

Resolver Option Module (OPCRES)

OPCRES Resolver Option is used for interfacing resolver moto feedback to AF-650 GP[™]. Resolvers are used basically as motor feedback device for Permanent Magnet brushless synchronous motors.

| | Resolver specifications: | |
|---|--------------------------|------------------------------------|
| r | Resolver poles | Par. RS-50: 2 *2 |
| ' | Resolver Input Voltage | Par. RS-51: 2.0-8.0 Vrms *7.0 Vrms |
| | Resolver Input Frequency | Par. RS-52: 2-15 kHz *10.0 kHz |
| | Transformation ratio | Par. RS-53: 0.1-1.1 *0.5 |
| | Secondary input voltage | Max. 4 Vrms |
| | Secondary load | App. 10 k <u>Ω</u> |

When the Resolver option is ordered separately the kit includes:

- Resolver Option Module (OPCRES)
- Larger keypad cradle and terminal cover for Unit Size 12, 13, and 23 drives (230V to 10HP & 460/575V to 20HP)

Configure Resolver Option Module in parameter group RS-## and with par. EC-60 *Feedback Direction* & EC-61 *Feedback Signal Monitoring*.

The Resolver Option Module supports a various number of resolver types.



NOTE!

The resolver option Module can only be used with rotor-supplied resolver types. Stator-supplied resolvers cannot be used.



LED Indicators

LED 1 is on when the reference signal is OK to resolver LED 2 is on when Cosinus signal is OK from resolver LED 3 is on when Sinus signal is OK from resolver

The LEDs are active when par. EC-61 is set to *Warning* or *Trip*.

Set-up example

In this example a Permanent Magnet (PM) Motor is used with the resolver as speed feedback. A PM motor must usually operate in flux mode.

Wiring:

The max. cable length is 150 m when a twisted pair type of cable is used.

NOTE!

Resolver cables must be screened and separated from the motor cables.

NOTE!

The screen of the resolver cable must be correctly connected to the de-coupling plate and connected to chassis (earth) on the motor to meet European EMC Standards.

NOTE!

Always use screened motor cables and brake chopper cables.

| Adjust following pa | rameters: | | |
|--|---------------------------|---------------------------------|--|
| Par. H-40 | Configuration Mode | Speed closed loop [1] | |
| Par. H-41 | Motor Control Principle | Flux with feedback [3] | |
| Par. P-20 | Motor Construction | PM, non salient SPM [1] | |
| Par. P-03 | Motor Current | Nameplate | |
| Par. P-06 | Motor Nominal Speed | Nameplate | |
| Par. P-42 | Motor Contr. Rated Torque | Nameplate | |
| Auto Tune (Par. P-04) is not available for use on permanent magnet motors. | | | |
| Par. P-37 | d-axis Inductance (Ld) | Motor data sheet (mH) | |
| Par. 1-39 | Motor Poles | Motor data sheet | |
| Par. P-40 | Back EMF at 1000 RPM | Motor data sheet | |
| Par. P-41 | Motor Angle Offset | Motor data sheet (Usually zero) | |
| Par. RS-50 | Poles | Resolver data sheet | |
| Par. RS-51 | Input Voltage | Resolver data sheet | |
| Par. RS-52 | Input Frequency | Resolver data sheet | |
| Par. RS-53 | Transformation Ratio | Resolver data sheet | |
| Par. RS-59 | Resolver Interface | Enabled [1] | |

The instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the GE company.

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imagination at work



