCP) only provides access to the Quick Setup parameters. To set parameters using the [Quick Menu] button - enter or change parameter data or settings in accordance with the following procedure:

1. Press Quick Menu button
2. Use the [▲] and [▼] buttons to find the parameter you want to change
3. Press [OK]
4. Use [▲] and [▼] buttons to select the correct parameter setting
5. Press [OK]
6. To move to a different digit within a parameter setting, use the [◀] and [▶] buttons
7. Highlighted area indicates digit selected for change
8. Press [Cancel] button to disregard change, or press [OK] to accept change and enter the new setting

Example of Changing Parameter Data

Assume parameter 22-60 is set to [Off]. However, you want to monitor the fan-belt condition - non- broken or broken - according to the following procedure:

1. Press Quick Menu key
2. Choose Function Setups with the [▼] button
3. Press [OK]
4. Choose Application Settings with the [▼] button
5. Press [OK]
6. Press [OK] again for Fan Functions
7. Choose Broken Belt Function by pressing [OK]
8. With [▼] button, choose [2] Trip

The frequency converter will now trip if a broken fan-belt is detected.

Select [My Personal Menu] to display personal parameters:

Select [My Personal Menu] to display only the parameters, which have been pre-selected and programmed as personal parameters. For example, an AHU or pump OEM may have pre-programmed personal parameters to be in My Personal Menu during factory commissioning to make on-site commissioning/ fine tuning simpler. These parameters are selected in par. 0-25 *My Personal Menu*. Up to 20 different parameters can be programmed in this menu.

Select [Changes Made] to get information about:

- the last 10 changes. Use the up/down navigation keys to scroll between the last 10 changed parameters.
- the changes made since default setting.

Select [Loggings]:

to get information about the display line read-outs. The information is shown as graphs.

Only display parameters selected in par.0-20 *Display Line 1.1 Small* and par. 0-24 *Display Line 3 Large* can be viewed. It is possible to store up to 120 samples in the memory for later reference.

Efficient Parameter Set-up for VLT HVAC Drive Applications:

The parameters can easily be set up for the vast majority of the VLT HVAC Drive applications only by using the [Quick Setup] option.

After pressing [Quick Menu], the different choices in the Quick Menu are listed. See also illustration 6.1 below and tables Q3-1 to Q3-4 in the following *Function Setups* section.

Example of using the Quick Setup option:

Assume you want to set the Ramp Down Time to 100 seconds!

1. Select [Quick Setup]. The first par.0-01 *Language* in Quick Setup appears
2. Press [▼] repeatedly until par.3-42 *Ramp 1 Ramp Down Time* appears with the default setting of 20 seconds
3. Press [OK]
4. Use the [◀] button to highlight the 3rd digit before the comma
5. Change '0' to '1' by using the [▲] button
6. Use the [▶] button to highlight the digit '2'
7. Change '2' to '0' with the [▼] button
8. Press [OK]

The new ramp-down time is now set to 100 seconds.
It is recommended to do the set-up in the order listed.

6**NB!**

A complete description of the function is found in the parameter sections of this manual.



Illustration 6.1: Quick Menu view.

The Quick Setup menu gives access to the 13 most important setup parameters of the frequency converter. After programming the frequency converter will, in most cases be ready for operation. The 13 (see footnote) Quick Setup parameters are shown in the table below. A complete description of the function is given in the parameter description sections of this manual.

| Parameter | [Units] |
|--|---------|
| par.0-01 <i>Language</i> | |
| par.1-20 <i>Motor Power [kW]</i> | [kW] |
| par.1-21 <i>Motor Power [HP]</i> | [HP] |
| par.1-22 <i>Motor Voltage</i> | [V] |
| par.1-23 <i>Motor Frequency</i> | [Hz] |
| par.1-24 <i>Motor Current</i> | [A] |
| par.1-25 <i>Motor Nominal Speed</i> | [RPM] |
| par.1-28 <i>Motor Rotation Check</i> | [Hz] |
| par.3-41 <i>Ramp 1 Ramp Up Time</i> | [s] |
| par.3-42 <i>Ramp 1 Ramp Down Time</i> | [s] |
| par.4-11 <i>Motor Speed Low Limit [RPM]</i> | [RPM] |
| par.4-12 <i>Motor Speed Low Limit [Hz]</i> | [Hz] |
| par.4-13 <i>Motor Speed High Limit [RPM]</i> | [RPM] |
| par.4-14 <i>Motor Speed High Limit [Hz]</i> | [Hz] |
| par. 3-19 <i>Jog Speed [RPM]</i> | [RPM] |
| par.3-11 <i>Jog Speed [Hz]</i> | [Hz] |
| par. 5-12 <i>Terminal 27 Digital Input</i> | |
| par.5-40 <i>Function Relay</i> | |

Table 6.1: Quick Setup parameters

*The display showing depends on choices made in par. 0-02 *Motor Speed Unit* and par. 0-03 *Regional Settings*. The default settings of par. 0-02 *Motor Speed Unit* and par. 0-03 *Regional Settings* depend on which region of the world the frequency converter is supplied to but can be re-programmed as required.

** par.5-40 *Function Relay*, is an array, where one may choose between Relay1 [0] or Relay2 [1]. Standard setting is Relay1 [0] with the default choice Alarm [9].

See the parameter description later in this chapter under Function Setup parameters.

For a detailed information about settings and programming, please see the *VLT HVAC Drive Programming Guide, MG.11.CX.YY*

x=version number

y=language

NB!
 If [No Operation] is selected in par. 5-12 *Terminal 27 Digital Input*, no connection to +24 V on terminal 27 is necessary to enable start.
 If [Coast Inverse] (factory default value) is selected in par. 5-12 *Terminal 27 Digital Input*, a connection to +24V is necessary to enable start.

6.1.2 Quick Set-up parameters

Parameters for Quick Set-up

0-01 Language

Option:

Function:

Defines the language to be used in the display.

The frequency converter can be delivered with 2 different language packages. English and German are included in both packages. English cannot be erased or manipulated.

[0] * English Part of Language packages 1 - 2

[1] Deutsch Part of Language packages 1 - 2

[2] Francais Part of Language package 1

[3] Dansk Part of Language package 1

[4] Spanish Part of Language package 1

[5] Italiano Part of Language package 1

[6] Svenska Part of Language package 1

[7] Nederlands Part of Language package 1

[10] Chinese Language package 2

[20] Suomi Part of Language package 1

[22] English US Part of Language package 1

[27] Greek Part of Language package 1

[28] Bras.port Part of Language package 1

[36] Slovenian Part of Language package 1

[39] Korean Part of Language package 2

[40] Japanese Part of Language package 2

[41] Turkish Part of Language package 1

[42] Trad.Chinese Part of Language package 2

[43] Bulgarian Part of Language package 1

[44] Srpski Part of Language package 1

[45] Romanian Part of Language package 1

[46] Magyar Part of Language package 1

[47] Czech Part of Language package 1

[48] Polski Part of Language package 1

[49] Russian Part of Language package 1

[50] Thai Part of Language package 2

[51] Bahasa Indonesia Part of Language package 2

1-20 Motor Power [kW]

Range:

4.00 kW* [0.09 - 3000.00 kW]

Function:

Enter the nominal motor power in kW according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit.
 This parameter cannot be adjusted while the motor is running. Depending on the choices made in par. 0-03 *Regional Settings*, either par.1-20 *Motor Power [kW]* or par.1-21 *Motor Power [HP]* is made invisible.

1-21 Motor Power [HP]

Range:

4.00 hp* [0.09 - 3000.00 hp]

Function:

Enter the nominal motor power in HP according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit.
 This parameter cannot be adjusted while the motor is running.
 Depending on the choices made in par. 0-03 *Regional Settings*, either par.1-20 *Motor Power [kW]* or par.1-21 *Motor Power [HP]* is made invisible.

1-22 Motor Voltage

Range:

400. V* [10. - 1000. V]

Function:

Enter the nominal motor voltage according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit.
 This parameter cannot be adjusted while the motor is running.

1-23 Motor Frequency

Range:

50. Hz* [20 - 1000 Hz]

Function:

Select the motor frequency value from the motor nameplate data. For 87 Hz operation with 230/400 V motors, set the nameplate data for 230 V/50 Hz. Adapt par.4-13 *Motor Speed High Limit [RPM]* and par.3-03 *Maximum Reference* to the 87 Hz application.

NB!
 This parameter cannot be adjusted while the motor is running.

1-24 Motor Current

Range:

7.20 A* [0.10 - 10000.00 A]

Function:

Enter the nominal motor current value from the motor nameplate data. This data is used for calculating motor torque, motor thermal protection etc.

NB!
 This parameter cannot be adjusted while the motor is running.

1-25 Motor Nominal Speed

Range:

1420. RPM* [100 - 60000 RPM]

Function:

Enter the nominal motor speed value from the motor nameplate data. This data is used for calculating automatic motor compensations.

NB!
 This parameter cannot be changed while the motor is running.

1-28 Motor Rotation Check**Option:****Function:**

Following installation and connection of the motor, this function allows the correct motor rotation direction to be verified. Enabling this function overrides any bus commands or digital inputs, except External Interlock and Safe Stop (if included).

[0] * Off

Motor Rotation Check is not active.

[1] Enabled

Motor Rotation Check is enabled. Once enabled, Display shows:
"Note! Motor may run in wrong direction".

Pressing [OK], [Back] or [Cancel] will dismiss the message and display a new message: "Press [Hand on] to start the motor. Press [Cancel] to abort". Pressing [Hand on] starts the motor at 5 Hz in forward direction and the display shows: "Motor is running. Check if motor rotation direction is correct. Press [Off] to stop the motor". Pressing [Off] stops the motor and resets par.1-28 *Motor Rotation Check*. If motor rotation direction is incorrect, two motor phase cables should be interchanged. IMPORTANT:

6



Mains power must be removed before disconnecting motor phase cables.

3-41 Ramp 1 Ramp Up Time**Range:**

10.00 s* [1.00 - 3600.00 s]

Function:

Enter the ramp-up time, i.e. the acceleration time from 0 RPM to par.1-25 *Motor Nominal Speed*. Choose a ramp-up time such that the output current does not exceed the current limit in par. 4-18 *Current Limit* during ramping. See ramp-down time in par.3-42 *Ramp 1 Ramp Down Time*.

$$par.3 - 41 = \frac{tacc \times nnorm [par.1 - 25]}{ref[rpm]} [s]$$

3-42 Ramp 1 Ramp Down Time**Range:**

20.00 s* [1.00 - 3600.00 s]

Function:

Enter the ramp-down time, i.e. the deceleration time from par.1-25 *Motor Nominal Speed* to 0 RPM. Choose a ramp-down time such that no over-voltage arises in the inverter due to regenerative operation of the motor, and such that the generated current does not exceed the current limit set in par. 4-18 *Current Limit*. See ramp-up time in par.3-41 *Ramp 1 Ramp Up Time*.

$$par.3 - 42 = \frac{tdec \times nnorm [par.1 - 25]}{ref[rpm]} [s]$$

4-11 Motor Speed Low Limit [RPM]**Range:**

0 RPM* [0 - par. 4-13 RPM]

Function:

Enter the minimum limit for motor speed. The Motor Speed Low Limit can be set to correspond to the manufacturer's recommended minimum motor speed. The Motor Speed Low Limit must not exceed the setting in par.4-13 *Motor Speed High Limit [RPM]*.

4-12 Motor Speed Low Limit [Hz]**Range:**

0 Hz* [0 - par. 4-14 Hz]

Function:

Enter the minimum limit for motor speed. The Motor Speed Low Limit can be set to correspond to the minimum output frequency of the motor shaft. The Speed Low Limit must not exceed the setting in par.4-14 *Motor Speed High Limit [Hz]*.

4-13 Motor Speed High Limit [RPM]

Range:

1500. RPM* [par. 4-11 - 60000. RPM]

Function:

Enter the maximum limit for motor speed. The Motor Speed High Limit can be set to correspond to the manufacturer's maximum rated motor. The Motor Speed High Limit must exceed the setting in par.4-11 *Motor Speed Low Limit [RPM]*. Only par.4-11 *Motor Speed Low Limit [RPM]* or par. 4-12 *Motor Speed Low Limit [Hz]* will be displayed depending on other parameters in the Main Menu and depending on default settings dependant on global location.



NB!

The output frequency value of the frequency converter must not exceed a value higher than 1/10 of the switching frequency.



NB!

Any changes in par.4-13 *Motor Speed High Limit [RPM]* will reset the value in par.4-53 *Warning Speed High* to the same value as set in par.4-13 *Motor Speed High Limit [RPM]*.

4-14 Motor Speed High Limit [Hz]

Range:

50/60.0 [par. 4-12 - par. 4-19 Hz]
Hz*

Function:

Enter the maximum limit for motor speed. The Motor Speed High Limit can be set to correspond to the manufacturer's recommended maximum of the motor shaft. The Motor Speed High Limit must exceed the in par.4-12 *Motor Speed Low Limit [Hz]*. Only par.4-11 *Motor Speed Low Limit [RPM]* or par.4-12 *Motor Speed Low Limit [Hz]* will be displayed depending on other parameters in the Main Menu and depending on default settings dependant on global location.



NB!

Max. output frequency cannot exceed 10% of the inverter switching frequency (par.14-01 *Switching Frequency*).

3-11 Jog Speed [Hz]

Range:

10.0 Hz* [0.0 - par. 4-14 Hz]

Function:

The jog speed is a fixed output speed at which the frequency converter is running when the jog function is activated.
See also par. 3-80 *Jog Ramp Time*.

Option:

Function:

5-12 Terminal 27 Digital Input

Option:

Function:

Same options and functions as par. 5-1*, except for *Pulse input*.

[0] * No operation

5-40 Function Relay

Array [8]

(Relay 1 [0], Relay 2 [1])

Option MCB 105: Relay 7 [6], Relay 8 [7] and Relay 9 [8].

Select options to define the function of the relays.

The selection of each mechanical relay is realised in an array parameter.

Option:

Function:

[0] * No operation

[1] Control ready

[2] Drive ready

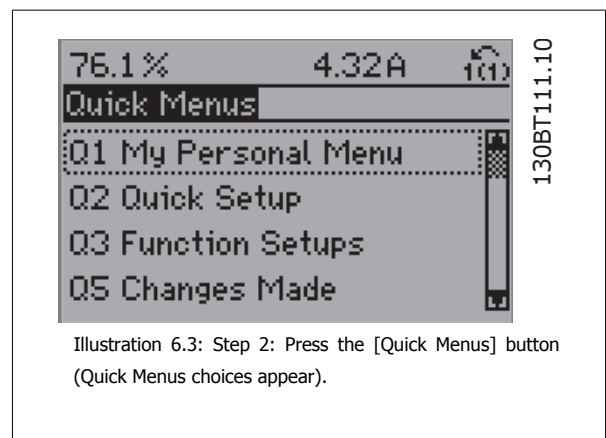
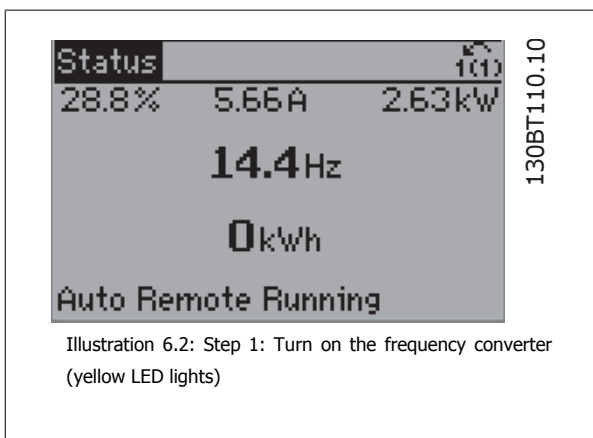
| | | |
|-------|------------------------|------------------------------|
| [3] | Drive rdy/rem ctrl | |
| [4] | Standby / no warning | |
| [5] * | Running | Default setting for relay 2. |
| [6] | Running / no warning | |
| [8] | Run on ref/no warn | |
| [9] * | Alarm | Default setting for relay 1. |
| [10] | Alarm or warning | |
| [11] | At torque limit | |
| [12] | Out of current range | |
| [13] | Below current, low | |
| [14] | Above current, high | |
| [15] | Out of speed range | |
| [16] | Below speed, low | |
| [17] | Above speed, high | |
| [18] | Out of feedb. range | |
| [19] | Below feedback, low | |
| [20] | Above feedback, high | |
| [21] | Thermal warning | |
| [25] | Reverse | |
| [26] | Bus OK | |
| [27] | Torque limit & stop | |
| [28] | Brake, no brake war | |
| [29] | Brake ready, no fault | |
| [30] | Brake fault (IGBT) | |
| [35] | External Interlock | |
| [36] | Control word bit 11 | |
| [37] | Control word bit 12 | |
| [40] | Out of ref range | |
| [41] | Below reference, low | |
| [42] | Above ref, high | |
| [45] | Bus ctrl. | |
| [46] | Bus ctrl, 1 if timeout | |
| [47] | Bus ctrl, 0 if timeout | |
| [60] | Comparator 0 | |
| [61] | Comparator 1 | |
| [62] | Comparator 2 | |
| [63] | Comparator 3 | |
| [64] | Comparator 4 | |
| [65] | Comparator 5 | |
| [70] | Logic rule 0 | |
| [71] | Logic rule 1 | |
| [72] | Logic rule 2 | |
| [73] | Logic rule 3 | |
| [74] | Logic rule 4 | |
| [75] | Logic rule 5 | |
| [80] | SL digital output A | |

| | |
|-------|----------------------|
| [81] | SL digital output B |
| [82] | SL digital output C |
| [83] | SL digital output D |
| [84] | SL digital output E |
| [85] | SL digital output F |
| [160] | No alarm |
| [161] | Running reverse |
| [165] | Local ref active |
| [166] | Remote ref active |
| [167] | Start command act. |
| [168] | Hand mode |
| [169] | Auto mode |
| [180] | Clock Fault |
| [181] | Prev. Maintenance |
| [190] | No-Flow |
| [191] | Dry Pump |
| [192] | End Of Curve |
| [193] | Sleep Mode |
| [194] | Broken Belt |
| [195] | Bypass Valve Control |
| [196] | Fire Mode |
| [197] | Fire Mode was Act. |
| [198] | Drive Bypass |
| [211] | Cascade Pump 1 |
| [212] | Cascade Pump 2 |
| [213] | Cascade Pump 3 |

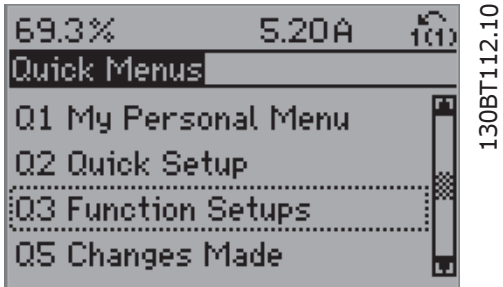
6.1.3 Function Setups

The Function set-up provides quick and easy access to all parameters required for the majority of VLT HVAC Drive applications including most VAV and CAV supply and return fans, cooling tower fans, Primary, Secondary and Condenser Water Pumps and other pump, fan and compressor applications.

How to access Function set-up - example

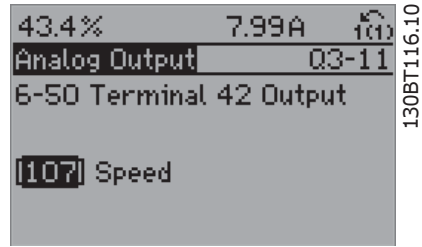


6



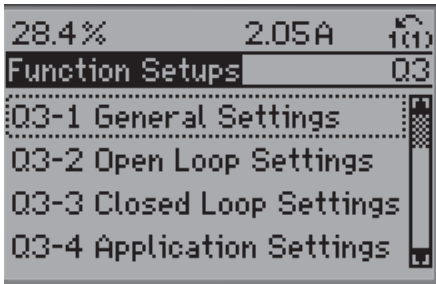
130BT112.10

Illustration 6.4: Step 3: Use the up/down navigation keys to scroll down to Function set-ups. Press [OK].



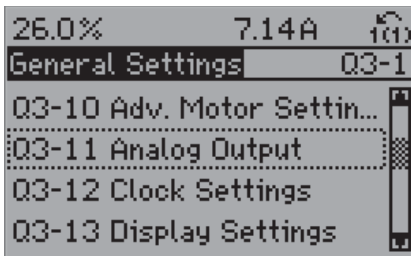
130BT116.10

Illustration 6.8: Step 7: Use the up/down navigation keys to select between the different choices. Press [OK].



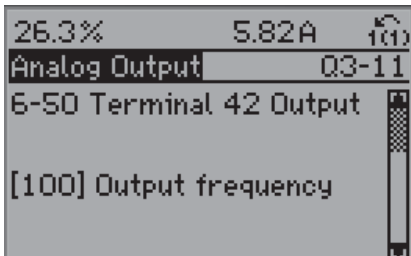
130BT113.10

Illustration 6.5: Step 4: Function set-ups choices appear. Choose 03-1 *General Settings*. Press [OK].



130BT114.10

Illustration 6.6: Step 5: Use the up/down navigation keys to scroll down to i.e. 03-11 *Analog Outputs*. Press [OK].



130BT115.10

Illustration 6.7: Step 6: Choose par. 6-50. Press [OK].

Function Set-ups parameters

The Function Setups parameters are grouped in the following way:

| Q3-1 General Settings | | | |
|--|--|--------------------------------------|--|
| Q3-10 Adv. Motor Settings | Q3-11 Analog Output | Q3-12 Clock Settings | Q3-13 Display Settings |
| par.1-90 <i>Motor Thermal Protection</i> | par.6-50 <i>Terminal 42 Output</i> | par.0-70 <i>Date and Time</i> | par.0-20 <i>Display Line 1.1 Small</i> |
| par.1-93 <i>Thermistor Source</i> | par.6-51 <i>Terminal 42 Output Min Scale</i> | par.0-71 <i>Date Format</i> | par.0-21 <i>Display Line 1.2 Small</i> |
| par.1-29 <i>Automatic Motor Adaptation (AMA)</i> | par.6-52 <i>Terminal 42 Output Max Scale</i> | par.0-72 <i>Time Format</i> | par.0-22 <i>Display Line 1.3 Small</i> |
| par.14-01 <i>Switching Frequency</i> | | par.0-74 <i>DST/Summertime</i> | par.0-23 <i>Display Line 2 Large</i> |
| par.4-53 <i>Warning Speed High</i> | | par.0-76 <i>DST/Summertime Start</i> | par.0-24 <i>Display Line 3 Large</i> |
| | | par.0-77 <i>DST/Summertime End</i> | par.0-37 <i>Display Text 1</i> |
| | | | par.0-38 <i>Display Text 2</i> |
| | | | par.0-39 <i>Display Text 3</i> |

| Q3-2 Open Loop Settings | |
|---|--|
| Q3-20 Digital Reference | Q3-21 Analog Reference |
| par.3-02 <i>Minimum Reference</i> | par.3-02 <i>Minimum Reference</i> |
| par.3-03 <i>Maximum Reference</i> | par.3-03 <i>Maximum Reference</i> |
| par.3-10 <i>Preset Reference</i> | par.6-10 <i>Terminal 53 Low Voltage</i> |
| par.5-13 <i>Terminal 29 Digital Input</i> | par.6-11 <i>Terminal 53 High Voltage</i> |
| par.5-14 <i>Terminal 32 Digital Input</i> | par.6-12 <i>Terminal 53 Low Current</i> |
| par.5-15 <i>Terminal 33 Digital Input</i> | par.6-13 <i>Terminal 53 High Current</i> |
| | par.6-14 <i>Terminal 53 Low Ref./Feedb. Value</i> |
| | par.6-15 <i>Terminal 53 High Ref./Feedb. Value</i> |

| Q3-3 Closed Loop Settings | | |
|--|--|--|
| Q3-30 Single Zone Int. Set Point | Q3-31 Single Zone Ext. Set Point | Q3-32 Multi Zone / Adv |
| par.1-00 <i>Configuration Mode</i> | par.1-00 <i>Configuration Mode</i> | par.1-00 <i>Configuration Mode</i> |
| par.20-12 <i>Reference/Feedback Unit</i> | par.20-12 <i>Reference/Feedback Unit</i> | par.3-15 <i>Reference 1 Source</i> |
| par.20-13 <i>Minimum Reference/Feedb.</i> | par.20-13 <i>Minimum Reference/Feedb.</i> | par.3-16 <i>Reference 2 Source</i> |
| par.20-14 <i>Maximum Reference/Feedb.</i> | par.20-14 <i>Maximum Reference/Feedb.</i> | par.20-00 <i>Feedback 1 Source</i> |
| par.6-22 <i>Terminal 54 Low Current</i> | par.6-10 <i>Terminal 53 Low Voltage</i> | par.20-01 <i>Feedback 1 Conversion</i> |
| par.6-24 <i>Terminal 54 Low Ref./Feedb. Value</i> | par.6-11 <i>Terminal 53 High Voltage</i> | par.20-02 <i>Feedback 1 Source Unit</i> |
| par.6-25 <i>Terminal 54 High Ref./Feedb. Value</i> | par.6-12 <i>Terminal 53 Low Current</i> | par.20-03 <i>Feedback 2 Source</i> |
| par.6-26 <i>Terminal 54 Filter Time Constant</i> | par.6-13 <i>Terminal 53 High Current</i> | par.20-04 <i>Feedback 2 Conversion</i> |
| par.6-27 <i>Terminal 54 Live Zero</i> | par.6-14 <i>Terminal 53 Low Ref./Feedb. Value</i> | par.20-05 <i>Feedback 2 Source Unit</i> |
| par.6-00 <i>Live Zero Timeout Time</i> | par.6-15 <i>Terminal 53 High Ref./Feedb. Value</i> | par.20-06 <i>Feedback 3 Source</i> |
| par.6-01 <i>Live Zero Timeout Function</i> | par.6-22 <i>Terminal 54 Low Current</i> | par.20-07 <i>Feedback 3 Conversion</i> |
| par.20-21 <i>Setpoint 1</i> | par.6-24 <i>Terminal 54 Low Ref./Feedb. Value</i> | par.20-08 <i>Feedback 3 Source Unit</i> |
| par.20-81 <i>PID Normal/ Inverse Control</i> | par.6-25 <i>Terminal 54 High Ref./Feedb. Value</i> | par.20-12 <i>Reference/Feedback Unit</i> |
| par.20-82 <i>PID Start Speed [RPM]</i> | par.6-26 <i>Terminal 54 Filter Time Constant</i> | par.20-13 <i>Minimum Reference/Feedb.</i> |
| par.20-83 <i>PID Start Speed [Hz]</i> | par.6-00 <i>Live Zero Timeout Time</i> | par.20-14 <i>Maximum Reference/Feedb.</i> |
| par.20-93 <i>PID Proportional Gain</i> | par.6-01 <i>Live Zero Timeout Function</i> | par.6-10 <i>Terminal 53 Low Voltage</i> |
| par.20-94 <i>PID Integral Time</i> | par.20-81 <i>PID Normal/ Inverse Control</i> | par.6-11 <i>Terminal 53 High Voltage</i> |
| par.20-70 <i>Closed Loop Type</i> | par.20-82 <i>PID Start Speed [RPM]</i> | par.6-12 <i>Terminal 53 Low Current</i> |
| par.20-71 <i>PID Performance</i> | par.20-83 <i>PID Start Speed [Hz]</i> | par.6-13 <i>Terminal 53 High Current</i> |
| par.20-72 <i>PID Output Change</i> | par.20-93 <i>PID Proportional Gain</i> | par.6-14 <i>Terminal 53 Low Ref./Feedb. Value</i> |
| par.20-73 <i>Minimum Feedback Level</i> | par.20-94 <i>PID Integral Time</i> | par.6-15 <i>Terminal 53 High Ref./Feedb. Value</i> |
| par.20-74 <i>Maximum Feedback Level</i> | par.20-70 <i>Closed Loop Type</i> | par.6-16 <i>Terminal 53 Filter Time Constant</i> |
| par.20-79 <i>PID Autotuning</i> | par.20-71 <i>PID Performance</i> | par.6-17 <i>Terminal 53 Live Zero</i> |
| | par.20-72 <i>PID Output Change</i> | par.6-20 <i>Terminal 54 Low Voltage</i> |
| | par.20-73 <i>Minimum Feedback Level</i> | par.6-21 <i>Terminal 54 High Voltage</i> |
| | par.20-74 <i>Maximum Feedback Level</i> | par.6-22 <i>Terminal 54 Low Current</i> |
| | par.20-79 <i>PID Autotuning</i> | par.6-23 <i>Terminal 54 High Current</i> |
| | | par.6-24 <i>Terminal 54 Low Ref./Feedb. Value</i> |
| | | par.6-25 <i>Terminal 54 High Ref./Feedb. Value</i> |
| | | par.6-26 <i>Terminal 54 Filter Time Constant</i> |
| | | par.6-27 <i>Terminal 54 Live Zero</i> |
| | | par.6-00 <i>Live Zero Timeout Time</i> |
| | | par.6-01 <i>Live Zero Timeout Function</i> |
| | | par.4-56 <i>Warning Feedback Low</i> |
| | | par.4-57 <i>Warning Feedback High</i> |
| | | par.20-20 <i>Feedback Function</i> |
| | | par.20-21 <i>Setpoint 1</i> |
| | | par.20-22 <i>Setpoint 2</i> |
| | | par.20-81 <i>PID Normal/ Inverse Control</i> |
| | | par.20-82 <i>PID Start Speed [RPM]</i> |
| | | par.20-83 <i>PID Start Speed [Hz]</i> |
| | | par.20-93 <i>PID Proportional Gain</i> |
| | | par.20-94 <i>PID Integral Time</i> |
| | | par.20-70 <i>Closed Loop Type</i> |
| | | par.20-71 <i>PID Performance</i> |
| | | par.20-72 <i>PID Output Change</i> |
| | | par.20-73 <i>Minimum Feedback Level</i> |
| | | par.20-74 <i>Maximum Feedback Level</i> |
| | | par.20-79 <i>PID Autotuning</i> |

| Q3-4 Application Settings | | |
|---|--|--|
| Q3-40 Fan Functions | Q3-41 Pump Functions | Q3-42 Compressor Functions |
| par.22-60 <i>Broken Belt Function</i> | par.22-20 <i>Low Power Auto Set-up</i> | par.1-03 <i>Torque Characteristics</i> |
| par.22-61 <i>Broken Belt Torque</i> | par.22-21 <i>Low Power Detection</i> | par.1-71 <i>Start Delay</i> |
| par.22-62 <i>Broken Belt Delay</i> | par.22-22 <i>Low Speed Detection</i> | par.22-75 <i>Short Cycle Protection</i> |
| par.4-64 <i>Semi-Auto Bypass Set-up</i> | par.22-23 <i>No-Flow Function</i> | par.22-76 <i>Interval between Starts</i> |
| par.1-03 <i>Torque Characteristics</i> | par.22-24 <i>No-Flow Delay</i> | par.22-77 <i>Minimum Run Time</i> |
| par.22-22 <i>Low Speed Detection</i> | par.22-40 <i>Minimum Run Time</i> | par.5-01 <i>Terminal 27 Mode</i> |
| par.22-23 <i>No-Flow Function</i> | par.22-41 <i>Minimum Sleep Time</i> | par.5-02 <i>Terminal 29 Mode</i> |
| par.22-24 <i>No-Flow Delay</i> | par.22-42 <i>Wake-up Speed [RPM]</i> | par. 5-12 <i>Terminal 27 Digital Input</i> |
| par.22-40 <i>Minimum Run Time</i> | par.22-43 <i>Wake-up Speed [Hz]</i> | par. 5-13 <i>Terminal 29 Digital Input</i> |
| par.22-41 <i>Minimum Sleep Time</i> | par.22-44 <i>Wake-up Ref./FB Difference</i> | par.5-40 <i>Function Relay</i> |
| par.22-42 <i>Wake-up Speed [RPM]</i> | par.22-45 <i>Setpoint Boost</i> | par.1-73 <i>Flying Start</i> |
| par.22-43 <i>Wake-up Speed [Hz]</i> | par.22-46 <i>Maximum Boost Time</i> | par.1-86 <i>Trip Speed Low [RPM]</i> |
| par.22-44 <i>Wake-up Ref./FB Difference</i> | par.22-26 <i>Dry Pump Function</i> | par.1-87 <i>Trip Speed Low [Hz]</i> |
| par.22-45 <i>Setpoint Boost</i> | par.22-27 <i>Dry Pump Delay</i> | |
| par.22-46 <i>Maximum Boost Time</i> | par.22-80 <i>Flow Compensation</i> | |
| par.2-10 <i>Brake Function</i> | par.22-81 <i>Square-linear Curve Approximation</i> | |
| par. 2-16 <i>AC brake Max. Current</i> | par.22-82 <i>Work Point Calculation</i> | |
| par.2-17 <i>Over-voltage Control</i> | par.22-83 <i>Speed at No-Flow [RPM]</i> | |
| par.1-73 <i>Flying Start</i> | par.22-84 <i>Speed at No-Flow [Hz]</i> | |
| par.1-71 <i>Start Delay</i> | par.22-85 <i>Speed at Design Point [RPM]</i> | |
| par.1-80 <i>Function at Stop</i> | par.22-86 <i>Speed at Design Point [Hz]</i> | |
| par.2-00 <i>DC Hold/Preheat Current</i> | par.22-87 <i>Pressure at No-Flow Speed</i> | |
| par.4-10 <i>Motor Speed Direction</i> | par.22-88 <i>Pressure at Rated Speed</i> | |
| | par.22-89 <i>Flow at Design Point</i> | |
| | par.22-90 <i>Flow at Rated Speed</i> | |
| | par.1-03 <i>Torque Characteristics</i> | |
| | par.1-73 <i>Flying Start</i> | |

See also *VLT HVAC Drive Programming Guide* for a detailed description of the Function Setups parameter groups.

0-20 Display Line 1.1 Small

| Option: | Function: |
|---------------------------------------|---|
| | Select a variable for display in line 1, left position. |
| [0] None | No display value selected |
| [37] Display Text 1 | Enables an individual text string to be written, for display in the LCP or to be read via serial communication. |
| [38] Display Text 2 | Enables an individual text string to be written, for display in the LCP or to be read via serial communication. |
| [39] Display Text 3 | Enables an individual text string to be written, for display in the LCP or to be read via serial communication. |
| [89] Date and Time Readout | Displays the current date and time. |
| [953] Profibus Warning Word | Displays Profibus communication warnings. |
| [1005] Readout Transmit Error Counter | View the number of CAN control transmission errors since the last power-up. |
| [1006] Readout Receive Error Counter | View the number of CAN control receipt errors since the last power-up. |
| [1007] Readout Bus Off Counter | View the number of Bus Off events since the last power-up. |
| [1013] Warning Parameter | View a DeviceNet-specific warning word. One separate bit is assigned to every warning. |
| [1115] LON Warning Word | Shows the LON-specific warnings. |
| [1117] XIF Revision | Shows the version of the external interface file of the Neuron C chip on the LON option. |
| [1118] LonWorks Revision | |
| [1501] Running Hours | View the number of running hours of the motor. |
| [1502] kWh Counter | View the mains power consumption in kWh. |
| [1600] Control Word | View the Control Word sent from the frequency converter via the serial communication port in hex code. |

| | | |
|----------|----------------------------|--|
| [1601] | Reference [Unit] | Total reference (sum of digital/analog/preset/bus/freeze ref./catch up and slow-down) in selected unit. |
| [1602] * | Reference [%] | |
| [1603] | Status Word | Present status word |
| [1605] | Main Actual Value [%] | View the two-byte word sent with the Status word to the bus Master reporting the Main Actual Value. |
| [1609] | Custom Readout | View the user-defined readouts as defined in par. 0-30 <i>Custom Readout Unit</i> , par. 0-31 <i>Custom Readout Min Value</i> and par. 0-32 <i>Custom Readout Max Value</i> . |
| [1610] | Power [kW] | Actual power consumed by the motor in kW. |
| [1611] | Power [hp] | Actual power consumed by the motor in HP. |
| [1612] | Motor Voltage | Voltage supplied to the motor. |
| [1613] | Frequency | |
| [1614] | Motor Current | Phase current of the motor measured as effective value. |
| [1615] | Frequency [%] | Motor frequency, i.e. the output frequency from the frequency converter in percent. |
| [1616] | Torque [Nm] | Present motor load as a percentage of the rated motor torque. |
| [1617] | Speed [RPM] | Motor speed reference. Actual speed will depend on slip compensation being used (compensation set in par. 1-62 <i>Slip Compensation</i>). If not used, actual speed will be the value read in the display minus motor slip. |
| [1618] | Motor Thermal | Thermal load on the motor, calculated by the ETR function. See also parameter group 1-9* Motor Temperature. |
| [1622] | Torque [%] | Shows the actual torque produced, in percentage. |
| [1626] | Power Filtered [kW] | |
| [1627] | Power Filtered [hp] | |
| [1630] | DC Link Voltage | Intermediate circuit voltage in the frequency converter. |
| [1632] | Brake Energy /s | |
| [1633] | Brake Energy /2 min | |
| [1634] | Heatsink Temp. | Present heat sink temperature of the frequency converter. The cut-out limit is 95 ± 5° C; cutting back in occurs at 70 ± 5° C. |
| [1635] | Inverter Thermal | |
| [1636] | Inv. Nom. Current | Nominal current of the frequency converter |
| [1637] | Inv. Max. Current | Maximum current of the frequency converter |
| [1638] | SL Controller State | |
| [1639] | Control Card Temp. | Temperature of the control card. |
| [1650] | External Reference | Sum of the external reference as a percentage, i.e. the sum of analog/pulse/bus. |
| [1652] | Feedback [Unit] | Reference value from programmed digital input(s). |
| [1653] | Digi Pot Reference | View the contribution of the digital potentiometer to the actual reference Feedback. |
| [1654] | Feedback 1 [Unit] | View the value of Feedback 1. See also par. 20-0*. |
| [1655] | Feedback 2 [Unit] | View the value of Feedback 2. See also par. 20-0*. |
| [1656] | Feedback 3 [Unit] | View the value of Feedback 3. See also par. 20-0*. |
| [1658] | PID Output [%] | Returns the Drive Closed Loop PID controller output value in percent. |
| [1660] | Digital Input | Displays the status of the digital inputs. Signal low = 0; Signal high = 1. Regarding order, see par. 16-60 <i>Digital Input</i> . Bit 0 is at the extreme right. |
| [1661] | Terminal 53 Switch Setting | Setting of input terminal 53. Current = 0; Voltage = 1. |

| | | |
|--------|----------------------------|--|
| [1662] | Analog Input 53 | Actual value at input 53 either as a reference or protection value. |
| [1663] | Terminal 54 Switch Setting | Setting of input terminal 54. Current = 0; Voltage = 1. |
| [1664] | Analog Input 54 | Actual value at input 54 either as reference or protection value. |
| [1665] | Analog Output 42 [mA] | Actual value at output 42 in mA. Use par.6-50 <i>Terminal 42 Output</i> to select the variable to be represented by output 42. |
| [1666] | Digital Output [bin] | Binary value of all digital outputs. |
| [1667] | Pulse Input #29 [Hz] | |
| [1668] | Pulse Input #33 [Hz] | |
| [1669] | Pulse Output #27 [Hz] | Actual value of pulses applied to terminal 27 in digital output mode. |
| [1670] | Pulse Output #29 [Hz] | Actual value of pulses applied to terminal 29 in digital output mode. |
| [1671] | Relay Output [bin] | View the setting of all relays. |
| [1672] | Counter A | View the present value of Counter A. |
| [1673] | Counter B | View the present value of Counter B. |
| [1675] | Analog In X30/11 | |
| [1676] | Analog In X30/12 | |
| [1677] | Analog Out X30/8 [mA] | |
| [1680] | Fieldbus CTW 1 | Control word (CTW) received from the Bus Master. |
| [1682] | Fieldbus REF 1 | Main reference value sent with control word via the serial communications network e.g. from the BMS, PLC or other master controller. |
| [1684] | Comm. Option STW | Extended fieldbus communication option status word. |
| [1685] | FC Port CTW 1 | Control word (CTW) received from the Bus Master. |
| [1686] | FC Port REF 1 | Status word (STW) sent to the Bus Master. |
| [1690] | Alarm Word | One or more alarms in a Hex code (used for serial communications) |
| [1691] | Alarm Word 2 | One or more alarms in a Hex code (used for serial communications) |
| [1692] | Warning Word | One or more warnings in a Hex code (used for serial communications) |
| [1693] | Warning Word 2 | One or more warnings in a Hex code (used for serial communications) |
| [1694] | Ext. Status Word | One or more status conditions in a Hex code (used for serial communications) |
| [1695] | Ext. Status Word 2 | One or more status conditions in a Hex code (used for serial communications) |
| [1696] | Maintenance Word | The bits reflect the status for the programmed Preventive Maintenance Events in parameter group 23-1* |
| [1830] | Analog Input X42/1 | Shows the value of the signal applied to terminal X42/1 on the Analog I/O card. |
| [1831] | Analog Input X42/3 | Shows the value of the signal applied to terminal X42/3 on the Analog I/O card. |
| [1832] | Analog Input X42/5 | Shows the value of the signal applied to terminal X42/5 on the Analog I/O card. |
| [1833] | Analog Out X42/7 [V] | Shows the value of the signal applied to terminal X42/7 on the Analog I/O card. |
| [1834] | Analog Out X42/9 [V] | Shows the value of the signal applied to terminal X42/9 on the Analog I/O card. |
| [1835] | Analog Out X42/11 [V] | Shows the value of the signal applied to terminal X42/11 on the Analog I/O card. |
| [1850] | Sensorless Readout [unit] | |
| [2117] | Ext. 1 Reference [Unit] | The value of the reference for extended Closed Loop Controller 1 |
| [2118] | Ext. 1 Feedback [Unit] | The value of the feedback signal for extended Closed Loop Controller 1 |
| [2119] | Ext. 1 Output [%] | The value of the output from extended Closed Loop Controller 1 |

| | | |
|--------|---------------------------|---|
| [2137] | Ext. 2 Reference [Unit] | The value of the reference for extended Closed Loop Controller 2 |
| [2138] | Ext. 2 Feedback [Unit] | The value of the feedback signal for extended Closed Loop Controller 2 |
| [2139] | Ext. 2 Output [%] | The value of the output from extended Closed Loop Controller 2 |
| [2157] | Ext. 3 Reference [Unit] | The value of the reference for extended Closed Loop Controller 3 |
| [2158] | Ext. 3 Feedback [Unit] | The value of the feedback signal for extended Closed Loop Controller 3 |
| [2159] | Ext. 3 Output [%] | The value of the output from extended Closed Loop Controller 3 |
| [2230] | No-Flow Power | The calculated No Flow Power for the actual operating speed |
| [2316] | Maintenance Text | |
| [2580] | Cascade Status | Status for the operation of the Cascade Controller |
| [2581] | Pump Status | Status for the operation of each individual pump controlled by the Cascade Controller |
| [3110] | Bypass Status Word | |
| [3111] | Bypass Running Hours | |
| [9913] | Idle time | |
| [9914] | Paramdb requests in queue | |
| [9920] | HS Temp. (PC1) | |
| [9921] | HS Temp. (PC2) | |
| [9922] | HS Temp. (PC3) | |
| [9923] | HS Temp. (PC4) | |
| [9924] | HS Temp. (PC5) | |
| [9925] | HS Temp. (PC6) | |
| [9926] | HS Temp. (PC7) | |
| [9927] | HS Temp. (PC8) | |

NB!
Please consult the *VLT HVAC Drive Programming Guide, MG.11.CX.YY* for detailed information.

0-21 Display Line 1.2 Small

Select a variable for display in line 1, middle position.

Option: **Function:**

| |
|------------------------|
| [1614] * Motor Current |
|------------------------|

The options are the same as those listed in par.0-20 *Display Line 1.1 Small*.

0-22 Display Line 1.3 Small

Select a variable for display in line 1, right position.

Option: **Function:**

| |
|---------------------|
| [1610] * Power [kW] |
|---------------------|

The options are the same as those listed in par.0-20 *Display Line 1.1 Small*.

0-23 Display Line 2 Large

Select a variable for display in line 2.

Option: **Function:**

| |
|--------------------|
| [1613] * Frequency |
|--------------------|

The options are the same as those listed in par.0-20 *Display Line 1.1 Small*.

0-24 Display Line 3 Large**Option:**

[1502] * kWh Counter

Function:

Select a variable for display in line 3. The options are the same as listed for par.0-20 *Display Line 1.1 Small*.

0-37 Display Text 1**Range:**

0 N/A* [0 - 0 N/A]

Function:

In this parameter it is possible to write an individual text string for display in the LCP or to be read via serial communication. If to be displayed permanently select Display Text 1 in par.0-20 *Display Line 1.1 Small*, par. 0-21 *Display Line 1.2 Small*, par. 0-22 *Display Line 1.3 Small*, par. 0-23 *Display Line 2 Large* or par. 0-24 *Display Line 3 Large*. Use the ▲ or ▼ buttons on the LCP to change a character. Use the ◀ and ▶ buttons to move the cursor. When a character is highlighted by the cursor, it can be changed. Use the ▲ or ▼ buttons on the LCP to change a character. A character can be inserted by placing the cursor between two characters and pressing ▲ or ▼.

0-38 Display Text 2**Range:**

0 N/A* [0 - 0 N/A]

Function:

In this parameter it is possible to write an individual text string for display in the LCP or to be read via serial communication. If to be displayed permanently select Display Text 2 in par.0-20 *Display Line 1.1 Small*, par. 0-21 *Display Line 1.2 Small*, par. 0-22 *Display Line 1.3 Small*, par. 0-23 *Display Line 2 Large* or par. 0-24 *Display Line 3 Large*. Use the ▲ or ▼ buttons on the LCP to change a character. Use the ◀ and ▶ buttons to move the cursor. When a character is highlighted by the cursor, this character can be changed. A character can be inserted by placing the cursor between two characters and pressing ▲ or ▼.

0-39 Display Text 3**Range:**

0 N/A* [0 - 0 N/A]

Function:

In this parameter it is possible to write an individual text string for display in the LCP or to be read via serial communication. If to be displayed permanently select Display Text 3 in par.0-20 *Display Line 1.1 Small*, par. 0-21 *Display Line 1.2 Small*, par. 0-22 *Display Line 1.3 Small*, par. 0-23 *Display Line 2 Large* or par. 0-24 *Display Line 3 Large*. Use the ▲ or ▼ buttons on the LCP to change a character. Use the ◀ and ▶ buttons to move the cursor. When a character is highlighted by the cursor, this character can be changed. A character can be inserted by placing the cursor between two characters and pressing ▲ or ▼.

0-70 Date and Time**Range:**

0 N/A* [0 - 0 N/A]

Function:

Sets the date and time of the internal clock. The format to be used is set in par.0-71 *Date Format* and par.0-72 *Time Format*.

0-71 Date Format**Option:**

[0] * YYYY-MM-DD

[1] * DD-MM-YYYY

[2] MM/DD/YYYY

Function:

Sets the date format to be used in the LCP.

0-72 Time Format

| Option: | Function: |
|----------------|---|
| | Sets the time format to be used in the LCP. |
| [0] * 24 h | |
| [1] 12 h | |

0-74 DST/Summertime

| Option: | Function: |
|------------------|--|
| | Choose how Daylight Saving Time/Summertime should be handled. For manual DST/Summertime enter the start date and end date in par.0-76 <i>DST/Summertime Start</i> and par.0-77 <i>DST/Summertime End</i> . |
| [0] * Off | |
| [2] Manual | |

0-76 DST/Summertime Start


| Range: | Function: |
|-----------------------|---|
| 0 N/A* [0 - 0 N/A] | Sets the date and time when summertime/DST starts. The date is programmed in the format selected in par.0-71 <i>Date Format</i> . |


0-77 DST/Summertime End

| Range: | Function: |
|-----------------------|---|
| 0 N/A* [0 - 0 N/A] | Sets the date and time when summertime/DST ends. The date is programmed in the format selected in par.0-71 <i>Date Format</i> . |

1-00 Configuration Mode

| Option: | Function: |
|-----------------------|---|
| [0] * Open Loop | Motor speed is determined by applying a speed reference or by setting desired speed when in Hand Mode. Open Loop is also used if the frequency converter is part of a closed loop control system based on an external PID controller providing a speed reference signal as output. |
| [3] Closed Loop | Motor Speed will be determined by a reference from the built-in PID controller varying the motor speed as part of a closed loop control process (e.g. constant pressure or flow). The PID controller must be configured in par. 20-** or via the Function Setups accessed by pressing the [Quick Menus] button. |

 **NB!**
This parameter cannot be changed when motor is running.

 **NB!**
When set for Closed Loop, the commands Reversing and Start Reversing will not reverse the direction of the motor.

1-03 Torque Characteristics**Option:****Function:**

| | | |
|-------|-----------------------|--|
| [0] | Compressor torque | <i>Compressor</i> [0]: For speed control of screw and scroll compressors. Provides a voltage which is optimized for a constant torque load characteristic of the motor in the entire range down to 10 Hz. |
| [1] | Variable torque | <i>Variable Torque</i> [1]: For speed control of centrifugal pumps and fans. Also to be used when controlling more than one motor from the same frequency converter (e.g. multiple condenser fans or cooling tower fans). Provides a voltage which is optimized for a squared torque load characteristic of the motor. |
| [2] | Auto Energy Optim. CT | <i>Auto Energy Optimization Compressor</i> [2]: For optimum energy efficient speed control of screw and scroll compressors. Provides a voltage which is optimized for a constant torque load characteristic of the motor in the entire range down to 15Hz but in addition the AEO feature will adapt the voltage exactly to the current load situation, thereby reducing energy consumption and audible noise from the motor. To obtain optimal performance, the motor power factor $\cos \phi$ must be set correctly. This value is set in par. 14-43 <i>Motor Cosphi</i> . The parameter has a default value which is automatically adjusted when the motor data is programmed. These settings will typically ensure optimum motor voltage but if the motor power factor $\cos \phi$ requires tuning, an AMA function can be carried out using par.1-29 <i>Automatic Motor Adaptation (AMA)</i> . It is very rarely necessary to adjust the motor power factor parameter manually. |
| [3] * | Auto Energy Optim. VT | <i>Auto Energy Optimization VT</i> [3]: For optimum energy efficient speed control of centrifugal pumps and fans. Provides a voltage which is optimized for a squared torque load characteristic of the motor but in addition the AEO feature will adapt the voltage exactly to the current load situation, thereby reducing energy consumption and audible noise from the motor. To obtain optimal performance, the motor power factor $\cos \phi$ must be set correctly. This value is set in par. 14-43 <i>Motor Cosphi</i> . The parameter has a default value and is automatically adjusted when the motor data is programmed. These settings will typically ensure optimum motor voltage but if the motor power factor $\cos \phi$ requires tuning, an AMA function can be carried out using par.1-29 <i>Automatic Motor Adaptation (AMA)</i> . It is very rarely necessary to adjust the motor power factor parameter manually. |

1-29 Automatic Motor Adaptation (AMA)**Option:****Function:**

| | | |
|-------|---------------------|---|
| | | The AMA function optimizes dynamic motor performance by automatically optimizing the advanced motor parameters par. 1-30 <i>Stator Resistance (Rs)</i> to par. 1-35 <i>Main Reactance (Xh)</i> while the motor is stationary. |
| [0] * | Off | No function |
| [1] | Enable complete AMA | performs AMA of the stator resistance R_s , the rotor resistance R_r , the stator leakage reactance X_{1l} , the rotor leakage reactance X_{2l} and the main reactance X_h . |
| [2] | Enable reduced AMA | performs a reduced AMA of the stator resistance R_s in the system only. Select this option if an LC filter is used between the frequency converter and the motor. |

Activate the AMA function by pressing [Hand on] after selecting [1] or [2]. See also the section *Automatic Motor Adaptation*. After a normal sequence, the display will read: "Press [OK] to finish AMA". After pressing the [OK] key the frequency converter is ready for operation.

Note:


- For the best adaptation of the frequency converter, run AMA on a cold motor
- AMA cannot be performed while the motor is running

**NB!**


It is important to set motor par. 1-2* Motor Data correctly, since these form part of the AMA algorithm. An AMA must be performed to achieve optimum dynamic motor performance. It may take up to 10 min., depending on motor power rating.



NB!
Avoid generating external torque during AMA



NB!
If one of the settings in par. 1-2* Motor Data is changed, par. 1-30 *Stator Resistance (Rs)* to par. 1-39 *Motor Poles*, the advanced motor parameters, will return to default setting.
This parameter cannot be adjusted while the motor is running



NB!
Full AMA should be run without filter only while reduced AMA should be run with filter.

See section: *Application Examples > Automatic Motor Adaptation* in the Design Guide.

1-71 Start Delay

| | |
|------------------------|---|
| Range: | Function: |
| 0.0 s* [0.0 - 120.0 s] | The function selected in par.1-80 <i>Function at Stop</i> is active in the delay period. Enter the time delay required before commencing acceleration. |

1-73 Flying Start


| | |
|----------------|---|
| Option: | Function: |
| | This function makes it possible to catch a motor which is spinning freely due to a mains drop-out. When par.1-73 <i>Flying Start</i> is enabled, par.1-71 <i>Start Delay</i> has no function. Search direction for flying start is linked to the setting in par.4-10 <i>Motor Speed Direction</i> . <i>Clockwise</i> [0]: Flying start search in clockwise direction. If not successful, a DC brake is carried out. <i>Both Directions</i> [2]: The flying start will first make a search in the direction determined by the last reference (direction). If not finding the speed it will make a search in the other direction. If not successful, a DC brake will be activated in the time set in par. 2-02 <i>DC Braking Time</i> . Start will then take place from 0 Hz. |
| [0] * Disabled | Select <i>Disable</i> [0] if this function is not required |
| [1] Enabled | Select <i>Enable</i> [1] to enable the frequency converter to "catch" and control a spinning motor. |

1-80 Function at Stop

| | |
|---------------------------|---|
| Option: | Function: |
| | Select the frequency converter function after a stop command or after the speed is ramped down to the settings in par. 1-81 <i>Min Speed for Function at Stop [RPM]</i> . |
| [0] * Coast | Leaves motor in free mode. |
| [1] DC Hold/Motor Preheat | Energizes motor with a DC holding current (see par.2-00 <i>DC Hold/Preheat Current</i>). |

1-86 Trip Speed Low [RPM]

| | |
|----------------------------|--|
| Range: | Function: |
| 0 RPM* [0 - par. 4-13 RPM] | If the Trip Speed is set to 0, the function is not active. If the speed at any time after the start (or during a stop) falls below the value in the parameter, the drive will trip with an alarm [A49] Speed Limit. Function at stop. |



NB!
This parameter is only available if par. 0-02 *Motor Speed Unit* is set to [RPM].

1-87 Trip Speed Low [Hz]**Range:**

0.0 Hz* [0.0 - par. 4-14 Hz]

Function:

If the Trip Speed is set to 0, the function is not active.

If the speed at any time after the start (or during a stop) falls below the value in the parameter, the drive will trip with an alarm [A49] Speed Limit. Function at stop.

**NB!**

This parameter is only available if par. 0-02 *Motor Speed Unit* is set to [RPM].

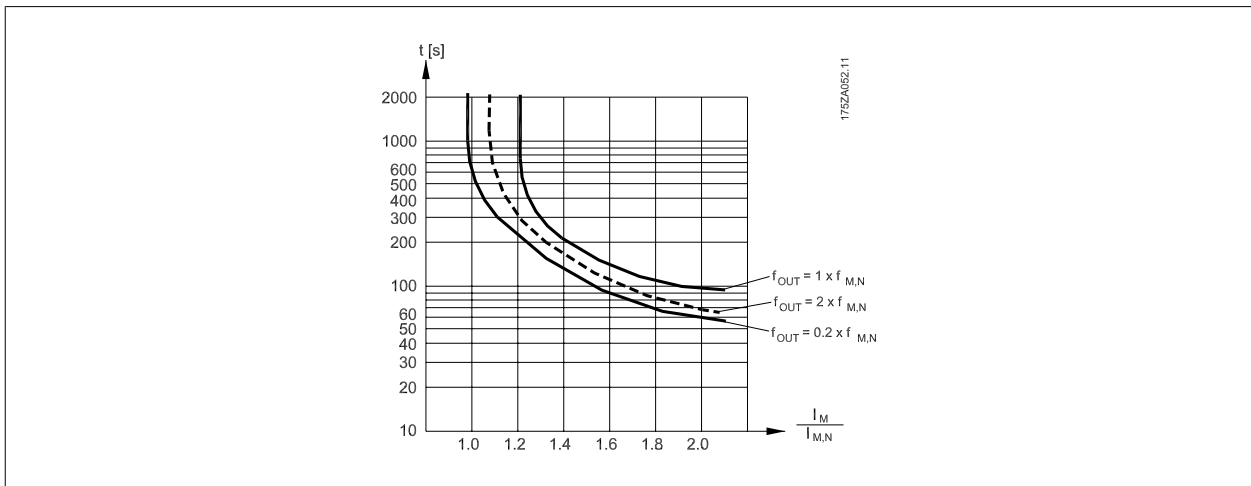
1-90 Motor Thermal Protection**Option:****Function:**

The frequency converter determines the motor temperature for motor protection in two different ways:

- Via a thermistor sensor connected to one of the analog or digital inputs (par.1-93 *Thermistor Source*).
- Via calculation (ETR = Electronic Thermal Relay) of the thermal load, based on the actual load and time. The calculated thermal load is compared with the rated motor current $I_{M,N}$ and the rated motor frequency $f_{M,N}$. The calculations estimate the need for a lower load at lower speed due to less cooling from the fan incorporated in the motor.

| | | |
|-------|--------------------|---|
| [0] | No protection | If the motor is continuously overloaded and no warning or trip of frequency converter is wanted. |
| [1] | Thermistor warning | Activates a warning when the connected thermistor in the motor reacts in the event of motor over-temperature. |
| [2] | Thermistor trip | Stops (trips) the frequency converter when the connected thermistor in the motor reacts in the event of motor over-temperature. |
| [3] | ETR warning 1 | |
| [4] * | ETR trip 1 | |
| [5] | ETR warning 2 | |
| [6] | ETR trip 2 | |
| [7] | ETR warning 3 | |
| [8] | ETR trip 3 | |
| [9] | ETR warning 4 | |
| [10] | ETR trip 4 | |

ETR (Electronic Thermal Relay) functions 1-4 will calculate the load when set-up where they were selected is active. For example ETR-3 starts calculating when set-up 3 is selected. For the North American market: The ETR functions provide class 20 motor overload protection in accordance with NEC.



NB!
Danfoss recommends using 24 VDC as thermistor supply voltage.

1-93 Thermistor Source

Option: **Function:**

Select the input to which the thermistor (PTC sensor) should be connected. An analog input option [1] or [2] cannot be selected if the analog input is already in use as a reference source (selected in par.3-15 *Reference 1 Source*, par.3-16 *Reference 2 Source* or par. 3-17 *Reference 3 Source*).
When using MCB112, choice [0] *None* must always be selected.

- [0] * None
- [1] Analog input 53
- [2] Analog input 54
- [3] Digital input 18
- [4] Digital input 19
- [5] Digital input 32
- [6] Digital input 33

NB!
This parameter cannot be adjusted while the motor is running.

NB!
Digital inputs should be set to "No operation" - see par. 5-1*.

2-00 DC Hold/Preheat Current

Range: **Function:**

50 %* [0 - 160. %]
Enter a value for holding current as a percentage of the rated motor current $I_{M,N}$ set in par. 1-24 *Motor Current*. 100% DC holding current corresponds to $I_{M,N}$.
This parameter holds the motor (holding torque) or pre-heats the motor.
This parameter is active if [1] DC hold/Preheat is selected in par.1-80 *Function at Stop*.

**NB!**

The maximum value depends on the rated motor current.

NB!

Avoid 100 % current for too long. It may damage the motor.

2-10 Brake Function

Option:**Function:**

| | | |
|-------|----------------|---|
| [0] * | Off | No brake resistor installed. |
| [1] | Resistor brake | Brake resistor incorporated in the system, for dissipation of surplus brake energy as heat. Connecting a brake resistor allows a higher DC link voltage during braking (generating operation). The Resistor brake function is only active in frequency converters with an integral dynamic brake. |
| [2] | AC brake | |

6

6.1.4 2-16 AC brake Max. Current

2-16 AC brake Max. Current

Range:**Function:**

| | | |
|----------|------------------|---|
| 100.0 %* | [0.0 - 1000.0 %] | Enter the maximum permissible current when using AC brake to avoid overheating of motor windings. The AC brake function is available in Flux mode only (FC 302 only). |
|----------|------------------|---|

2-17 Over-voltage Control

Option:**Function:**

| | | |
|-------|----------|---|
| | | Over-voltage control (OVC) reduces the risk of the frequency converter tripping due to an over voltage on the DC link caused by generative power from the load. |
| [0] | Disabled | No OVC required. |
| [2] * | Enabled | Activates OVC. |

**NB!**

The ramp time is automatically adjusted to avoid tripping of the frequency converter.

3-02 Minimum Reference

Range:

0.000 Ref- [-999999.999 - par. 3-03 ReferenceFeed-ceFeedbackUnit] backUnit*

Function:

Enter the Minimum Reference. The Minimum Reference is the lowest value obtainable by summing all references. The Minimum Reference value and unit matches the configuration choice made in par.1-00 *Configuration Mode* and par. 20-12 *Reference/Feedback Unit*, respectively.



NB!

This parameter is used in open loop only.

3-03 Maximum Reference

Range:

50.000 Ref- [par. 3-02 - 999999.999 ReferenceFeed-ceFeedbackUnit] backUnit*

Function:

Enter the maximum acceptable value for the remote reference. The Maximum Reference value and unit matches the configuration choice made in par.1-00 *Configuration Mode* and par. 20-12 *Reference/Feedback Unit*, respectively.



NB!

If operating with par. 1-00, Configuration Mode set for Closed Loop [3], par. 20-14, Maximum Reference/Feedb. must be used.

3-10 Preset Reference

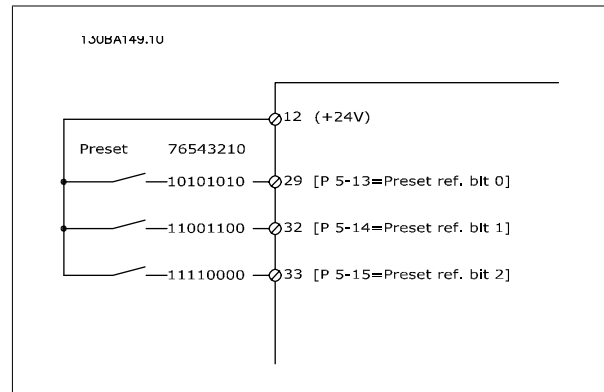
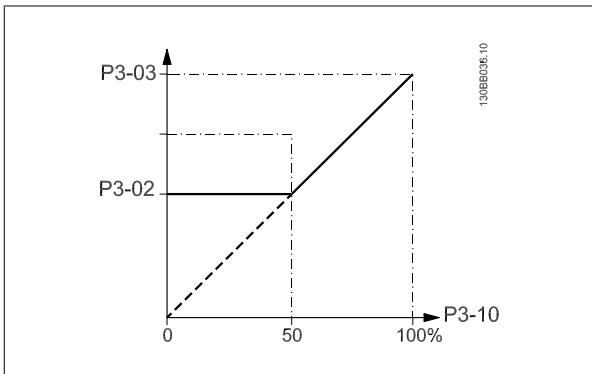
Array [8]

Range:

0.00 %* [-100.00 - 100.00 %]

Function:

Enter up to eight different preset references (0-7) in this parameter, using array programming. The preset reference is stated as a percentage of the value Ref_{MAX} (par.3-03 *Maximum Reference*, for closed loop see par.20-14 *Maximum Reference/Feedb.*). When using preset references, select Preset ref. bit 0 / 1 / 2 [16], [17] or [18] for the corresponding digital inputs in parameter group 5-1* Digital Inputs.



3-15 Reference 1 Source

Option:

Function:

Select the reference input to be used for the first reference signal. par.3-15 *Reference 1 Source*, par.3-16 *Reference 2 Source* and par. 3-17 *Reference 3 Source* define up to three different reference signals. The sum of these reference signals defines the actual reference.

This parameter cannot be adjusted while the motor is running.

[0] No function

[1] * Analog input 53

[2] Analog input 54

[7] Pulse input 29

[8] Pulse input 33

[20] Digital pot.meter

[21] Analog input X30/11

[22] Analog input X30/12

[23] Analog Input X42/1

[24] Analog Input X42/3

[25] Analog Input X42/5

[30] Ext. Closed Loop 1

[31] Ext. Closed Loop 2

[32] Ext. Closed Loop 3

3-16 Reference 2 Source**Option:****Function:**

Select the reference input to be used for the second reference signal. par.3-15 *Reference 1 Source*, par.3-16 *Reference 2 Source* and par. 3-17 *Reference 3 Source* define up to three different reference signals. The sum of these reference signals defines the actual reference.

This parameter cannot be adjusted while the motor is running.

[0] No function

[1] Analog input 53

[2] Analog input 54

[7] Pulse input 29

[8] Pulse input 33

[20] * Digital pot.meter

[21] Analog input X30/11

[22] Analog input X30/12

[23] Analog Input X42/1

[24] Analog Input X42/3

[25] Analog Input X42/5

[30] Ext. Closed Loop 1

[31] Ext. Closed Loop 2

[32] Ext. Closed Loop 3

4-10 Motor Speed Direction**Option:****Function:**

Selects the motor speed direction required.
Use this parameter to prevent unwanted reversing.

[0] Clockwise

Only operation in clockwise direction will be allowed.

[2] * Both directions

Operation in both clockwise and anti-clockwise direction will be allowed.

**NB!**

The setting in par.4-10 *Motor Speed Direction* has impact on the Flying Start in par.1-73 *Flying Start*.

4-53 Warning Speed High

Range:

par. 4-13 [par. 4-52 - par. 4-13 RPM] RPM*

Function:

Enter the n_{HIGH} value. When the motor speed exceeds this limit (n_{HIGH}), the display reads SPEED HIGH. The signal outputs can be programmed to produce a status signal on terminal 27 or 29 and on relay output 01 or 02. Programme the upper signal limit of the motor speed, n_{HIGH}, within the normal working range of the frequency converter. Refer to the drawing in this section.



NB!

Any changes in par.4-13 *Motor Speed High Limit [RPM]* will reset the value in par.4-53 *Warning Speed High* to the same value as set in par.4-13 *Motor Speed High Limit [RPM]*.

If a different value is needed in par.4-53 *Warning Speed High*, it must be set after programming of par.4-13 *Motor Speed High Limit [RPM]*.

4-56 Warning Feedback Low

Range:

-999999.99 [-999999.999 - par. 4-57 Proc-9 Proc-essCtrlUnit] essCtrlUnit*

Function:

Enter the lower feedback limit. When the feedback falls below this limit, the display reads Feedb Low. The signal outputs can be programmed to produce a status signal on terminal 27 or 29 and on relay output 01 or 02.

4-57 Warning Feedback High

Range:

999999.999 [par. 4-56 - 999999.999 ProcessCtr-ProcessCtr- lUnit] lUnit*

Function:

Enter the upper feedback limit. When the feedback exceeds this limit, the display reads Feedb High. The signal outputs can be programmed to produce a status signal on terminal 27 or 29 and on relay output 01 or 02.

4-64 Semi-Auto Bypass Set-up

Option:

[0] * Off
[1] Enabled

Function:

No function
Starts the Semi-Automatic Bypass set-up and continue with the procedure described above.

5-01 Terminal 27 Mode

| Option: | Function: |
|-------------|--|
| [0] * Input | Defines terminal 27 as a digital input. |
| [1] Output | Defines terminal 27 as a digital output. |

Please note that this parameter cannot be adjusted while the motor is running.

5-02 Terminal 29 Mode

| Option: | Function: |
|-------------|--|
| [0] * Input | Defines terminal 29 as a digital input. |
| [1] Output | Defines terminal 29 as a digital output. |

This parameter cannot be adjusted while the motor is running.

6.1.5 5-1* Digital Inputs

Parameters for configuring the input functions for the input terminals.

The digital inputs are used for selecting various functions in the frequency converter. All digital inputs can be set to the following functions:

| Digital input function | Select | Terminal |
|-------------------------|--------|--------------------------|
| No operation | [0] | All *terminal 19, 32, 33 |
| Reset | [1] | All |
| Coast inverse | [2] | 27 |
| Coast and reset inverse | [3] | All |
| DC-brake inverse | [5] | All |
| Stop inverse | [6] | All |
| External interlock | [7] | All |
| Start | [8] | All *terminal 18 |
| Latched start | [9] | All |
| Reversing | [10] | All |
| Start reversing | [11] | All |
| Jog | [14] | All *terminal 29 |
| Preset reference on | [15] | All |
| Preset ref bit 0 | [16] | All |
| Preset ref bit 1 | [17] | All |
| Preset ref bit 2 | [18] | All |
| Freeze reference | [19] | All |
| Freeze output | [20] | All |
| Speed up | [21] | All |
| Speed down | [22] | All |
| Set-up select bit 0 | [23] | All |
| Set-up select bit 1 | [24] | All |
| Pulse input | [32] | terminal 29, 33 |
| Ramp bit 0 | [34] | All |
| Mains failure inverse | [36] | All |
| Fire mode | [37] | All |
| Run Permissive | [52] | All |
| Hand start | [53] | All |
| Auto start | [54] | All |
| DigiPot Increase | [55] | All |
| DigiPot Decrease | [56] | All |
| DigiPot Clear | [57] | All |
| Counter A (up) | [60] | 29, 33 |
| Counter A (down) | [61] | 29, 33 |
| Reset Counter A | [62] | All |
| Counter B (up) | [63] | 29, 33 |
| Counter B (down) | [64] | 29, 33 |
| Reset Counter B | [65] | All |
| Sleep Mode | [66] | All |
| Reset Maintenance Word | [78] | All |
| Lead Pump Start | [120] | All |
| Lead Pump Alternation | [121] | All |
| Pump 1 Interlock | [130] | All |
| Pump 2 Interlock | [131] | All |
| Pump 3 Interlock | [132] | All |

6.1.6 Digital Inputs, 5-1* continued

All = Terminals 18, 19, 27, 29, 32, 33, X30/2, X30/3, X30/4. X30/ are the terminals on MCB 101.

Functions dedicated to only one digital input are stated in the associated parameter.

All digital inputs can be programmed to these functions:


| | | |
|--|-------------------------|--|
| [0] | No operation | No reaction to signals transmitted to terminal. |
| [1] | Reset | Resets frequency converter after a TRIP/ALARM. Not all alarms can be reset. |
| [2] | Coast inverse | Leaves motor in free mode. Logic '0' => coasting stop. (Default Digital input 27): Coasting stop, inverted input (NC). |
| [3] | Coast and reset inverse | Reset and coasting stop Inverted input (NC). Leaves motor in free mode and resets the frequency converter. Logic '0' => coasting stop and reset. |
| [5] | DC-brake inverse | Inverted input for DC braking (NC). Stops motor by energizing it with a DC current for a certain time period. See par. 2-01 <i>DC Brake Current</i> to par. 2-03 <i>DC Brake Cut In Speed [RPM]</i> . The function is only active when the value in par. 2-02 <i>DC Braking Time</i> is different from 0. Logic '0' => DC braking. |
| [6] | Stop inverse | Stop Inverted function. Generates a stop function when the selected terminal goes from logical level '1' to '0'. The stop is performed according to the selected ramp time (par.3-42 <i>Ramp 1 Ramp Down Time</i> , par. 3-52 <i>Ramp 2 Ramp Down Time</i> , par. 3-62, par. 3-72). |
| <div style="display: flex; align-items: center;"> <div> <p>NB!</p> <p>When the frequency converter is at the torque limit and has received a stop command, it may not stop by itself. To ensure that the frequency converter stops, configure a digital output to <i>Torque limit & stop</i> [27] and connect this digital output to a digital input that is configured as coast.</p> </div> </div> | | |
| [7] | External Interlock | Same function as Coasting stop, inverse, but External Interlock generates the alarm message 'external fault' on the display when the terminal which is programmed for Coast Inverse is logic '0'. The alarm message will also be active via digital outputs and relay outputs, if programmed for External Interlock. The alarm can be reset using a digital input or the [RESET] key if the cause for the External Interlock has been removed. A delay can be programmed in par. 22-00 <i>External Interlock Delay</i> , External Interlock Time. After applying a signal to the input, the reaction described above will be delayed with the time set in par. 22-00 <i>External Interlock Delay</i> . |
| [8] | Start | Select start for a start/stop command. Logic '1' = start, logic '0' = stop. (Default Digital input 18) |
| [9] | Latched start | Motor starts, if a pulse is applied for min. 2 ms. Motor stops when Stop inverse is activated |
| [10] | Reversing | Changes direction of motor shaft rotation. Select Logic '1' to reverse. The reversing signal only changes the direction of rotation. It does not activate the start function. Select both directions in par.4-10 <i>Motor Speed Direction</i> . (Default Digital input 19). |
| [11] | Start reversing | Used for start/stop and for reversing on the same wire. Signals on start are not allowed at the same time. |
| [14] | Jog | Used for activating jog speed. See par.3-11 <i>Jog Speed [Hz]</i> . (Default Digital input 29) |
| [15] | Preset reference on | Used for shifting between external reference and preset reference. It is assumed that <i>External/preset</i> [1] has been selected in par. 3-04 <i>Reference Function</i> . Logic '0' = external reference active; logic '1' = one of the eight preset references is active. |
| [16] | Preset ref bit 0 | Enables a choice between one of the eight preset references according to the table below. |
| [17] | Preset ref bit 1 | Enables a choice between one of the eight preset references according to the table below. |
| [18] | Preset ref bit 2 | Enables a choice between one of the eight preset references according to the table below. |

| | | | |
|-----------------|---|---|---|
| Preset ref. bit | 2 | 1 | 0 |
| Preset ref. 0 | 0 | 0 | 0 |
| Preset ref. 1 | 0 | 0 | 1 |
| Preset ref. 2 | 0 | 1 | 0 |
| Preset ref. 3 | 0 | 1 | 1 |
| Preset ref. 4 | 1 | 0 | 0 |
| Preset ref. 5 | 1 | 0 | 1 |
| Preset ref. 6 | 1 | 1 | 0 |
| Preset ref. 7 | 1 | 1 | 1 |

6

[19] Freeze ref
Freezes actual reference. The frozen reference is now the point of enable/condition for Speed up and Speed down to be used. If Speed up/down is used, the speed change always follows ramp 2 (par. 3-51 *Ramp 2 Ramp Up Time* and par. 3-52 *Ramp 2 Ramp Down Time*) in the range 0 - par. 3-03 *Maximum Reference*. (For closed loop see par.20-14 *Maximum Reference/Feedb.*).

[20] Freeze output
Freezes actual motor frequency (Hz). The frozen motor frequency is now the point of enable/condition for Speed up and Speed down to be used. If Speed up/down is used, the speed change always follows ramp 2 (par. 3-51 *Ramp 2 Ramp Up Time* and par. 3-52 *Ramp 2 Ramp Down Time*) in the range 0 - par.1-23 *Motor Frequency*.



NB!
When Freeze output is active, the frequency converter cannot be stopped via a low 'start [13]' signal. Stop the frequency converter via a terminal programmed for Coasting inverse [2] or Coast and reset, inverse [3].

[21] Speed up
For digital control of the up/down speed is desired (motor potentiometer). Activate this function by selecting either Freeze reference or Freeze output. When Speed up is activated for less than 400 msec. the resulting reference will be increased by 0.1 %. If Speed up is activated for more than 400 msec. the resulting reference will ramp according to Ramp 1 in par.3-41 *Ramp 1 Ramp Up Time*.

[22] Speed down
Same as Speed up [21].

[23] Set-up select bit 0
Selects one of the four set-ups. Set par. 0-10 to Multi Set-up.

[24] Set-up select bit 1
Same as Set-up select bit 0 [23].
(Default Digital input 32)


[32] Pulse input
Select Pulse input when using a pulse sequence as either reference or feedback. Scaling is done in par. group 5-5*.

[34] Ramp bit 0
Select which ramp to use. Logic "0" will select ramp 1 while logic "1" will select ramp 2.

[36] Mains failure inverse
Select to activate function selected in par. 14-10 *Mains Failure*. Mains failure is active in the Logic "0" situation.

[37] Fire mode
A signal applied will put the frequency converter into Fire Mode and all other commands will be disregarded. See 24-0* *Fire Mode*.

[52] Run Permissive
The input terminal, for which the Run permissive has been programmed must be logic "1" before a start command can be accepted. Run permissive has a logic 'AND' function related to the terminal which is programmed for *START* [8], *Jog* [14] or *Freeze Output* [20], which means that in order to start running the motor, both conditions must be fulfilled. If Run Permissive is programmed on multiple terminals, Run permissive needs only be logic '1' on one of the terminals for the function to be carried out. The digital output signal for Run Request (*Start* [8], *Jog* [14] or *Freeze output* [20]) programmed in par. 5-3*, or par. 5-4*, will not be affected by Run Permissive.



NB!
If no Run Permissive signal is applied but either Run, Jog or Freeze commands is activated, the status line in the display will show either Run Requested, Jog Requested or Freeze Requested.

[53] Hand start
A signal applied will put the frequency converter into Hand mode as if button *Hand On* on the LCP has been pressed and a normal stop command will be overridden. If disconnecting the signal, the motor will stop. To make any other start commands valid, another digital input must be assign to *Auto Start* and a signal applied to this. The *Hand On* and *Auto On* buttons on the LCP has no impact. The *Off* button on the LCP will override *Hand Start* and *Auto Start*. Press either the *Hand On* or *Auto On* button to make *Hand Start* and *Auto Start* active again. If no signal on neither *Hand Start* nor *Auto Start*, the motor will stop regardless of any normal Start command applied. If signal applied

to both *Hand Start* and *Auto Start*, the function will be *Auto Start*. If pressing the *Off* button on the LCP the motor will stop regardless of signals on *Hand Start* and *Auto Start*.

| | | |
|------|-----------------------------------|--|
| [54] | Auto start | A signal applied will put the frequency converter into Auto mode as if the LCP button <i>Auto On</i> has been pressed. See also <i>Hand Start</i> [53] |
| [55] | DigiPot Increase | Uses the input as an INCREASE signal to the Digital Potentiometer function described in parameter group 3-9* |
| [56] | DigiPot Decrease | Uses the input as a DECREASE signal to the Digital Potentiometer function described in parameter group 3-9* |
| [57] | DigiPot Clear | Uses the input to CLEAR the Digital Potentiometer reference described in parameter group 3-9* |
| [60] | Counter A (up) | (Terminal 29 or 33 only) Input for increment counting in the SLC counter. |
| [61] | Counter A (down) | (Terminal 29 or 33 only) Input for decrement counting in the SLC counter. |
| [62] | Reset Counter A | Input for reset of counter A. |
| [63] | Counter B (up) | (Terminal 29 and 33 only) Input for increment counting in the SLC counter. |
| [64] | Counter B (down) | (Terminal 29 and 33 only) Input for decrement counting in the SLC counter. |
| [65] | Reset Counter B | Input for reset of counter B. |
| [66] | Sleep Mode | Forces frequency converter into Sleep Mode (see par. 22-4*). Reacts on the rising edge of signal applied! |
| [78] | Reset Preventive Maintenance Word | Resets all data in par. 16-96 <i>Maintenance Word</i> to 0. |

6

The below setting options are all related to the Cascade Controller. Wiring diagrams and settings for parameter, see group 25-** for more details.

| | | |
|-------|-----------------------|---|
| [120] | Lead Pump Start | Starts/Stops the Lead Pump (controlled by the frequency converter). A start requires that also a System Start signal has been applied e.g. to one of the digital inputs set for <i>Start</i> [8]! |
| [121] | Lead Pump Alternation | Forces alternation of the lead pump in a Cascade Controller. par. 25-50 <i>Lead Pump Alternation</i> , must be set to either <i>At Command</i> [2] or <i>At Staging or At Command</i> [3]. par. 25-51 <i>Alternation Event</i> , can be set to any of the four options. |

[130 - 138] Pump1 Interlock - Pump9 Interlock For the above 9 setting options, par. 25-10 must be set to *On* [1]. The function will also depend on the setting in par. 25-05 *Fixed Lead Pump*. If set to *No* [0], then Pump1 refers to the pump controlled by relay RELAY1 etc. If set to *Yes* [1], Pump1 refers to the pump controlled by the frequency converter only (without any of the build in relays involved) and Pump2 to the pump controlled by the relay RELAY1. Variable speed pump (lead) cannot be interlocked. See below table:

| Setting in Par. 5-1* | Setting in par. 25-06 <i>Number of Pumps</i> | |
|-----------------------|--|--|
| | [0] No | [1] Yes |
| [130] Pump1 Interlock | Controlled by RELAY1 (only if not lead pump) | Frequency Converter controlled (cannot be interlocked) |
| [131] Pump2 Interlock | Controlled by RELAY2 | Controlled by RELAY1 |
| [132] Pump3 Interlock | Controlled by RELAY3 | Controlled by RELAY2 |
| [133] Pump4 Interlock | Controlled by RELAY4 | Controlled by RELAY3 |
| [134] Pump5 Interlock | Controlled by RELAY5 | Controlled by RELAY4 |
| [135] Pump6 Interlock | Controlled by RELAY6 | Controlled by RELAY5 |
| [136] Pump7 Interlock | Controlled by RELAY7 | Controlled by RELAY6 |
| [137] Pump8 Interlock | Controlled by RELAY8 | Controlled by RELAY7 |
| [138] Pump9 Interlock | Controlled by RELAY9 | Controlled by RELAY8 |

Option: **Function:**

5-12 Terminal 27 Digital Input

Option: **Function:**

Same options and functions as par. 5-1*, except for *Pulse input*.

[0] * No operation

5-13 Terminal 29 Digital Input**Option:****Function:**

Same options and functions as par. 5-1*.

[14] * Jog

5-14 Terminal 32 Digital Input**Option:****Function:**Same options and functions as par. 5-1*, except for *Pulse input*.

[0] * No operation

[1] Reset

[2] Coast inverse

[3] Coast and reset inv

[5] DC-brake inverse

[6] Stop inverse

[7] External interlock

[8] Start

[9] Latched start

[10] Reversing

[11] Start reversing

[14] Jog

[15] Preset reference on

[16] Preset ref bit 0

[17] Preset ref bit 1

[18] Preset ref bit 2

[19] Freeze reference

[20] Freeze output

[21] Speed up

[22] Speed down

[23] Set-up select bit 0

[24] Set-up select bit 1

[34] Ramp bit 0

[36] Mains failure inverse

[37] Fire Mode

[52] Run permissive

[53] Hand start

[54] Auto start

[55] DigiPot increase

[56] DigiPot decrease

[57] DigiPot clear

[62] Reset Counter A

[65] Reset Counter B

[66] Sleep Mode

[78] Reset Maint. Word

[120] Lead Pump Start

[121] Lead Pump Alternation

[130] Pump 1 Interlock

[131] Pump 2 Interlock

[132] Pump 3 Interlock

5-15 Terminal 33 Digital Input

Option:

Function:

Same options and functions as par. 5-1* Digital Inputs.

[0] * No operation

5-40 Function Relay

Array [8]

(Relay 1 [0], Relay 2 [1])

Option MCB 105: Relay 7 [6], Relay 8 [7] and Relay 9 [8].

Select options to define the function of the relays.

The selection of each mechanical relay is realised in an array parameter.

Option:

Function:

[0] * No operation

[1] Control ready

[2] Drive ready

[3] Drive rdy/rem ctrl

[4] Standby / no warning

[5] * Running Default setting for relay 2.

[6] Running / no warning

[8] Run on ref/no warn

[9] * Alarm Default setting for relay 1.

[10] Alarm or warning

[11] At torque limit

[12] Out of current range

[13] Below current, low

[14] Above current, high

[15] Out of speed range

[16] Below speed, low

[17] Above speed, high

[18] Out of feedb. range

[19] Below feedback, low

[20] Above feedback, high

[21] Thermal warning

[25] Reverse

[26] Bus OK

[27] Torque limit & stop

[28] Brake, no brake war

[29] Brake ready, no fault

[30] Brake fault (IGBT)

[35] External Interlock

[36] Control word bit 11

[37] Control word bit 12

[40] Out of ref range

[41] Below reference, low

[42] Above ref, high

[45] Bus ctrl.

[46] Bus ctrl, 1 if timeout

[47] Bus ctrl, 0 if timeout

| | |
|-------|----------------------|
| [60] | Comparator 0 |
| [61] | Comparator 1 |
| [62] | Comparator 2 |
| [63] | Comparator 3 |
| [64] | Comparator 4 |
| [65] | Comparator 5 |
| [70] | Logic rule 0 |
| [71] | Logic rule 1 |
| [72] | Logic rule 2 |
| [73] | Logic rule 3 |
| [74] | Logic rule 4 |
| [75] | Logic rule 5 |
| [80] | SL digital output A |
| [81] | SL digital output B |
| [82] | SL digital output C |
| [83] | SL digital output D |
| [84] | SL digital output E |
| [85] | SL digital output F |
| [160] | No alarm |
| [161] | Running reverse |
| [165] | Local ref active |
| [166] | Remote ref active |
| [167] | Start command act. |
| [168] | Hand mode |
| [169] | Auto mode |
| [180] | Clock Fault |
| [181] | Prev. Maintenance |
| [190] | No-Flow |
| [191] | Dry Pump |
| [192] | End Of Curve |
| [193] | Sleep Mode |
| [194] | Broken Belt |
| [195] | Bypass Valve Control |
| [196] | Fire Mode |
| [197] | Fire Mode was Act. |
| [198] | Drive Bypass |
| [211] | Cascade Pump 1 |
| [212] | Cascade Pump 2 |
| [213] | Cascade Pump 3 |

6-00 Live Zero Timeout Time

Range:

10 s* [1 - 99 s]

Function:

Enter the Live Zero Time-out time period. Live Zero Time-out Time is active for analog inputs, i.e. terminal 53 or terminal 54, used as reference or feedback sources. If the reference signal value associated with the selected current input falls below 50% of the value set in par.6-10 *Terminal 53 Low Voltage*, par.6-12 *Terminal 53 Low Current*, par.6-20 *Terminal 54 Low Voltage* or par. 6-22 *Terminal 54 Low Current* for a time period longer than the time set in par.6-00 *Live Zero Timeout Time*, the function selected in par.6-01 *Live Zero Timeout Function* will be activated.

6-01 Live Zero Timeout Function

Option:

Function:

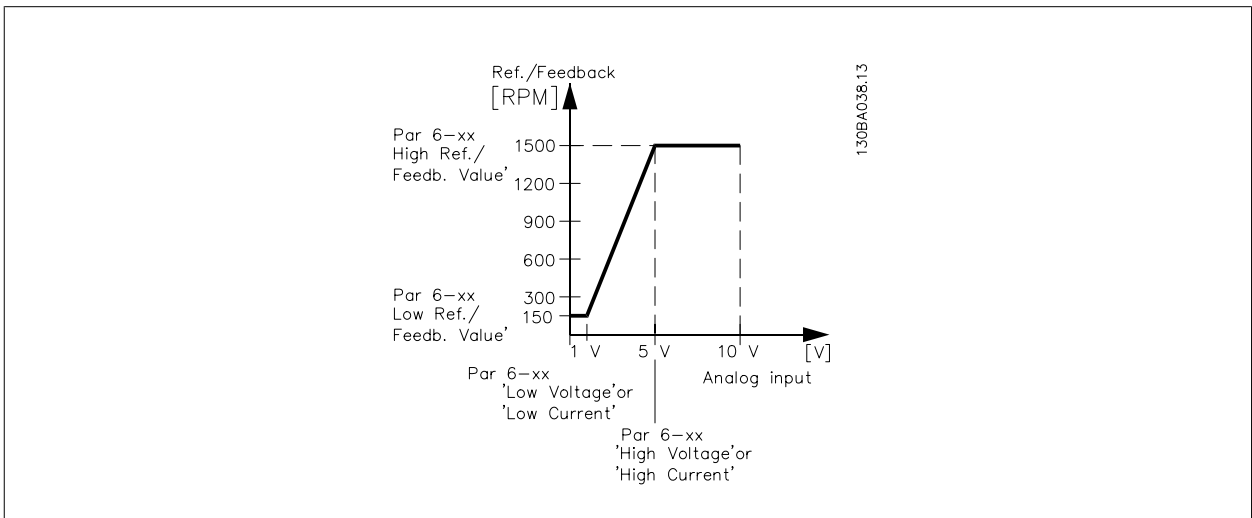
Select the time-out function. The function set in par.6-01 *Live Zero Timeout Function* will be activated if the input signal on terminal 53 or 54 is below 50% of the value in par.6-10 *Terminal 53 Low Voltage*, par.6-12 *Terminal 53 Low Current*, par.6-20 *Terminal 54 Low Voltage* or par. 6-22 *Terminal 54 Low Current* for a time period defined in par.6-00 *Live Zero Timeout Time*. If several time-outs occur simultaneously, the frequency converter prioritises the time-out functions as follows:

1. par.6-01 *Live Zero Timeout Function*
2. par. 8-04 *Control Timeout Function*

The output frequency of the frequency converter can be:

- [1] frozen at the present value
- [2] overruled to stop
- [3] overruled to jog speed
- [4] overruled to max. speed
- [5] overruled to stop with subsequent trip

| | |
|-------|---------------|
| [0] * | Off |
| [1] | Freeze output |
| [2] | Stop |
| [3] | Jogging |
| [4] | Max. speed |
| [5] | Stop and trip |



6-10 Terminal 53 Low Voltage

Range:

0.07 V* [0.00 - par. 6-11 V]

Function:

Enter the low voltage value. This analog input scaling value should correspond to the low reference/feedback value set in par.6-14 *Terminal 53 Low Ref./Feedb. Value*.

6-11 Terminal 53 High Voltage

Range:

10.00 V* [par. 6-10 - 10.00 V]

Function:

Enter the high voltage value. This analog input scaling value should correspond to the high reference/feedback value set in par.6-15 *Terminal 53 High Ref./Feedb. Value*.

6-12 Terminal 53 Low Current**Range:**

4.00 mA* [0.00 - par. 6-13 mA]

Function:

Enter the low current value. This reference signal should correspond to the low reference/feedback value, set in par.6-14 *Terminal 53 Low Ref./Feedb. Value*. The value must be set at >2 mA in order to activate the Live Zero Time-out Function in par.6-01 *Live Zero Timeout Function*.

6-13 Terminal 53 High Current**Range:**

20.00 mA* [par. 6-12 - 20.00 mA]

Function:

Enter the high current value corresponding to the high reference/feedback set in par.6-15 *Terminal 53 High Ref./Feedb. Value*.

6-22 Terminal 54 Low Current**Range:**

4.00 mA* [0.00 - par. 6-23 mA]

Function:

Enter the low current value. This reference signal should correspond to the low reference/feedback value, set in par.6-24 *Terminal 54 Low Ref./Feedb. Value*. The value must be set at >2 mA in order to activate the Live Zero Time-out Function in par.6-01 *Live Zero Timeout Function*.

6-23 Terminal 54 High Current**Range:**

20.00 mA* [par. 6-22 - 20.00 mA]

Function:

Enter the high current value corresponding to the high reference/feedback value set in par. 6-25 *Terminal 54 High Ref./Feedb. Value*.

6-14 Terminal 53 Low Ref./Feedb. Value**Range:**

0.000 N/A* [-999999.999 - 999999.999 N/A]

Function:

Enter the analog input scaling value that corresponds to the low voltage/low current set in par. 6-10 *Terminal 53 Low Voltage* and par.6-12 *Terminal 53 Low Current*.

6-15 Terminal 53 High Ref./Feedb. Value**Range:**

50.000 N/A* [-999999.999 - 999999.999 N/A]

Function:

Enter the analog input scaling value that corresponds to the high voltage/high current value set in par.6-11 *Terminal 53 High Voltage* and par.6-13 *Terminal 53 High Current*.

6-16 Terminal 53 Filter Time Constant**Range:**

0.001 s* [0.001 - 10.000 s]

Function:

Enter the time constant. This is a first-order digital low pass filter time constant for suppressing electrical noise in terminal 53. A high time constant value improves dampening but also increases the time delay through the filter.
This parameter cannot be adjusted while the motor is running.

6-17 Terminal 53 Live Zero**Option:****Function:**

This parameter makes it possible to disable the Live Zero monitoring. E.g. to be used if the analog outputs are used as part of a de-central I/O system (e.g. when not as part of any frequency converter related control functions, but feeding a Building Management system with data).

[0] Disabled

[1]* Enabled

6-20 Terminal 54 Low Voltage**Range:**

0.07 V* [0.00 - par. 6-21 V]

Function:

Enter the low voltage value. This analog input scaling value should correspond to the low reference/feedback value, set in par.6-24 *Terminal 54 Low Ref./Feedb. Value*.

6-21 Terminal 54 High Voltage**Range:**

10.00 V* [par. 6-20 - 10.00 V]

Function:

Enter the high voltage value. This analog input scaling value should correspond to the high reference/feedback value set in par.6-25 *Terminal 54 High Ref./Feedb. Value*.

6-22 Terminal 54 Low Current**Range:**

4.00 mA* [0.00 - par. 6-23 mA]

Function:

Enter the low current value. This reference signal should correspond to the low reference/feedback value, set in par.6-24 *Terminal 54 Low Ref./Feedb. Value*. The value must be set at >2 mA in order to activate the Live Zero Time-out Function in par.6-01 *Live Zero Timeout Function*.

6-23 Terminal 54 High Current**Range:**

20.00 mA* [par. 6-22 - 20.00 mA]

Function:

Enter the high current value corresponding to the high reference/feedback value set in par. 6-25 *Terminal 54 High Ref./Feedb. Value*.

6-24 Terminal 54 Low Ref./Feedb. Value**Range:**

0.000 N/A* [-999999.999 - 999999.999 N/A]

Function:

Enter the analog input scaling value that corresponds to the low voltage/low current value set in par.6-20 *Terminal 54 Low Voltage* and par.6-22 *Terminal 54 Low Current*.

6-25 Terminal 54 High Ref./Feedb. Value**Range:**

100.000 N/A* [-999999.999 - 999999.999 N/A]

Function:

Enter the analog input scaling value that corresponds to the high voltage/high current value set in par.6-21 *Terminal 54 High Voltage* and par.6-23 *Terminal 54 High Current*.

6-26 Terminal 54 Filter Time Constant**Range:**

0.001 s* [0.001 - 10.000 s]

Function:

Enter the time constant. This is a first-order digital low pass filter time constant for suppressing electrical noise in terminal 54. A high time constant value improves dampening but also increases the time delay through the filter.

This parameter cannot be adjusted while the motor is running.

6-27 Terminal 54 Live Zero**Option:****Function:**

This parameter makes it possible to disable the Live Zero monitoring. E.g. to be used if the analog outputs are used as part of a de-central I/O system (e.g. when not as part of any frequency converter related control functions, but feeding a Building Management System with data).

[0] Disabled

[1] * Enabled

6-50 Terminal 42 Output**Option:****Function:**

Select the function of Terminal 42 as an analog current output. A motor current of 20 mA corresponds to I_{max} .

[0] * No operation

[100] Output freq. 0-100 : 0 - 100 Hz, (0-20 mA)

[101] Reference Min-Max : Minimum reference - Maximum reference, (0-20 mA)

[102] Feedback +-200% : -200% to +200% of par. 20-14, (0-20 mA)

[103] Motor cur. 0-Imax : 0 - Inverter Max. Current (par. 16-37), (0-20 mA)

| | | |
|---------|----------------------|--|
| [104] | Torque 0-Tlim | : 0 - Torque limit (par. 4-16), (0-20 mA) |
| [105] | Torque 0-Tnom | : 0 - Motor rated torque, (0-20 mA) |
| [106] | Power 0-Pnom | : 0 - Motor rated power, (0-20 mA) |
| [107] * | Speed 0-HighLim | : 0 - Speed High Limit (par. 4-13 and par. 4-14), (0-20 mA) |
| [113] | Ext. Closed Loop 1 | : 0 - 100%, (0-20 mA) |
| [114] | Ext. Closed Loop 2 | : 0 - 100%, (0-20 mA) |
| [115] | Ext. Closed Loop 3 | : 0 - 100%, (0-20 mA) |
| [130] | Out frq 0-100 4-20mA | : 0 - 100 Hz |
| [131] | Reference 4-20mA | : Minimum Reference - Maximum Reference |
| [132] | Feedback 4-20mA | : -200% to +200% of par.20-14 <i>Maximum Reference/Feedb.</i> |
| [133] | Motor cur. 4-20mA | : 0 - Inverter Max. Current (par. 16-37 <i>Inv. Max. Current</i>) |
| [134] | Torq.0-lim 4-20 mA | : 0 - Torque limit (par. 4-16) |
| [135] | Torq.0-nom 4-20mA | : 0 - Motor rated torque |
| [136] | Power 4-20mA | : 0 - Motor rated power |
| [137] | Speed 4-20mA | : 0 - Speed High Limit (4-13 and 4-14) |
| [139] | Bus ctrl. | : 0 - 100%, (0-20 mA) |
| [140] | Bus ctrl. 4-20 mA | : 0 - 100% |
| [141] | Bus ctrl t.o. | : 0 - 100%, (0-20 mA) |
| [142] | Bus ctrl t.o. 4-20mA | : 0 - 100% |
| [143] | Ext. CL 1 4-20mA | : 0 - 100% |
| [144] | Ext. CL 2 4-20mA | : 0 - 100% |
| [145] | Ext. CL 3 4-20mA | : 0 - 100% |

NB!

Values for setting the Minimum Reference is found in open loop par.3-02 *Minimum Reference* and for closed loop par.20-13 *Minimum Reference/Feedb.* - values for maximum reference for open loop is found in par.3-03 *Maximum Reference* and for closed loop par.20-14 *Maximum Reference/Feedb.*

6-51 Terminal 42 Output Min Scale**Range:**

0.00 %* [0.00 - 200.00 %]

Function:

Scale for the minimum output (0 or 4 mA) of the analogue signal at terminal 42.
Set the value to be the **percentage** of the full range of the variable selected in par.6-50 *Terminal 42 Output*.

6-52 Terminal 42 Output Max Scale

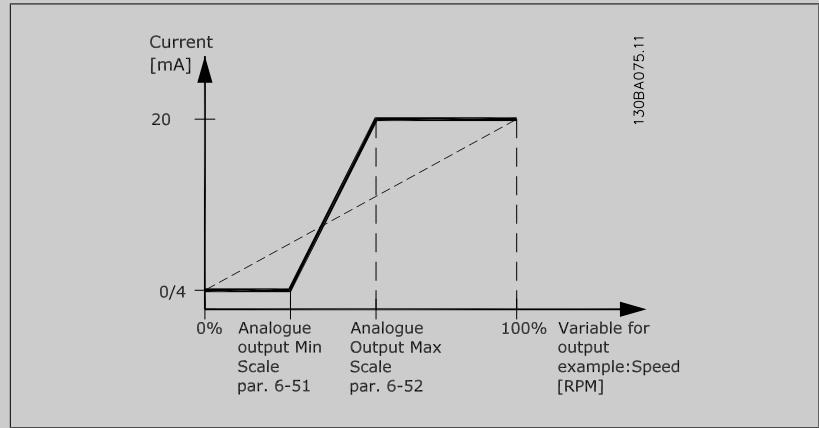
Range:

100.00 %* [0.00 - 200.00 %]

Function:

Scale for the maximum output (20 mA) of the analog signal at terminal 42.

Set the value to be the percentage of the full range of the variable selected in par.6-50 *Terminal 42 Output*.



It is possible to get a value lower than 20 mA at full scale by programming values >100% by using a formula as follows:

$$20 \text{ mA} / \text{desired maximum current} \times 100 \%$$

i.e. $10 \text{ mA} : \frac{20 \text{ mA}}{10 \text{ mA}} \times 100 \% = 200 \%$

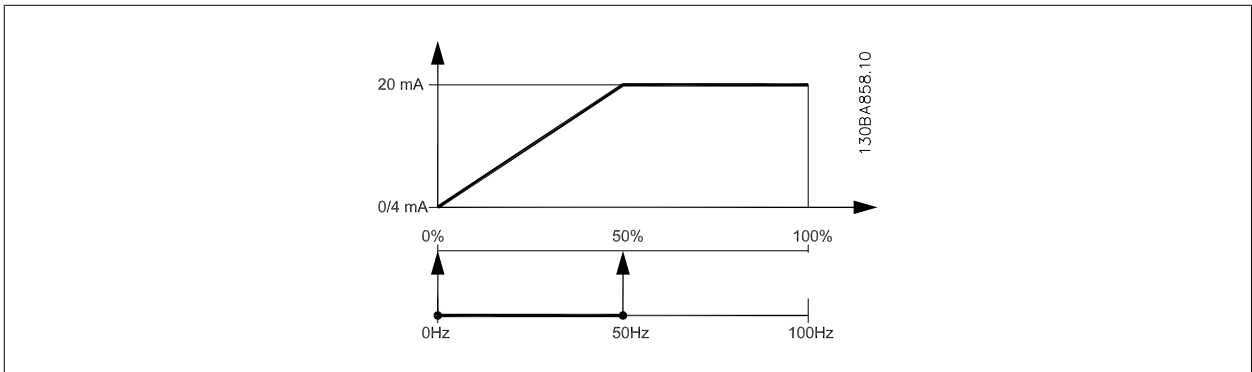
EXAMPLE 1:

Variable value= OUTPUT FREQUENCY, range = 0-100 Hz

Range needed for output = 0-50 Hz

Output signal 0 or 4 mA is needed at 0 Hz (0% of range) - set par.6-51 *Terminal 42 Output Min Scale* to 0%

Output signal 20 mA is needed at 50 Hz (50% of range) - set par.6-52 *Terminal 42 Output Max Scale* to 50%



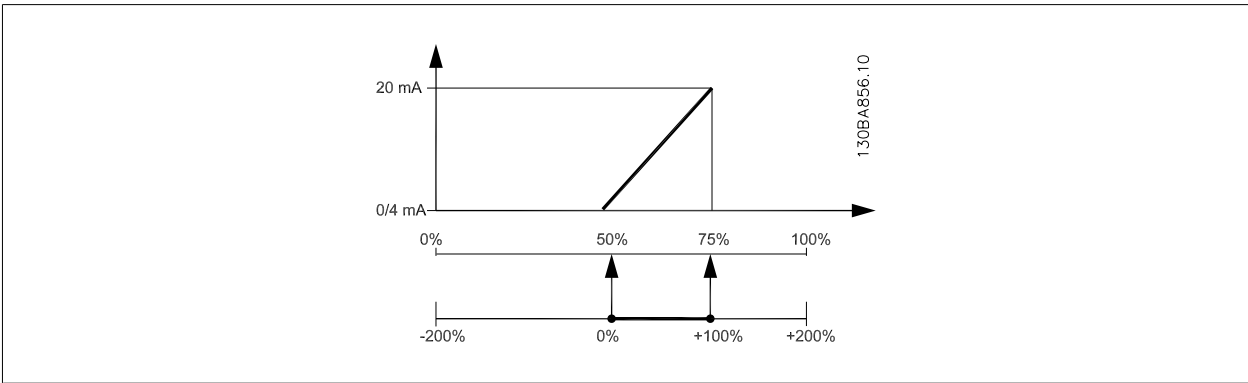
EXAMPLE 2:

Variable= FEEDBACK, range= -200% to +200%

Range needed for output= 0-100%

Output signal 0 or 4 mA is needed at 0% (50% of range) - set par.6-51 *Terminal 42 Output Min Scale* to 50%

Output signal 20 mA is needed at 100% (75% of range) - set par.6-52 *Terminal 42 Output Max Scale* to 75%



EXAMPLE 3:

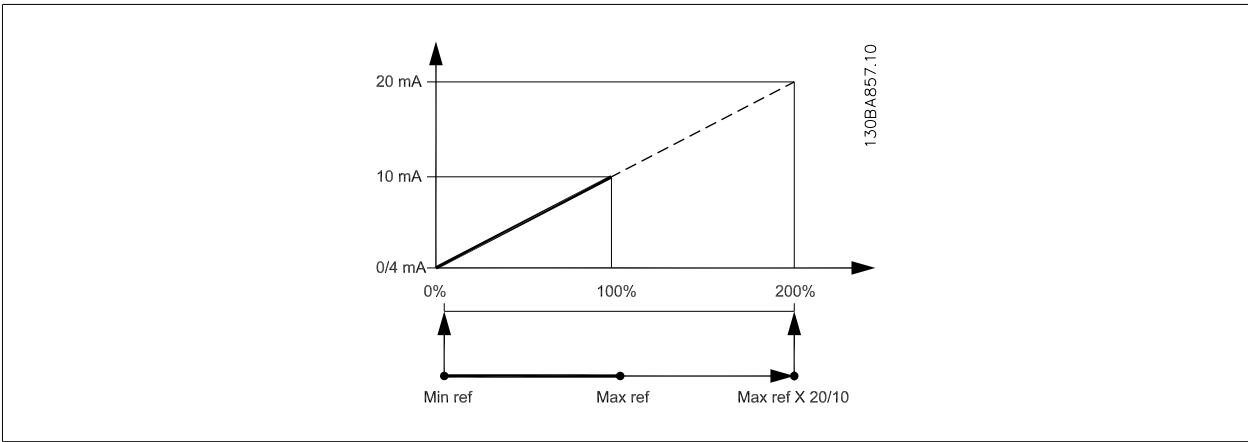
Variable value= REFERENCE, range= Min ref - Max ref

Range needed for output= Min ref (0%) - Max ref (100%), 0-10 mA

Output signal 0 or 4 mA is needed at Min ref - set par.6-51 *Terminal 42 Output Min Scale* to 0%

Output signal 10 mA is needed at Max ref (100% of range) - set par.6-52 *Terminal 42 Output Max Scale* to 200% (20 mA / 10 mA x 100%=200%).

6



14-01 Switching Frequency**Option:****Function:**

Select the inverter switching frequency. Changing the switching frequency can help to reduce acoustic noise from the motor.

**NB!**

The output frequency value of the frequency converter must never exceed 1/10 of the switching frequency. When the motor is running, adjust the switching frequency in par.14-01 *Switching Frequency* until the motor is as noiseless as possible. See also par. 14-00 *Switching Pattern* and the section *Derating*.

| | |
|-------|----------|
| [0] | 1.0 kHz |
| [1] | 1.5 kHz |
| [2] | 2.0 kHz |
| [3] | 2.5 kHz |
| [4] | 3.0 kHz |
| [5] | 3.5 kHz |
| [6] | 4.0 kHz |
| [7] * | 5.0 kHz |
| [8] | 6.0 kHz |
| [9] | 7.0 kHz |
| [10] | 8.0 kHz |
| [11] | 10.0 kHz |
| [12] | 12.0 kHz |
| [13] | 14.0 kHz |
| [14] | 16.0 kHz |

14-03 Overmodulation**Option:****Function:**

| | |
|-------|-----|
| [0] | Off |
| [1] * | On |

Selects no over-modulation of the output voltage in order to avoid torque ripple on the motor shaft.

The over-modulation function generates an extra voltage of up-to 8% of U_{max} output voltage without over-modulation, which results in an extra torque of 10-12% in the middle of the over-synchronous range (from 0% at nominal speed rising to approximately 12% at double nominal speed).

20-00 Feedback 1 Source**Option:****Function:**

Up to three different feedback signals can be used to provide the feedback signal for the frequency converter's PID Controller.

This parameter defines which input will be used as the source of the first feedback signal.

Analog input X30/11 and Analog input X30/12 refer to inputs on the optional General Purpose I/O board.

| | |
|-------|---------------------|
| [0] | No function |
| [1] | Analog input 53 |
| [2] * | Analog input 54 |
| [3] | Pulse input 29 |
| [4] | Pulse input 33 |
| [7] | Analog input X30/11 |
| [8] | Analog input X30/12 |
| [9] | Analog Input X42/1 |
| [10] | Analog Input X42/3 |

| | |
|-------|---------------------|
| [11] | Analog Input X42/5 |
| [100] | Bus feedback 1 |
| [101] | Bus feedback 2 |
| [102] | Bus feedback 3 |
| [104] | Sensorless Flow |
| [105] | Sensorless Pressure |

**NB!**

If a feedback is not used, its source must be set to *No Function* [0]. par.20-20 *Feedback Function* determines how the three possible feedbacks will be used by the PID Controller.

20-01 Feedback 1 Conversion

Option:**Function:**

This parameter allows a conversion function to be applied to Feedback 1.

| | | |
|-------|-------------------------|---|
| [0] * | Linear | <i>Linear</i> [0] has no effect on the feedback. |
| [1] | Square root | <i>Square root</i> [1] is commonly used when a pressure sensor is used to provide flow feedback ($(flow \propto \sqrt{pressure})$). |
| [2] | Pressure to temperature | <i>Pressure to temperature</i> [2] is used in compressor applications to provide temperature feedback using a pressure sensor. The temperature of the refrigerant is calculated using the following formula: $Temperature = \frac{A2}{(\ln(Pe + 1) - A1)} - A3$, where A1, A2 and A3 are refrigerant-specific constants. The refrigerant must be selected in par. 20-30 <i>Refrigerant</i> . par.20-21 <i>Setpoint 1</i> through par. 20-23 <i>Setpoint 3</i> allow the values of A1, A2 and A3 to be entered for a refrigerant that is not listed in par. 20-30 <i>Refrigerant</i> . |

20-02 Feedback 1 Source Unit

Option:**Function:**

This parameter determines the unit that is used for this Feedback Source, prior to applying the feedback conversion of par.20-01 *Feedback 1 Conversion*. This unit is not used by the PID Controller.

| | |
|-------|---------------------|
| [0] * | |
| [1] | % |
| [5] | PPM |
| [10] | 1/min |
| [11] | RPM |
| [12] | Pulse/s |
| [20] | l/s |
| [21] | l/min |
| [22] | l/h |
| [23] | m ³ /s |
| [24] | m ³ /min |
| [25] | m ³ /h |
| [30] | kg/s |
| [31] | kg/min |
| [32] | kg/h |
| [33] | t/min |
| [34] | t/h |
| [40] | m/s |

| | |
|-------|----------------------|
| [41] | m/min |
| [45] | m |
| [60] | °C |
| [70] | mbar |
| [71] | bar |
| [72] | Pa |
| [73] | kPa |
| [74] | m WG |
| [75] | mm Hg |
| [80] | kW |
| [120] | GPM |
| [121] | gal/s |
| [122] | gal/min |
| [123] | gal/h |
| [124] | CFM |
| [125] | ft ³ /s |
| [126] | ft ³ /min |
| [127] | ft ³ /h |
| [130] | lb/s |
| [131] | lb/min |
| [132] | lb/h |
| [140] | ft/s |
| [141] | ft/min |
| [145] | ft |
| [160] | °F |
| [170] | psi |
| [171] | lb/in ² |
| [172] | in WG |
| [173] | ft WG |
| [174] | in Hg |
| [180] | HP |

**NB!**

This parameter is only available when using pressure to temperature feedback conversion.

If the choice Linear [0] is selected in par.20-01 *Feedback 1 Conversion*, then the setting of any choice in par.20-02 *Feedback 1 Source Unit* does not matter as conversion will be one-to-one.

20-03 Feedback 2 Source**Option:****Function:**See par.20-00 *Feedback 1 Source* for details.

| | |
|-------|---------------------|
| [0] * | No function |
| [1] | Analog input 53 |
| [2] | Analog input 54 |
| [3] | Pulse input 29 |
| [4] | Pulse input 33 |
| [7] | Analog input X30/11 |
| [8] | Analog input X30/12 |
| [9] | Analog Input X42/1 |
| [10] | Analog Input X42/3 |
| [11] | Analog Input X42/5 |
| [100] | Bus feedback 1 |
| [101] | Bus feedback 2 |
| [102] | Bus feedback 3 |

20-04 Feedback 2 Conversion**Option:****Function:**See par.20-01 *Feedback 1 Conversion* for details.

| | |
|-------|-------------------------|
| [0] * | Linear |
| [1] | Square root |
| [2] | Pressure to temperature |

20-05 Feedback 2 Source Unit**Option:****Function:**See par.20-02 *Feedback 1 Source Unit* for details.**20-06 Feedback 3 Source****Option:****Function:**See par.20-00 *Feedback 1 Source* for details.**20-07 Feedback 3 Conversion****Option:****Function:**See par.20-01 *Feedback 1 Conversion* for details.

| | |
|-------|-------------------------|
| [0] * | Linear |
| [1] | Square root |
| [2] | Pressure to temperature |

20-08 Feedback 3 Source Unit**Option:****Function:**See par.20-02 *Feedback 1 Source Unit* for details.**20-12 Reference/Feedback Unit****Option:****Function:**See par.20-02 *Feedback 1 Source Unit* for details.

20-13 Minimum Reference/Feedb.

Range:

0.000 Proc- [-999999.999 - par. 20-14 Proc-
 essCtrlU- essCtrlUnit]
 nit*

Function:

Enter the desired minimum value for the remote reference when operating with par. 1-00, Configuration Mode set for Closed Loop [3] operation. Units are set in par. 20-12, Reference/Feedback Unit.

Minimum feedback will be -200% of either the value set in par. 20-13 or in par. 20-14, whichever numeric value is the highest.

NB!

If operating with par.1-00, Configuration Mode set for Open Loop [0], par. 3-02, Minimum Reference must be used.

20-14 Maximum Reference/Feedb.

Range:

100.000 [par. 20-13 - 999999.999 Proc-
 ProcessCtr- essCtrlUnit]
 lUnit*

Function:

Enter the maximum reference/feedback for closed loop operation. The setting determines the highest value obtainable by summing all reference sources for closed loop operation. The setting determines 100% feedback in open and closed loop (total feedback range: -200% to +200%).

NB!

If operating with par.1-00 Configuration Mode set for Open Loop [0], par.3-03 Maximum Reference must be used.



NB!

The dynamics of the PID controller will depend on the value set in this parameter. Please see also par.20-93 *PID Proportional Gain*. Par. 20-13 and par. 20-14 also determine the feedback range when using feedback for display readout with par.1-00 Configuration Mode set for Open Loop [0]. Same condition as above.

20-20 Feedback Function

Option:

Function:

This parameter determines how the three possible feedbacks will be used to control the output frequency of the frequency converter.

[0] Sum

Sum [0] sets up the PID Controller to use the sum of Feedback 1, Feedback 2 and Feedback 3 as the feedback.



NB!

Any unused feedbacks must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source*, or par. 20-06 *Feedback 3 Source*.

The sum of Setpoint 1 and any other references that are enabled (see par. group 3-1*) will be used as the PID Controller's set-point reference.

[1] Difference

Difference [1] sets up the PID controller to use the difference between Feedback 1 and Feedback 2 as the feedback. Feedback 3 will not be used with this selection. Only Setpoint 1 will be used. The sum of Setpoint 1 and any other references that are enabled (see par. group 3-1*) will be used as the PID controller's set-point reference.

[2] Average

Average [2] sets up the PID Controller to use the average of Feedback 1, Feedback 2 and Feedback 3 as the feedback.



NB!

Any unused feedbacks must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source*, or par. 20-06 *Feedback 3 Source*. The sum of Setpoint 1 and any other references that are enabled (see par. group 3-1*) will be used as the PID Controller's set-point reference.

[3] * Minimum

Minimum [3] sets up the PID Controller to compare Feedback 1, Feedback 2 and Feedback 3 and use the lowest value as the feedback.

**NB!**

Any unused feedbacks must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source*, or par. 20-06 *Feedback 3 Source*. Only setpoint 1 will be used. The sum of Setpoint 1 and any other references that are enabled (see par. group 3-1*) will be used as the PID Controller's setpoint reference.

[4] Maximum

Maximum [4] sets up the PID Controller to compare Feedback 1, Feedback 2 and Feedback 3 and use the highest value as the feedback.

**NB!**

Any unused feedbacks must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source*, or par. 20-06 *Feedback 3 Source*.

Only Setpoint 1 will be used. The sum of Setpoint 1 and any other references that are enabled (see par. group 3-1*) will be used as the PID Controller's setpoint reference.

[5] Multi Setpoint Min

Multi-setpoint minimum [5] sets up the PID Controller to calculate the difference between Feedback 1 and Setpoint 1, Feedback 2 and Setpoint 2, and Feedback 3 and Setpoint 3. It will use the feedback/setpoint pair in which the feedback is the farthest below its corresponding setpoint reference. If all feedback signals are above their corresponding setpoints, the PID Controller will use the feedback/setpoint pair in which the difference between the feedback and setpoint is the least.

**NB!**

If only two feedback signals are used, the feedback that is not to be used must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source* or par. 20-06 *Feedback 3 Source*. Note that each setpoint reference will be the sum of its respective parameter value (par.20-21 *Setpoint 1*, par. 20-22 *Setpoint 2* and par. 20-23 *Setpoint 3*) and any other references that are enabled (see par. group 3-1*).

[6] Multi Setpoint Max

Multi-setpoint maximum [6] sets up the PID Controller to calculate the difference between Feedback 1 and Setpoint 1, Feedback 2 and Setpoint 2, and Feedback 3 and Setpoint 3. It will use the feedback/setpoint pair in which the feedback is farthest above its corresponding setpoint reference. If all feedback signals are below their corresponding setpoints, the PID Controller will use the feedback/setpoint pair in which the difference between the feedback and the setpoint reference is the least.

**NB!**

If only two feedback signals are used, the feedback that is not to be used must be set to *No Function* in par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source* or par. 20-06 *Feedback 3 Source*. Note that each setpoint reference will be the sum of its respective parameter value (par.20-21 *Setpoint 1*, par. 20-22 *Setpoint 2* and par. 20-23 *Setpoint 3*) and any other references that are enabled (see par. group 3-1*).

**NB!**

Any unused feedback must be set to "No function" in its Feedback Source parameter: par.20-00 *Feedback 1 Source*, par.20-03 *Feedback 2 Source* or par. 20-06 *Feedback 3 Source*.

The feedback resulting from the function selected in par.20-20 *Feedback Function* will be used by the PID Controller to control the output frequency of the frequency converter. This feedback can also be shown on the frequency converter’s display, be used to control a frequency converter’s analog output, and be transmitted over various serial communication protocols.

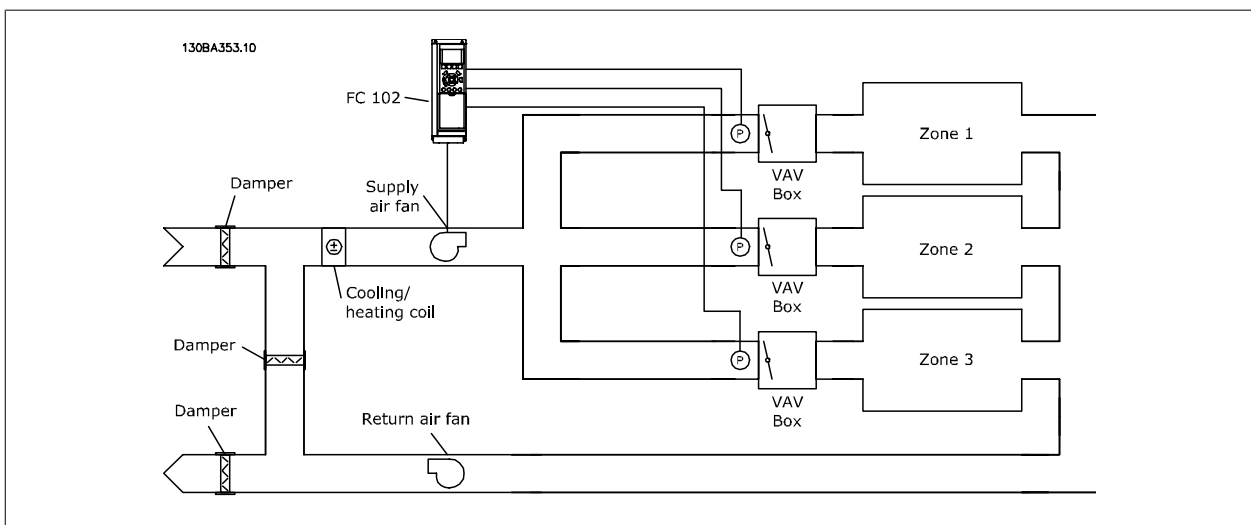
The frequency converter can be configured to handle multi zone applications. Two different multi zone applications are supported:

- Multi zone, single setpoint
- Multi zone, multi setpoint

The difference between the two is illustrated by the following examples:

Example 1 – Multi zone, single setpoint

In an office building, a VAV (variable air volume) VLT HVAC Drive system must ensure a minimum pressure at selected VAV boxes. Due to the varying pressure losses in each duct, the pressure at each VAV box cannot be assumed to be the same. The minimum pressure required is the same for all VAV boxes. This control method can be set up by setting par.20-20 *Feedback Function* to option [3], Minimum, and entering the desired pressure in par. 20-21 *Setpoint 1*. The PID Controller will increase the speed of the fan if any one feedback is below the setpoint and decrease the speed of the fan if all feedbacks are above the setpoint.



Example 2 – Multi zone, multi setpoint

The previous example can be used to illustrate the use of multi zone, multi setpoint control. If the zones require different pressures for each VAV box, each setpoint may be specified in par.20-21 *Setpoint 1*, par.20-22 *Setpoint 2* and par. 20-23 *Setpoint 3*. By selecting *Multi setpoint minimum*, [5], in par. 20-20 *Feedback Function*, the PID Controller will increase the speed of the fan if any one of the feedbacks is below its setpoint and decrease the speed of the fan if all feedbacks are above their individual setpoints.

20-21 Setpoint 1

Range:

0.000 Proc- [-999999.999 - 999999.999 Proc-
essCtrlU- essCtrlUnit]
nit*

Function:

Setpoint 1 is used in Closed Loop Mode to enter a setpoint reference that is used by the frequency converter’s PID Controller. See the description of par.20-20 *Feedback Function*.

NB!
Setpoint reference entered here is added to any other references that are enabled (see par. group 3-1*).

20-22 Setpoint 2

Range:

0.000 Proc- [-999999.999 - 999999.999 Proc-
essCtrlU- essCtrlUnit]
nit*

Function:

Setpoint 2 is used in Closed Loop Mode to enter a setpoint reference that may be used by the frequency converter’s PID Controller. See the description of *Feedback Function*, par.20-20 *Feedback Function*.

**NB!**

The set-point reference entered here is added to any other references that are enabled (see par. group 3-1*).

20-70 Closed Loop Type**Option:****Function:**

This parameter defines the application response. The default mode should be sufficient for most applications. If the application response speed is known, it can be selected here. This will decrease the time needed for carrying out PID autotuning. The setting has no impact on the value of the tuned parameters and is used only for the autotuning sequence.

- [0] * Auto
- [1] Fast Pressure
- [2] Slow Pressure
- [3] Fast Temperature
- [4] Slow Temperature

20-71 PID Performance**Option:****Function:**

- [0] * Normal Normal setting of this parameter will be suitable for pressure control in fan systems.
- [1] Fast Fast setting would generally be used in pumping systems, where a faster control response is desirable.

20-72 PID Output Change**Range:****Function:**

0.10 N/A* [0.01 - 0.50 N/A]

This parameter sets the magnitude of step change during autotuning. The value is a percentage of full speed. I.e. if maximum output frequency in par.4-13 *Motor Speed High Limit [RPM]* par. 4-14 *Motor Speed High Limit [Hz]* is set to 50Hz, 0.10 is 10% of 50Hz, which is 5Hz. This parameter should be set to a value resulting in feedback changes of between 10% and 20% for best tuning accuracy.

20-73 Minimum Feedback Level**Range:****Function:**

-999999.00 [-999999.999 - par. 20-74 Proc-
0 Proc-essCtrlUnit]
essCtrlU-
nit*

The minimum allowable feedback level should be entered here in User units as defined in par. 20-12 *Reference/Feedback Unit*. If the level falls below par.20-73 *Minimum Feedback Level*, autotuning is aborted and an error message will appear on the LCP.

20-74 Maximum Feedback Level**Range:****Function:**

999999.000 [par. 20-73 - 999999.999 Proc-
ProcessCtr- essCtrlUnit]
IUnit*

The maximum allowable feedback level should be entered here in User units as defined in par. 20-12 *Reference/Feedback Unit*. If the level rises above par.20-74 *Maximum Feedback Level*, autotuning is aborted and an error message will appear on the LCP.

20-79 PID Autotuning**Option:****Function:**

This parameter starts the PID autotuning sequence. Once the autotuning has successfully completed and the settings have been accepted or rejected by the user, by pressing [OK] or [Cancel] buttons on the LCP at the end of tuning, this parameter is reset to [0] Disabled.

- [0] * Disabled
- [1] Enabled

20-81 PID Normal/ Inverse Control

Option:

[0] * Normal

Function:

Normal [0] causes the frequency converter's output frequency to decrease when the feedback is greater than the setpoint reference. This is common for pressure-controlled supply fan and pump applications.

[1] Inverse

Inverse [1] causes the frequency converter's output frequency to increase when the feedback is greater than the setpoint reference. This is common for temperature-controlled cooling applications, such as cooling towers.

20-82 PID Start Speed [RPM]

Range:

0 RPM* [0 - par. 4-13 RPM]

Function:

When the frequency converter is first started, it initially ramps up to this output speed in Open Loop Mode, following the active Ramp Up Time. When the output speed programmed here is reached, the frequency converter will automatically switch to Closed Loop Mode and the PID Controller will begin to function. This is useful in applications in which the driven load must first quickly accelerate to a minimum speed when it is started.



NB!

This parameter will only be visible if par. 0-02 *Motor Speed Unit* is set to [0], RPM.

20-83 PID Start Speed [Hz]

Range:

0 Hz* [0.0 - par. 4-14 Hz]

Function:

When the frequency converter is first started, it initially ramps up to this output frequency in Open Loop Mode, following the active Ramp Up Time. When the output frequency programmed here is reached, the frequency converter will automatically switch to Closed Loop Mode and the PID Controller will begin to function. This is useful in applications in which the driven load must first quickly accelerate to a minimum speed when it is started.



NB!

This parameter will only be visible if par. 0-02 *Motor Speed Unit* is set to [1], Hz.

20-93 PID Proportional Gain

Range:

0.50 N/A* [0.00 - 10.00 N/A]

Function:

If (Error x Gain) jumps with a value equal to what is set in par.20-14 *Maximum Reference/Feedb.* the PID controller will try to change the output speed equal to what is set in par.4-13 *Motor Speed High Limit [RPM]*/par.4-14 *Motor Speed High Limit [Hz]* but in practice of course limited by this setting. The proportional band (error causing output to change from 0-100%) can be calculated by means of the formula:

$$\left(\frac{1}{\text{Proportional Gain}} \right) \times (\text{Max Reference})$$

NB!

Always set the desired for par.20-14 *Maximum Reference/Feedb.* before setting the values for the PID controller in par. group 20-9*.

20-94 PID Integral Time**Range:**

20.00 s* [0.01 - 10000.00 s]

Function:

Over time, the integrator accumulates a contribution to the output from the PID controller as long as there is a deviation between the Reference/Setpoint and feedback signals. The contribution is proportional to the size of the deviation. This ensures that the deviation (error) approaches zero. Quick response on any deviation is obtained when the integral time is set to a low value. Setting it too low, however, may cause the control to become unstable.

The value set, is the time needed for the integrator to add the same contribution as the proportional part for a certain deviation.

If the value is set to 10,000, the controller will act as a pure proportional controller with a P-band based on the value set in par.20-93 *PID Proportional Gain*. When no deviation is present, the output from the proportional controller will be 0.

22-20 Low Power Auto Set-up**Option:****Function:**

When set for *Enabled*, an auto set up sequence is activated, automatically setting speed to approx. 50 and 85% of rated motor speed (par.4-13 *Motor Speed High Limit [RPM]*, par.4-14 *Motor Speed High Limit [Hz]*). At those two speeds, the power consumption is automatically measured and stored. Before enabling Auto Set Up:

1. Close valve(s) in order to create a no flow condition
2. The frequency converter must be set for Open Loop (par.1-00 *Configuration Mode*). Note that it is important also to set par.1-03 *Torque Characteristics*.

[0] * Off

[1] Enabled

**NB!**

Auto Set Up must be done when the system has reached normal operating temperature!

**NB!**

It is important that the par.4-13 *Motor Speed High Limit [RPM]* or par.4-14 *Motor Speed High Limit [Hz]* is set to the max. operational speed of the motor!

It is important to do the Auto Set-up before configuring the integrated PI Controller as settings will be reset when changing from Closed to Open Loop in par.1-00 *Configuration Mode*.

**NB!**Carry out the tuning with the same settings in par.1-03 *Torque Characteristics*, as for operation after the tuning.**22-21 Low Power Detection****Option:****Function:**

[0] * Disabled

[1] Enabled

If selecting Enabled, the Low Power Detection commissioning must be carried out in order to set the parameters in group 22-3* for proper operation!

22-22 Low Speed Detection**Option:****Function:**

[0] * Disabled

[1] Enabled

Select Enabled for detecting when the motor operates with a speed as set in par.4-11 *Motor Speed Low Limit [RPM]* or par.4-12 *Motor Speed Low Limit [Hz]*.

22-23 No-Flow Function

Option:

Function:

Common actions for Low Power Detection and Low Speed Detection (Individual selections not possible).

[0] * Off

[1] Sleep Mode

[2] Warning

Messages in the Local Control Panel display (if mounted) and/or signal via a relay or a digital output.

[3] Alarm

The frequency converter trips and motor stays stopped until reset.

22-24 No-Flow Delay

Range:

Function:

10 s* [1 - 600 s]

Set the time Low Power/Low Speed must stay detected to activate signal for actions. If detection disappears before run out of the timer, the timer will be reset.

22-26 Dry Pump Function

Option:

Function:

Low Power Detection must be Enabled (par.22-21 *Low Power Detection*) and commissioned (using either parameter group 22-3*, *No Flow Power Tuning*, or par.22-20 *Low Power Auto Set-up*) in order to use Dry Pump Detection.

[0] * Off

[1] Warning

Messages in the Local Control Panel display (if mounted) and/or signal via a relay or a digital output.

[2] Alarm

The frequency converter trips and motor stays stopped until reset.

22-27 Dry Pump Delay

Range:

Function:

10 s* [0 - 600 s]

Defines for how long the Dry Pump condition must be active before activating Warning or Alarm

22-40 Minimum Run Time

Range:

Function:

10 s* [0 - 600 s]

Set the desired minimum running time for the motor after a start command (digital input or Bus) before entering Sleep Mode.

22-41 Minimum Sleep Time

Range:

Function:

10 s* [0 - 600 s]

Set the desired Minimum Time for staying in Sleep Mode. This will override any wake up conditions.

22-42 Wake-up Speed [RPM]

Range:

Function:

0 RPM* [par. 4-11 - par. 4-13 RPM]

To be used if par. 0-02 *Motor Speed Unit* has been set for RPM (parameter not visible if Hz selected). Only to be used if par.1-00 *Configuration Mode* is set for Open Loop and speed reference is applied by an external controller.
Set the reference speed at which the Sleep Mode should be cancelled.

22-43 Wake-up Speed [Hz]

Range:

Function:

0 Hz* [par. 4-12 - par. 4-14 Hz]

To be used if par. 0-02 *Motor Speed Unit*, has been set for Hz (parameter not visible if RPM selected). Only to be used if par.1-00 *Configuration Mode*, is set for Open Loop and speed reference is applied by an external controller controlling the pressure.
Set the reference speed at which the Sleep Mode should be cancelled.

22-44 Wake-up Ref./FB Difference**Range:**

10 %* [0 - 100 %]

Function:

Only to be used if par.1-00 *Configuration Mode* is set for Closed Loop and the integrated PI controller is used for controlling the pressure.

Set the pressure drop allowed in percentage of set point for the pressure (Pset) before cancelling the Sleep Mode.

**NB!**

If used in application where the integrated PI controller is set for inverse control (e.g. cooling tower applications) in par.20-71 *PID Performance*, the value set in par.22-44 *Wake-up Ref./FB Difference* will automatically be added.

22-45 Setpoint Boost**Range:**

0 %* [-100 - 100 %]

Function:

Only to be used if par.1-00 *Configuration Mode*, is set for Closed Loop and the integrated PI controller is used. In systems with e.g. constant pressure control, it is advantageous to increase the system pressure before the motor is stopped. This will extend the time in which the motor is stopped and help to avoid frequent start/stop.

Set the desired over pressure/temperature in percentage of set point for the pressure (Pset)/temperature before entering the Sleep Mode.

If setting for 5%, the boost pressure will be $Pset * 1.05$. The negative values can be used for e.g. cooling tower control where a negative change is needed.

22-46 Maximum Boost Time**Range:**

60 s* [0 - 600 s]

Function:

Only to be used if par.1-00 *Configuration Mode* is set for Closed Loop and the integrated PI controller is used for controlling the pressure.

Set the maximum time for which boost mode will be allowed. If the set time is exceeded, Sleep Mode will be entered, not waiting for the set boost pressure to be reached.

22-60 Broken Belt Function**Option:**

[0] * Off

[1] Warning

[2] Trip

Function:

Selects the action to be performed if the Broken Belt condition is detected

22-61 Broken Belt Torque**Range:**

10 %* [0 - 100 %]

Function:

Sets the broken belt torque as a percentage of the rated motor torque.

22-62 Broken Belt Delay**Range:**

10 s [0 - 600 s]

Function:

Sets the time for which the Broken Belt conditions must be active before carrying out the action selected in par.22-60 *Broken Belt Function*.

22-75 Short Cycle Protection**Option:**

[0] * Disabled

[1] Enabled

Function:

Timer set in par.22-76 *Interval between Starts* is disabled.

Timer set in par.22-76 *Interval between Starts* is enabled.

22-76 Interval between Starts

Range:

par. 22-77 [par. 22-77 - 3600 s]
s*

Function:

Sets the time desired as minimum time between two starts. Any normal start command (Start/Jog/Freeze) will be disregarded until the timer has expired.

22-77 Minimum Run Time

Range:

0 s* [0 - par. 22-76 s]

Function:

Sets the time desired as minimum run time after a normal start command (Start/Jog/Freeze). Any normal stop command will be disregarded until the set time has expired. The timer will start counting following a normal start command (Start/Jog/Freeze).

The timer will be overridden by a Coast (Inverse) or an External Interlock command.



NB!

Does not work in cascade mode.

22-80 Flow Compensation

Option:

[0] * Disabled

Function:

[0] *Disabled:* Set-Point compensation not active.

[1] Enabled

[1] *Enabled:* Set-Point compensation is active. Enabling this parameter allows the Flow Compensated Setpoint operation.

22-81 Square-linear Curve Approximation

Range:

100 %* [0 - 100 %]

Function:

Example 1:

Adjustment of this parameter allows the shape of the control curve to be adjusted.

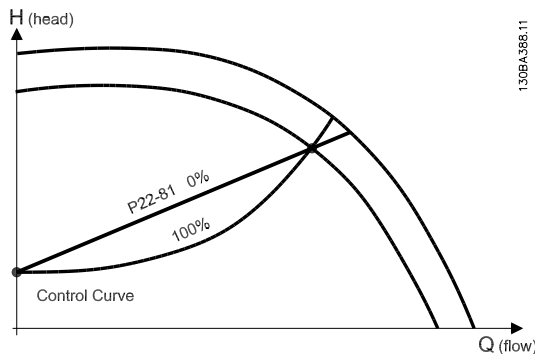
0 = Linear

100% = Ideal shape (theoretical).



NB!

Please note: Not visible when running in cascade.

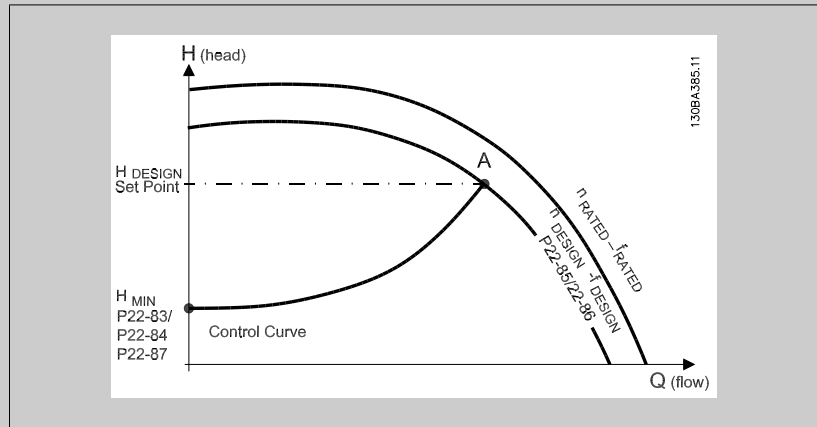


22-82 Work Point Calculation

Option:

Function:

Example 1: Speed at System Design Working Point is known:

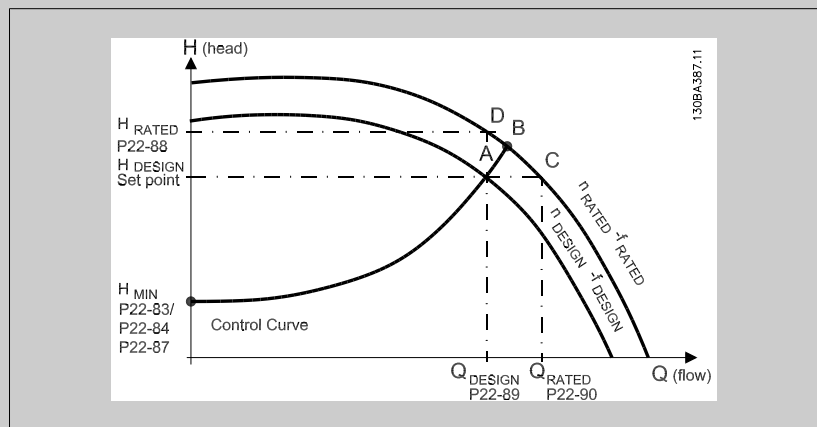


From the data sheet showing characteristics for the specific equipment at different speeds, simply reading across from the H_{DESIGN} point and the Q_{DESIGN} point allows us to find point A, which is the System Design Working Point. The pump characteristics at this point should be identified and the associated speed programmed. Closing the valves and adjusting the speed until H_{MIN} has been achieved allows the speed at the no flow point to be identified.

Adjustment of par.22-81 *Square-linear Curve Approximation* then allows the shape of the control curve to be adjusted infinitely.

Example 2:

Speed at System Design Working Point is not known: Where the Speed at System Design Working Point is unknown, another reference point on the control curve needs to be determined by means of the data sheet. By looking at the curve for the rated speed and plotting the design pressure (H_{DESIGN} , Point C) the flow at that pressure Q_{RATED} can be determined. Similarly, by plotting the design flow (Q_{DESIGN} , Point D), the pressure H_D at that flow can be determined. Knowing these two points on the pump curve, along with H_{MIN} as described above, allows the frequency converter to calculate the reference point B and thus to plot the control curve which will also include the System design Working Point A.



[0] * Disabled

Disabled [0]: Work Point Calculation not active. To be used if speed at design point is known (see table above).

[1] Enabled

Enabled [1]: Work Point Calculation is active. Enabling this parameter allows the calculation of the unknown System Design Working Point at 50/60 Hz speed, from the input data set in par. 22-83 *Speed at No-Flow [RPM]* par.22-84 *Speed at No-Flow [Hz]*, par.22-87 *Pressure at No-Flow Speed*, par.22-88 *Pressure at Rated Speed*, par.22-89 *Flow at Design Point* and par.22-90 *Flow at Rated Speed*.

22-83 Speed at No-Flow [RPM]**Range:**

300. RPM* [0 - par. 22-85 RPM]

Function:

Resolution 1 RPM.

The speed of the motor at which flow is zero and minimum pressure H_{MIN} is achieved should be entered here in RPM. Alternatively, the speed in Hz can be entered in par.22-84 *Speed at No-Flow [Hz]*. If it has been decided to use RPM in par. 0-02 *Motor Speed Unit* then par.22-85 *Speed at Design Point [RPM]* should also be used. Closing the valves and reducing the speed until minimum pressure H_{MIN} is achieved will determine this value.

22-84 Speed at No-Flow [Hz]**Range:**

50.0 Hz* [0.0 - par. 22-86 Hz]

Function:

Resolution 0.033 Hz.

The speed of the motor at which flow has effectively stopped and minimum pressure H_{MIN} is achieved should be entered here in Hz. Alternatively, the speed in RPM can be entered in par.22-83 *Speed at No-Flow [RPM]*. If it has been decided to use Hz in par. 0-02 *Motor Speed Unit* then par. 22-86 *Speed at Design Point [Hz]* should also be used. Closing the valves and reducing the speed until minimum pressure H_{MIN} is achieved will determine this value.

22-85 Speed at Design Point [RPM]**Range:**

1500. RPM* [par. 22-83 - 60000. RPM]

Function:

Resolution 1 RPM.

Only visible when par.22-82 *Work Point Calculation* is set to *Disable*. The speed of the motor at which the System Design Working Point is achieved should be entered here in RPM. Alternatively, the speed in Hz can be entered in par.22-86 *Speed at Design Point [Hz]*. If it has been decided to use RPM in par. 0-02 *Motor Speed Unit* then par.22-83 *Speed at No-Flow [RPM]* should also be used.

22-86 Speed at Design Point [Hz]**Range:**

50/60.0 Hz* [par. 22-84 - par. 4-19 Hz]

Function:

Resolution 0.033 Hz.

Only visible when par.22-82 *Work Point Calculation* is set to *Disable*. The speed of the motor at which the System Design Working Point is achieved should be entered here in Hz. Alternatively, the speed in RPM can be entered in par.22-85 *Speed at Design Point [RPM]*. If it has been decided to use Hz in par. 0-02 *Motor Speed Unit*, then par.22-83 *Speed at No-Flow [RPM]* should also be used.

22-87 Pressure at No-Flow Speed**Range:**

0.000 N/A* [0.000 - par. 22-88 N/A]

Function:Enter the pressure H_{MIN} corresponding to Speed at No Flow in Reference/Feedback Units.**22-88 Pressure at Rated Speed****Range:**

999999.999 N/A* [par. 22-87 - 999999.999 N/A]

Function:

Enter the value corresponding to the Pressure at Rated Speed, in Reference/Feedback Units. This value can be defined using the pump datasheet.

22-89 Flow at Design Point**Range:**

0.000 N/A* [0.000 - 999999.999 N/A]

Function:

Enter the value corresponding to the Flow at Design Point. No units necessary.

22-90 Flow at Rated Speed**Range:**

0.000 N/A* [0.000 - 999999.999 N/A]

Function:

Enter the value corresponding to Flow at Rated Speed. This value can be defined using the pump datasheet.

6.1.7 Parameter Set-Up

| Group | Title | Function |
|-------|---------------------------|---|
| 0- | Operation and Display | Parameters used to program the fundamental functions of the frequency converter and the LCP including: selection of language; selection of which variables are displayed at each position in the display (e.g. static duct pressure or condenser water return temperature can be displayed with the setpoint in small digits in the top row and feedback in large digits in the centre of the display); enabling/disabling of the LCP keys/buttons; passwords for the LCP; upload and download of commissioned parameters to/from the LCP and setting the built in clock. |
| 1- | Load / Motor | Parameters used to configure the frequency converter for the specific application and motor including: open or closed loop operation; type of application such as compressor, fan or centrifugal pump; motor nameplate data; auto-tuning of the drive to the motor for optimum performance; flying start (typically used for fan applications) and motor thermal protection. |
| 2- | Brakes | Parameters used to configure braking functions of the frequency converter which although not common in many HVAC applications, can be useful on special fan applications. Parameters including: DC braking; dynamic/resistor braking and over voltage control (which provides automatic adjustment of the deceleration rate (auto-ramping) to avoid tripping when decelerating large inertia fans) |
| 3- | Reference / Ramps | Parameters used to program the minimum and maximum reference limits of speed (RPM/Hz) in open loop or in actual units when operating in closed loop); digital/preset references; jog speed; definition of the source of each reference (e.g. which analog input the reference signal is connected to); ramp up and down times and digital potentiometer settings. |
| 4- | Limits / Warnings | Parameters used to program limits and warnings of operation including: allowable motor direction; minimum and maximum motor speeds (e.g. in pump applications it is typical to program a minimum speed to approx 30-40% to ensure pump seals are adequately lubricated at all times, avoid cavitation and ensure adequate head is produced at all times to create flow); torque and current limits to protect the pump, fan or compressor driven by the motor; warnings for low/high current, speed, reference, and feedback; missing motor phase protection; speed bypass frequencies including semi-automatic setup of these frequencies (e.g. to avoid resonance conditions on cooling tower and other fans). |
| 5- | Digital In / Out | Parameters used to program the functions of all digital inputs, digital outputs, relay outputs, pulse inputs and pulse outputs for terminals on the control card and all option cards. |
| 6- | Analog In / Out | Parameters used to program the functions associated with all analog inputs and analog outputs for the terminals on the control card and General Purpose I/O option (MCB101) (note: NOT Analog I/O option MCB109, see parameter group 26-00) including: analog input live zero timeout function (which for example can be used to command a cooling tower fan to operate at full speed if the condenser water return sensor fails); scaling of the analog input signals (for example to match the analog input to the mA and pressure range of a static duct pressure sensor); filter time constant to filter out electrical noise on the analog signal which can sometimes occur when long cables are installed; function and scaling of the analog outputs (for example to provide an analog output representing motor current or kW to an analog input of a DDC controller) and to configure the analog outputs to be controlled by the BMS via a high level interface (HLI) (e.g. to control a chilled water valve) including ability to define a default value of these outputs in the event of the HLI failing. |
| 8- | Communication and Options | Parameters used for configuring and monitoring functions associated with the serial communications / high level interface to the frequency converter |
| 9- | Profibus | Parameters only applicable when a Profibus option is installed. |
| 10- | CAN Fieldbus | Parameters only applicable when a DeviceNet option is installed. |
| 11- | LonWorks | Parameters only applicable when a Lonworks option is installed. |
| 13- | Smart Logic Controller | Parameters used to configure the built in Smart Logic Controller (SLC) which can be used for simple functions such as comparators (e.g. if running above xHz, activate output relay), timers (e.g. when a start signal is applied, first activate output relay to open supply air damper and wait x seconds before ramping up) or a more complex sequence of user defined actions executed by the SLC when the associated user defined event is evaluated as TRUE by the SLC. (For example, initiate an economiser mode in a simple AHU cooling application control scheme where there is no BMS. For such an application the SLC can monitor the outside air relative humidity and if it is below a defined value, the supply air temperature setpoint could be automatically increased. With the frequency converter monitoring the outside air relative humidity and supply air temperature via its analog inputs and controlling the chilled water valve via one of the extended PI(D) loops and an analog output, it would then modulate that valve to maintain a higher supply air temperature). The SLC can often replace the need for other external control equipment. |

Table 6.2: Parameter Groups

| Group | Title | Function |
|-------|---------------------------|--|
| 14- | Special Functions | Parameters used to configure special functions of the frequency converter including: setting of the switching frequency to reduce audible noise from the motor (sometimes required for fan applications); kinetic back-up function (especially useful for critical applications in semi-conductor installations where performance under mains dip/mains loss is important); mains imbalance protection; automatic reset (to avoid the need for a manual reset of Alarms); energy optimisation parameters (which typically do not need changing but enable fine tuning of this automatic function (if necessary) ensuring the frequency converter and motor combination operate at their optimum efficiency at full and partial load conditions) and auto-derating functions (which enable the frequency converter to continue operation at reduced performance under extreme operating conditions ensuring maximum up time). |
| 15- | FC Information | Parameters providing operating data and other drive information including: operating and running hour counters; kWh counter; resetting of the running and kWh counters; alarm/fault log (where the past 10 alarms are logged along with any associated value and time) and drive and option card identification parameters such as code number and software version. |
| 16- | Data Readouts | Read only parameters which display the status/value of many operating variables which can be displayed on the LCP or viewed in this parameter group. These parameters can be particularly useful during commissioning when interfacing with a BMS via a high level interface. |
| 18- | Info & Readouts | Read only parameters which display the last 10 preventative maintenance log items, actions and time and the value of analog inputs and outputs on the Analog I/O option card which can be particularly useful during commissioning when interfacing with a BMS via a high level interface. |
| 20- | FC Closed Loop | Parameters used to configure the closed loop PI(D) controller which controls the speed of the pump, fan or compressor in closed loop mode including: defining where each of the 3 possible feedback signals come from (e.g. which analog input or the BMS HLI); conversion factor for each of the feedback signals (e.g. where a pressure signal is used for indication of flow in an AHU or converting from pressure to temperature in a compressor application); engineering unit for the reference and feedback (e.g. Pa, kPa, m Wg, in Wg, bar, m3/s, m3/h, °C, °F etc); the function (e.g. sum, difference, average, minimum or maximum) used to calculate the resulting feedback for single zone applications or the control philosophy for multi-zone applications; programming of the setpoint(s) and manual or auto-tuning of the PI(D) loop. |
| 21- | Extended Closed Loop | Parameters used to configure the 3 extended closed loop PI(D) controllers which for example can be used to control external actuators (e.g. chilled water valve to maintain supply air temperature in a VAV system) including: engineering unit for the reference and feedback of each controller (e.g. °C, °F etc); defining the range of the reference/setpoint for each controller; defining where each of the references/setpoints and feedback signals come from (e.g. which analog input or the BMS HLI); programming of the setpoint and manual or auto-tuning of the each of the PI(D) controllers. |
| 22- | Application Functions | Parameters used to monitor, protect and control pumps, fans and compressors including: no flow detection and protection of pumps (including auto-setup of this function); dry pump protection; end of curve detection and protection of pumps; sleep mode (especially useful for cooling tower and booster pump sets); broken belt detection (typically used for fan applications to detect no air flow instead of using a Δp switch installed across the fan); short cycle protection of compressors and pump flow compensation of setpoint (especially useful for secondary chilled water pump applications where the Δp sensor has been installed close to the pump and not across the furthest most significant load(s) in the system; using this function can compensate for the sensor installation and help to realise the maximum energy savings). |
| 23- | Time Based Functions | Time based parameters including: those used to initiate daily or weekly actions based on the built in real time clock (e.g. change of setpoint for night set back mode or start/stop of the pump/fan/compressor start/stop of a external equipment); preventative maintenance functions which can be based on running or operating hour time intervals or on specific dates and times; energy log (especially useful in retrofit applications or where information of the actual historical load (kW) on the pump/fan/compressor is of interest); trending (especially useful in retrofit or other applications where there is an interest to log operating power, current, frequency or speed of the pump/fan/compressor for analysis and a payback counter). |
| 24- | Application Functions 2 | Parameters used to set-up Fire Mode and/or to control a bypass contactor/starter if designed into the system. |
| 25- | Cascade Controller | Parameters used to configure and monitor the built in pump cascade controller (typically used for pump booster sets). |
| 26- | Analog I/O Option MCB 109 | Parameters used to configure the Analog I/O option (MCB109) including: definition of the analog input types (e.g. voltage, Pt1000 or Ni1000) and scaling and definition of the analog output functions and scaling. |

Parameter descriptions and selections are displayed on the graphic (GLCP) or numeric (NLCP) display. (See relevant section for details.) Access the parameters by pressing the [Quick Menu] or [Main Menu] button on the control panel. The Quick Menu is used primarily for commissioning the unit at start-up by providing the parameters necessary to start operation. The Main Menu provides access to all parameters for detailed application programming.

All digital input/output and analog input/output terminals are multifunctional. All terminals have factory default functions suitable for the majority of HVAC applications but if other special functions are required, they must be programmed as explained in parameter group 5 or 6.

6.1.8 Main Menu Mode

Both the GLCP and NLCP provide access to the main menu mode. Select the Main Menu mode by pressing the [Main Menu] key. Illustration 6.2 shows the resulting read-out, which appears on the display of the GLCP. Lines 2 through 5 on the display show a list of parameter groups which can be chosen by toggling the up and down buttons.

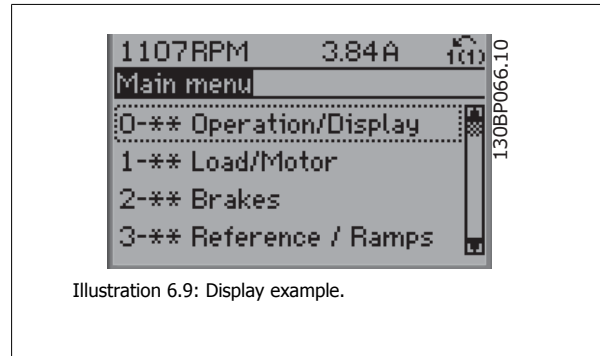


Illustration 6.9: Display example.

Each parameter has a name and number which remain the same regardless of the programming mode. In the Main Menu mode, the parameters are divided into groups. The first digit of the parameter number (from the left) indicates the parameter group number.

6

All parameters can be changed in the Main Menu. The configuration of the unit (par.1-00 *Configuration Mode*) will determine other parameters available for programming. For example, selecting Closed Loop enables additional parameters related to closed loop operation. Option cards added to the unit enable additional parameters associated with the option device.

6.1.9 Changing Data

1. Press [Quick Menu] or [Main Menu] key.
2. Use [▲] and [▼] keys to find parameter group to edit.
3. Press [OK] key.
4. Use [▲] and [▼] keys to find parameter to edit.
5. Press [OK] key.
6. Use [▲] and [▼] keys to select correct parameter setting. Or, to move to digits within a number, use keys. Cursor indicates digit selected to change. [▲] key increases the value, [▼] key decreases the value.
7. Press [Cancel] key to disregard change, or press [OK] key to accept change and enter new setting.

6.1.10 Changing a Text Value

If the selected parameter is a text value, change the text value by means of the up/down navigation keys.

The up key increases the value, and the down key decreases the value. Place the cursor on the value to be saved and press [OK].

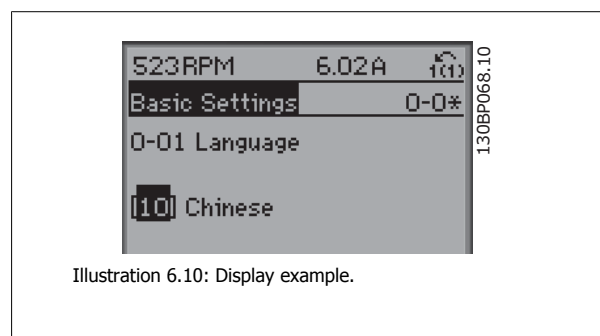


Illustration 6.10: Display example.

6.1.11 Changing a Group of Numeric Data Values

If the chosen parameter represents a numeric data value, change the chosen data value by means of the [←] and [→] navigation keys as well as the up/down [▲] [▼] navigation keys. Use the [←] and [→] navigation keys to move the cursor horizontally.

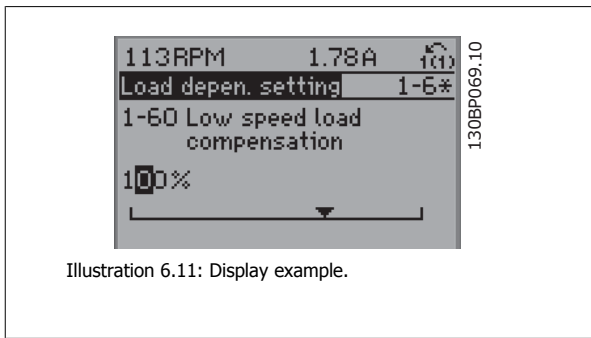


Illustration 6.11: Display example.

Use the up/down navigation keys to change the data value. The up key enlarges the data value, and the down key reduces the data value. Place the cursor on the value to be saved and press [OK].

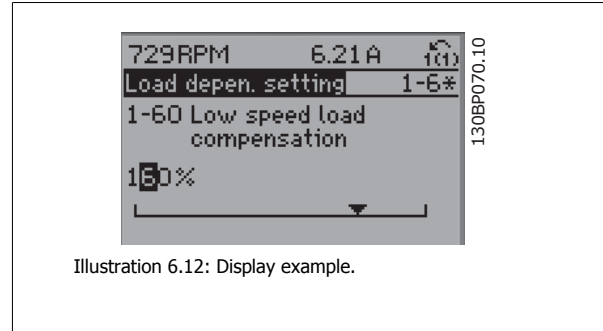


Illustration 6.12: Display example.

6.1.12 Changing of Data Value, Step-by-Step

Certain parameters can be changed step by step or infinitely variably. This applies to par.1-20 *Motor Power [kW]*, par.1-22 *Motor Voltage* and par. 1-23 *Motor Frequency*.

The parameters are changed both as a group of numeric data values and as numeric data values infinitely variably.

6.1.13 Read-out and Programming of Indexed Parameters

Parameters are indexed when placed in a rolling stack.

par. 15-30 *Alarm Log: Error Code* to par. 15-32 *Alarm Log: Time* contain a fault log which can be read out. Choose a parameter, press [OK], and use the up/down navigation keys to scroll through the value log.

Use par.3-10 *Preset Reference* as another example:

Choose the parameter, press [OK], and use the up/down navigation keys to scroll through the indexed values. To change the parameter value, select the indexed value and press [OK]. Change the value by using the up/down keys. Press [OK] to accept the new setting. Press [Cancel] to abort. Press [Back] to leave the parameter.

6.2 Parameter list

6.2.1 0- ** Operation and Display

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------------------------|----------------------------------|--------------------------|-------------|-------------------------|------------------|------------|
| 0-0* Basic Settings | | | | | | |
| 0-01 | Language | [0] English | 1 set-up | TRUE | - | Uint8 |
| 0-02 | Motor Speed Unit | [1] Hz | 2 set-ups | FALSE | - | Uint8 |
| 0-03 | Regional Settings | [0] International | 2 set-ups | FALSE | - | Uint8 |
| 0-04 | Operating State at Power-up | [0] Resume | All set-ups | TRUE | - | Uint8 |
| 0-05 | Local Mode Unit | [0] As Motor Speed Unit | 2 set-ups | FALSE | - | Uint8 |
| 0-1* Set-up Operations | | | | | | |
| 0-10 | Active Set-up | [1] Set-up 1 | 1 set-up | TRUE | - | Uint8 |
| 0-11 | Programming Set-up | [9] Active Set-up | All set-ups | TRUE | - | Uint8 |
| 0-12 | This Set-up Linked to | [0] Not linked | All set-ups | FALSE | - | Uint8 |
| 0-13 | Readout: Linked Set-ups | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 0-14 | Readout: Prog. Set-ups / Channel | 0 N/A | All set-ups | TRUE | 0 | Int32 |
| 0-2* LCP Display | | | | | | |
| 0-20 | Display Line 1.1 Small | 1602 | All set-ups | TRUE | - | Uint16 |
| 0-21 | Display Line 1.2 Small | 1614 | All set-ups | TRUE | - | Uint16 |
| 0-22 | Display Line 1.3 Small | 1610 | All set-ups | TRUE | - | Uint16 |
| 0-23 | Display Line 2 Large | 1613 | All set-ups | TRUE | - | Uint16 |
| 0-24 | Display Line 3 Large | 1502 | All set-ups | TRUE | - | Uint16 |
| 0-25 | My Personal Menu | SR | 1 set-up | TRUE | 0 | Uint16 |
| 0-3* LCP Custom Readout | | | | | | |
| 0-30 | Custom Readout Unit | [1] % | All set-ups | TRUE | - | Uint8 |
| 0-31 | Custom Readout Min Value | SR | All set-ups | TRUE | -2 | Int32 |
| 0-32 | Custom Readout Max Value | 100.00 CustomReadoutUnit | All set-ups | TRUE | -2 | Int32 |
| 0-37 | Display Text 1 | 0 N/A | 1 set-up | TRUE | 0 | VisStr[25] |
| 0-38 | Display Text 2 | 0 N/A | 1 set-up | TRUE | 0 | VisStr[25] |
| 0-39 | Display Text 3 | 0 N/A | 1 set-up | TRUE | 0 | VisStr[25] |
| 0-4* LCP Keypad | | | | | | |
| 0-40 | [Hand on] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 0-41 | [Off] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 0-42 | [Auto on] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 0-43 | [Reset] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 0-44 | [Off/Reset] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 0-45 | [Drive Bypass] Key on LCP | [1] Enabled | All set-ups | TRUE | - | Uint8 |

| Par. No. # | Parameter description | Default value (SR = Size related) | 4-set-up | Change during operation | Conversion index | Type |
|----------------------------|--------------------------------------|--------------------------------------|-------------|-------------------------|------------------|-------------|
| 0-5* Copy/Save | | | | | | |
| 0-50 | LCP Copy | [0] No copy | All set-ups | FALSE | - | Uint8 |
| 0-51 | Set-up Copy | [0] No copy | All set-ups | FALSE | - | Uint8 |
| 0-6* Password | | | | | | |
| 0-60 | Main Menu Password | 100 N/A | 1 set-up | TRUE | 0 | Int16 |
| 0-61 | Access to Main Menu w/o Password | [0] Full access | 1 set-up | TRUE | - | Uint8 |
| 0-65 | Personal Menu Password | 200 N/A | 1 set-up | TRUE | 0 | Int16 |
| 0-66 | Access to Personal Menu w/o Password | [0] Full access | 1 set-up | TRUE | - | Uint8 |
| 0-7* Clock Settings | | | | | | |
| 0-70 | Date and Time | SR | All set-ups | TRUE | 0 | TimeOfDay |
| 0-71 | Date Format | null | 1 set-up | TRUE | - | Uint8 |
| 0-72 | Time Format | null | 1 set-up | TRUE | - | Uint8 |
| 0-74 | DST/Summertime | [0] Off | 1 set-up | TRUE | - | Uint8 |
| 0-76 | DST/Summertime Start | SR | 1 set-up | TRUE | 0 | TimeOfDay |
| 0-77 | DST/Summertime End | SR | 1 set-up | TRUE | 0 | TimeOfDay |
| 0-79 | Clock Fault | null | 1 set-up | TRUE | - | Uint8 |
| 0-81 | Working Days | null | 1 set-up | TRUE | - | Uint8 |
| 0-82 | Additional Working Days | SR | 1 set-up | TRUE | 0 | TimeOfDay |
| 0-83 | Additional Non-Working Days | SR | 1 set-up | TRUE | 0 | TimeOfDay |
| 0-89 | Date and Time Readout | 0 N/A | All set-ups | TRUE | 0 | VisStr[25] |

6.2.2 1- ** Load / Motor

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|--------------------------------------|---------------------------|-------------|-------------------------|------------------|--------|
| 1-0* General Settings | | | | | | |
| 1-00 | Configuration Mode | null | All set-ups | TRUE | - | Uint8 |
| 1-03 | Torque Characteristics | [3] Auto Energy Optim. VT | All set-ups | TRUE | - | Uint8 |
| 1-2* Motor Data | | | | | | |
| 1-20 | Motor Power [kW] | SR | All set-ups | FALSE | 1 | Uint32 |
| 1-21 | Motor Power [HP] | SR | All set-ups | FALSE | -2 | Uint32 |
| 1-22 | Motor Voltage | SR | All set-ups | FALSE | 0 | Uint16 |
| 1-23 | Motor Frequency | SR | All set-ups | FALSE | 0 | Uint16 |
| 1-24 | Motor Current | SR | All set-ups | FALSE | -2 | Uint32 |
| 1-25 | Motor Nominal Speed | SR | All set-ups | FALSE | 67 | Uint16 |
| 1-28 | Motor Rotation Check | [0] Off | All set-ups | FALSE | - | Uint8 |
| 1-29 | Automatic Motor Adaptation (AMA) | [0] Off | All set-ups | FALSE | - | Uint8 |
| 1-3* Adv. Motor Data | | | | | | |
| 1-30 | Stator Resistance (Rs) | SR | All set-ups | FALSE | -4 | Uint32 |
| 1-31 | Rotor Resistance (Rr) | SR | All set-ups | FALSE | -4 | Uint32 |
| 1-35 | Main Reactance (Xh) | SR | All set-ups | FALSE | -4 | Uint32 |
| 1-36 | Iron Loss Resistance (Rfe) | SR | All set-ups | FALSE | -3 | Uint32 |
| 1-39 | Motor Poles | SR | All set-ups | FALSE | 0 | Uint8 |
| 1-5* Load Indep. Setting | | | | | | |
| 1-50 | Motor Magnetisation at Zero Speed | 100 % | All set-ups | TRUE | 0 | Uint16 |
| 1-51 | Min Speed Normal Magnetising [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 1-52 | Min Speed Normal Magnetising [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 1-6* Load Depen. Setting | | | | | | |
| 1-60 | Low Speed Load Compensation | 100 % | All set-ups | TRUE | 0 | Int16 |
| 1-61 | High Speed Load Compensation | 100 % | All set-ups | TRUE | 0 | Int16 |
| 1-62 | Slip Compensation | 0 % | All set-ups | TRUE | 0 | Int16 |
| 1-63 | Slip Compensation Time Constant | SR | All set-ups | TRUE | -2 | Uint16 |
| 1-64 | Resonance Dampening | 100 % | All set-ups | TRUE | 0 | Uint16 |
| 1-65 | Resonance Dampening Time Constant | 5 ms | All set-ups | TRUE | -3 | Uint8 |
| 1-7* Start Adjustments | | | | | | |
| 1-71 | Start Delay | 0.0 s | All set-ups | TRUE | -1 | Uint16 |
| 1-73 | Flying Start | [0] Disabled | All set-ups | FALSE | - | Uint8 |
| 1-8* Stop Adjustments | | | | | | |
| 1-80 | Function at Stop | [0] Coast | All set-ups | TRUE | - | Uint8 |
| 1-81 | Min Speed for Function at Stop [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 1-82 | Min Speed for Function at Stop [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 1-86 | Trip Speed Low [RPM] | 0 RPM | All set-ups | TRUE | 67 | Uint16 |
| 1-87 | Trip Speed Low [Hz] | 0.0 Hz | All set-ups | TRUE | -1 | Uint16 |
| 1-9* Motor Temperature | | | | | | |
| 1-90 | Motor Thermal Protection | [4] ETR trip 1 | All set-ups | TRUE | - | Uint8 |
| 1-91 | Motor External Fan | [0] No | All set-ups | TRUE | - | Uint16 |
| 1-93 | Thermistor Source | [0] None | All set-ups | TRUE | - | Uint8 |

6.2.3 2- ** Brakes

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|-----------------------------|---------------|-------------|-------------------------|------------------|--------|
| 2-0* DC-Brake | | | | | | |
| 2-00 | DC Hold/Preheat Current | 50 % | All set-ups | TRUE | 0 | Uint8 |
| 2-01 | DC Brake Current | 50 % | All set-ups | TRUE | 0 | Uint16 |
| 2-02 | DC Braking Time | 10.0 s | All set-ups | TRUE | -1 | Uint16 |
| 2-03 | DC Brake Cut In Speed [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 2-04 | DC Brake Cut In Speed [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 2-1* Brake Energy Funct. | | | | | | |
| 2-10 | Brake Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 2-11 | Brake Resistor (ohm) | SR | All set-ups | TRUE | -2 | Uint32 |
| 2-12 | Brake Power Limit (kW) | SR | All set-ups | TRUE | 0 | Uint32 |
| 2-13 | Brake Power Monitoring | [0] Off | All set-ups | TRUE | - | Uint8 |
| 2-15 | Brake Check | [0] Off | All set-ups | TRUE | - | Uint8 |
| 2-16 | AC brake Max. Current | 100.0 % | All set-ups | TRUE | -1 | Uint32 |
| 2-17 | Over-voltage Control | [2] Enabled | All set-ups | TRUE | - | Uint8 |

6.2.4 3- ** Reference / Ramps

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-------------------------------|---------------------------|---------------------------|-------------|-------------------------|------------------|--------|
| 3-0* Reference Limits | | | | | | |
| 3-02 | Minimum Reference | SR | All set-ups | TRUE | -3 | Int32 |
| 3-03 | Maximum Reference | SR | All set-ups | TRUE | -3 | Int32 |
| 3-04 | Reference Function | null | All set-ups | TRUE | - | UInt8 |
| 3-1* References | | | | | | |
| 3-10 | Preset Reference | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 3-11 | Jog Speed [Hz] | SR | All set-ups | TRUE | -1 | UInt16 |
| 3-13 | Reference Site | [0] Linked to Hand / Auto | All set-ups | TRUE | - | UInt8 |
| 3-14 | Preset Relative Reference | 0.00 % | All set-ups | TRUE | -2 | Int32 |
| 3-15 | Reference 1 Source | [1] Analog input 53 | All set-ups | TRUE | - | UInt8 |
| 3-16 | Reference 2 Source | [20] Digital pot.meter | All set-ups | TRUE | - | UInt8 |
| 3-17 | Reference 3 Source | [0] No function | All set-ups | TRUE | - | UInt8 |
| 3-19 | Jog Speed [RPM] | SR | All set-ups | TRUE | 67 | UInt16 |
| 3-4* Ramp 1 | | | | | | |
| 3-41 | Ramp 1 Ramp Up Time | SR | All set-ups | TRUE | -2 | UInt32 |
| 3-42 | Ramp 1 Ramp Down Time | SR | All set-ups | TRUE | -2 | UInt32 |
| 3-5* Ramp 2 | | | | | | |
| 3-51 | Ramp 2 Ramp Up Time | SR | All set-ups | TRUE | -2 | UInt32 |
| 3-52 | Ramp 2 Ramp Down Time | SR | All set-ups | TRUE | -2 | UInt32 |
| 3-8* Other Ramps | | | | | | |
| 3-80 | Jog Ramp Time | SR | All set-ups | TRUE | -2 | UInt32 |
| 3-81 | Quick Stop Ramp Time | SR | 2 set-ups | TRUE | -2 | UInt32 |
| 3-9* Digital Pot.Meter | | | | | | |
| 3-90 | Step Size | 0.10 % | All set-ups | TRUE | -2 | UInt16 |
| 3-91 | Ramp Time | 1.00 s | All set-ups | TRUE | -2 | UInt32 |
| 3-92 | Power Restore | [0] Off | All set-ups | TRUE | - | UInt8 |
| 3-93 | Maximum Limit | 100 % | All set-ups | TRUE | 0 | Int16 |
| 3-94 | Minimum Limit | 0 % | All set-ups | TRUE | 0 | Int16 |
| 3-95 | Ramp Delay | SR | All set-ups | TRUE | -3 | TimD |

6.2.5 4- * Limits / Warnings

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------|------------------------------|-----------------------------|-------------|-------------------------|------------------|--------|
| 4-1* Motor Limits | | | | | | |
| 4-10 | Motor Speed Direction | [2] Both directions | All set-ups | FALSE | - | Uint8 |
| 4-11 | Motor Speed Low Limit [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 4-12 | Motor Speed Low Limit [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 4-13 | Motor Speed High Limit [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 4-14 | Motor Speed High Limit [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 4-16 | Torque Limit Motor Mode | SR | All set-ups | TRUE | -1 | Uint16 |
| 4-17 | Torque Limit Generator Mode | 100.0 % | All set-ups | TRUE | -1 | Uint16 |
| 4-18 | Current Limit | SR | All set-ups | TRUE | -1 | Uint32 |
| 4-19 | Max Output Frequency | SR | All set-ups | FALSE | -1 | Uint16 |
| 4-5* Adj. Warnings | | | | | | |
| 4-50 | Warning Current Low | 0.00 A | All set-ups | TRUE | -2 | Uint32 |
| 4-51 | Warning Current High | ImaxVLT (P1637) | All set-ups | TRUE | -2 | Uint32 |
| 4-52 | Warning Speed Low | 0 RPM | All set-ups | TRUE | 67 | Uint16 |
| 4-53 | Warning Speed High | outputSpeedHighLimit (P413) | All set-ups | TRUE | 67 | Uint16 |
| 4-54 | Warning Reference Low | -999999,999 N/A | All set-ups | TRUE | -3 | Int32 |
| 4-55 | Warning Reference High | 999999,999 N/A | All set-ups | TRUE | -3 | Int32 |
| 4-56 | Warning Feedback Low | -999999,999 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 4-57 | Warning Feedback High | 999999,999 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 4-58 | Missing Motor Phase Function | [2] Trip 1000 ms | All set-ups | TRUE | - | Uint8 |
| 4-6* Speed Bypass | | | | | | |
| 4-60 | Bypass Speed From [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 4-61 | Bypass Speed From [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 4-62 | Bypass Speed To [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 4-63 | Bypass Speed To [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 4-64 | Semi-Auto Bypass Set-up | [0] Off | All set-ups | FALSE | - | Uint8 |

6.2.6 5- * * Digital In / Out

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|------------------------------|---------------------------------|-------------------------|-------------|-------------------------|------------------|--------|
| 5-0* Digital I/O mode | | | | | | |
| 5-00 | Digital I/O Mode | [0] PNP - Active at 24V | All set-ups | FALSE | - | Uint8 |
| 5-01 | Terminal 27 Mode | [0] Input | All set-ups | TRUE | - | Uint8 |
| 5-02 | Terminal 29 Mode | [0] Input | All set-ups | TRUE | - | Uint8 |
| 5-1* Digital Inputs | | | | | | |
| 5-10 | Terminal 18 Digital Input | [8] Start | All set-ups | TRUE | - | Uint8 |
| 5-11 | Terminal 19 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-12 | Terminal 27 Digital Input | null | All set-ups | TRUE | - | Uint8 |
| 5-13 | Terminal 29 Digital Input | [14] Jog | All set-ups | TRUE | - | Uint8 |
| 5-14 | Terminal 32 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-15 | Terminal 33 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-16 | Terminal X30/2 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-17 | Terminal X30/3 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-18 | Terminal X30/4 Digital Input | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-3* Digital Outputs | | | | | | |
| 5-30 | Terminal 27 Digital Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-31 | Terminal 29 Digital Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-32 | Term X30/6 Digi Out (MCB 101) | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-33 | Term X30/7 Digi Out (MCB 101) | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-4* Relays | | | | | | |
| 5-40 | Function Relay | null | All set-ups | TRUE | - | Uint8 |
| 5-41 | On Delay, Relay | 0.01 s | All set-ups | TRUE | -2 | Uint16 |
| 5-42 | Off Delay, Relay | 0.01 s | All set-ups | TRUE | -2 | Uint16 |
| 5-5* Pulse Input | | | | | | |
| 5-50 | Term. 29 Low Frequency | 100 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-51 | Term. 29 High Frequency | 100 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-52 | Term. 29 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 5-53 | Term. 29 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 5-54 | Pulse Filter Time Constant #29 | 100 ms | All set-ups | FALSE | -3 | Uint16 |
| 5-55 | Term. 33 Low Frequency | 100 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-56 | Term. 33 High Frequency | 100 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-57 | Term. 33 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 5-58 | Term. 33 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 5-59 | Pulse Filter Time Constant #33 | 100 ms | All set-ups | FALSE | -3 | Uint16 |

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|----------------------------|--------------------------------------|------------------|-------------|-------------------------|------------------|--------|
| 5-6* Pulse Output | | | | | | |
| 5-60 | Terminal 27 Pulse Output Variable | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-62 | Pulse Output Max Freq #27 | 5000 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-63 | Terminal 29 Pulse Output Variable | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-65 | Pulse Output Max Freq #29 | 5000 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-66 | Terminal X30/6 Pulse Output Variable | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 5-68 | Pulse Output Max Freq #X30/6 | 5000 Hz | All set-ups | TRUE | 0 | Uint32 |
| 5-9* Bus Controlled | | | | | | |
| 5-90 | Digital & Relay Bus Control | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 5-93 | Pulse Out #27 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 5-94 | Pulse Out #27 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |
| 5-95 | Pulse Out #29 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 5-96 | Pulse Out #29 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |
| 5-97 | Pulse Out #X30/6 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 5-98 | Pulse Out #X30/6 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |

6.2.7 6-** Analog In / Out

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|--------------------------------------|---------------|-------------|-------------------------|------------------|--------|
| 6-0* Analog I/O Mode | | | | | | |
| 6-00 | Live Zero Timeout Time | 10 s | All set-ups | TRUE | 0 | Uint8 |
| 6-01 | Live Zero Timeout Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 6-02 | Fire Mode Live Zero Timeout Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 6-1* Analog Input 53 | | | | | | |
| 6-10 | Terminal 53 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 6-11 | Terminal 53 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 6-12 | Terminal 53 Low Current | 4.00 mA | All set-ups | TRUE | -5 | Int16 |
| 6-13 | Terminal 53 High Current | 20.00 mA | All set-ups | TRUE | -5 | Int16 |
| 6-14 | Terminal 53 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-15 | Terminal 53 High Ref./Feedb. Value | SR | All set-ups | TRUE | -3 | Int32 |
| 6-16 | Terminal 53 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 6-17 | Terminal 53 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 6-2* Analog Input 54 | | | | | | |
| 6-20 | Terminal 54 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 6-21 | Terminal 54 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 6-22 | Terminal 54 Low Current | 4.00 mA | All set-ups | TRUE | -5 | Int16 |
| 6-23 | Terminal 54 High Current | 20.00 mA | All set-ups | TRUE | -5 | Int16 |
| 6-24 | Terminal 54 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-25 | Terminal 54 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-26 | Terminal 54 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 6-27 | Terminal 54 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 6-3* Analog Input X30/11 | | | | | | |
| 6-30 | Terminal X30/11 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 6-31 | Terminal X30/11 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 6-34 | Term. X30/11 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-35 | Term. X30/11 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-36 | Term. X30/11 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 6-37 | Term. X30/11 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 6-4* Analog Input X30/12 | | | | | | |
| 6-40 | Terminal X30/12 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 6-41 | Terminal X30/12 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 6-44 | Term. X30/12 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-45 | Term. X30/12 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 6-46 | Term. X30/12 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 6-47 | Term. X30/12 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |

6

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|--------------------------------------|------------------|-------------|-------------------------|------------------|--------|
| 6-5* Analog Output 42 | | | | | | |
| 6-50 | Terminal 42 Output | null | All set-ups | TRUE | - | Uint8 |
| 6-51 | Terminal 42 Output Min Scale | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 6-52 | Terminal 42 Output Max Scale | 100.00 % | All set-ups | TRUE | -2 | Int16 |
| 6-53 | Terminal 42 Output Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 6-54 | Terminal 42 Output Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |
| 6-6* Analog Output X30/8 | | | | | | |
| 6-60 | Terminal X30/8 Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 6-61 | Terminal X30/8 Min. Scale | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 6-62 | Terminal X30/8 Max. Scale | 100.00 % | All set-ups | TRUE | -2 | Int16 |
| 6-63 | Terminal X30/8 Output Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 6-64 | Terminal X30/8 Output Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |

6.2.8 8- * Communication and Options

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|------------------------------|-------------------------|-------------|-------------------------|------------------|------------|
| 8-0* General Settings | | | | | | |
| 8-01 | Control Site | null | All set-ups | TRUE | - | Uint8 |
| 8-02 | Control Source | null | All set-ups | TRUE | - | Uint8 |
| 8-03 | Control Timeout Time | SR | 1 set-up | TRUE | -1 | Uint32 |
| 8-04 | Control Timeout Function | [0] Off | 1 set-up | TRUE | - | Uint8 |
| 8-05 | End-of-Timeout Function | [1] Resume set-up | 1 set-up | TRUE | - | Uint8 |
| 8-06 | Reset Control Timeout | [0] Do not reset | All set-ups | TRUE | - | Uint8 |
| 8-07 | Diagnosis Trigger | [0] Disable | 2 set-ups | TRUE | - | Uint8 |
| 8-1* Control Settings | | | | | | |
| 8-10 | Control Profile | [0] FC profile | All set-ups | TRUE | - | Uint8 |
| 8-13 | Configurable Status Word STW | [1] Profile Default | All set-ups | TRUE | - | Uint8 |
| 8-3* FC Port Settings | | | | | | |
| 8-30 | Protocol | null | 1 set-up | TRUE | - | Uint8 |
| 8-31 | Address | SR | 1 set-up | TRUE | 0 | Uint8 |
| 8-32 | Baud Rate | null | 1 set-up | TRUE | - | Uint8 |
| 8-33 | Parity / Stop Bits | null | 1 set-up | TRUE | - | Uint8 |
| 8-35 | Minimum Response Delay | SR | 1 set-up | TRUE | -3 | Uint16 |
| 8-36 | Maximum Response Delay | SR | 1 set-up | TRUE | -3 | Uint16 |
| 8-37 | Maximum Inter-Char Delay | SR | 1 set-up | TRUE | -5 | Uint16 |
| 8-4* FC MC protocol set | | | | | | |
| 8-40 | Telegram Selection | [1] Standard telegram 1 | 2 set-ups | TRUE | - | Uint8 |
| 8-5* Digital/Bus | | | | | | |
| 8-50 | Coasting Select | [3] Logic OR | All set-ups | TRUE | - | Uint8 |
| 8-52 | DC Brake Select | [3] Logic OR | All set-ups | TRUE | - | Uint8 |
| 8-53 | Start Select | [3] Logic OR | All set-ups | TRUE | - | Uint8 |
| 8-54 | Reversing Select | null | All set-ups | TRUE | - | Uint8 |
| 8-55 | Set-up Select | [3] Logic OR | All set-ups | TRUE | - | Uint8 |
| 8-56 | Preset Reference Select | [3] Logic OR | All set-ups | TRUE | - | Uint8 |
| 8-7* BACnet | | | | | | |
| 8-70 | BACnet Device Instance | 1 N/A | 1 set-up | TRUE | 0 | Uint32 |
| 8-72 | MS/TP Max Masters | 127 N/A | 1 set-up | TRUE | 0 | Uint8 |
| 8-73 | MS/TP Max Info Frames | 1 N/A | 1 set-up | TRUE | 0 | Uint16 |
| 8-74 | "I-Am" Service | [0] Send at power-up | 1 set-up | TRUE | - | Uint8 |
| 8-75 | Initialisation Password | SR | 1 set-up | TRUE | 0 | VisStr[20] |
| 8-8* FC Port Diagnostics | | | | | | |
| 8-80 | Bus Message Count | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-81 | Bus Error Count | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-82 | Slave Messages Rcvd | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-83 | Slave Error Count | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-84 | Slave Messages Sent | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-85 | Slave Timeout Errors | 0 N/A | All set-ups | TRUE | 0 | Uint32 |
| 8-89 | Diagnostics Count | 0 N/A | 1 set-up | TRUE | 0 | Uint32 |
| 8-9* Bus Jog / Feedback | | | | | | |
| 8-90 | Bus Jog 1 Speed | 100 RPM | All set-ups | TRUE | 67 | Uint16 |
| 8-91 | Bus Jog 2 Speed | 200 RPM | All set-ups | TRUE | 67 | Uint16 |
| 8-94 | Bus Feedback 1 | 0 N/A | 1 set-up | TRUE | 0 | N2 |
| 8-95 | Bus Feedback 2 | 0 N/A | 1 set-up | TRUE | 0 | N2 |
| 8-96 | Bus Feedback 3 | 0 N/A | 1 set-up | TRUE | 0 | N2 |

6.2.9 9- * * Profibus

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|------------|---------------------------|--------------------------|-------------|-------------------------|------------------|-----------|
| 9-00 | Setpoint | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-07 | Actual Value | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-15 | PCD Write Configuration | SR | 2 set-ups | TRUE | - | Uint16 |
| 9-16 | PCD Read Configuration | SR | 2 set-ups | TRUE | - | Uint16 |
| 9-18 | Node Address | 126 N/A | 1 set-up | TRUE | 0 | Uint8 |
| 9-22 | Telegram Selection | [108] PPO 8 | 1 set-up | TRUE | - | Uint8 |
| 9-23 | Parameters for Signals | 0 | All set-ups | TRUE | - | Uint16 |
| 9-27 | Parameter Edit | [1] Enabled | 2 set-ups | FALSE | - | Uint16 |
| 9-28 | Process Control | [1] Enable cyclic master | 2 set-ups | FALSE | - | Uint8 |
| 9-44 | Fault Message Counter | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-45 | Fault Code | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-47 | Fault Number | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-52 | Fault Situation Counter | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-53 | Profibus Warning Word | 0 N/A | All set-ups | TRUE | 0 | V2 |
| 9-63 | Actual Baud Rate | [255] No baudrate found | All set-ups | TRUE | - | Uint8 |
| 9-64 | Device Identification | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 9-65 | Profile Number | 0 N/A | All set-ups | TRUE | 0 | OctStr[2] |
| 9-67 | Control Word 1 | 0 N/A | All set-ups | TRUE | 0 | V2 |
| 9-68 | Status Word 1 | 0 N/A | All set-ups | TRUE | 0 | V2 |
| 9-71 | Profibus Save Data Values | [0] Off | All set-ups | TRUE | - | Uint8 |
| 9-72 | ProfibusDriveReset | [0] No action | 1 set-up | FALSE | - | Uint8 |
| 9-80 | Defined Parameters (1) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-81 | Defined Parameters (2) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-82 | Defined Parameters (3) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-83 | Defined Parameters (4) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-84 | Defined Parameters (5) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-90 | Changed Parameters (1) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-91 | Changed Parameters (2) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-92 | Changed Parameters (3) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-93 | Changed Parameters (4) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 9-94 | Changed Parameters (5) | 0 N/A | All set-ups | FALSE | 0 | Uint16 |

6.2.10 10- ** CAN Fieldbus

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-------------------------------|--------------------------------|---------------|-------------|-------------------------|------------------|--------|
| 10-0* Common Settings | | | | | | |
| 10-00 | CAN Protocol | null | 2 set-ups | FALSE | - | Uint8 |
| 10-01 | Baud Rate Select | null | 2 set-ups | TRUE | - | Uint8 |
| 10-02 | MAC ID | SR | 2 set-ups | TRUE | 0 | Uint8 |
| 10-05 | Readout Transmit Error Counter | 0 N/A | All set-ups | TRUE | 0 | Uint8 |
| 10-06 | Readout Receive Error Counter | 0 N/A | All set-ups | TRUE | 0 | Uint8 |
| 10-07 | Readout Bus Off Counter | 0 N/A | All set-ups | TRUE | 0 | Uint8 |
| 10-1* DeviceNet | | | | | | |
| 10-10 | Process Data Type Selection | null | All set-ups | TRUE | - | Uint8 |
| 10-11 | Process Data Config Write | SR | 2 set-ups | TRUE | - | Uint16 |
| 10-12 | Process Data Config Read | SR | 2 set-ups | TRUE | - | Uint16 |
| 10-13 | Warning Parameter | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 10-14 | Net Reference | [0] Off | 2 set-ups | TRUE | - | Uint8 |
| 10-15 | Net Control | [0] Off | 2 set-ups | TRUE | - | Uint8 |
| 10-2* COS Filters | | | | | | |
| 10-20 | COS Filter 1 | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 10-21 | COS Filter 2 | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 10-22 | COS Filter 3 | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 10-23 | COS Filter 4 | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 10-3* Parameter Access | | | | | | |
| 10-30 | Array Index | 0 N/A | 2 set-ups | TRUE | 0 | Uint8 |
| 10-31 | Store Data Values | [0] Off | All set-ups | TRUE | - | Uint8 |
| 10-32 | DeviceNet Revision | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 10-33 | Store Always | [0] Off | 1 set-up | TRUE | - | Uint8 |
| 10-34 | DeviceNet Product Code | 120 N/A | 1 set-up | TRUE | 0 | Uint16 |
| 10-39 | DeviceNet F Parameters | 0 N/A | All set-ups | TRUE | 0 | Uint32 |

6.2.11 11- * LonWorks

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------------------------|-----------------------|-----------------|-------------|-------------------------|------------------|-----------|
| 11-0* LonWorks ID | | | | | | |
| 11-00 | Neuron ID | 0 N/A | All set-ups | TRUE | 0 | OctStr[6] |
| 11-1* LON Functions | | | | | | |
| 11-10 | Drive Profile | [0] VSD profile | All set-ups | TRUE | - | Uint8 |
| 11-15 | LON Warning Word | 0 N/A | All set-ups | TRUE | 0 | Uint16 |
| 11-17 | XIF Revision | 0 N/A | All set-ups | TRUE | 0 | VisStr[5] |
| 11-18 | LonWorks Revision | 0 N/A | All set-ups | TRUE | 0 | VisStr[5] |
| 11-2* LON Param. Access | | | | | | |
| 11-21 | Store Data Values | [0] Off | All set-ups | TRUE | - | Uint8 |

6.2.12 13- ** Smart Logic Controller

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------|-----------------------|----------------------|-------------|-------------------------|------------------|-------|
| 13-0* SLC Settings | | | | | | |
| 13-00 | SL Controller Mode | null | 2 set-ups | TRUE | - | Uint8 |
| 13-01 | Start Event | null | 2 set-ups | TRUE | - | Uint8 |
| 13-02 | Stop Event | null | 2 set-ups | TRUE | - | Uint8 |
| 13-03 | Reset SLC | [0] Do not reset SLC | All set-ups | TRUE | - | Uint8 |
| 13-1* Comparators | | | | | | |
| 13-10 | Comparator Operand | null | 2 set-ups | TRUE | - | Uint8 |
| 13-11 | Comparator Operator | null | 2 set-ups | TRUE | - | Uint8 |
| 13-12 | Comparator Value | SR | 2 set-ups | TRUE | -3 | Int32 |
| 13-2* Timers | | | | | | |
| 13-20 | SL Controller Timer | SR | 1 set-up | TRUE | -3 | TimD |
| 13-4* Logic Rules | | | | | | |
| 13-40 | Logic Rule Boolean 1 | null | 2 set-ups | TRUE | - | Uint8 |
| 13-41 | Logic Rule Operator 1 | null | 2 set-ups | TRUE | - | Uint8 |
| 13-42 | Logic Rule Boolean 2 | null | 2 set-ups | TRUE | - | Uint8 |
| 13-43 | Logic Rule Operator 2 | null | 2 set-ups | TRUE | - | Uint8 |
| 13-44 | Logic Rule Boolean 3 | null | 2 set-ups | TRUE | - | Uint8 |
| 13-5* States | | | | | | |
| 13-51 | SL Controller Event | null | 2 set-ups | TRUE | - | Uint8 |
| 13-52 | SL Controller Action | null | 2 set-ups | TRUE | - | Uint8 |

6.2.13 14- * * Special Functions

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|----------------------------------|-------------------------------------|----------------------|-------------|-------------------------|------------------|--------|
| 14-0* Inverter Switching | | | | | | |
| 14-00 | Switching Pattern | [0] 60 AVM | All set-ups | TRUE | - | Uint8 |
| 14-01 | Switching Frequency | null | All set-ups | TRUE | - | Uint8 |
| 14-03 | Overmodulation | [1] On | All set-ups | FALSE | - | Uint8 |
| 14-04 | PWM Random | [0] Off | All set-ups | TRUE | - | Uint8 |
| 14-1* Mains On/Off | | | | | | |
| 14-10 | Mains Failure | [0] No function | All set-ups | FALSE | - | Uint8 |
| 14-11 | Mains Voltage at Mains Fault | SR | All set-ups | TRUE | 0 | Uint16 |
| 14-12 | Function at Mains Imbalance | [0] Trip | All set-ups | TRUE | - | Uint8 |
| 14-2* Reset Functions | | | | | | |
| 14-20 | Reset Mode | null | All set-ups | TRUE | - | Uint8 |
| 14-21 | Automatic Restart Time | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 14-22 | Operation Mode | [0] Normal operation | All set-ups | TRUE | - | Uint8 |
| 14-23 | Typecode Setting | null | 2 set-ups | FALSE | - | Uint8 |
| 14-25 | Trip Delay at Torque Limit | 60 s | All set-ups | TRUE | 0 | Uint8 |
| 14-26 | Trip Delay at Inverter Fault | SR | All set-ups | TRUE | 0 | Uint8 |
| 14-28 | Production Settings | [0] No action | All set-ups | TRUE | - | Uint8 |
| 14-29 | Service Code | 0 N/A | All set-ups | TRUE | 0 | Int32 |
| 14-3* Current Limit Ctrl. | | | | | | |
| 14-30 | Current Lim Ctrl, Proportional Gain | 100 % | All set-ups | FALSE | 0 | Uint16 |
| 14-31 | Current Lim Ctrl, Integration Time | 0.020 s | All set-ups | FALSE | -3 | Uint16 |
| 14-32 | Current Lim Ctrl, Filter Time | 26.0 ms | All set-ups | TRUE | -4 | Uint16 |
| 14-4* Energy Optimising | | | | | | |
| 14-40 | VT Level | 66 % | All set-ups | FALSE | 0 | Uint8 |
| 14-41 | AEO Minimum Magnetisation | SR | All set-ups | TRUE | 0 | Uint8 |
| 14-42 | Minimum AEO Frequency | 10 Hz | All set-ups | TRUE | 0 | Uint8 |
| 14-43 | Motor Cosphi | SR | All set-ups | TRUE | -2 | Uint16 |
| 14-5* Environment | | | | | | |
| 14-50 | RFI Filter | [1] On | 1 set-up | FALSE | - | Uint8 |
| 14-52 | Fan Control | [0] Auto | All set-ups | TRUE | - | Uint8 |
| 14-53 | Fan Monitor | [1] Warning | All set-ups | TRUE | - | Uint8 |
| 14-59 | Actual Number of Inverter Units | SR | 1 set-up | FALSE | 0 | Uint8 |
| 14-6* Auto Derate | | | | | | |
| 14-60 | Function at Over Temperature | [0] Trip | All set-ups | TRUE | - | Uint8 |
| 14-61 | Function at Inverter Overload | [0] Trip | All set-ups | TRUE | - | Uint8 |
| 14-62 | Inv. Overload Derate Current | 95 % | All set-ups | TRUE | 0 | Uint16 |

6.2.14 15- ** FC Information

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-----------------------------------|-----------------------------------|------------------|-------------|-------------------------|------------------|------------|
| 15-0* Operating Data | | | | | | |
| 15-00 | Operating Hours | 0 h | All set-ups | FALSE | 74 | Uint32 |
| 15-01 | Running Hours | 0 h | All set-ups | FALSE | 74 | Uint32 |
| 15-02 | kWh Counter | 0 kWh | All set-ups | FALSE | 75 | Uint32 |
| 15-03 | Power Up's | 0 N/A | All set-ups | FALSE | 0 | Uint32 |
| 15-04 | Over Temp's | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 15-05 | Over Volt's | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 15-06 | Reset kWh Counter | [0] Do not reset | All set-ups | TRUE | - | Uint8 |
| 15-07 | Reset Running Hours Counter | [0] Do not reset | All set-ups | TRUE | - | Uint8 |
| 15-08 | Number of Starts | 0 N/A | All set-ups | FALSE | 0 | Uint32 |
| 15-1* Data Log Settings | | | | | | |
| 15-10 | Logging Source | 0 | 2 set-ups | TRUE | - | Uint16 |
| 15-11 | Logging Interval | SR | 2 set-ups | TRUE | -3 | TimD |
| 15-12 | Trigger Event | [0] False | 1 set-up | TRUE | - | Uint8 |
| 15-13 | Logging Mode | [0] Log always | 2 set-ups | TRUE | - | Uint8 |
| 15-14 | Samples Before Trigger | 50 N/A | 2 set-ups | TRUE | 0 | Uint8 |
| 15-2* Historic Log | | | | | | |
| 15-20 | Historic Log: Event | 0 N/A | All set-ups | FALSE | 0 | Uint8 |
| 15-21 | Historic Log: Value | 0 N/A | All set-ups | FALSE | 0 | Uint32 |
| 15-22 | Historic Log: Time | 0 ms | All set-ups | FALSE | -3 | Uint32 |
| 15-23 | Historic Log: Date and Time | SR | All set-ups | FALSE | 0 | TimeOfDay |
| 15-3* Alarm Log | | | | | | |
| 15-30 | Alarm Log: Error Code | 0 N/A | All set-ups | FALSE | 0 | Uint8 |
| 15-31 | Alarm Log: Value | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 15-32 | Alarm Log: Time | 0 s | All set-ups | FALSE | 0 | Uint32 |
| 15-33 | Alarm Log: Date and Time | SR | All set-ups | FALSE | 0 | TimeOfDay |
| 15-4* Drive Identification | | | | | | |
| 15-40 | FC Type | 0 N/A | All set-ups | FALSE | 0 | VisStr[6] |
| 15-41 | Power Section | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-42 | Voltage | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-43 | Software Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[5] |
| 15-44 | Ordered Typecode String | 0 N/A | All set-ups | FALSE | 0 | VisStr[40] |
| 15-45 | Actual Typecode String | 0 N/A | All set-ups | FALSE | 0 | VisStr[40] |
| 15-46 | Frequency Converter Ordering No | 0 N/A | All set-ups | FALSE | 0 | VisStr[8] |
| 15-47 | Power Card Ordering No | 0 N/A | All set-ups | FALSE | 0 | VisStr[8] |
| 15-48 | LCP Id No | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-49 | SW ID Control Card | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-50 | SW ID Power Card | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-51 | Frequency Converter Serial Number | 0 N/A | All set-ups | FALSE | 0 | VisStr[10] |
| 15-53 | Power Card Serial Number | 0 N/A | All set-ups | FALSE | 0 | VisStr[19] |

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-----------------------------|---------------------------|---------------|-------------|-------------------------|------------------|------------|
| 15-6* Option Ident | | | | | | |
| 15-60 | Option Mounted | 0 N/A | All set-ups | FALSE | 0 | VisStr[30] |
| 15-61 | Option SW Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-62 | Option Ordering No | 0 N/A | All set-ups | FALSE | 0 | VisStr[8] |
| 15-63 | Option Serial No | 0 N/A | All set-ups | FALSE | 0 | VisStr[18] |
| 15-70 | Option in Slot A | 0 N/A | All set-ups | FALSE | 0 | VisStr[30] |
| 15-71 | Slot A Option SW Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-72 | Option in Slot B | 0 N/A | All set-ups | FALSE | 0 | VisStr[30] |
| 15-73 | Slot B Option SW Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-74 | Option in Slot C0 | 0 N/A | All set-ups | FALSE | 0 | VisStr[30] |
| 15-75 | Slot C0 Option SW Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-76 | Option in Slot C1 | 0 N/A | All set-ups | FALSE | 0 | VisStr[30] |
| 15-77 | Slot C1 Option SW Version | 0 N/A | All set-ups | FALSE | 0 | VisStr[20] |
| 15-9* Parameter Info | | | | | | |
| 15-92 | Defined Parameters | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 15-93 | Modified Parameters | 0 N/A | All set-ups | FALSE | 0 | Uint16 |
| 15-98 | Drive Identification | 0 N/A | All set-ups | FALSE | 0 | VisStr[40] |
| 15-99 | Parameter Metadata | 0 N/A | All set-ups | FALSE | 0 | Uint16 |

6.2.15 16- ** Data Readouts

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------------------------|-----------------------|-----------------------------|-------------|-------------------------|------------------|--------|
| 16-0* General Status | | | | | | |
| 16-00 | Control Word | 0 N/A | All set-ups | FALSE | 0 | V2 |
| 16-01 | Reference [Unit] | 0.000 ReferenceFeedbackUnit | All set-ups | FALSE | -3 | Int32 |
| 16-02 | Reference [%] | 0.0 % | All set-ups | FALSE | -1 | Int16 |
| 16-03 | Status Word | 0 N/A | All set-ups | FALSE | 0 | V2 |
| 16-05 | Main Actual Value [%] | 0.00 % | All set-ups | FALSE | -2 | N2 |
| 16-09 | Custom Readout | 0.00 CustomReadoutUnit | All set-ups | FALSE | -2 | Int32 |
| 16-1* Motor Status | | | | | | |
| 16-10 | Power [kW] | 0.00 kW | All set-ups | FALSE | 1 | Int32 |
| 16-11 | Power [hp] | 0.00 hp | All set-ups | FALSE | -2 | Int32 |
| 16-12 | Motor Voltage | 0.0 V | All set-ups | FALSE | -1 | Uint16 |
| 16-13 | Frequency | 0.0 Hz | All set-ups | FALSE | -1 | Uint16 |
| 16-14 | Motor Current | 0.00 A | All set-ups | FALSE | -2 | Int32 |
| 16-15 | Frequency [%] | 0.00 % | All set-ups | FALSE | -2 | N2 |
| 16-16 | Torque [Nm] | 0.0 Nm | All set-ups | FALSE | -1 | Int32 |
| 16-17 | Speed [RPM] | 0 RPM | All set-ups | FALSE | 67 | Int32 |
| 16-18 | Motor Thermal | 0 % | All set-ups | FALSE | 0 | Int8 |
| 16-22 | Torque [%] | 0 % | All set-ups | FALSE | 0 | Int16 |
| 16-26 | Power Filtered [kW] | 0.000 kW | All set-ups | FALSE | 0 | Int32 |
| 16-27 | Power Filtered [hp] | 0.000 hp | All set-ups | FALSE | -3 | Int32 |
| 16-3* Drive Status | | | | | | |
| 16-30 | DC Link Voltage | 0 V | All set-ups | FALSE | 0 | Uint16 |
| 16-32 | Brake Energy /s | 0.000 kW | All set-ups | FALSE | 0 | Int32 |
| 16-33 | Brake Energy /2 min | 0.000 kW | All set-ups | FALSE | 0 | Int32 |
| 16-34 | Heatsink Temp. | 0 °C | All set-ups | FALSE | 100 | Uint8 |
| 16-35 | Inverter Thermal | 0 % | All set-ups | FALSE | 0 | Uint8 |
| 16-36 | Inv. Nom. Current | SR | All set-ups | FALSE | -2 | Uint32 |
| 16-37 | Inv. Max. Current | SR | All set-ups | FALSE | -2 | Uint32 |
| 16-38 | SL Controller State | 0 N/A | All set-ups | FALSE | 0 | Int8 |
| 16-39 | Control Card Temp. | 0 °C | All set-ups | FALSE | 100 | Uint8 |
| 16-40 | Logging Buffer Full | [0] No | All set-ups | TRUE | - | Uint8 |
| 16-5* Ref. & Feedb. | | | | | | |
| 16-50 | External Reference | 0.0 N/A | All set-ups | FALSE | -1 | Int16 |
| 16-52 | Feedback [Unit] | 0.000 ProcessCtrlUnit | All set-ups | FALSE | -3 | Int32 |
| 16-53 | Digi Pot Reference | 0.00 N/A | All set-ups | FALSE | -2 | Int16 |
| 16-54 | Feedback 1 [Unit] | 0.000 ProcessCtrlUnit | All set-ups | FALSE | -3 | Int32 |
| 16-55 | Feedback 2 [Unit] | 0.000 ProcessCtrlUnit | All set-ups | FALSE | -3 | Int32 |
| 16-56 | Feedback 3 [Unit] | 0.000 ProcessCtrlUnit | All set-ups | FALSE | -3 | Int32 |
| 16-58 | PID Output [%] | 0.0 % | All set-ups | TRUE | -1 | Int16 |

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-------------------------------------|----------------------------|---------------|-------------|-------------------------|------------------|--------|
| 16-6* Inputs & Outputs | | | | | | |
| 16-60 | Digital Input | 0 N/A | All set-ups | FALSE | 0 | UInt16 |
| 16-61 | Terminal 53 Switch Setting | [0] Current | All set-ups | FALSE | - | UInt8 |
| 16-62 | Analog Input 53 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 16-63 | Terminal 54 Switch Setting | [0] Current | All set-ups | FALSE | - | UInt8 |
| 16-64 | Analog Input 54 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 16-65 | Analog Output 42 [mA] | 0.000 N/A | All set-ups | FALSE | -3 | Int16 |
| 16-66 | Digital Output [bin] | 0 N/A | All set-ups | FALSE | 0 | Int16 |
| 16-67 | Pulse Input #29 [Hz] | 0 N/A | All set-ups | FALSE | 0 | Int32 |
| 16-68 | Pulse Input #33 [Hz] | 0 N/A | All set-ups | FALSE | 0 | Int32 |
| 16-69 | Pulse Output #27 [Hz] | 0 N/A | All set-ups | FALSE | 0 | Int32 |
| 16-70 | Pulse Output #29 [Hz] | 0 N/A | All set-ups | FALSE | 0 | Int32 |
| 16-71 | Relay Output [bin] | 0 N/A | All set-ups | FALSE | 0 | Int16 |
| 16-72 | Counter A | 0 N/A | All set-ups | TRUE | 0 | Int32 |
| 16-73 | Counter B | 0 N/A | All set-ups | TRUE | 0 | Int32 |
| 16-75 | Analog In X30/11 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 16-76 | Analog In X30/12 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 16-77 | Analog Out X30/8 [mA] | 0.000 N/A | All set-ups | FALSE | -3 | Int16 |
| 16-8* Fieldbus & FC Port | | | | | | |
| 16-80 | Fieldbus CTW 1 | 0 N/A | All set-ups | FALSE | 0 | V2 |
| 16-82 | Fieldbus REF 1 | 0 N/A | All set-ups | FALSE | 0 | N2 |
| 16-84 | Comm. Option STW | 0 N/A | All set-ups | FALSE | 0 | V2 |
| 16-85 | FC Port CTW 1 | 0 N/A | All set-ups | FALSE | 0 | V2 |
| 16-86 | FC Port REF 1 | 0 N/A | All set-ups | FALSE | 0 | N2 |
| 16-9* Diagnosis Readouts | | | | | | |
| 16-90 | Alarm Word | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-91 | Alarm Word 2 | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-92 | Warning Word | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-93 | Warning Word 2 | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-94 | Ext. Status Word | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-95 | Ext. Status Word 2 | 0 N/A | All set-ups | FALSE | 0 | UInt32 |
| 16-96 | Maintenance Word | 0 N/A | All set-ups | FALSE | 0 | UInt32 |

6.2.16 18- ** Info & Readouts

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-----------------------------------|--------------------------------|----------------------|-------------|-------------------------|------------------|-----------|
| 18-0* Maintenance Log | | | | | | |
| 18-00 | Maintenance Log: Item | 0 N/A | All set-ups | FALSE | 0 | Uint8 |
| 18-01 | Maintenance Log: Action | 0 N/A | All set-ups | FALSE | 0 | Uint8 |
| 18-02 | Maintenance Log: Time | 0 s | All set-ups | FALSE | 0 | Uint32 |
| 18-03 | Maintenance Log: Date and Time | SR | All set-ups | FALSE | 0 | TimeOfDay |
| 18-1* Fire Mode Log | | | | | | |
| 18-10 | Fire Mode Log: Event | 0 N/A | All set-ups | FALSE | 0 | Uint8 |
| 18-11 | Fire Mode Log: Time | 0 s | All set-ups | FALSE | 0 | Uint32 |
| 18-12 | Fire Mode Log: Date and Time | SR | All set-ups | FALSE | 0 | TimeOfDay |
| 18-3* Inputs & Outputs | | | | | | |
| 18-30 | Analog Input X42/1 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 18-31 | Analog Input X42/3 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 18-32 | Analog Input X42/5 | 0.000 N/A | All set-ups | FALSE | -3 | Int32 |
| 18-33 | Analog Out X42/7 [V] | 0.000 N/A | All set-ups | FALSE | -3 | Int16 |
| 18-34 | Analog Out X42/9 [V] | 0.000 N/A | All set-ups | FALSE | -3 | Int16 |
| 18-35 | Analog Out X42/11 [V] | 0.000 N/A | All set-ups | FALSE | -3 | Int16 |
| 18-5* Ref. & Feedb. | | | | | | |
| 18-50 | Sensorless Readout [unit] | 0.000 SensorlessUnit | All set-ups | FALSE | -3 | Int32 |

6.2.17 20- * * FC Closed Loop

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|-----------------------------|-----------------------------|-------------|-------------------------|------------------|------------|
| 20-0* Feedback | | | | | | |
| 20-00 | Feedback 1 Source | [2] Analog input: 54 | All set-ups | TRUE | - | Uint8 |
| 20-01 | Feedback 1 Conversion | [0] Linear | All set-ups | FALSE | - | Uint8 |
| 20-02 | Feedback 1 Source Unit | null | All set-ups | TRUE | - | Uint8 |
| 20-03 | Feedback 2 Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 20-04 | Feedback 2 Conversion | [0] Linear | All set-ups | FALSE | - | Uint8 |
| 20-05 | Feedback 2 Source Unit | null | All set-ups | TRUE | - | Uint8 |
| 20-06 | Feedback 3 Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 20-07 | Feedback 3 Conversion | [0] Linear | All set-ups | FALSE | - | Uint8 |
| 20-08 | Feedback 3 Source Unit | null | All set-ups | TRUE | - | Uint8 |
| 20-12 | Reference/Feedback Unit | null | All set-ups | TRUE | - | Uint8 |
| 20-13 | Minimum Reference/Feedb. | 0.000 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 20-14 | Maximum Reference/Feedb. | 100.000 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 20-2* Feedback/Setpoint | | | | | | |
| 20-20 | Feedback Function | [3] Minimum | All set-ups | TRUE | - | Uint8 |
| 20-21 | Setpoint 1 | 0.000 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 20-22 | Setpoint 2 | 0.000 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 20-23 | Setpoint 3 | 0.000 ProcessCtrlUnit | All set-ups | TRUE | -3 | Int32 |
| 20-3* Feedb. Adv. Conv. | | | | | | |
| 20-30 | Refrigerant | [0] R22 | All set-ups | TRUE | - | Uint8 |
| 20-31 | User Defined Refrigerant A1 | 10.0000 N/A | All set-ups | TRUE | -4 | Uint32 |
| 20-32 | User Defined Refrigerant A2 | -2250.00 N/A | All set-ups | TRUE | -2 | Int32 |
| 20-33 | User Defined Refrigerant A3 | 250.000 N/A | All set-ups | TRUE | -3 | Uint32 |
| 20-6* Sensorless | | | | | | |
| 20-60 | Sensorless Unit | null | All set-ups | TRUE | - | Uint8 |
| 20-69 | Sensorless Information | 0 N/A | All set-ups | TRUE | 0 | VisStr[25] |
| 20-7* PID Autotuning | | | | | | |
| 20-70 | Closed Loop Type | [0] Auto | 2 set-ups | TRUE | - | Uint8 |
| 20-71 | PID Performance | [0] Normal | 2 set-ups | TRUE | - | Uint8 |
| 20-72 | PID Output Change | 0.10 N/A | 2 set-ups | TRUE | -2 | Uint16 |
| 20-73 | Minimum Feedback Level | -999999,000 ProcessCtrlUnit | 2 set-ups | TRUE | -3 | Int32 |
| 20-74 | Maximum Feedback Level | 999999,000 ProcessCtrlUnit | 2 set-ups | TRUE | -3 | Int32 |
| 20-79 | PID Autotuning | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 20-8* PID Basic Settings | | | | | | |
| 20-81 | PID Normal/ Inverse Control | [0] Normal | All set-ups | TRUE | - | Uint8 |
| 20-82 | PID Start Speed [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 20-83 | PID Start Speed [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 20-84 | On Reference Bandwidth | 5 % | All set-ups | TRUE | 0 | Uint8 |
| 20-9* PID Controller | | | | | | |
| 20-91 | PID Anti Windup | [1] On | All set-ups | TRUE | - | Uint8 |
| 20-93 | PID Proportional Gain | 0.50 N/A | All set-ups | TRUE | -2 | Uint16 |
| 20-94 | PID Integral Time | 20.00 s | All set-ups | TRUE | -2 | Uint32 |
| 20-95 | PID Differentiation Time | 0.00 s | All set-ups | TRUE | -2 | Uint16 |
| 20-96 | PID Diff. Gain Limit | 5.0 N/A | All set-ups | TRUE | -1 | Uint16 |

6.2.18 21- ** Ext. Closed Loop

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|-------------------------------|---------------------|-------------|-------------------------|------------------|--------|
| 21-0* Ext. CL Autotuning | | | | | | |
| 21-00 | Closed Loop Type | [0] Auto | 2 set-ups | TRUE | - | Uint8 |
| 21-01 | PID Performance | [0] Normal | 2 set-ups | TRUE | - | Uint8 |
| 21-02 | PID Output Change | 0.10 N/A | 2 set-ups | TRUE | -2 | Uint16 |
| 21-03 | Minimum Feedback Level | -99999.000 N/A | 2 set-ups | TRUE | -3 | Int32 |
| 21-04 | Maximum Feedback Level | 99999.000 N/A | 2 set-ups | TRUE | -3 | Int32 |
| 21-09 | PID Autotuning | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 21-1* Ext. CL 1 Ref./Fb. | | | | | | |
| 21-10 | Ext. 1 Ref./Feedback Unit | [1] % | All set-ups | TRUE | - | Uint8 |
| 21-11 | Ext. 1 Minimum Reference | 0.000 ExtPID1Unit | All set-ups | TRUE | -3 | Int32 |
| 21-12 | Ext. 1 Maximum Reference | 100.000 ExtPID1Unit | All set-ups | TRUE | -3 | Int32 |
| 21-13 | Ext. 1 Reference Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-14 | Ext. 1 Feedback Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-15 | Ext. 1 Setpoint | 0.000 ExtPID1Unit | All set-ups | TRUE | -3 | Int32 |
| 21-17 | Ext. 1 Reference [Unit] | 0.000 ExtPID1Unit | All set-ups | TRUE | -3 | Int32 |
| 21-18 | Ext. 1 Feedback [Unit] | 0.000 ExtPID1Unit | All set-ups | TRUE | -3 | Int32 |
| 21-19 | Ext. 1 Output [%] | 0 % | All set-ups | TRUE | 0 | Int32 |
| 21-2* Ext. CL 1 PID | | | | | | |
| 21-20 | Ext. 1 Normal/Inverse Control | [0] Normal | All set-ups | TRUE | - | Uint8 |
| 21-21 | Ext. 1 Proportional Gain | 0.01 N/A | All set-ups | TRUE | -2 | Uint16 |
| 21-22 | Ext. 1 Integral Time | 10000.00 s | All set-ups | TRUE | -2 | Uint32 |
| 21-23 | Ext. 1 Differentiation Time | 0.00 s | All set-ups | TRUE | -2 | Uint16 |
| 21-24 | Ext. 1 Dif. Gain Limit | 5.0 N/A | All set-ups | TRUE | -1 | Uint16 |
| 21-3* Ext. CL 2 Ref./Fb. | | | | | | |
| 21-30 | Ext. 2 Ref./Feedback Unit | [1] % | All set-ups | TRUE | - | Uint8 |
| 21-31 | Ext. 2 Minimum Reference | 0.000 ExtPID2Unit | All set-ups | TRUE | -3 | Int32 |
| 21-32 | Ext. 2 Maximum Reference | 100.000 ExtPID2Unit | All set-ups | TRUE | -3 | Int32 |
| 21-33 | Ext. 2 Reference Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-34 | Ext. 2 Feedback Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-35 | Ext. 2 Setpoint | 0.000 ExtPID2Unit | All set-ups | TRUE | -3 | Int32 |
| 21-37 | Ext. 2 Reference [Unit] | 0.000 ExtPID2Unit | All set-ups | TRUE | -3 | Int32 |
| 21-38 | Ext. 2 Feedback [Unit] | 0.000 ExtPID2Unit | All set-ups | TRUE | -3 | Int32 |
| 21-39 | Ext. 2 Output [%] | 0 % | All set-ups | TRUE | 0 | Int32 |
| 21-4* Ext. CL 2 PID | | | | | | |
| 21-40 | Ext. 2 Normal/Inverse Control | [0] Normal | All set-ups | TRUE | - | Uint8 |
| 21-41 | Ext. 2 Proportional Gain | 0.01 N/A | All set-ups | TRUE | -2 | Uint16 |
| 21-42 | Ext. 2 Integral Time | 10000.00 s | All set-ups | TRUE | -2 | Uint32 |
| 21-43 | Ext. 2 Differentiation Time | 0.00 s | All set-ups | TRUE | -2 | Uint16 |
| 21-44 | Ext. 2 Dif. Gain Limit | 5.0 N/A | All set-ups | TRUE | -1 | Uint16 |

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------|-------------------------------|---------------------|-------------|-------------------------|------------------|--------|
| 21-5* | Ext. CL 3 Ref./Fb. | | | | | |
| 21-50 | Ext. 3 Ref./Feedback Unit | [1] % | All set-ups | TRUE | - | Uint8 |
| 21-51 | Ext. 3 Minimum Reference | 0.000 ExtPID3Unit | All set-ups | TRUE | -3 | Int32 |
| 21-52 | Ext. 3 Maximum Reference | 100.000 ExtPID3Unit | All set-ups | TRUE | -3 | Int32 |
| 21-53 | Ext. 3 Reference Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-54 | Ext. 3 Feedback Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 21-55 | Ext. 3 Setpoint | 0.000 ExtPID3Unit | All set-ups | TRUE | -3 | Int32 |
| 21-57 | Ext. 3 Reference [Unit] | 0.000 ExtPID3Unit | All set-ups | TRUE | -3 | Int32 |
| 21-58 | Ext. 3 Feedback [Unit] | 0.000 ExtPID3Unit | All set-ups | TRUE | -3 | Int32 |
| 21-59 | Ext. 3 Output [%] | 0 % | All set-ups | TRUE | 0 | Int32 |
| 21-6* | Ext. CL 3 PID | | | | | |
| 21-60 | Ext. 3 Normal/Inverse Control | [0] Normal | All set-ups | TRUE | - | Uint8 |
| 21-61 | Ext. 3 Proportional Gain | 0.01 N/A | All set-ups | TRUE | -2 | Uint16 |
| 21-62 | Ext. 3 Integral Time | 10000.00 s | All set-ups | TRUE | -2 | Uint32 |
| 21-63 | Ext. 3 Differentiation Time | 0.00 s | All set-ups | TRUE | -2 | Uint16 |
| 21-64 | Ext. 3 Dif. Gain Limit | 5.0 N/A | All set-ups | TRUE | -1 | Uint16 |

6.2.19 22- ** Application Functions

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-------------------------------------|----------------------------|------------------------------------|-------------|-------------------------|------------------|--------|
| 22-0* Miscellaneous | | | | | | |
| 22-00 | External Interlock Delay | 0 s | All set-ups | TRUE | 0 | Uint16 |
| 22-01 | Power Filter Time | 0.50 s | 2 set-ups | TRUE | -2 | Uint16 |
| 22-2* No-Flow Detection | | | | | | |
| 22-20 | Low Power Auto Set-up | [0] Off | All set-ups | FALSE | - | Uint8 |
| 22-21 | Low Power Detection | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 22-22 | Low Speed Detection | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 22-23 | No-Flow Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 22-24 | No-Flow Delay | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-26 | Dry Pump Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 22-27 | Dry Pump Delay | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-3* No-Flow Power Tuning | | | | | | |
| 22-30 | No-Flow Power | 0.00 kW | All set-ups | TRUE | 1 | Uint32 |
| 22-31 | Power Correction Factor | 100 % | All set-ups | TRUE | 0 | Uint16 |
| 22-32 | Low Speed [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 22-33 | Low Speed [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 22-34 | Low Speed Power [kW] | SR | All set-ups | TRUE | 1 | Uint32 |
| 22-35 | Low Speed Power [HP] | SR | All set-ups | TRUE | -2 | Uint32 |
| 22-36 | High Speed [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 22-37 | High Speed [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 22-38 | High Speed Power [kW] | SR | All set-ups | TRUE | 1 | Uint32 |
| 22-39 | High Speed Power [HP] | SR | All set-ups | TRUE | -2 | Uint32 |
| 22-4* Sleep Mode | | | | | | |
| 22-40 | Minimum Run Time | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-41 | Minimum Sleep Time | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-42 | Wake-up Speed [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 22-43 | Wake-up Speed [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 22-44 | Wake-up Ref./FB Difference | 10 % | All set-ups | TRUE | 0 | Int8 |
| 22-45 | Setpoint Boost | 0 % | All set-ups | TRUE | 0 | Int8 |
| 22-46 | Maximum Boost Time | 60 s | All set-ups | TRUE | 0 | Uint16 |
| 22-5* End of Curve | | | | | | |
| 22-50 | End of Curve Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 22-51 | End of Curve Delay | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-6* Broken Belt Detection | | | | | | |
| 22-60 | Broken Belt Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 22-61 | Broken Belt Torque | 10 % | All set-ups | TRUE | 0 | Uint8 |
| 22-62 | Broken Belt Delay | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 22-7* Short Cycle Protection | | | | | | |
| 22-75 | Short Cycle Protection | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 22-76 | Interval between Starts | start_to_start_min_on_time (P2277) | All set-ups | TRUE | 0 | Uint16 |
| 22-77 | Minimum Run Time | 0 s | All set-ups | TRUE | 0 | Uint16 |

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| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------------------------|-----------------------------------|----------------|-------------|-------------------------|------------------|--------|
| 22-8* Flow Compensation | | | | | | |
| 22-80 | Flow Compensation | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 22-81 | Square-linear Curve Approximation | 100 % | All set-ups | TRUE | 0 | Uint8 |
| 22-82 | Work Point Calculation | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 22-83 | Speed at No-Flow [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 22-84 | Speed at No-Flow [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 22-85 | Speed at Design Point [RPM] | SR | All set-ups | TRUE | 67 | Uint16 |
| 22-86 | Speed at Design Point [Hz] | SR | All set-ups | TRUE | -1 | Uint16 |
| 22-87 | Pressure at No-Flow Speed | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 22-88 | Pressure at Rated Speed | 999999.999 N/A | All set-ups | TRUE | -3 | Int32 |
| 22-89 | Flow at Design Point | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 22-90 | Flow at Rated Speed | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |

6.2.20 23- ** Time Based Functions

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|--------------------------------|---------------------------|--------------------|-------------|-------------------------|------------------|-----------------|
| 23-0* Timed Actions | | | | | | |
| 23-00 | ON Time | SR | 2 set-ups | TRUE | 0 | TimeOfDayWoDate |
| 23-01 | ON Action | [0] Disabled | 2 set-ups | TRUE | - | UInt8 |
| 23-02 | OFF Time | SR | 2 set-ups | TRUE | 0 | TimeOfDayWoDate |
| 23-03 | OFF Action | [0] Disabled | 2 set-ups | TRUE | - | UInt8 |
| 23-04 | Occurrence | [0] All days | 2 set-ups | TRUE | - | UInt8 |
| 23-1* Maintenance | | | | | | |
| 23-10 | Maintenance Item | [1] Motor bearings | 1 set-up | TRUE | - | UInt8 |
| 23-11 | Maintenance Action | [1] Lubricate | 1 set-up | TRUE | - | UInt8 |
| 23-12 | Maintenance Time Base | [0] Disabled | 1 set-up | TRUE | - | UInt8 |
| 23-13 | Maintenance Time Interval | 1 h | 1 set-up | TRUE | 74 | UInt32 |
| 23-14 | Maintenance Date and Time | SR | 1 set-up | TRUE | 0 | TimeOfDay |
| 23-1* Maintenance Reset | | | | | | |
| 23-15 | Reset Maintenance Word | [0] Do not reset | All set-ups | TRUE | - | UInt8 |
| 23-16 | Maintenance Text | 0 N/A | 1 set-up | TRUE | 0 | VisStr[20] |
| 23-5* Energy Log | | | | | | |
| 23-50 | Energy Log Resolution | [5] Last 24 Hours | 2 set-ups | TRUE | - | UInt8 |
| 23-51 | Period Start | SR | 2 set-ups | TRUE | 0 | TimeOfDay |
| 23-53 | Energy Log | 0 N/A | All set-ups | TRUE | 0 | UInt32 |
| 23-54 | Reset Energy Log | [0] Do not reset | All set-ups | TRUE | - | UInt8 |
| 23-6* Trending | | | | | | |
| 23-60 | Trend Variable | [0] Power [kW] | 2 set-ups | TRUE | - | UInt8 |
| 23-61 | Continuous Bin Data | 0 N/A | All set-ups | TRUE | 0 | UInt32 |
| 23-62 | Timed Bin Data | 0 N/A | All set-ups | TRUE | 0 | UInt32 |
| 23-63 | Timed Period Start | SR | 2 set-ups | TRUE | 0 | TimeOfDay |
| 23-64 | Timed Period Stop | SR | 2 set-ups | TRUE | 0 | TimeOfDay |
| 23-65 | Minimum Bin Value | SR | 2 set-ups | TRUE | 0 | UInt8 |
| 23-66 | Reset Continuous Bin Data | [0] Do not reset | All set-ups | TRUE | - | UInt8 |
| 23-67 | Reset Timed Bin Data | [0] Do not reset | All set-ups | TRUE | - | UInt8 |
| 23-8* Payback Counter | | | | | | |
| 23-80 | Power Reference Factor | 100 % | 2 set-ups | TRUE | 0 | UInt8 |
| 23-81 | Energy Cost | 1.00 N/A | 2 set-ups | TRUE | -2 | UInt32 |
| 23-82 | Investment | 0 N/A | 2 set-ups | TRUE | 0 | UInt32 |
| 23-83 | Energy Savings | 0 kWh | All set-ups | TRUE | 75 | Int32 |
| 23-84 | Cost Savings | 0 N/A | All set-ups | TRUE | 0 | Int32 |

6.2.21 24- * Application Functions 2

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|-----------------------------|---------------------------|-------------|-------------------------|------------------|--------|
| 24-0* Fire Mode | | | | | | |
| 24-00 | Fire Mode Function | [0] Disabled | 2 set-ups | TRUE | - | Uint8 |
| 24-01 | Fire Mode Configuration | [0] Open Loop | All set-ups | TRUE | - | Uint8 |
| 24-02 | Fire Mode Unit | null | All set-ups | TRUE | - | Uint8 |
| 24-03 | Fire Mode Min Reference | SR | All set-ups | TRUE | -3 | Int32 |
| 24-04 | Fire Mode Max Reference | SR | All set-ups | TRUE | -3 | Int32 |
| 24-05 | Fire Mode Preset Reference | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 24-06 | Fire Mode Reference Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 24-07 | Fire Mode Feedback Source | [0] No function | All set-ups | TRUE | - | Uint8 |
| 24-09 | Fire Mode Alarm Handling | [1] Trip, Critical Alarms | 2 set-ups | FALSE | - | Uint8 |
| 24-1* Drive Bypass | | | | | | |
| 24-10 | Drive Bypass Function | [0] Disabled | 2 set-ups | TRUE | - | Uint8 |
| 24-11 | Drive Bypass Delay Time | 0 s | 2 set-ups | TRUE | 0 | Uint16 |
| 24-9* Multi-Motor Funct. | | | | | | |
| 24-90 | Missing Motor Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 24-91 | Missing Motor Coefficient 1 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-92 | Missing Motor Coefficient 2 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-93 | Missing Motor Coefficient 3 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-94 | Missing Motor Coefficient 4 | 0.0000 N/A | All set-ups | TRUE | -3 | Int32 |
| 24-95 | Locked Rotor Function | [0] Off | All set-ups | TRUE | - | Uint8 |
| 24-96 | Locked Rotor Coefficient 1 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-97 | Locked Rotor Coefficient 2 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-98 | Locked Rotor Coefficient 3 | 0.0000 N/A | All set-ups | TRUE | -4 | Int32 |
| 24-99 | Locked Rotor Coefficient 4 | 0.0000 N/A | All set-ups | TRUE | -3 | Int32 |

6.2.22 25- ** Cascade Controller

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|-----------------------------------|-----------------------------|---------------------------------|-------------|-------------------------|------------------|-----------------|
| 25-0* System Settings | | | | | | |
| 25-00 | Cascade Controller | [0] Disabled | 2 set-ups | FALSE | - | Uint8 |
| 25-02 | Motor Start | [0] Direct on Line | 2 set-ups | FALSE | - | Uint8 |
| 25-04 | Pump Cycling | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 25-05 | Fixed Lead Pump | [1] Yes | 2 set-ups | FALSE | - | Uint8 |
| 25-06 | Number of Pumps | 2 N/A | 2 set-ups | FALSE | 0 | Uint8 |
| 25-2* Bandwidth Settings | | | | | | |
| 25-20 | Staging Bandwidth | 10 % | All set-ups | TRUE | 0 | Uint8 |
| 25-21 | Override Bandwidth | 100 % | All set-ups | TRUE | 0 | Uint8 |
| 25-22 | Fixed Speed Bandwidth | casco_staging_bandwidth (P2520) | All set-ups | TRUE | 0 | Uint8 |
| 25-23 | SBW Staging Delay | 15 s | All set-ups | TRUE | 0 | Uint16 |
| 25-24 | SBW Destaging Delay | 15 s | All set-ups | TRUE | 0 | Uint16 |
| 25-25 | OBW Time | 10 s | All set-ups | TRUE | 0 | Uint16 |
| 25-26 | Destage At No-Flow | [0] Disabled | All set-ups | TRUE | - | Uint8 |
| 25-27 | Stage Function | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 25-28 | Stage Function Time | 15 s | All set-ups | TRUE | 0 | Uint16 |
| 25-29 | Destage Function | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 25-30 | Destage Function Time | 15 s | All set-ups | TRUE | 0 | Uint16 |
| 25-4* Staging Settings | | | | | | |
| 25-40 | Ramp Down Delay | 10.0 s | All set-ups | TRUE | -1 | Uint16 |
| 25-41 | Ramp Up Delay | 2.0 s | All set-ups | TRUE | -1 | Uint16 |
| 25-42 | Staging Threshold | SR | All set-ups | TRUE | 0 | Uint8 |
| 25-43 | Destaging Threshold | SR | All set-ups | TRUE | 0 | Uint8 |
| 25-44 | Staging Speed [RPM] | 0 RPM | All set-ups | TRUE | 67 | Uint16 |
| 25-45 | Staging Speed [Hz] | 0.0 Hz | All set-ups | TRUE | -1 | Uint16 |
| 25-46 | Destaging Speed [RPM] | 0 RPM | All set-ups | TRUE | 67 | Uint16 |
| 25-47 | Destaging Speed [Hz] | 0.0 Hz | All set-ups | TRUE | -1 | Uint16 |
| 25-5* Alternation Settings | | | | | | |
| 25-50 | Lead Pump Alternation | [0] Off | All set-ups | TRUE | - | Uint8 |
| 25-51 | Alternation Event | [0] External | All set-ups | TRUE | - | Uint8 |
| 25-52 | Alternation Time Interval | 24 h | All set-ups | TRUE | 74 | Uint16 |
| 25-53 | Alternation Timer Value | 0 N/A | All set-ups | TRUE | 0 | VisStrf[7] |
| 25-54 | Alternation Predefined Time | SR | All set-ups | TRUE | 0 | TimeOfDayWoDate |
| 25-55 | Alternate if Load < 50% | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 25-56 | Staging Mode at Alternation | [0] Slow | All set-ups | TRUE | - | Uint8 |
| 25-58 | Run Next Pump Delay | 0.1 s | All set-ups | TRUE | -1 | Uint16 |
| 25-59 | Run on Mains Delay | 0.5 s | All set-ups | TRUE | -1 | Uint16 |

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| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|----------------------|-----------------------|------------------|-------------|-------------------------|------------------|-------------|
| 25-8* Status | | | | | | |
| 25-80 | Cascade Status | 0 N/A | All set-ups | TRUE | 0 | VisStrf[25] |
| 25-81 | Pump Status | 0 N/A | All set-ups | TRUE | 0 | VisStrf[25] |
| 25-82 | Lead Pump | 0 N/A | All set-ups | TRUE | 0 | Uint8 |
| 25-83 | Relay Status | 0 N/A | All set-ups | TRUE | 0 | VisStrf[4] |
| 25-84 | Pump ON Time | 0 h | All set-ups | TRUE | 74 | Uint32 |
| 25-85 | Relay ON Time | 0 h | All set-ups | TRUE | 74 | Uint32 |
| 25-86 | Reset Relay Counters | [0] Do not reset | All set-ups | TRUE | - | Uint8 |
| 25-9* Service | | | | | | |
| 25-90 | Pump Interlock | [0] Off | All set-ups | TRUE | - | Uint8 |
| 25-91 | Manual Alternation | 0 N/A | All set-ups | TRUE | 0 | Uint8 |

6.2.23 26- ** Analog I / O Option MCB 109

| Par. No. # | Parameter description | Default value | 4-set-up | Change during operation | Conversion index | Type |
|---------------------------------|------------------------------------|------------------|-------------|-------------------------|------------------|--------|
| 26-0* Analog I/O Mode | | | | | | |
| 26-00 | Terminal X42/1 Mode | [1] Voltage | All set-ups | TRUE | - | Uint8 |
| 26-01 | Terminal X42/3 Mode | [1] Voltage | All set-ups | TRUE | - | Uint8 |
| 26-02 | Terminal X42/5 Mode | [1] Voltage | All set-ups | TRUE | - | Uint8 |
| 26-1* Analog Input X42/1 | | | | | | |
| 26-10 | Terminal X42/1 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 26-11 | Terminal X42/1 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 26-14 | Term. X42/1 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-15 | Term. X42/1 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-16 | Term. X42/1 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 26-17 | Term. X42/1 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 26-2* Analog Input X42/3 | | | | | | |
| 26-20 | Terminal X42/3 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 26-21 | Terminal X42/3 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 26-24 | Term. X42/3 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-25 | Term. X42/3 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-26 | Term. X42/3 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 26-27 | Term. X42/3 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 26-3* Analog Input X42/5 | | | | | | |
| 26-30 | Terminal X42/5 Low Voltage | 0.07 V | All set-ups | TRUE | -2 | Int16 |
| 26-31 | Terminal X42/5 High Voltage | 10.00 V | All set-ups | TRUE | -2 | Int16 |
| 26-34 | Term. X42/5 Low Ref./Feedb. Value | 0.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-35 | Term. X42/5 High Ref./Feedb. Value | 100.000 N/A | All set-ups | TRUE | -3 | Int32 |
| 26-36 | Term. X42/5 Filter Time Constant | 0.001 s | All set-ups | TRUE | -3 | Uint16 |
| 26-37 | Term. X42/5 Live Zero | [1] Enabled | All set-ups | TRUE | - | Uint8 |
| 26-4* Analog Out X42/7 | | | | | | |
| 26-40 | Terminal X42/7 Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 26-41 | Terminal X42/7 Min. Scale | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-42 | Terminal X42/7 Max. Scale | 100.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-43 | Terminal X42/7 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 26-44 | Terminal X42/7 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |
| 26-5* Analog Out X42/9 | | | | | | |
| 26-50 | Terminal X42/9 Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 26-51 | Terminal X42/9 Min. Scale | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-52 | Terminal X42/9 Max. Scale | 100.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-53 | Terminal X42/9 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 26-54 | Terminal X42/9 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |
| 26-6* Analog Out X42/11 | | | | | | |
| 26-60 | Terminal X42/11 Output | [0] No operation | All set-ups | TRUE | - | Uint8 |
| 26-61 | Terminal X42/11 Min. Scale | 0.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-62 | Terminal X42/11 Max. Scale | 100.00 % | All set-ups | TRUE | -2 | Int16 |
| 26-63 | Terminal X42/11 Bus Control | 0.00 % | All set-ups | TRUE | -2 | N2 |
| 26-64 | Terminal X42/11 Timeout Preset | 0.00 % | 1 set-up | TRUE | -2 | Uint16 |

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7 Troubleshooting

7.1 Alarms and warnings

7.1.1 Alarms and warnings

A warning or an alarm is signalled by the relevant LED on the front of the frequency converter and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the frequency converter will have tripped. Alarms must be reset to restart operation once their cause has been rectified.

This may be done in four ways:

1. By using the [RESET] control button on the LCP control panel.
2. Via a digital input with the "Reset" function.
3. Via serial communication/optional fieldbus.
4. By resetting automatically using the [Auto Reset] function, which is a default setting for VLT AQUA Drive. see par. 14-20 *Reset Mode* in VLT AQUA Drive Programming Guide



NB!

After a manual reset using the [RESET] button on the LCP, the [AUTO ON] or [HAND ON] button must be pressed to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also table on following page).

Alarms that are trip-locked offer additional protection, means that the mains supply must be switched off before the alarm can be reset. After being switched back on, the frequency converter is no longer blocked and may be reset as described above once the cause has been rectified.

Alarms that are not trip-locked can also be reset using the automatic reset function in par. 14-20 *Reset Mode* (Warning: automatic wake-up is possible!)

If a warning and alarm is marked against a code in the table on the following page, this means that either a warning occurs before an alarm, or it can be specified whether it is a warning or an alarm that is to be displayed for a given fault.

This is possible, for instance, in par.1-90 *Motor Thermal Protection*. After an alarm or trip, the motor carries on coasting, and the alarm and warning flash on the frequency converter. Once the problem has been rectified, only the alarm continues flashing.

| No. | Description | Warning | Alarm/Trip | Alarm/Trip Lock | Parameter Reference |
|-----|--|---------|-----------------|-----------------|---------------------|
| 1 | 10 Volts low | X | | | |
| 2 | Live zero error | (X) | (X) | | 6-01 |
| 3 | No motor | (X) | | | 1-80 |
| 4 | Mains phase loss | (X) | (X) | (X) | 14-12 |
| 5 | DC link voltage high | X | | | |
| 6 | DC link voltage low | X | | | |
| 7 | DC over voltage | X | X | | |
| 8 | DC under voltage | X | X | | |
| 9 | Inverter overloaded | X | X | | |
| 10 | Motor ETR over temperature | (X) | (X) | | 1-90 |
| 11 | Motor thermistor over temperature | (X) | (X) | | 1-90 |
| 12 | Torque limit | X | X | | |
| 13 | Over Current | X | X | X | |
| 14 | Earth fault | X | X | X | |
| 15 | Hardware mismatch | | X | X | |
| 16 | Short Circuit | | X | X | |
| 17 | Control word timeout | (X) | (X) | | 8-04 |
| 23 | Internal Fan Fault | X | | | |
| 24 | External Fan Fault | X | | | 14-53 |
| 25 | Brake resistor short-circuited | X | | | |
| 26 | Brake resistor power limit | (X) | (X) | | 2-13 |
| 27 | Brake chopper short-circuited | X | X | | |
| 28 | Brake check | (X) | (X) | | 2-15 |
| 29 | Drive over temperature | X | X | X | |
| 30 | Motor phase U missing | (X) | (X) | (X) | 4-58 |
| 31 | Motor phase V missing | (X) | (X) | (X) | 4-58 |
| 32 | Motor phase W missing | (X) | (X) | (X) | 4-58 |
| 33 | Inrush fault | | X | X | |
| 34 | Fieldbus communication fault | X | X | | |
| 35 | Out of frequency range | X | X | | |
| 36 | Mains failure | X | X | | |
| 37 | Phase Imbalance | X | X | | |
| 38 | Internal fault | | X | X | |
| 39 | Heatsink sensor | | X | X | |
| 40 | Overload of Digital Output Terminal 27 | (X) | | | 5-00, 5-01 |
| 41 | Overload of Digital Output Terminal 29 | (X) | | | 5-00, 5-02 |
| 42 | Overload of Digital Output On X30/6 | (X) | | | 5-32 |
| 42 | Overload of Digital Output On X30/7 | (X) | | | 5-33 |
| 46 | Pwr. card supply | | X | X | |
| 47 | 24 V supply low | X | X | X | |
| 48 | 1.8 V supply low | | X | X | |
| 49 | Speed limit | X | | | |
| 50 | AMA calibration failed | | X | | |
| 51 | AMA check U_{nom} and I_{nom} | | X | | |
| 52 | AMA low I_{nom} | | X | | |
| 53 | AMA motor too big | | X | | |
| 54 | AMA motor too small | | X | | |
| 55 | AMA parameter out of range | | X | | |
| 56 | AMA interrupted by user | | X | | |
| 57 | AMA timeout | | X | | |
| 58 | AMA internal fault | X | X | | |
| 59 | Current limit | X | | | |
| 60 | External Interlock | X | | | |
| 62 | Output Frequency at Maximum Limit | X | | | |
| 64 | Voltage Limit | X | | | |
| 65 | Control Board Over-temperature | X | X | X | |
| 66 | Heat sink Temperature Low | X | | | |
| 67 | Option Configuration has Changed | | X | | |
| 68 | Safe Stop Activated | | X ¹⁾ | | |
| 69 | Pwr. Card Temp | | X | X | |
| 70 | Illegal FC configuration | | | X | |
| 71 | PTC 1 Safe Stop | X | X ¹⁾ | | |
| 72 | Dangerous Failure | | | X ¹⁾ | |
| 73 | Safe Stop Auto Restart | | | | |
| 79 | Illegal PS config | | X | X | |
| 80 | Drive Initialised to Default Value | | X | | |
| 91 | Analog input 54 wrong settings | | | X | |
| 92 | NoFlow | X | X | | 22-2* |
| 93 | Dry Pump | X | X | | 22-2* |
| 94 | End of Curve | X | X | | 22-5* |
| 95 | Broken Belt | X | X | | 22-6* |
| 96 | Start Delayed | X | | | 22-7* |
| 97 | Stop Delayed | X | | | 22-7* |
| 98 | Clock Fault | X | | | 0-7* |

Table 7.1: Alarm/Warning code list

| No. | Description | Warning | Alarm/Trip | Alarm/Trip Lock | Parameter Reference |
|-----|------------------------|---------|------------|-----------------|---------------------|
| 201 | Fire M was Active | | | | |
| 202 | Fire M Limits Exceeded | | | | |
| 203 | Missing Motor | | | | |
| 204 | Locked Rotor | | | | |
| 243 | Brake IGBT | X | X | | |
| 244 | Heatsink temp | X | X | X | |
| 245 | Heatsink sensor | | X | X | |
| 246 | Pwr.card supply | | X | X | |
| 247 | Pwr.card temp | | X | X | |
| 248 | Illegal PS config | | X | X | |
| 250 | New spare part | | | X | |
| 251 | New Type Code | | X | X | |

Table 7.2: Alarm/Warning code list

(X) Dependent on parameter

1) Can not be Auto reset via par. 14-20 *Reset Mode*

A trip is the action when an alarm has appeared. The trip will coast the motor and can be reset by pressing the reset button or make a reset by a digital input (Parameter group 5-1* [1]). The origin event that caused an alarm cannot damage the frequency converter or cause dangerous conditions. A trip lock is an action when an alarm occurs, which may cause damage to frequency converter or connected parts. A Trip Lock situation can only be reset by a power cycling.

| LED indication | |
|----------------|----------------|
| Warning | yellow |
| Alarm | flashing red |
| Trip locked | yellow and red |



| Alarm Word and Extended Status Word | | | | | |
|-------------------------------------|----------|------------|-------------------|------------------|----------------------|
| Bit | Hex | Dec | Alarm Word | Warning Word | Extended Status Word |
| 0 | 00000001 | 1 | Brake Check | Brake Check | Ramping |
| 1 | 00000002 | 2 | Pwr. Card Temp | Pwr. Card Temp | AMA Running |
| 2 | 00000004 | 4 | Earth Fault | Earth Fault | Start CW/CCW |
| 3 | 00000008 | 8 | Ctrl.Card Temp | Ctrl.Card Temp | Slow Down |
| 4 | 00000010 | 16 | Ctrl. Word TO | Ctrl. Word TO | Catch Up |
| 5 | 00000020 | 32 | Over Current | Over Current | Feedback High |
| 6 | 00000040 | 64 | Torque Limit | Torque Limit | Feedback Low |
| 7 | 00000080 | 128 | Motor Th Over | Motor Th Over | Output Current High |
| 8 | 00000100 | 256 | Motor ETR Over | Motor ETR Over | Output Current Low |
| 9 | 00000200 | 512 | Inverter Overld. | Inverter Overld. | Output Freq High |
| 10 | 00000400 | 1024 | DC under Volt | DC under Volt | Output Freq Low |
| 11 | 00000800 | 2048 | DC over Volt | DC over Volt | Brake Check OK |
| 12 | 00001000 | 4096 | Short Circuit | DC Voltage Low | Braking Max |
| 13 | 00002000 | 8192 | Inrush Fault | DC Voltage High | Braking |
| 14 | 00004000 | 16384 | Mains ph. Loss | Mains ph. Loss | Out of Speed Range |
| 15 | 00008000 | 32768 | AMA Not OK | No Motor | OVC Active |
| 16 | 00010000 | 65536 | Live Zero Error | Live Zero Error | |
| 17 | 00020000 | 131072 | Internal Fault | 10V Low | |
| 18 | 00040000 | 262144 | Brake Overload | Brake Overload | |
| 19 | 00080000 | 524288 | U phase Loss | Brake Resistor | |
| 20 | 00100000 | 1048576 | V phase Loss | Brake IGBT | |
| 21 | 00200000 | 2097152 | W phase Loss | Speed Limit | |
| 22 | 00400000 | 4194304 | Fieldbus Fault | Fieldbus Fault | |
| 23 | 00800000 | 8388608 | 24 V Supply Low | 24V Supply Low | |
| 24 | 01000000 | 16777216 | Mains Failure | Mains Failure | |
| 25 | 02000000 | 33554432 | 1.8V Supply Low | Current Limit | |
| 26 | 04000000 | 67108864 | Brake Resistor | Low Temp | |
| 27 | 08000000 | 134217728 | Brake IGBT | Voltage Limit | |
| 28 | 10000000 | 268435456 | Option Change | Unused | |
| 29 | 20000000 | 536870912 | Drive Initialised | Unused | |
| 30 | 40000000 | 1073741824 | Safe Stop | Unused | |

Table 7.3: Description of Alarm Word, Warning Word and Extended Status Word

The alarm words, warning words and extended status words can be read out via serial bus or optional fieldbus for diagnosis. See also par. 16-90 *Alarm Word*, par. 16-92 *Warning Word* and par. 16-94 *Ext. Status Word*.

7.1.2 Fault messages

WARNING 1, 10 volts low

The control card voltage is below 10 V from terminal 50.

Remove some of the load from terminal 50, as the 10 V supply is overloaded. Max. 15 mA or minimum 590 Ω.

This condition can be caused by a short in a connected potentiometer or improper wiring of the potentiometer.

Troubleshooting: Remove the wiring from terminal 50. If the warning clears, the problem is with the customer wiring. If the warning does not clear, replace the control card.

WARNING/ALARM 2, Live zero error

This warning or alarm will only appear if programmed by the user in parameter 6-01, Live Zero Timeout Function. The signal on one of the analog inputs is less than 50% of the minimum value programmed for that input. This condition can be caused by broken wiring or faulty device sending the signal.

Troubleshooting:

Check connections on all the analog input terminals. Control card terminals 53 and 54 for signals, terminal 55 common. MCB 101 terminals 11 and 12 for signals, terminal 10 common. MCB 109 terminals 1, 3, 5 for signals, terminals 2, 4, 6 common).

Check that the drive programming and switch settings match the analog signal type.

Perform Input Terminal Signal Test.

WARNING/ALARM 3, No motor

No motor has been connected to the output of the frequency converter. This warning or alarm will only appear if programmed by the user in parameter 1-80, Function at Stop.

Troubleshooting: Check the connection between the drive and the motor.

WARNING/ALARM 4, Mains phase loss

A phase is missing on the supply side, or the mains voltage imbalance is too high. This message also appears for a fault in the input rectifier on the frequency converter. Options are programmed at parameter 14-12, Function at Mains Imbalance

Troubleshooting: Check the supply voltage and supply currents to the frequency converter.

WARNING 5, DC link voltage high

The intermediate circuit voltage (DC) is higher than the high voltage warning limit. The limit is dependent on the drive voltage rating. The frequency converter is still active.

WARNING 6, DC link voltage low

The intermediate circuit voltage (DC) is lower than the low voltage warning limit. The limit is dependent on the drive voltage rating. The frequency converter is still active.

WARNING/ALARM 7, DC overvoltage

If the intermediate circuit voltage exceeds the limit, the frequency converter trips after a time.

Troubleshooting:

Connect a brake resistor

Extend the ramp time

Change the ramp type

Activate functions in par. 2-10 *Brake Function*

Increase par. 14-26 *Trip Delay at Inverter Fault*

WARNING/ALARM 8, DC under voltage

If the intermediate circuit voltage (DC) drops below the under voltage limit, the frequency converter checks if a 24 V backup supply is connected. If no 24 V backup supply is connected, the frequency converter trips after a fixed time delay. The time delay varies with unit size.

Troubleshooting:

Check that the supply voltage matches the frequency converter voltage.

Perform Input voltage test

Perform soft charge and rectifier circuit test

WARNING/ALARM 9, Inverter overloaded

The frequency converter is about to cut out because of an overload (too high current for too long). The counter for electronic, thermal inverter protection gives a warning at 98% and trips at 100%, while giving an alarm. The frequency converter *cannot* be reset until the counter is below 90%.

The fault is that the frequency converter is overloaded by more than 100% for too long.

Troubleshooting:

Compare the output current shown on the LCP keypad with the drive rated current.

Compare the output current shown on the LCP keypad with measured motor current.

Display the Thermal Drive Load on the keypad and monitor the value. When running above the drive continuous current rating, the counter should increase. When running below the drive continuous current rating, the counter should decrease.

Note: See the derating section in the Design Guide for more details if a high switching frequency is required.

WARNING/ALARM 10, Motor overload temperature

According to the electronic thermal protection (ETR), the motor is too hot. Select whether the frequency converter gives a warning or an alarm when the counter reaches 100% in par. 1-90 *Motor Thermal Protection*. The fault is that the motor is overloaded by more than 100% for too long.

Troubleshooting:

Check if motor is over heating.

If the motor is mechanically overloaded

That the motor par. 1-24 *Motor Current* is set correctly.

Motor data in parameters 1-20 through 1-25 are set correctly.

The setting in parameter 1-91, Motor External Fan.

Run AMA in parameter 1-29.

WARNING/ALARM 11, Motor thermistor over temp

The thermistor or the thermistor connection is disconnected. Select whether the frequency converter gives a warning or an alarm when the counter reaches 100% in par. 1-90 *Motor Thermal Protection*.

Troubleshooting:

Check if motor is over heating.

Check if the motor is mechanically overloaded.

Check that the thermistor is connected correctly between terminal 53 or 54 (analog voltage input) and terminal 50 (+10 V supply), or between terminal 18 or 19 (digital input PNP only) and terminal 50.

If a KTY sensor is used, check for correct connection between terminal 54 and 55.

If using a thermal switch or thermistor, check the programming of parameter 1-93 matches sensor wiring.

If using a KTY sensor, check the programming of parameters 1-95, 1-96, and 1-97 match sensor wiring.

WARNING/ALARM 12, Torque limit

The torque is higher than the value in par. 4-16 *Torque Limit Motor Mode* (in motor operation) or the torque is higher than the value in par. 4-17 *Torque Limit Generator Mode* (in regenerative operation). Parameter 14-25 can be used to change this from a warning only condition to a warning followed by an alarm.

WARNING/ALARM 13, Over Current

The inverter peak current limit (approx. 200% of the rated current) is exceeded. The warning lasts about 1.5 sec., then the frequency converter trips and issues an alarm. If extended mechanical brake control is selected, trip can be reset externally.

Troubleshooting:

This fault may be caused by shock loading or fast acceleration with high inertia loads.

Turn off the frequency converter. Check if the motor shaft can be turned.

Check that the motor size matches the frequency converter.

Incorrect motor data in parameters 1-20 through 1-25.

ALARM 14, Earth (ground) fault

There is a discharge from the output phases to earth, either in the cable between the frequency converter and the motor or in the motor itself.

Troubleshooting:

Turn off the frequency converter and remove the earth fault.

Measure the resistance to ground of the motor leads and the motor with a megohmmeter to check for earth faults in the motor.

Perform current sensor test.

ALARM 15, Hardware mismatch

A fitted option is not operational with the present control board hardware or software.

Record the value of the following parameters and contact your Danfoss supplier:

- 15-40 FC Type
- 15-41 Power Section
- 15-42 Voltage
- 15-43 Software Version
- 15-45 Actual Typecode String
- 15-49 SW ID Control Card
- 15-50 SW ID Power Card
- 15-60 Option Mounted (for each option slot)
- 15-61 Option SW Version (for each option slot)

ALARM 16, Short circuit

There is short-circuiting in the motor or on the motor terminals. Turn off the frequency converter and remove the short-circuit.

WARNING/ALARM 17, Control word timeout

There is no communication to the frequency converter.

The warning will only be active when par. 8-04 *Control Word Timeout Function* is NOT set to OFF.

If par. 8-04 *Control Word Timeout Function* is set to *Stop* and *Trip*, a warning appears and the frequency converter ramps down until it trips, while giving an alarm.

Troubleshooting:

Check connections on the serial communication cable.

Increase par. 8-03 *Control Word Timeout Time*

Check operation of the communication equipment.

Verify proper installation based on EMC requirements.

WARNING 23, Internal fan fault

The fan warning function is an extra protection function that checks if the fan is running / mounted. The fan warning can be disabled in par. 14-53 *Fan Monitor* ([0] Disabled).

For the D, E, and F Frame drives, the regulated voltage to the fans is monitored.

Troubleshooting:

Check fan resistance.

Check soft charge fuses.

WARNING 24, External fan fault

The fan warning function is an extra protection function that checks if the fan is running / mounted. The fan warning can be disabled in par. 14-53 *Fan Monitor* ([0] Disabled).

For the D, E, and F Frame drives, the regulated voltage to the fans is monitored.

Troubleshooting:

Check fan resistance.

Check soft charge fuses.

WARNING 25, Brake resistor short circuit

The brake resistor is monitored during operation. If it short circuits, the brake function is disconnected and the warning appears. The frequency converter still works, but without the brake function. Turn off the frequency converter and replace the brake resistor (see par. 2-15 *Brake Check*).

WARNING/ALARM 26, Brake resistor power limit

The power transmitted to the brake resistor is calculated: as a percentage, as a mean value over the last 120 seconds, on the basis of the resistance value of the brake resistor, and the intermediate circuit voltage. The warning is active when the dissipated braking power is higher than 90%. If *Trip* [2] has been selected in par. 2-13 *Brake Power Monitoring*, the frequency converter cuts out and issues this alarm, when the dissipated braking power is higher than 100%.



Warning: There is a risk of substantial power being transmitted to the brake resistor if the brake transistor is short-circuited.

WARNING/ALARM 27, Brake chopper fault

The brake transistor is monitored during operation and if it short-circuits, the brake function disconnects and issues a warning. The frequency converter is still able to run, but since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive. Turn off the frequency converter and remove the brake resistor. This alarm/ warning could also occur should the brake resistor overheat. Terminal 104 to 106 are available as brake resistor. Klixon inputs, see section Brake Resistor Temperature Switch.

WARNING/ALARM 28, Brake check failed

Brake resistor fault: the brake resistor is not connected or not working. Check parameter 2-15, Brake Check.

ALARM 29, Heatsink temp

The maximum temperature of the heatsink has been exceeded. The temperature fault will not be reset until the temperature falls below a defined heatsink temperature. The trip and reset point are different based on the drive power size.

Troubleshooting:

- Ambient temperature too high.
- Too long motor cable.
- Incorrect clearance above and below the drive.
- Dirty heatsink.
- Blocked air flow around the drive.
- Damaged heatsink fan.

For the D, E, and F Frame Drives, this alarm is based on the temperature measured by the heatsink sensor mounted inside the IGBT modules. For the F Frame drives, this alarm can also be caused by the thermal sensor in the Rectifier module.

Troubleshooting:

- Check fan resistance.
- Check soft charge fuses.
- IGBT thermal sensor.

ALARM 30, Motor phase U missing

Motor phase U between the frequency converter and the motor is missing. Turn off the frequency converter and check motor phase U.

ALARM 31, Motor phase V missing

Motor phase V between the frequency converter and the motor is missing. Turn off the frequency converter and check motor phase V.

ALARM 32, Motor phase W missing

Motor phase W between the frequency converter and the motor is missing. Turn off the frequency converter and check motor phase W.

ALARM 33, Inrush fault

Too many power-ups have occurred within a short time period. Let unit cool to operating temperature.

WARNING/ALARM 34, Fieldbus communication fault

The fieldbus on the communication option card is not working.

WARNING/ALARM 35, Out of frequency range:

This warning is active if the output frequency has reached the high limit (set in parameter 4-53) or low limit (set in parameter 4-52). In *Process Control*, *Closed Loop* (parameter 1-00) this warning is displayed.

WARNING/ALARM 36, Mains failure

This warning/alarm is only active if the supply voltage to the frequency converter is lost and par. 14-10 *Mains Failure* is NOT set to OFF. Check the fuses to the frequency converter

ALARM 38, Internal fault

It may be necessary to contact your Danfoss supplier. Some typical alarm messages:

| | |
|-----------|--|
| 0 | Serial port cannot be initialized. Serious hardware failure |
| 256-258 | Power EEPROM data is defect or too old |
| 512 | Control board EEPROM data is defect or too old |
| 513 | Communication time out reading EEPROM data |
| 514 | Communication time out reading EEPROM data |
| 515 | Application Orientated Control cannot recognize the EEPROM data |
| 516 | Cannot write to the EEPROM because a write command is on progress |
| 517 | Write command is under time out |
| 518 | Failure in the EEPROM |
| 519 | Missing or invalid Barcode data in EEPROM |
| 783 | Parameter value outside of min/max limits |
| 1024-1279 | A can-telegram that has to be sent, couldn't be sent |
| 1281 | Digital Signal Processor flash timeout |
| 1282 | Power micro software version mismatch |
| 1283 | Power EEPROM data version mismatch |
| 1284 | Cannot read Digital Signal Processor software version |
| 1299 | Option SW in slot A is too old |
| 1300 | Option SW in slot B is too old |
| 1301 | Option SW in slot C0 is too old |
| 1302 | Option SW in slot C1 is too old |
| 1315 | Option SW in slot A is not supported (not allowed) |
| 1316 | Option SW in slot B is not supported (not allowed) |
| 1317 | Option SW in slot C0 is not supported (not allowed) |
| 1318 | Option SW in slot C1 is not supported (not allowed) |
| 1379 | Option A did not respond when calculating Platform Version. |
| 1380 | Option B did not respond when calculating Platform Version. |
| 1381 | Option C0 did not respond when calculating Platform Version. |
| 1382 | Option C1 did not respond when calculating Platform Version. |
| 1536 | An exception in the Application Orientated Control is registered. Debug information written in LCP |
| 1792 | DSP watchdog is active. Debugging of power part data |
| 2049 | Motor Orientated Control data not transferred correctly |
| 2049 | Power data restarted |
| 2064-2072 | H081x: option in slot x has restarted |
| 2080-2088 | H082x: option in slot x has issued a powerup-wait |
| 2096-2104 | H083x: option in slot x has issued a legal powerup-wait |
| 2304 | Could not read any data from power EEPROM |
| 2305 | Missing SW version from power unit |
| 2314 | Missing power unit data from power unit |
| 2315 | Missing SW version from power unit |
| 2316 | Missing io_statepage from power unit |
| 2324 | Power card configuration is determined to be incorrect at power up |
| 2325 | A power card has stopped communicating while main power is applied |
| 2326 | Power card configuration is determined to be incorrect after the delay for power cards to register |
| 2327 | Too many power card locations have been registered as present |
| 2330 | Power size information between the power cards does not match |
| 2561 | No communication from DSP to ATACD |
| 2562 | No communication from ATACD to DSP (state running) |
| 2816 | Stack overflow Control board module |
| 2817 | Scheduler slow tasks |
| 2818 | Fast tasks |
| 2819 | Parameter thread |
| 2820 | LCP Stack overflow |
| 2821 | Serial port overflow |
| 2822 | USB port overflow |
| 2836 | cfListMempool to small |
| 3072-5122 | Parameter value is outside its limits |
| 5123 | Option in slot A: Hardware incompatible with Control board hardware |
| 5124 | Option in slot B: Hardware incompatible with Control board hardware |
| 5125 | Option in slot C0: Hardware incompatible with Control board hardware |
| 5126 | Option in slot C1: Hardware incompatible with Control board hardware |
| 5376-6231 | Out of memory |

ALARM 39, Heatsink sensor

No feedback from the heatsink temperature sensor.

The signal from the IGBT thermal sensor is not available on the power card. The problem could be on the power card, on the gate drive card, or the ribbon cable between the power card and gate drive card.

WARNING 40, Overload of Digital Output Terminal 27

Check the load connected to terminal 27 or remove short-circuit connection. Check par. 5-00 *Digital I/O Mode* and par. 5-01 *Terminal 27 Mode*.

WARNING 41, Overload of Digital Output Terminal 29

Check the load connected to terminal 29 or remove short-circuit connection. Check par. 5-00 *Digital I/O Mode* and par. 5-02 *Terminal 29 Mode*.

WARNING 42, Overload of Digital Output on X30/6 or Overload of Digital Output on X30/7

For X30/6, check the load connected to X30/6 or remove short-circuit connection. Check par. 5-32 *Term X30/6 Digi Out (MCB 101)*.

For X30/7, check the load connected to X30/7 or remove short-circuit connection. Check par. 5-33 *Term X30/7 Digi Out (MCB 101)*.

ALARM 46, Power card supply

The supply on the power card is out of range.

There are three power supplies generated by the switch mode power supply (SMPS) on the power card: 24 V, 5V, +/- 18V. When powered with 24 VDC with the MCB 107 option, only the 24 V and 5 V supplies are monitored. When powered with three phase mains voltage, all three supplied are monitored.

WARNING 47, 24 V supply low

The 24 VDC is measured on the control card. The external 24 VDC backup power supply may be overloaded, otherwise contact your Danfoss supplier.

WARNING 48, 1.8 V supply low

The 1.8 Volt DC supply used on the control card is outside of allowable limits. The power supply is measured on the control card.

WARNING 49, Speed limit

When the speed is not within the specified range in par. 4-11 and par. 4-13, the drive will show a warning. When the speed is below the specified limit in par. 1-86 (except when starting or stopping) the drive will trip.

ALARM 50, AMA calibration failed

Contact your Danfoss supplier.

ALARM 51, AMA check Unom and Inom

The setting of motor voltage, motor current, and motor power is presumably wrong. Check the settings.

ALARM 52, AMA low Inom

The motor current is too low. Check the settings.

ALARM 53, AMA motor too big

The motor is too big for the AMA to be carried out.

ALARM 54, AMA motor too small

The motor is too big for the AMA to be carried out.

ALARM 55, AMA parameter out of range

The parameter values found from the motor are outside acceptable range.

ALARM 56, AMA interrupted by user

The AMA has been interrupted by the user.



ALARM 57, AMA timeout

Try to start the AMA again a number of times, until the AMA is carried out. Please note that repeated runs may heat the motor to a level where the resistance R_s and R_r are increased. In most cases, however, this is not critical.

ALARM 58, AMA internal fault

Contact your Danfoss supplier.

WARNING 59, Current limit

The current is higher than the value in par. 4-18, *Current Limit*.

WARNING 60, External interlock

External interlock has been activated. To resume normal operation, apply 24 VDC to the terminal programmed for external interlock and reset the frequency converter (via serial communication, digital I/O, or by pressing reset button on keypad).

WARNING 61, Tracking error

An error has been detected between calculated motor speed and speed measurement from feedback device. The function for Warning/Alarm/Disable is set in par 4-30, *Motor Feedback Loss Function*, error setting in par 4-31, *Motor Feedback Speed Error*, and the allowed error time in par 4-32, *Motor Feedback Loss Timeout*. During a commissioning procedure the function may be effective.

WARNING 62, Output frequency at maximum limit

The output frequency is higher than the value set in par. 4-19 *Max Output Frequency*

WARNING 64, Voltage limit

The load and speed combination demands a motor voltage higher than the actual DC link voltage.

WARNING/ALARM/TRIP 65, Control card over temperature

Control card over temperature: The cutout temperature of the control card is 80° C.

WARNING 66, Heatsink temperature low

This warning is based on the temperature sensor in the IGBT module.

Troubleshooting:

The heatsink temperature measured as 0° C could indicate that the temperature sensor is defective causing the fan speed to increase to the maximum. If the sensor wire between the IGBT and the gate drive card is disconnected, this warning would result. Also, check the IGBT thermal sensor.

ALARM 67, Option module configuration has changed

One or more options have either been added or removed since the last power-down.

ALARM 68, Safe stop activated

Safe stop has been activated. To resume normal operation, apply 24 VDC to terminal 37, then send a reset signal (via Bus, Digital I/O, or by pressing the reset key. See parameter 5-19, Terminal 37 Safe Stop.

ALARM 69, Power card temperature

The temperature sensor on the power card is either too hot or too cold.

Troubleshooting:

Check the operation of the door fans.

Check that the filters for the door fans are not blocked.

Check that the gland plate is properly installed on IP 21 and IP 54 (NEMA 1 and NEMA 12) drives.

ALARM 70, Illegal FC Configuration

Actual combination of control board and power board is illegal.

WARNING/ALARM 71, PTC 1 safe stop

Safe Stop has been activated from the MCB 112 PTC Thermistor Card (motor too warm). Normal operation can be resumed when the MCB 112 applies 24 V DC to T-37 again (when the motor temperature reaches an acceptable level) and when the Digital Input from the MCB 112 is deactivated. When that happens, a reset signal must be sent (via serial communication, digital I/O, or by pressing reset button on keypad). Note that if automatic restart is enabled, the motor may start when the fault is cleared.

ALARM 72, Dangerous failure

Safe stop with trip lock. Unexpected signal levels on safe stop and digital input from the MCB 112 PTC thermistor card.

Warning 73, Safe stop auto restart

Safe stopped. Note that with automatic restart enabled, the motor may start when the fault is cleared.

WARNING 77, Reduced power mode:

This warning indicates that the drive is operating in reduced power mode (i.e. less than the allowed number of inverter sections). This warning will be generated on power cycle when the drive is set to run with fewer inverters and will remain on.

ALARM 79, Illegal power section configuration

The scaling card is the incorrect part number or not installed. Also MK102 connector on the power card could not be installed.

ALARM 80, Drive initialized to default value

Parameter settings are initialized to default settings after a manual reset.

ALARM 91, Analog input 54 wrong settings

Switch S202 has to be set in position OFF (voltage input) when a KTY sensor is connected to analog input terminal 54.

ALARM 92, No flow

A no-load situation has been detected in the system. See parameter group 22-2.

ALARM 93, Dry pump

A no-flow situation and high speed indicates that the pump has run dry. See parameter group 22-2.

ALARM 94, End of curve

Feedback stays lower than the set point which may indicate leakage in the pipe system. See parameter group 22-5.

ALARM 95, Broken belt

Torque is below the torque level set for no load, indicating a broken belt. See parameter group 22-6.

ALARM 96, Start delayed

Motor start has been delayed due to short-cycle protection active. See parameter group 22-7.

WARNING 97, Stop delayed

Stopping the motor has been delayed due to short cycle protection is active. See parameter group 22-7.

WARNING 98, Clock fault

Clock Fault. Time is not set or RTC clock (if mounted) has failed. See parameter group 0-7.

WARNING 201, Fire M was Active

Fire Mode has been active.

WARNING 202, Fire M Limits Exceeded

Fire Mode has suppressed one or more warranty voiding alarms.

WARNING 203, Missing Motor

A multi-motor under-load situation was detected, this could be due to e.g. a missing motor.

WARNING 204, Locked Rotor

A multi-motor overload situation was detected, this could be due to e.g. a locked rotor.

ALARM 243, Brake IGBT

This alarm is only for F Frame drives. It is equivalent to Alarm 27. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 244, Heatsink temperature

This alarm is only for F Frame drives. It is equivalent to Alarm 29. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 245, Heatsink sensor

This alarm is only for F Frame drives. It is equivalent to Alarm 39. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 246, Power card supply

This alarm is only for F Frame drives. It is equivalent to Alarm 46. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 247, Power card temperature

This alarm is only for F Frame drives. It is equivalent to Alarm 69. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 248, Illegal power section configuration

This alarm is only for F-frame drives. It is equivalent to Alarm 79. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F2 or F4 drive.
- 2 = right inverter module in F1 or F3 drive.
- 3 = right inverter module in F2 or F4 drive.
- 5 = rectifier module.

ALARM 250, New spare part

The power or switch mode power supply has been exchanged. The frequency converter type code must be restored in the EEPROM. Select the correct type code in par. 14-23 *Typecode Setting* according to the label on the unit. Remember to select 'Save to EEPROM' to complete.

ALARM 251, New type code

The frequency converter has a new type code.

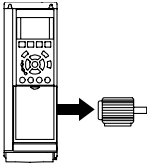
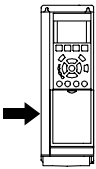
7.2 Acoustic noise or vibration

If the motor or the equipment driven by the motor - e.g. a fan blade - is making noise or vibrations at certain frequencies, try the following:

- Speed Bypass, parameter group 4-6*
- Over-modulation, parameter 14-03 set to off
- Switching pattern and -frequency parameter group 14-0*
- Resonance Dampening, parameter 1-64

8 Specifications

8.1 General Specifications

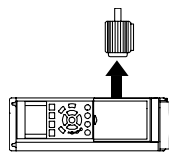
| Mains supply 200 - 240 VAC - Normal overload 110% for 1 minute | | | | | | |
|--|---|------|------|------|------|------|
| Frequency converter | P1K1 | P1K5 | P2K2 | P3K0 | P3K7 | |
| Typical Shaft Output [kW] | 1.1 | 1.5 | 2.2 | 3 | 3.7 | |
| IP 20 / Chassis | A2 | A2 | A2 | A3 | A3 | |
| IP 21 / NEMA 1 | A2 | A2 | A2 | A3 | A3 | |
| IP 55 / NEMA 12 | A5 | A5 | A5 | A5 | A5 | |
| IP 66 / NEMA 12 | A5 | A5 | A5 | A5 | A5 | |
| Typical Shaft Output [HP] at 208 V | 1.5 | 2.0 | 2.9 | 4.0 | 4.9 | |
| Output current | | | | | | |
|  | Continuous (3 x 200-240 V) [A] | 6.6 | 7.5 | 10.6 | 12.5 | 16.7 |
| | Intermittent (3 x 200-240 V) [A] | 7.3 | 8.3 | 11.7 | 13.8 | 18.4 |
| | Continuous kVA (208 V AC) [kVA] | 2.38 | 2.70 | 3.82 | 4.50 | 6.00 |
| | Max. cable size: (mains, motor, brake) [mm ² /AWG] ²⁾ | | | 4/10 | | |
| | Max. input current | | | | | |
|  | Continuous (3 x 200-240 V) [A] | 5.9 | 6.8 | 9.5 | 11.3 | 15.0 |
| | Intermittent (3 x 200-240 V) [A] | 6.5 | 7.5 | 10.5 | 12.4 | 16.5 |
| | Max. pre-fuses ¹⁾ [A] | 20 | 20 | 20 | 32 | 32 |
| | Environment | | | | | |
| | Estimated power loss at rated max. load [W] ⁴⁾ | 63 | 82 | 116 | 155 | 185 |
| | Weight enclosure IP20 [kg] | 4.9 | 4.9 | 4.9 | 6.6 | 6.6 |
| | Weight enclosure IP21 [kg] | 5.5 | 5.5 | 5.5 | 7.5 | 7.5 |
| Weight enclosure IP55 [kg] | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | |
| Weight enclosure IP 66 [kg] | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | |
| Efficiency ³⁾ | 0.96 | 0.96 | 0.96 | 0.96 | 0.96 | |

Mains Supply 3 x 380 - 480 VAC - Normal overload 110% for 1 minute

| | P1K1 | P1K5 | P2K2 | P3K0 | P4K0 | P5K5 | P7K5 |
|------------------------------------|------|------|------|------|------|------|------|
| Frequency converter | 1.1 | 1.5 | 2.2 | 3 | 4 | 5.5 | 7.5 |
| Typical Shaft Output [kW] | 1.5 | 2.0 | 2.9 | 4.0 | 5.0 | 7.5 | 10 |
| Typical Shaft Output [HP] at 460 V | A2 | A2 | A2 | A2 | A2 | A3 | A3 |
| IP 20 / Chassis | A5 | A5 | A5 | A5 | A5 | A5 | A5 |
| IP 21 / NEMA 1 | A5 | A5 | A5 | A5 | A5 | A5 | A5 |
| IP 55 / NEMA 12 | A5 | A5 | A5 | A5 | A5 | A5 | A5 |
| IP 66 / NEMA 12 | A5 | A5 | A5 | A5 | A5 | A5 | A5 |

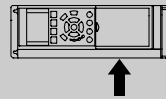
Output current

| | | | | | | | |
|---|----------|-----|-----|-----|-----|------|------|
| Continuous (3 x 380-440 V) [A] | 3 | 4.1 | 5.6 | 7.2 | 10 | 13 | 16 |
| Intermittent (3 x 380-440 V) [A] | 3.3 | 4.5 | 6.2 | 7.9 | 11 | 14.3 | 17.6 |
| Continuous (3 x 441-480 V) [A] | 2.7 | 3.4 | 4.8 | 6.3 | 8.2 | 11 | 14.5 |
| Intermittent (3 x 441-480 V) [A] | 3.0 | 3.7 | 5.3 | 6.9 | 9.0 | 12.1 | 15.4 |
| Continuous kVA (400 V AC) [kVA] | 2.1 | 2.8 | 3.9 | 5.0 | 6.9 | 9.0 | 11.0 |
| Continuous kVA (460 V AC) [kVA] | 2.4 | 2.7 | 3.8 | 5.0 | 6.5 | 8.8 | 11.6 |
| Max. cable size: (mains, motor, brake) [[mm ²]/ AWG] ²⁾ | 4/ 10 | | | | | | |



Max. input current

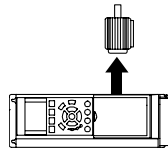
| | | | | | | | |
|--|------|------|------|------|------|------|------|
| Continuous (3 x 380-440 V) [A] | 2.7 | 3.7 | 5.0 | 6.5 | 9.0 | 11.7 | 14.4 |
| Intermittent (3 x 380-440 V) [A] | 3.0 | 4.1 | 5.5 | 7.2 | 9.9 | 12.9 | 15.8 |
| Continuous (3 x 441-480 V) [A] | 2.7 | 3.1 | 4.3 | 5.7 | 7.4 | 9.9 | 13.0 |
| Intermittent (3 x 441-480 V) [A] | 3.0 | 3.4 | 4.7 | 6.3 | 8.1 | 10.9 | 14.3 |
| Max. pre-fuses ³⁾ [A] | 10 | 10 | 20 | 20 | 20 | 32 | 32 |
| Environment | | | | | | | |
| Estimated power loss at rated max. load [W] ⁴⁾ | 58 | 62 | 88 | 116 | 124 | 187 | 255 |
| Weight enclosure IP20 [kg] | 4.8 | 4.9 | 4.9 | 4.9 | 4.9 | 6.6 | 6.6 |
| Weight enclosure IP 21 [kg] | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | 14.2 | 14.2 |
| Weight enclosure IP 55 [kg] | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | 14.2 | 14.2 |
| Weight enclosure IP 66 [kg] | 0.96 | 0.97 | 0.97 | 0.97 | 0.97 | 0.97 | 0.97 |
| Efficiency ³⁾ | | | | | | | |





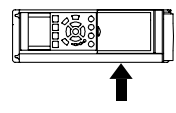
Mains Supply 3 x 380 - 480 VAC - Normal overload 110% for 1 minute

| Frequency converter | P11K | P15K | P18K | P22K | P30K | P37K | P45K | P55K | P75K | P90K |
|--|------|------|------|------|------|------|------------------|------|--------|--------------|
| Typical Shaft Output [kW] | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 |
| Typical Shaft Output [HP] at 460 V | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 75 | 100 | 125 |
| IP 20 / Chassis Danfoss | B3 | B3 | B3 | B4 | B4 | B4 | C3 | C3 | C4 | C4 |
| (B3+4 and C3+4 may be converted to IP21 using a conversion kit (Please contact Danfoss)) | | | | | | | | | | |
| IP 21 / NEMA 1 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| IP 55 / NEMA 12 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| IP 66 / NEMA 12 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| Output current | | | | | | | | | | |
| Continuous (3 x 380-439 V) [A] | 24 | 32 | 37.5 | 44 | 61 | 73 | 90 | 106 | 147 | 177 |
| Intermittent (3 x 380-439 V) [A] | 26.4 | 35.2 | 41.3 | 48.4 | 67.1 | 80.3 | 99 | 117 | 162 | 195 |
| Continuous (3 x 440-480 V) [A] | 21 | 27 | 34 | 40 | 52 | 65 | 80 | 105 | 130 | 160 |
| Intermittent (3 x 440-480 V) [A] | 23.1 | 29.7 | 37.4 | 44 | 61.6 | 71.5 | 88 | 116 | 143 | 176 |
| Continuous kVA (400 V AC) [kVA] | 16.6 | 22.2 | 26 | 30.5 | 42.3 | 50.6 | 62.4 | 73.4 | 102 | 123 |
| Continuous kVA (460 V AC) [kVA] | 16.7 | 21.5 | 27.1 | 31.9 | 41.4 | 51.8 | 63.7 | 83.7 | 104 | 128 |
| Max. cable size: (mains, motor, brake) [mm ² /AWG] ²⁾ | 10/7 | | | 35/2 | | | 50/1/0 (B4=35/2) | | 95/4/0 | 120/MCM250 |
| With mains disconnect switch included: | | | 16/6 | | | 35/2 | | 35/2 | 70/3/0 | 185/kcmil350 |



Max. input current

| | | | | | | | | | | |
|---|------|------|------|------|------|------|------|------|------|------|
| Continuous (3 x 380-439 V) [A] | 22 | 29 | 34 | 40 | 55 | 66 | 82 | 96 | 133 | 161 |
| Intermittent (3 x 380-439 V) [A] | 24.2 | 31.9 | 37.4 | 44 | 60.5 | 72.6 | 90.2 | 106 | 146 | 177 |
| Continuous (3 x 440-480 V) [A] | 19 | 25 | 31 | 36 | 47 | 59 | 73 | 95 | 118 | 145 |
| Intermittent (3 x 440-480 V) [A] | 20.9 | 27.5 | 34.1 | 39.6 | 51.7 | 64.9 | 80.3 | 105 | 130 | 160 |
| Max. pre-fuses ¹⁾ [A] | 63 | 63 | 63 | 63 | 80 | 100 | 125 | 160 | 250 | 250 |
| Environment | | | | | | | | | | |
| Estimated power loss at rated max. load [W] ⁴⁾ | 278 | 392 | 465 | 525 | 698 | 739 | 843 | 1083 | 1384 | 1474 |
| Weight enclosure IP20 [kg] | 12 | 12 | 12 | 23.5 | 23.5 | 23.5 | 35 | 35 | 50 | 50 |
| Weight enclosure IP 21 [kg] | 23 | 23 | 23 | 27 | 27 | 45 | 45 | 45 | 65 | 65 |
| Weight enclosure IP 55 [kg] | 23 | 23 | 23 | 27 | 27 | 45 | 45 | 45 | 65 | 65 |
| Weight enclosure IP 66 [kg] | 23 | 23 | 23 | 27 | 27 | 45 | 45 | 45 | 65 | 65 |
| Efficiency ³⁾ | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.99 |



8.1.1 Mains Supply 3 x 525 - 600 VAC

| Normal overload 110% for 1 minute | | P1K1 | P1K5 | P2K2 | P3K0 | P3K7 | P4K0 | P5K5 | P7K5 | P11K | P15K | P18K | P22K | P30K | P37K | P45K | P55K | P75K | P90K |
|---|--|------|------|------|------|------|------|------|------|------|------|------|------|------|------|--------|------|--------|--------------------------|
| Size: | | 1.1 | 1.5 | 2.2 | 3 | 3.7 | 4 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 |
| Typical Shaft Output [kW] | | A2 | A2 | A2 | A2 | A2 | A2 | A3 | A3 | B3 | B3 | B3 | B4 | B4 | B4 | C3 | C3 | C4 | C4 |
| IP 20 / Chassis | | A2 | A2 | A2 | A2 | A2 | A2 | A3 | A3 | B1 | B1 | B1 | B2 | B2 | B2 | C1 | C1 | C2 | C2 |
| IP 21 / NEMA 1 | | A5 | A5 | A5 | A5 | A5 | A5 | A5 | A5 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| IP 55 / NEMA 12 | | A5 | A5 | A5 | A5 | A5 | A5 | A5 | A5 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| IP 66 / NEMA 12 | | A5 | A5 | A5 | A5 | A5 | A5 | A5 | A5 | B1 | B1 | B1 | B2 | B2 | C1 | C1 | C1 | C2 | C2 |
| Output current | | | | | | | | | | | | | | | | | | | |
| Continuous (3 x 525-550 V) [A] | | 2.6 | 2.9 | 4.1 | 5.2 | - | 6.4 | 9.5 | 11.5 | 19 | 23 | 28 | 36 | 43 | 54 | 65 | 87 | 105 | 137 |
| Intermittent (3 x 525-550 V) [A] | | 2.9 | 3.2 | 4.5 | 5.7 | - | 7.0 | 10.5 | 12.7 | 21 | 25 | 31 | 40 | 47 | 59 | 72 | 96 | 116 | 151 |
| Continuous (3 x 525-600 V) [A] | | 2.4 | 2.7 | 3.9 | 4.9 | - | 6.1 | 9.0 | 11.0 | 18 | 22 | 27 | 34 | 41 | 52 | 62 | 83 | 100 | 131 |
| Intermittent (3 x 525-600 V) [A] | | 2.6 | 3.0 | 4.3 | 5.4 | - | 6.7 | 9.9 | 12.1 | 20 | 24 | 30 | 37 | 45 | 57 | 68 | 91 | 110 | 144 |
| Continuous kVA (525 V AC) [kVA] | | 2.5 | 2.8 | 3.9 | 5.0 | - | 6.1 | 9.0 | 11.0 | 18.1 | 21.9 | 26.7 | 34.3 | 41 | 51.4 | 61.9 | 82.9 | 100 | 130.5 |
| Continuous kVA (575 V AC) [kVA] | | 2.4 | 2.7 | 3.9 | 4.9 | - | 6.1 | 9.0 | 11.0 | 17.9 | 21.9 | 26.9 | 33.9 | 40.8 | 51.8 | 61.7 | 82.7 | 99.6 | 130.5 |
| Max. cable size, IP 21/55/66 (mains, motor, brake) [mm ²]/[AWG] ²⁾ | | | | | 4/10 | | | | | | 10/7 | | | 25/4 | | 50/1/0 | | 95/4/0 | 120/MCM250 |
| Max. cable size, IP 20 (mains, motor, brake) [mm ²]/[AWG] ²⁾ | | | | | 4/10 | | | | | | 16/6 | | | 35/2 | | 50/1/0 | | 95/4/0 | 150/MCM250 ⁵⁾ |
| With mains disconnect switch included: | | | | | 4/10 | | | | | | 16/6 | | | | 35/2 | | | 70/3/0 | 185/kcmil350 |
| Max. input current | | | | | | | | | | | | | | | | | | | |
| Continuous (3 x 525-600 V) [A] | | 2.4 | 2.7 | 4.1 | 5.2 | - | 5.8 | 8.6 | 10.4 | 17.2 | 20.9 | 25.4 | 32.7 | 39 | 49 | 59 | 78.9 | 95.3 | 124.3 |
| Intermittent (3 x 525-600 V) [A] | | 2.7 | 3.0 | 4.5 | 5.7 | - | 6.4 | 9.5 | 11.5 | 19 | 23 | 28 | 36 | 43 | 54 | 65 | 87 | 105 | 137 |
| Max. pre-fuses ¹⁾ [A] | | 10 | 10 | 20 | 20 | - | 20 | 32 | 32 | 63 | 63 | 63 | 63 | 80 | 100 | 125 | 160 | 250 | 250 |
| Environment: | | | | | | | | | | | | | | | | | | | |
| Estimated power loss at rated max. load [W] ⁴⁾ | | 50 | 65 | 92 | 122 | - | 145 | 195 | 261 | 300 | 400 | 475 | 525 | 700 | 750 | 850 | 1100 | 1400 | 1500 |
| Weight enclosure IP20 [kg] | | 6.5 | 6.5 | 6.5 | 6.5 | - | 6.5 | 6.6 | 6.6 | 12 | 12 | 12 | 23.5 | 23.5 | 23.5 | 35 | 35 | 50 | 50 |
| Weight enclosure IP21/55 [kg] | | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | 14.2 | 14.2 | 23 | 23 | 23 | 27 | 27 | 27 | 45 | 45 | 65 | 65 |
| Efficiency ⁴⁾ | | 0.97 | 0.97 | 0.97 | 0.97 | - | 0.97 | 0.97 | 0.97 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 |

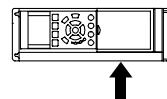
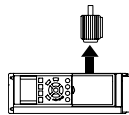


Table 8.1: ⁵⁾ With brake and load sharing 95/ 4/0

8.1.2 General specifications:

Mains supply (L1, L2, L3):

| | |
|----------------|---|
| Supply voltage | 200-240 V ±10% 380-480 V ±10% 525-600 V ±10% 525-690 V ±10% |
|----------------|---|

Mains voltage low / mains drop-out:

During low mains voltage or a mains drop-out, the FC continues until the intermediate circuit voltage drops below the minimum stop level, which corresponds typically to 15% below the FC's lowest rated supply voltage. Power-up and full torque cannot be expected at mains voltage lower than 10% below the FC's lowest rated supply voltage.

| | |
|--|---|
| Supply frequency | 50/60 Hz ±5% |
| Max. imbalance temporary between mains phases | 3.0 % of rated supply voltage |
| True Power Factor () | ≥ 0.9 nominal at rated load |
| Displacement Power Factor (cos) near unity | (> 0.98) |
| Switching on input supply L1, L2, L3 (power-ups) ≤ enclosure type A | maximum twice/min. |
| Switching on input supply L1, L2, L3 (power-ups) ≥ enclosure type B, C | maximum once/min. |
| Switching on input supply L1, L2, L3 (power-ups) ≥ enclosure type D, E | maximum once/2 min. |
| Environment according to EN60664-1 | overvoltage category III / pollution degree 2 |

The unit is suitable for use on a circuit capable of delivering not more than 100.000 RMS symmetrical Amperes, 480/600 V maximum.

Motor output (U, V, W):

| | |
|---------------------|----------------------------|
| Output voltage | 0 - 100% of supply voltage |
| Output frequency | 0 - 1000 Hz* |
| Switching on output | Unlimited |
| Ramp times | 1 - 3600 sec. |

** Dependent on power size.*

Torque characteristics:

| | |
|-----------------------------------|------------------------------|
| Starting torque (Constant torque) | maximum 110% for 1 min.* |
| Starting torque | maximum 135% up to 0.5 sec.* |
| Overload torque (Constant torque) | maximum 110% for 1 min.* |

**Percentage relates to the frequency converter's nominal torque.*

Cable lengths and cross sections:

| | |
|--|---|
| Max. motor cable length, screened/armoured | VLT HVAC Drive: 150 m |
| Max. motor cable length, unscreened/unarmoured | VLT HVAC Drive: 300 m |
| Max. cross section to motor, mains, load sharing and brake * | |
| Maximum cross section to control terminals, rigid wire | 1.5 mm ² /16 AWG (2 x 0.75 mm ²) |
| Maximum cross section to control terminals, flexible cable | 1 mm ² /18 AWG |
| Maximum cross section to control terminals, cable with enclosed core | 0.5 mm ² /20 AWG |
| Minimum cross section to control terminals | 0.25 mm ² |

** See Mains Supply tables for more information!*

Digital inputs:

| | |
|----------------------------------|---|
| Programmable digital inputs | 4 (6) |
| Terminal number | 18, 19, 27 ¹⁾ , 29 ¹⁾ , 32, 33, |
| Logic | PNP or NPN |
| Voltage level | 0 - 24 V DC |
| Voltage level, logic '0' PNP | < 5 V DC |
| Voltage level, logic '1' PNP | > 10 V DC |
| Voltage level, logic '0' NPN | > 19 V DC |
| Voltage level, logic '1' NPN | < 14 V DC |
| Maximum voltage on input | 28 V DC |
| Input resistance, R _i | approx. 4 k |

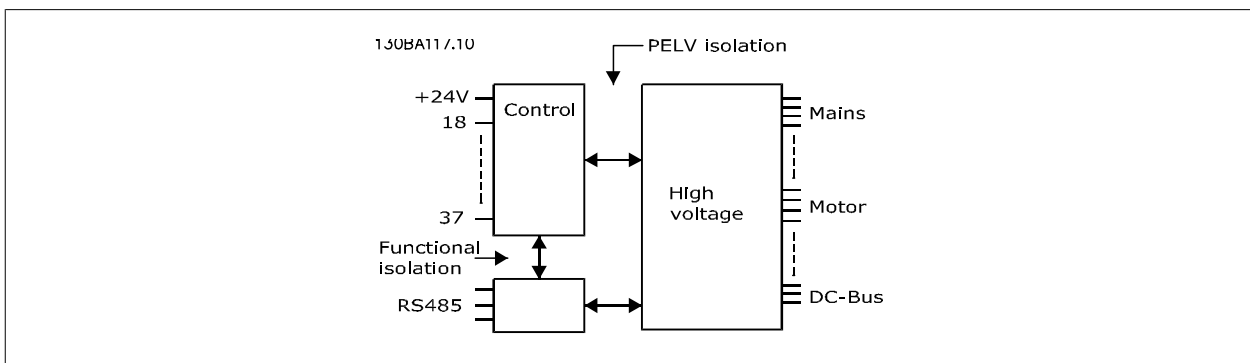
All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

1) Terminals 27 and 29 can also be programmed as output.

Analog inputs:

| | |
|----------------------------------|-----------------------------------|
| Number of analog inputs | 2 |
| Terminal number | 53, 54 |
| Modes | Voltage or current |
| Mode select | Switch S201 and switch S202 |
| Voltage mode | Switch S201/switch S202 = OFF (U) |
| Voltage level | : 0 to + 10 V (scaleable) |
| Input resistance, R _i | approx. 10 kΩ |
| Max. voltage | ± 20 V |
| Current mode | Switch S201/switch S202 = ON (I) |
| Current level | 0/4 to 20 mA (scaleable) |
| Input resistance, R _i | approx. 200 Ω |
| Max. current | 30 mA |
| Resolution for analog inputs | 10 bit (+ sign) |
| Accuracy of analog inputs | Max. error 0.5% of full scale |
| Bandwidth | : 200 Hz |

The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.



Pulse inputs:

| | |
|------------------------------------|--------------------------------|
| Programmable pulse inputs | 2 |
| Terminal number pulse | 29, 33 |
| Max. frequency at terminal, 29, 33 | 110 kHz (Push-pull driven) |
| Max. frequency at terminal, 29, 33 | 5 kHz (open collector) |
| Min. frequency at terminal 29, 33 | 4 Hz |
| Voltage level | see section on Digital input |
| Maximum voltage on input | 28 V DC |
| Input resistance, R _i | approx. 4 kΩ |
| Pulse input accuracy (0.1 - 1 kHz) | Max. error: 0.1% of full scale |

Analog output:

| | |
|---|---------------------------------|
| Number of programmable analog outputs | 1 |
| Terminal number | 42 |
| Current range at analog output | 0/4 - 20 mA |
| Max. resistor load to common at analog output | 500 Ω |
| Accuracy on analog output | Max. error: 0.8 % of full scale |
| Resolution on analog output | 8 bit |

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, RS-485 serial communication:

| | |
|--------------------|----------------------------------|
| Terminal number | 68 (P,TX+, RX+), 69 (N,TX-, RX-) |
| Terminal number 61 | Common for terminals 68 and 69 |

The RS-485 serial communication circuit is functionally separated from other central circuits and galvanically isolated from the supply voltage (PELV).

Digital output:

| | |
|--|---------------------------------|
| Programmable digital/pulse outputs | 2 |
| Terminal number | 27, 29 ¹⁾ |
| Voltage level at digital/frequency output | 0 - 24 V |
| Max. output current (sink or source) | 40 mA |
| Max. load at frequency output | 1 kΩ |
| Max. capacitive load at frequency output | 10 nF |
| Minimum output frequency at frequency output | 0 Hz |
| Maximum output frequency at frequency output | 32 kHz |
| Accuracy of frequency output | Max. error: 0.1 % of full scale |
| Resolution of frequency outputs | 12 bit |

1) Terminal 27 and 29 can also be programmed as input.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, 24 V DC output:

| | |
|-----------------|----------|
| Terminal number | 12, 13 |
| Max. load | : 200 mA |

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same potential as the analog and digital inputs and outputs.

Relay outputs:

| | |
|--|---|
| Programmable relay outputs | 2 |
| Relay 01 Terminal number | 1-3 (break), 1-2 (make) |
| Max. terminal load (AC-1) ¹⁾ on 1-3 (NC), 1-2 (NO) (Resistive load) | 240 V AC, 2 A |
| Max. terminal load (AC-15) ¹⁾ (Inductive load @ cosφ 0.4) | 240 V AC, 0.2 A |
| Max. terminal load (DC-1) ¹⁾ on 1-2 (NO), 1-3 (NC) (Resistive load) | 60 V DC, 1A |
| Max. terminal load (DC-13) ¹⁾ (Inductive load) | 24 V DC, 0.1A |
| Relay 02 Terminal number | 4-6 (break), 4-5 (make) |
| Max. terminal load (AC-1) ¹⁾ on 4-5 (NO) (Resistive load) ²⁾³⁾ | 400 V AC, 2 A |
| Max. terminal load (AC-15) ¹⁾ on 4-5 (NO) (Inductive load @ cosφ 0.4) | 240 V AC, 0.2 A |
| Max. terminal load (DC-1) ¹⁾ on 4-5 (NO) (Resistive load) | 80 V DC, 2 A |
| Max. terminal load (DC-13) ¹⁾ on 4-5 (NO) (Inductive load) | 24 V DC, 0.1A |
| Max. terminal load (AC-1) ¹⁾ on 4-6 (NC) (Resistive load) | 240 V AC, 2 A |
| Max. terminal load (AC-15) ¹⁾ on 4-6 (NC) (Inductive load @ cosφ 0.4) | 240 V AC, 0.2A |
| Max. terminal load (DC-1) ¹⁾ on 4-6 (NC) (Resistive load) | 50 V DC, 2 A |
| Max. terminal load (DC-13) ¹⁾ on 4-6 (NC) (Inductive load) | 24 V DC, 0.1 A |
| Min. terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO) | 24 V DC 10 mA, 24 V AC 20 mA |
| Environment according to EN 60664-1 | overvoltage category III/pollution degree 2 |

1) IEC 60947 part 4 and 5

The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).

2) Overvoltage Category II

3) UL applications 300 V AC 2A

Control card, 10 V DC output:

| | |
|-----------------|---------------|
| Terminal number | 50 |
| Output voltage | 10.5 V ±0.5 V |
| Max. load | 25 mA |

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control characteristics:

| | |
|---|--|
| Resolution of output frequency at 0 - 1000 Hz | : +/- 0.003 Hz |
| System response time (terminals 18, 19, 27, 29, 32, 33) | : ≤ 2 ms |
| Speed control range (open loop) | 1:100 of synchronous speed |
| Speed accuracy (open loop) | 30 - 4000 rpm: Maximum error of ±8 rpm |

All control characteristics are based on a 4-pole asynchronous motor

Surroundings:

| | |
|----------------------|---|
| Enclosure type A | IP 20/Chassis, IP 21kit/Type 1, IP55/Type12, IP 66/Type12 |
| Enclosure type B1/B2 | IP 21/Type 1, IP55/Type12, IP 66/12 |
| Enclosure type B3/B4 | IP20/Chassis |

| | |
|--|---|
| Enclosure type C1/C2 | IP 21/Type 1, IP55/Type 12, IP66/12 |
| Enclosure type C3/C4 | IP20/Chassis |
| Enclosure type D1/D2/E1 | IP21/Type 1, IP54/Type12 |
| Enclosure type D3/D4/E2 | IP00/Chassis |
| Enclosure type F1/F3 | IP21, 54/Type1, 12 |
| Enclosure type F2/F4 | IP21, 54/Type1, 12 |
| Enclosure kit available ≤ enclosure type D | IP21/NEMA 1/IP 4x on top of enclosure |
| Vibration test enclosure A, B, C | 1.0 g |
| Vibration test enclosure D, E, F | 0.7 g |
| Relative humidity | 5% - 95%(IEC 721-3-3; Class 3K3 (non-condensing) during operation |
| Aggressive environment (IEC 60068-2-43) H ₂ S test | class Kd |
| Test method according to IEC 60068-2-43 H ₂ S (10 days) | |
| Ambient temperature (at 60 AVM switching mode) | |
| - with derating | max. 55° C ¹⁾ |
| - with full output power of typical EFF2 motors (up to 90% output current) | max. 50° C ¹⁾ |
| - at full continuous FC output current | max. 45° C ¹⁾ |

¹⁾ For more information on derating see the Design Guide, section on Special Conditions.

| | |
|---|-----------------|
| Minimum ambient temperature during full-scale operation | 0 °C |
| Minimum ambient temperature at reduced performance | - 10 °C |
| Temperature during storage/transport | -25 - +65/70 °C |
| Maximum altitude above sea level without derating | 1000 m |
| Maximum altitude above sea level with derating | 3000 m |


Derating for high altitude, see section on special conditions

| | |
|-------------------------|--|
| EMC standards, Emission | EN 61800-3, EN 61000-6-3/4, EN 55011, IEC 61800-3 EN 61800-3, EN 61000-6-1/2, |
| EMC standards, Immunity | EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6 |

See section on special conditions!

Control card performance:

| | |
|---|--------------------------|
| Scan interval | : 5 ms |
| Control card, USB serial communication: | |
| USB standard | 1.1 (Full speed) |
| USB plug | USB type B "device" plug |



Connection to PC is carried out via a standard host/device USB cable.
 The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.
 The USB connection is not galvanically isolated from protection earth. Use only isolated laptop/PC as connection to the USB connector on frequency converter or an isolated USB cable/converter.

Protection and Features:

- Electronic thermal motor protection against overload.
- Temperature monitoring of the heatsink ensures that the frequency converter trips if the temperature reaches 95 °C ± 5°C. An overload temperature cannot be reset until the temperature of the heatsink is below 70 °C ± 5°C (Guideline - these temperatures may vary for different power sizes, enclosures etc.). The frequency converter has an auto derating function to avoid it's heatsink reaching 95 deg C.
- The frequency converter is protected against short-circuits on motor terminals U, V, W.
- If a mains phase is missing, the frequency converter trips or issues a warning (depending on the load).
- Monitoring of the intermediate circuit voltage ensures that the frequency converter trips if the intermediate circuit voltage is too low or too high.
- The frequency converter is protected against earth faults on motor terminals U, V, W.

8.2 Special Conditions

8.2.1 Purpose of derating

Derating must be taken into account when using the frequency converter at low air pressure (heights), at low speeds, with long motor cables, cables with a large cross section or at high ambient temperature. The required action is described in this section.

8.2.2 Derating for Ambient Temperature

90% frequency converter output current can be maintained up to max. 50 °C ambient temperature.

With a typical full load current of EFF 2 motors, full output shaft power can be maintained up to 50 °C.
For more specific data and/or derating information for other motors or conditions, please contact Danfoss.

8.2.3 Automatic Adaptations to Ensure Performance

The frequency converter constantly checks for critical levels of internal temperature, load current, high voltage on the intermediate circuit and low motor speeds. As a response to a critical level, the frequency converter can adjust the switching frequency and / or change the switching pattern in order to ensure the performance of the frequency converter. The capability to automatically reduce the output current extends the acceptable operating conditions even further.

8

8.2.4 Derating for Low Air Pressure

The cooling capability of air is decreased at lower air pressure.

Below 1000 m altitude no derating is necessary but above 1000 m the ambient temperature (T_{AMB}) or max. output current (I_{out}) should be derated in accordance with the shown diagram.

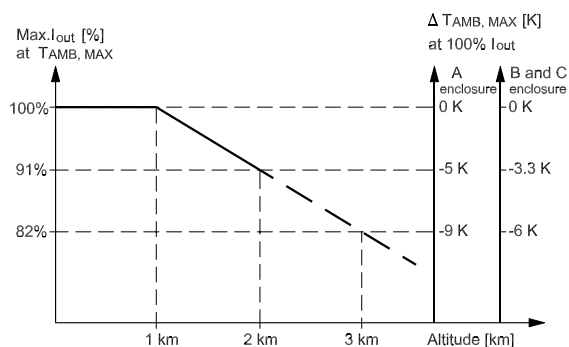


Illustration 8.1: Derating of output current versus altitude at $T_{AMB, MAX}$ for frame sizes A, B and C. At altitudes above 2 km, please contact Danfoss regarding PELV.

An alternative is to lower the ambient temperature at high altitudes and thereby ensure 100% output current at high altitudes. As an example of how to read the graph, the situation at 2 km is elaborated. At a temperature of 45° C ($T_{AMB, MAX} - 3.3$ K), 91% of the rated output current is available. At a temperature of 41.7° C, 100% of the rated output current is available.

8.2.5 Derating for Running at Low Speed

When a motor is connected to a frequency converter, it is necessary to check that the cooling of the motor is adequate.

The level of heating depends on the load on the motor, as well as the operating speed and time.

Constant torque applications (CT mode)

A problem may occur at low RPM values in constant torque applications. In a constant torque application a motor may over-heat at low speeds due to less cooling air from the motor integral fan.

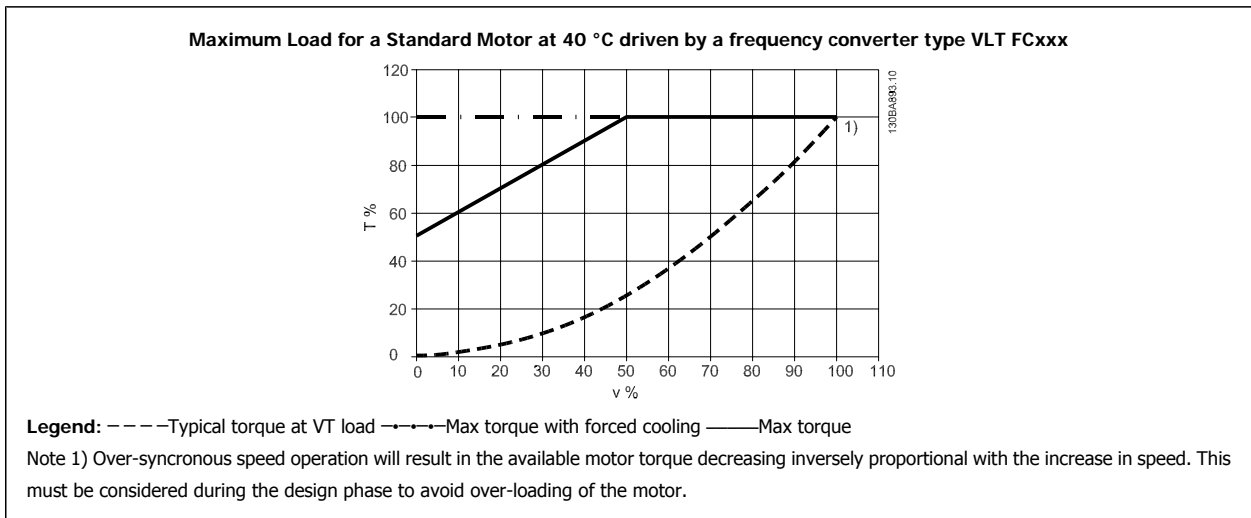
Therefore, if the motor is to be run continuously at an RPM value lower than half of the rated value, the motor must be supplied with additional air-cooling (or a motor designed for this type of operation may be used).

An alternative is to reduce the load level of the motor by choosing a larger motor. However, the design of the frequency converter puts a limit to the motor size.

Variable (Quadratic) torque applications (VT)

In VT applications such as centrifugal pumps and fans, where the torque is proportional to the square of the speed and the power is proportional to the cube of the speed, there is no need for additional cooling or de-rating of the motor.

In the graphs shown below, the typical VT curve is below the maximum torque with de-rating and maximum torque with forced cooling at all speeds.



8.2.6 Derating for Installing Long Motor Cables or Cables with Larger Cross-Section

NB!
Applicable for drives up to 90 kW only.

The maximum cable length for this frequency converter is 300 m unscreened and 150 m screened cable.

The frequency converter has been designed to work using a motor cable with a rated cross-section. If a cable with a larger cross-section is used, reduce the output current by 5% for every step the cross-section is increased.

(Increased cable cross-section leads to increased capacity to earth, and thus an increased earth leakage current).

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