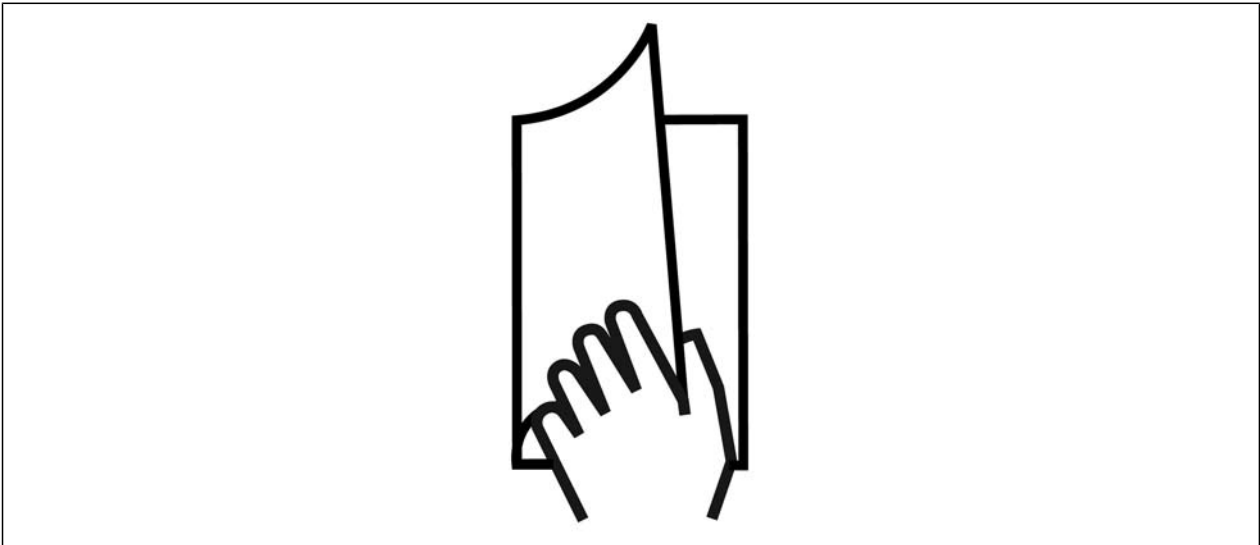


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How to Read this Instruction Manual



□ How to Read the Instruction Manual

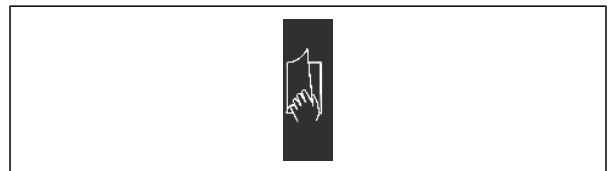
VLT® AutomationDrive FC 300 is designed to provide high shaft performance on electrical motors. Please read this manual carefully for proper use. Incorrect handling of the adjustable frequency drive may cause improper operation of the adjustable frequency drive or related equipment, shorten lifetime or cause other problems.

This Instruction Manual will help you get started and install, program, and troubleshoot your VLT® AutomationDrive FC 300.

The VLT® AutomationDrive FC 300 comes in two shaft performance levels. The VLT® AutomationDrive FC 300 comes in two shaft performance levels. FC 301 ranges from scalar (U/f) to VVC+ and handles asynchronous motors only. The FC 302 is a high performance adjustable frequency drive for asynchronous as well as permanent motors and handles various kinds of motor control principles such as scalar (U/f), VVC + and Flux vector motor control.

This Instruction Manual covers both the FC 301 and the FC 302. Where information covers both series, we refer to the FC 300. Otherwise, we refer specifically to either the FC 301 or the FC 302.

Chapter 1, **How to Read this Instruction Manual**, introduces the manual and informs you of the approvals, symbols and abbreviations used in this literature.



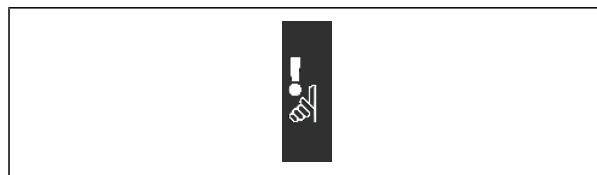
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VLT® AutomationDrive FC 300 Instruction Manual

— How to Read this Instruction Manual —

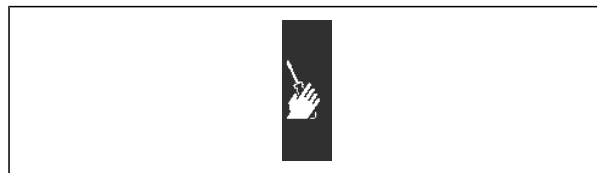


Chapter 2, **Safety Instructions and General Warnings**, contains instructions on how to handle the FC 300 correctly.



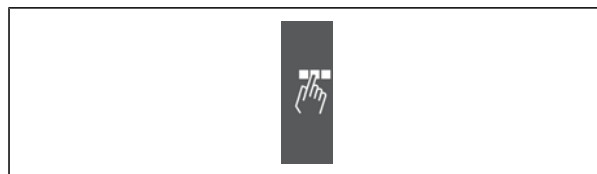
Page divider for Safety Instructions and General Warnings.

Chapter 3, **How to Install**, guides you through mechanical and technical installation.



Page divider for How to Install

Chapter 4, **How to Program**, shows you how to operate and program the FC 300 via the Local Control Panel.



Page divider for How to Program.

Chapter 5, **General Specifications**, contains technical data about the FC 300.



Page divider for General Specifications.

Chapter 6, **Troubleshooting**, assists you in solving problems that may occur when using the FC 300.



Page divider for Troubleshooting.

Available literature for FC 300

- The VLT® AutomationDrive FC 300 Instruction Manual provides the information needed to get the drive up and running.
- The VLT® AutomationDrive FC 300 Design Guide contains all the technical information about the drive design and applications including encoder, resolver and relay options.

VLT® AutomationDrive FC 300 Instruction Manual

— How to Read this Instruction Manual —

- The VLT® AutomationDrive FC 300 Profibus Instruction Manual provides the information required for controlling, monitoring and programming the drive via aProfibusserial communication bus.
- The VLT® AutomationDrive FC 300 DeviceNet Instruction Manual provides the information required for controlling, monitoring and programming the drive via aDeviceNetserial communication bus.
- The VLT® AutomationDrive FC 300MCT 10Instruction Manual provides information for installation and use of the software on a PC.
- The VLT® AutomationDrive FC 300 IP21 / Type 1 Instruction provides information for installing the IP21 / Type 1 option.
- The VLT® AutomationDrive FC 300 24 V DC Backup Instruction provides information for installing the 24 V DC Backup option.



Danfoss Drives technical literature is also available online at www.danfoss.com/drives.

□ Approvals



□ Symbols

Symbols used in these Operating Instructions.



NOTE

Indicates something to be noted by the reader



Indicates a general warning.



Indicates a high voltage warning

* Indicates default setting


▣ Abbreviations

Alternating current	AC
American wire gauge	AWG
Ampere/AMP	A
Automatic Motor Adaptation	AMA
Current limit	I_{LIM}
Degrees Celsius	°C
Direct current	DC
Drive Dependent	D-TYPE
Electro Magnetic Compatibility	EMC
Electronic Thermal Relay	ETR
Adjustable Frequency Drive	AFD
Gram	g
Hertz	Hz
Kilohertz	kHz
Local Control Panel	LCP
Meter	m
Milli Henry Inductance	mH
Milliampere	mA
Millisecond	ms
Minute	min
Motion Control Tool	MCT
Nanofarad	nF
Newton meter	Nm
Nominal motor current	$I_{M,N}$
Nominal motor frequency	$f_{M,N}$
Nominal motor power	$P_{M,N}$
Nominal motor voltage	$U_{M,N}$
Parameter	par.
Protective Extra Low Voltage	PELV
Printed Circuit Board	PCB
Rated Inverter Output Current	I_{INV}
Revolutions per minute	RPM
Second	s
Torque limit	T_{LIM}
Volt	V

Safety Instructions and General Warning



□ Disposal Instructions



Equipment containing electrical components may not be disposed of together with domestic waste.
It must be collected separately as electrical and electronic waste according to local and currently valid legislation.



Caution

The FC 300 AutomationDrive DC link capacitors remain charged after power has been disconnected. To avoid electrical shock, disconnect the FC 300 from the line supply before carrying out maintenance procedures. Before servicing the adjustable frequency drive, wait the minimum amount of time indicated below:

FC 300:	0.3-10 hp [0.25 – 7.5 kW]	4 minutes
FC 300:	15-30 hp [11 – 22 kW]	15 minutes
FC 300:	40-100 hp [30-75 kW]	15 minutes

FC 300
Instruction Manual
Software version: 4.0x



This Instruction Manual can be used for all FC 300 adjustable frequency drives with software version 4.0x.
The software version number can be seen in parameter 15-43.

□ **High voltage warning**



The voltage of the FC 300 is dangerous whenever the converter is connected to electrical power. Incorrect fitting of the motor or adjustable frequency drive may cause damage to the equipment, serious injury or death. Consequently, it is essential to comply with the instructions in this manual as well as local and national rules and safety regulations.

□ **Safety Instructions**

- Make sure the FC 300 is properly connected to ground.
- Do not remove mains plugs or motor plugs while the FC 300 is connected to mains.
- Protect users against supply voltage.
- Protect the motor against overloading according to national and local regulations.
- Motor overload protection is not included in the default settings. To add this function, set parameter 1-90 *Motor thermal protection* to value *ETR trip* or *ETR warning*. For the North American market: ETR functions provide class 20 motor overload protection, in accordance with NEC.
- The ground leakage current exceeds 3.5 mA.
- The [OFF] key is not a safety switch. It does not disconnect the FC 300 from mains.

General warning



Warning:

Touching the electrical parts may be fatal - even after the equipment has been disconnected from line power.

Make sure that other voltage inputs have been disconnected, such as load-sharing (linkage of DC intermediate circuit), as well as the motor connection for kinetic back-up.

Using VLT® AutomationDrive FC 300: wait at least 15 minutes.

A shorter time is allowed only if indicated on the nameplate for the specific unit.

Leakage Current

The ground leakage current from the FC 300 exceeds 3.5 mA. To ensure that the ground cable has a good mechanical connection to the ground connection (terminal 95), the cable-cross section must be at least 0.016 in.² [10 mm²] or 2 times rated ground wires terminated separately.

Residual Current Device

This product can produce D.C. current in the protective conductor. If a residual current device (RCD) is used for extra protection, only an RCD of Type B (time delayed) may be used on the supply side of this product. See also RCD Application Note MN.90.GX.02.

Protective grounding of the FC 300 and the use of RCDs must always meet national and local regulations.



Installation at high altitudes:

At altitudes higher than 6,600 feet [2 km], please contact Danfoss Drives regarding PELV.

□ Before Commencing Repair Work

1. Disconnect FC 300 from AC line.
2. Disconnect DC bus terminals 88 and 89
3. Wait at least 15 minutes
4. Remove motor cable

□ Avoid Unintended Start

While the FC 300 is connected to line power, the motor can be started/stopped using digital commands, bus commands, references or via the Local Control Panel (LCP).

- Disconnect the FC 300 from line power whenever personal safety considerations make it necessary to avoid an unintended start.
- To avoid an unintended starts, always activate the [OFF] key before changing parameters.
- An electronic fault, temporary overload, a fault in the line supply, or lost motor connection may cause a stopped motor to start. The FC 300 with Safe Stop (i.e., FC 301 in A1 enclosure and FC 302) provides protection against unintended starts if the Safe Stop Terminal 37 is on low voltage level or disconnected.

□ Safe Stop of FC 300

The FC 302, and also the FC301 in A1 enclosure, can perform the safety function *Safe Torque Off* (As defined by draft CD IEC 61800-5-2) or *Stop Category 0* (as defined in EN 60204-1).

FC 301 A1 enclosure: When Safe Stop is included in the drive, position 18 of Type Code must be either T or U. If position 18 is B or X, Safe Stop Terminal 37 is not included!

Example:

Type Code for FC 301 A1 with Safe Stop: FC-301PK75T4**Z20**H4TGCXXXSXXXXA0BXCXXXD0

It is designed and deemed suitable for the requirements of Safety Category 3 in EN 954-1. This functionality is called Safe Stop. Prior to integrating and using Safe Stop in an installation, a thorough risk analysis must be carried out on the installation in order to determine whether the Safe Stop functionality and safety category are appropriate and sufficient. In order to install and use the Safe Stop function in accordance with the requirements of Safety Category 3 in EN 954-1, the related information and instructions of the FC 300 Design Guide MG.33.BX.YY must be followed! The information and instructions



contained in the Instruction Manual are not sufficient for a correct and safe use of the Safe Stop functionality!

Prüf- und Zertifizierungsstelle im BG-PRÜFZERT

BGIA
 Berufsgenossenschaftliches Institut für Arbeitsschutz
 Hauptverband der gewerblichen Berufsgenossenschaften

Translation
 In any case, the German original shall prevail.

Type Test Certificate No. of certificate: 05 06004

Name and address of the holder of the certificate (customer): Danfoss Drives A/S, Ulnøes 1, DK-6300 Graasten, Dänemark

Name and address of the manufacturer: Danfoss Drives A/S, Ulnøes 1, DK-6300 Graasten, Dänemark

Ref. of customer: Ref. of Test and Certification Body: Apl/Köln VE-Nr. 2003 23220 Date of issue: 13.04.2005

Product designation: Frequency converter with integrated safety functions

Type: VLT® Automation Drive FC 302

Intended purpose: Implementation of safety function „Safe Stop“

Testing based on: EN 954-1, 1997-03, DKE AK 224.02, 1998-06, EN ISO 13849-2; 2003-12, EN 61800-3, 2001-02, EN 61800-5-1, 2003-09.

Test certificate: No.: 2003 23220 from 13.04.2005

Remarks: The presented types of the frequency converter FC 302 meet the requirements laid down in the test bases. With correct wiring a category 3 according to DIN EN 954-1 is reached for the safety function.

The type tested complies with the provisions laid down in the directive 98/37/EC (Machinery).
 Further conditions are laid down in the Rules of Procedure for Testing and Certification of April 2004.

Head of certification body: (Prof. Dr. rer. nat. Diemar Reimer)
 Certification officer: (Dipl.-Ing. R. Aphfeld)

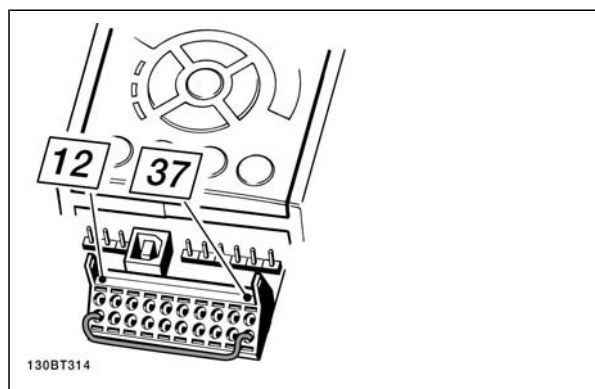
Postal address: 53754 Sankt Augustin
 Office: Alte Heerstraße 111, 53757 Sankt Augustin
 Phone: 0 22 41/2 31-02, Fax: 0 22 41/2 31-22 34



Safe Stop Installation (FC 302 and FC 301 - A1 enclosure only)

To carry out an installation of a Category 0 Stop (EN60204) in accordance with Safety Category 3 (EN954-1), follow these instructions:

1. The bridge (jumper) between Terminal 37 and 24 V DC must be removed. Cutting or breaking the jumper is not sufficient. Remove it entirely to avoid short-circuiting. See jumper on illustration.
2. Connect terminal 37 to 24 V DC by a short circuit-protected cable. The 24 V DC voltage supply must be interruptible by an EN954-1 category 3 circuit interrupt device. If the interrupt device and the adjustable frequency drive are placed in the same installation panel, you can use a regular cable instead of a protected one.



Bridge jumper between terminal 37 and 24 VDC

The illustration below shows a Stopping Category 0 (EN 60204-1) with safety Category 3 (EN 954-1). The circuit interruption is caused by an opening door contact. The illustration also shows how to connect a non-safety-related hardware coast.

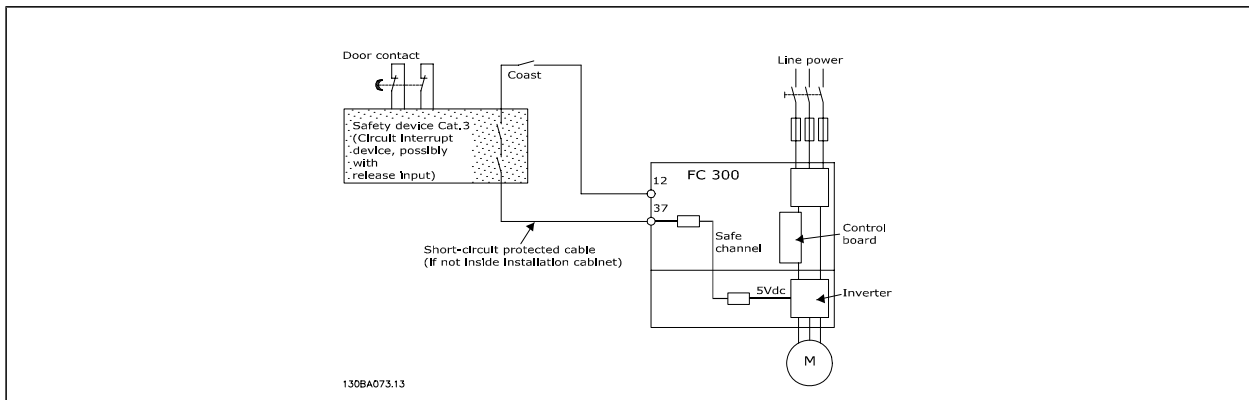


Illustration of the essential aspects of an installation to achieve a Stopping Category 0 (EN 60204-1) with safety Category 3 (EN 954-1).

□ IT Line

Do not connect 400 V adjustable frequency drives with RFI filters to the line supply with a voltage between phase and ground of more than 440 V.

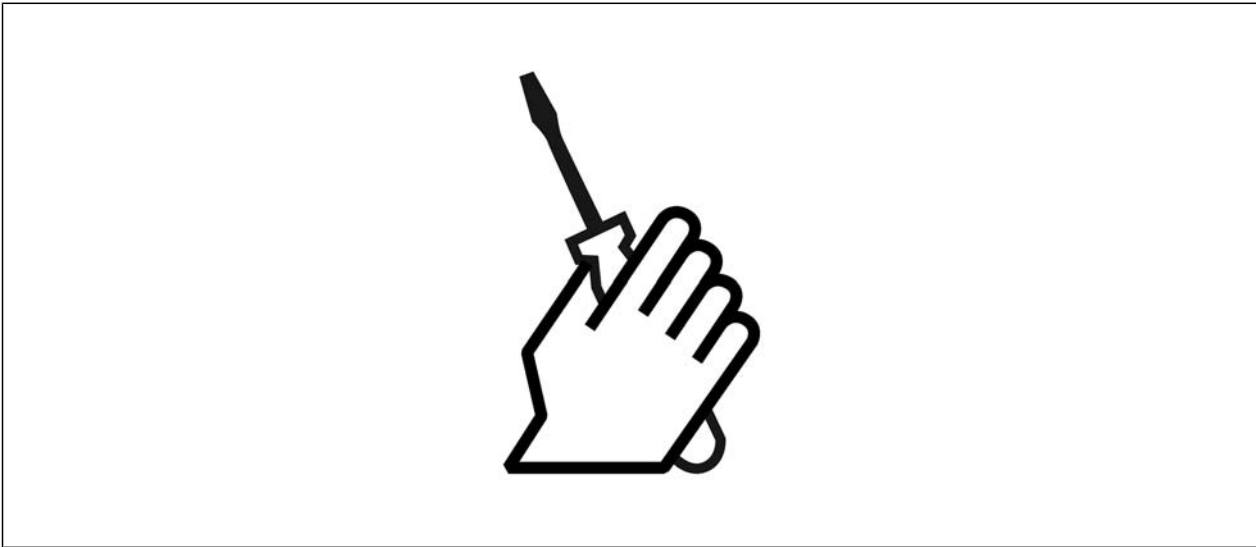
For IT lines and delta ground (grounded leg), line voltage may exceed 440 V between phase and ground.

On the FC 302, par. 14-50 *RFI 1* can be used to disconnect the internal RFI capacitors from the RFI filter to ground. If this is done, it will reduce the RFI performance to A2 level.





How to Install



□ **About How to Install**

This chapter covers mechanical and electrical installations to and from power terminals and control card terminals.

Electrical installation of *options* is described in the corresponding Instructions and Design Guide MG33.BX.YY.

□ **How to Get Started**

The FC 300 AutomationDrive is designed for quick installation and is EMC compliant. Just follow the steps described below.



Read the safety instructions before installing the unit.

Mechanical Installation

- Mechanical Mounting

Electrical Installation

- Connection to Line and Protecting Ground
- Motor connection and cables
- Fuses and circuit breakers
- Control terminals - cables

Quick setup

- Local Control Panel, LCP
- Automatic Motor Adaptation, AMA

- Programming

Frame size is dependent on enclosure type, power range and line voltage.

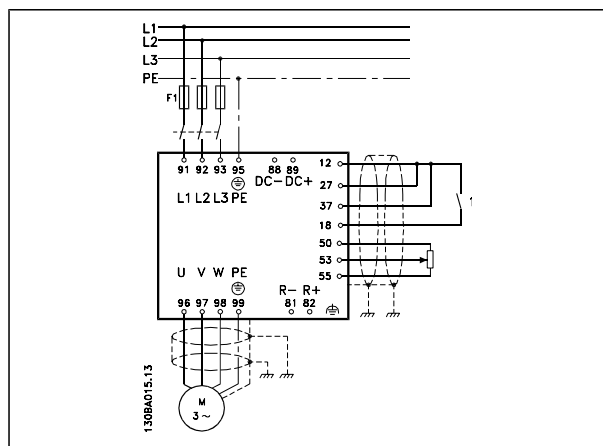


Diagram showing basic installation including line power, motor, start/stop key, and potentiometer for speed adjustment.



Enclosure type	A1		A2		A3		A5		B1		B2		C1		C2	
	IP	NEMA	IP	NEMA	IP	NEMA	IP	NEMA	IP	NEMA	IP	NEMA	IP	NEMA	IP	NEMA
	20/21	1	20/21	1	20/21	1	55/66	4X	21/55/66	12	21/55/66	12	21/55/66	21/55/66	21/55/66	21/55/66
Rated power	0.34-2 hp [0.25-1.5 kW] (200-240 V) 0.5-2 hp [0.37-1.5 kW] (380-480 V)	Chassis/ Type 1	0.34-4 hp [0.25-3 kW] (200-240 V) 0.5-5 hp [0.37-4.0 kW] (380-480/ 500V) 7.5-10 hp 500V	Chassis/ Type 1	5 hp [3.7 kW] (200-240 V) 7.5-10 hp [5.5-7.5 kW] (380-480/ 500 V) 7.5-10 hp [5.5-7.5 kW] (525-600V)	Chassis/ Type 1	0.34-5 hp [0.25-3.7 kW] (200-240 V) 0.5-10 hp [0.37-7.5 kW] (380-480/ 500 V) 1-10 hp [0.75 -7.5 kW] (525-600 V)	Type 12/Type 4X	7.5-10 hp [5.5-7.5 kW] (200-240 V) 15-20 hp [11-15 kW] (380-480/ 500V)	Type 1/Type 12	15 hp [11 kW] (200-250 V) 25-30 hp [18.5-22 kW] (380-480/ 500V)	Type 1/Type 12	20-30 hp [15-22 kW] (200-240 V) 40-60 hp [30-45 kW] (380-480/ 500V)	40-50 hp [30-37 kW] (200-240 V) 75-100 hp [55-75 kW] (380-480/ 500V)		

□ **Accessory Bag**

The following parts are included in the FC 100/300
 Accessory Bag:

130BT309.11
 Frame sizes A1, A2 and A3
 IP20/Chassis

130BT339.10
 Frame size A5
 IP55/Type 12

130BT330
 Frame sizes B1 and B2
 IP21/IP55/Type 1/Type 12

130B406.10
 Frame sizes C1 and C2
 IP55/66/Type 1/Type 12

1 + 2 only available in units with brake chopper. Only one relay connector is included for FC 101/301 units. For DC link connection (Load sharing), the connector 1 can be ordered separately (Code no 130B1064).
 An eight-pole connector is included in the accessory bag for the FC 101/301 without Safe Stop.



□ Mechanical Installation

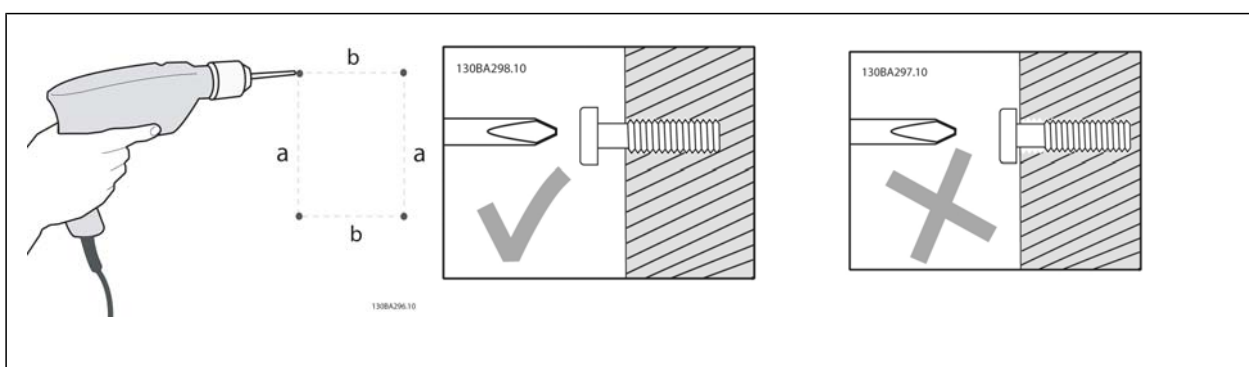
□ Mechanical Mounting

FC 300 IP20 Frame sizes A1, A2 and A3 allow side-by-side installation. Due to cooling conditions, there must be a minimum of 4 in. [100 mm] free air passage above and below the FC 300.

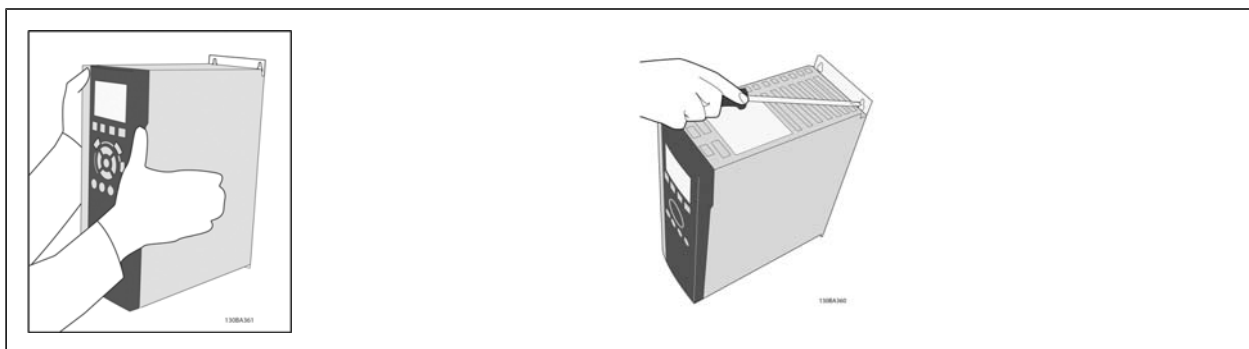
If the IP 21 Enclosure kit (130B1122 or 130B1123) is used, there must be a min. clearance of 2 in. [50 mm] between the drives.

B1, B2, C1 and C2 enclosures allow for side-by-side installation.

1. Drill holes in accordance with the measurements given.
2. You must use screws that are suitable for the surface on which you want to mount the FC 300. Retighten all four screws.



Mounting frame sizes A1, A2 and A3:

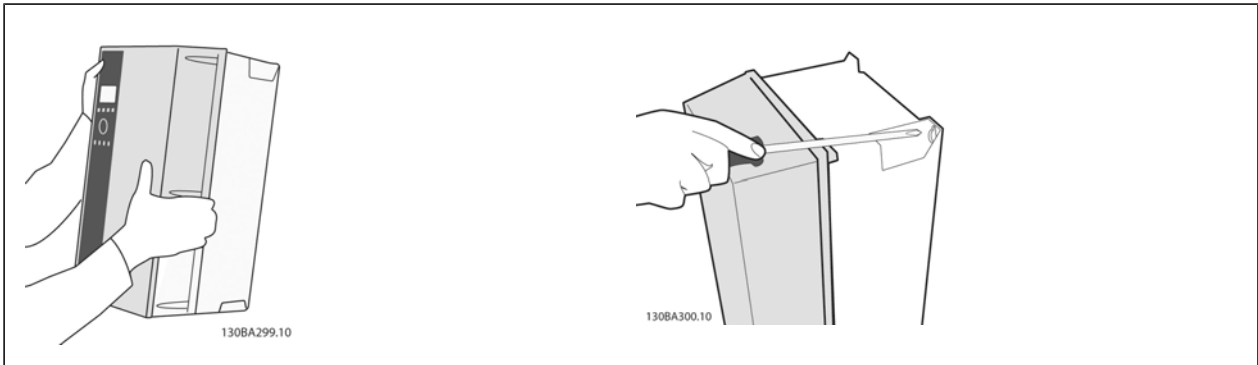


VLT® AutomationDrive FC 300 Instruction Manual

— How to Install —

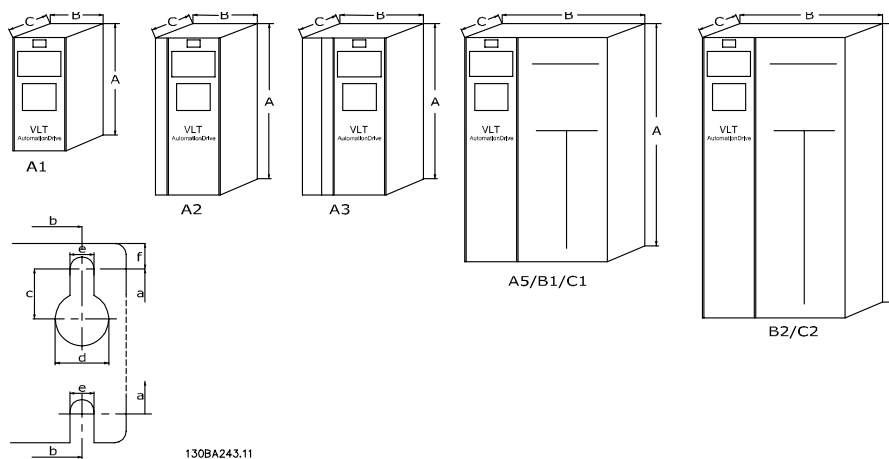
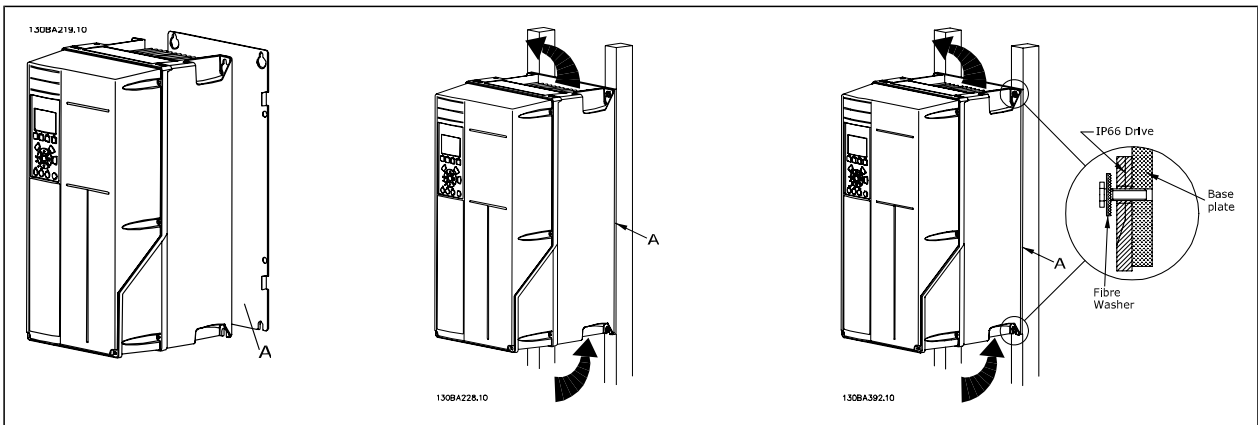
Mounting frame sizes A5, B1, B2, C1 and C2:

The back wall must always be solid for optimum cooling.



When mounting frame sizes A5, B1, B2, C1 and C2 on a non-solid back wall, the drive must be

provided with a back plate A due to insufficient cooling air over the heatsink.



See the following table for enclosure dimensions.

Frame size	Mechanical dimensions												
	A1	A2	A3	A5	B1	B2	C1	C2					
	0.3-2 hp [0.25-1.5 kW] (200-240 V) 0.5-2 hp [0.37-1.5 kW] (380-480 V)	0.3-4 hp [0.25-3 kW] (200-240 V) 0.5-5 hp [0.37-4.0 kW] (380-480/500 V) 1-5 hp [0.75-4 kW] (525-600 V)	5 hp [3.7 kW] (200-240 V) 7.5-10 hp [5.5-7.5 kW] (380-480/500 V) 7.5-10 hp [5.5-7.5 kW] (525-600 V)	0.3-5 hp [0.25-3.7 kW] (200-240 V) 0.5-10 hp [0.37-7.5 kW] (380-480/500 V) 1-10 hp [0.75-7.5 kW] (525-600 V)	7.5-10 hp [5.5-7.5 kW] (200-240 V) 15-20 hp [11-15 kW] (380-480/500 V)	11 kW (200-240 V) 25-30 hp [18.5-22 kW] (380-480/500 V)	20-30 hp [15-22 kW] (200-240 V) 40-60 hp [30-45 kW] (380-480/500 V)	40-50 hp [30-37 kW] (200-240 V) 75-100 hp [55-75 kW] (380-480/500 V)					
IP NEMA	20 Chassis Type 1	21 Type 1	20 Chassis Type 1	21 Type 1	21 Type 1	21 Type 1	55/66 Type 12	21/55/66 Type 1/Type 12	21/55/66 Type 1/Type 12	21/55/66 Type 1/Type 12	21/55/66 Type 1/Type 12	21/55/66 Type 1/Type 12	
Height													
Height of back-plate	A 7.87 in. [200 mm]												
Height with de-coupling plate	A 315.95												
Distance between mounting holes	a 7.5 in. [190 mm]												
Width													
Width of back-plate	B 2.95 in. [75 mm]												
Width of back-plate with one C option	B 5.12 in. [130 mm]												
Width of back-plate with two C options	B 5.91 in. [150 mm]												
Distance between mounting holes	b 2.36 in. [60 mm]												
Depth													
Depth without option A/B	C 8.07 in. [205 mm]												
With option A/B	C 8.66 [220 mm]												
Without option A/B	D 8.14 in. [207 mm]												
With option A/B	D 8.74 in. [222 mm]												
Screw holes													
c	0.24 in. [6.0 mm]												
d	ø0.35 in. [8 mm]												
e	ø0.20 in. [5 mm]												
f	0.20 in. [5 mm]												
Max weight	5.95 lbs [2.7 kg]	10.8 lbs [4.9 kg]	14.55 lbs [6.6 kg]	14.55 lbs [6.6 kg]	15.43 lbs [7.0 kg]	15.43 lbs [7.0 kg]	29.76/31.31 lbs [13.5/14.2 kg]	0.35 in. [9 mm]	0.35 in. [9 mm]	0.35 in. [9 mm]	0.35 in. [9 mm]	59.51 lbs [27 kg]	94.8 [43 kg]

□ Electrical Installation



NOTE

Cables General

All cabling must comply with national and local regulations on cable cross-sections and ambient temperature. Copper (140°-167°F [60/75°C]) conductors are recommended.

Aluminum Conductors

Terminals can accept aluminum conductors, but the conductor surface must be clean, and the oxidation must be removed and sealed by neutral acid-free Vaseline grease before the conductor is connected.

Furthermore, the terminal screw must be retightened after two days due to the softness of the aluminum. It is crucial to keep the connection a gas-tight joint, otherwise the aluminum surface will oxidize again.

Tightening-up Torque					
AFD size	200-240 V	380-500 V	525-600 V	Cable for:	Tightening torque
A1	0.3-2 hp [0.25-1.5 kW]	0.5-2 hp [0.37-1.5 kW]	-	Line, brake resistor, load sharing, motor cables	0.5-0.6 Nm
A2	0.3-3 hp [0.25-2.2 kW]	0.5-5 hp [0.37-4 kW]	1-5 hp [0.75-4 kW]		
A3	4-5 hp [3-3.7 kW]	7.5-10 hp [5.5-7.5 kW]	7.5-10 hp [5.5-7.5 kW]		
A5	4-5 hp [3-3.7 kW]	7.5-10 hp [5.5-7.5 kW]	1-10 hp [0.75-7.5 kW]		
B1	7.5-10 hp [5.5-7.5 kW]	15-20 hp [11-15 kW]	-	Line, brake resistor, load sharing, motor cables	1.8 Nm
B2	11 kW	18.5-22 kW	-	Relay	0.5-0.6 Nm
				Ground	2-3 Nm
				Line, brake resistor, load sharing cables	4.5 Nm
C1	20-30 hp [15-22 kW]	40-60 hp [30-45 kW]	-	Motor cables	4.5 Nm
				Relay	0.5-0.6 Nm
				Ground	2-3 Nm
C2	40-50 hp [30-37 kW]	75-100 hp [55-75 kW]	-	Line, brake resistor, load sharing cables	14 Nm
				Motor cables	10 Nm
				Relay	0.5-0.6 Nm
				Ground	2-3 Nm

□ Removal of Knockouts for Extra Cables

1. Remove the cable entry from the adjustable frequency drive (avoid foreign parts entering the adjustable frequency drive when removing knockouts).
2. The cable entry must be supported around the knockout you intend to remove.
3. The knockout can now be removed with a strong mandrel and a hammer.
4. Remove burrs from the hole.
5. Mount cable entry on adjustable frequency drive.



□ Connection to Line and Ground



NOTE

The plug connector for power can be connected to FC 302 for up to 10 hp [7.5 kW].

1. Insert the two screws into the de-coupling plate, slide it into place and tighten the screws.
2. Make sure the FC 300 is properly grounded. Connect to the ground connection (terminal 95). Use the screw from the accessory bag.
3. Place plug connector 91(L1), 92(L2), 93(L3) from the accessory bag onto the terminals labeled MAINS at the bottom of the FC 300.
4. Attach the line wires to the line power plug connector.
5. Support the cable with the enclosed supporting brackets.



NOTE

Make sure that the line voltage corresponds to the given line voltage on the FC 300 nameplate.

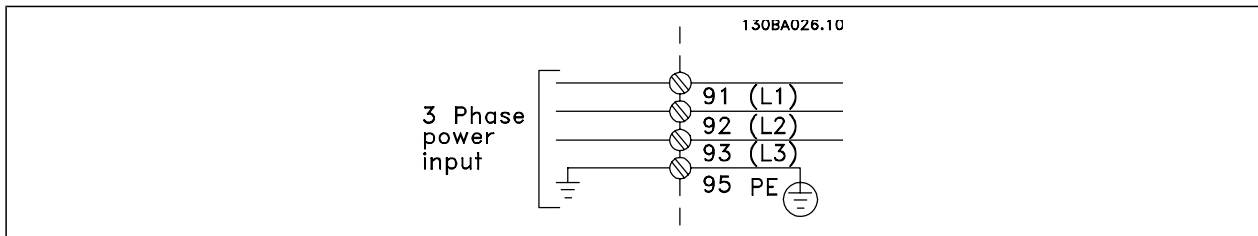
IT Line

Do not connect 400 V adjustable frequency drives with RFI filters to line supplies with a voltage between phase and ground of more than 440 V.



The ground connection cable cross-section must be at least 0.016 in.² [10 mm²] or 2 x rated line wires terminated separately according to EN 50178.

The line connection is fitted to the line switch if this is included.

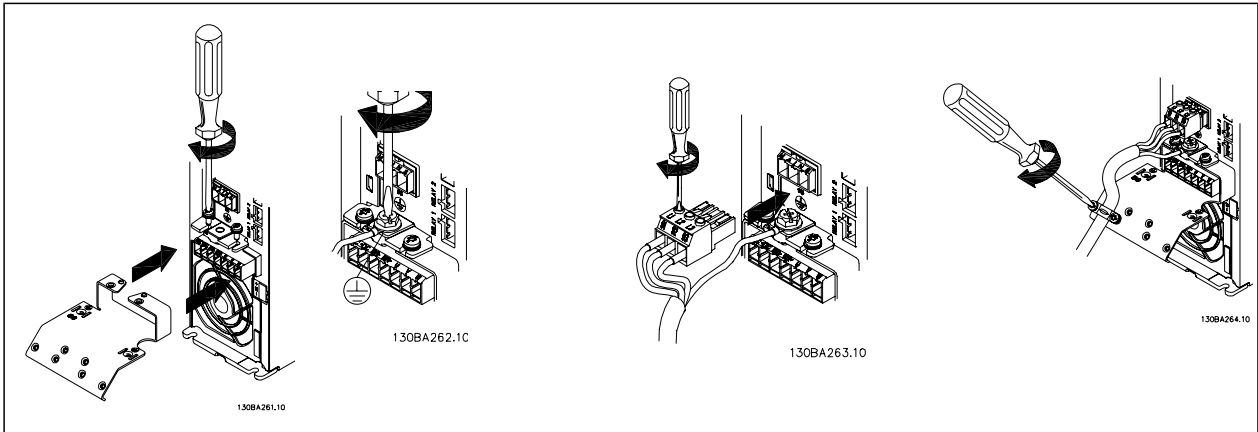


Line connection for A1, A2 and A3 frame sizes:

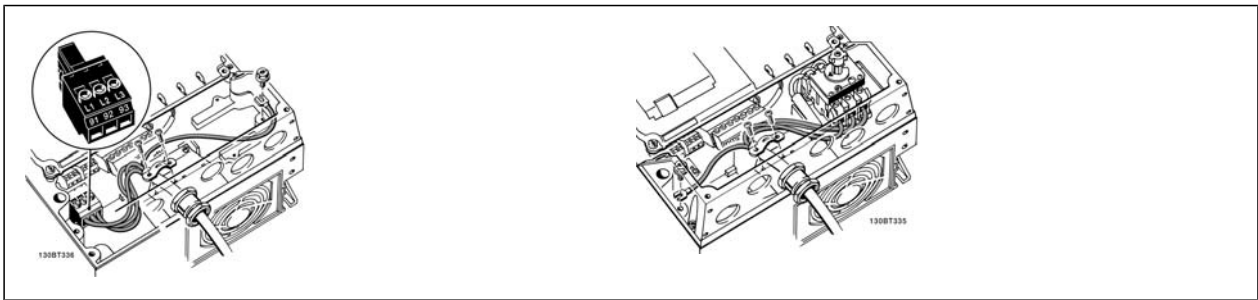


NOTE

The plug connector for power can be removed.

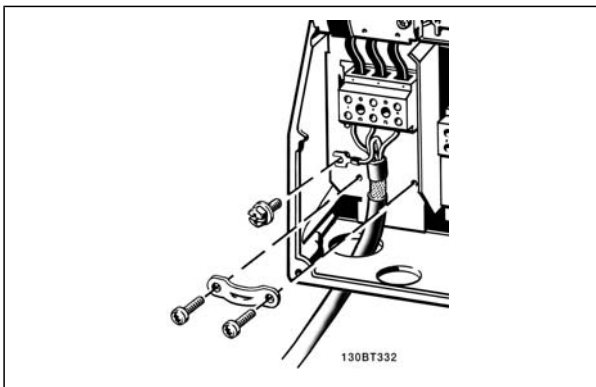


Line connector A5 (IP 55/66) Enclosure

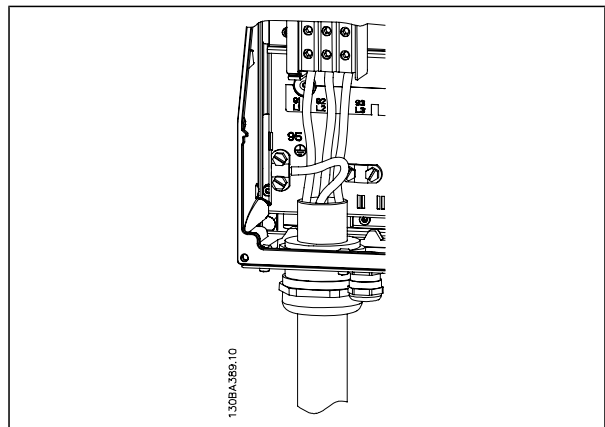


When the disconnecter is used (A5 enclosure), the PE must be mounted on the left side of the drive.

Line connection B1 and B2 (IP 21/NEMA Type 1 and IP 55/66/ NEMA Type 12) enclosures



Line connection C1 and C2 (IP 21/ NEMA Type 1 and IP 55/66/ NEMA Type 12) enclosures



The power cables for line power are usually unshielded cables.

□ **Motor Connection**



NOTE

Motor cable must be shielded/armored. The use of an unshielded/unarmored cable is against EMC requirements. Use a shielded/armored motor cable to comply with EMC emission specifications. For more information, see *EMC specifications* in the *VLT® AutomationDrive FC 300 Design Guide*.

See the General Specifications section for the correct dimensioning of the motor cable cross-section and length.

Shielding of cables: Avoid installation with twisted shield ends (pigtailed). If it is necessary to break the shield to install a motor isolator or motor contactor, the shield must be continued at the lowest possible HF impedance.

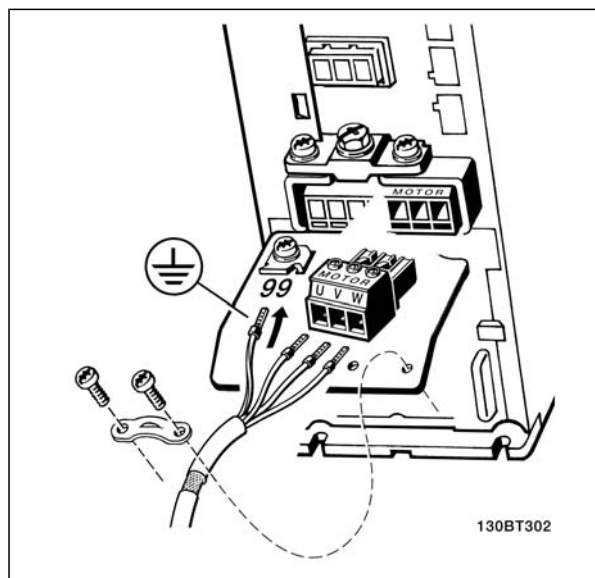
Connect the motor cable shield to both the FC 300 decoupling plate and the motor's metal housing. Make the shield connections with the largest possible surface area (cable clamp). This is done by using the supplied installation devices in the FC 300.

If it is necessary to split the shield to install a motor isolator or motor relay, the shield must be continued with the lowest possible HF impedance.

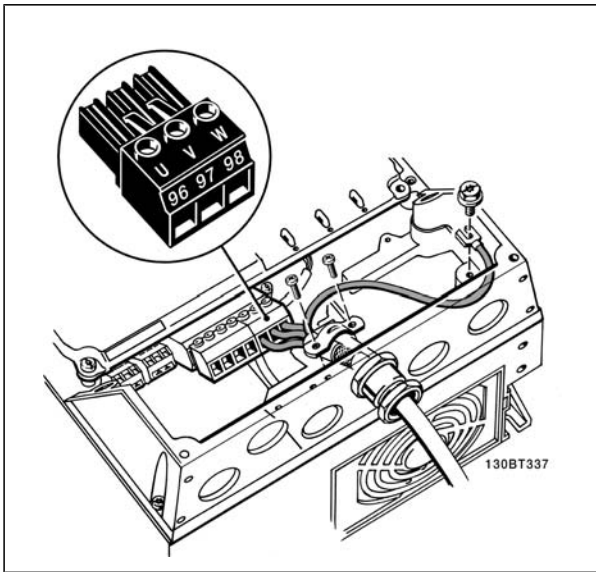
Cable-length and cross-section: The adjustable frequency drive has been tested with a given length and cross-section of that cable. If the cross-section is increased, the cable capacitance - and thus the leakage current - may increase, thereby requiring the cable length to be reduced correspondingly. Keep the motor cable as short as possible to reduce the noise level and leakage currents.

Switching frequency: When adjustable frequency drives are used together with LC filters to reduce the acoustic noise from a motor, the switching frequency must be set according to the LC filter instructions in Par. 14-01.

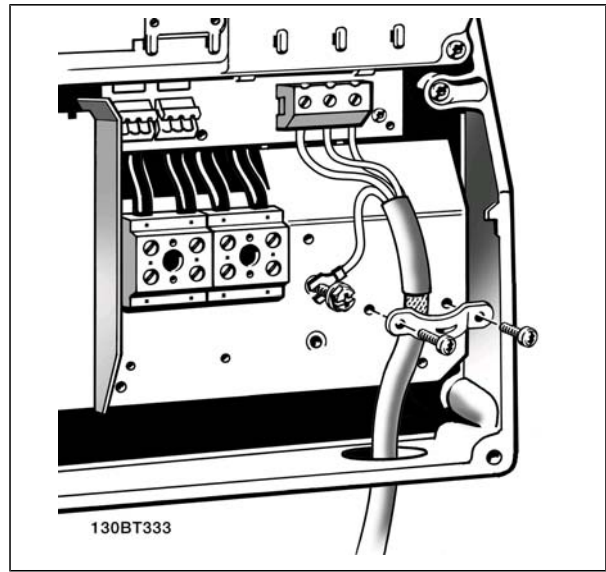
1. Fasten decoupling plate to the bottom of the FC 300 with screws and washers from the accessory bag.
2. Attach motor cable to terminals 96 (U), 97 (V), 98 (W).
3. Connect to ground connection (terminal 99) on decoupling plate with screws from the accessory bag.
4. Insert plug connectors 96 (U), 97 (V), 98 (W) (up to 10 hp [7.5 kW]) and motor cable to terminals labeled MOTOR.
5. Fasten shielded cable to the decoupling plate with screws and washers from the accessory bag.



Motor connection for A1, A2 and A3

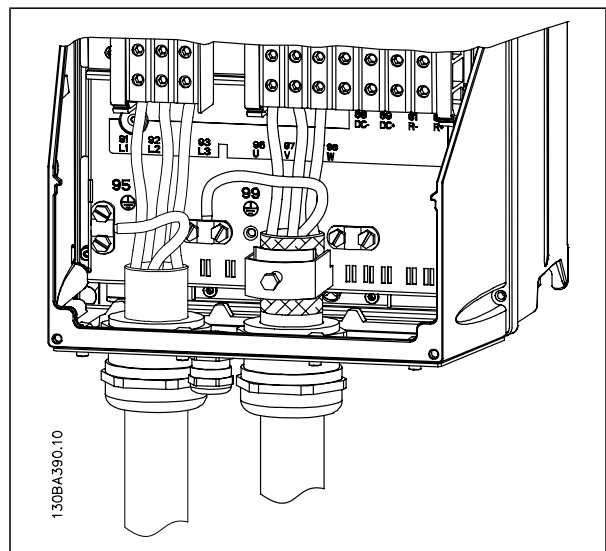


Motor connection for A5 (IP 55/66/NEMA Type 12) enclosure



Motor connection for B1 and B2 (IP 21/ NEMA Type 1, IP 55/ NEMA Type 12 and IP66/ NEMA Type 4X) enclosure

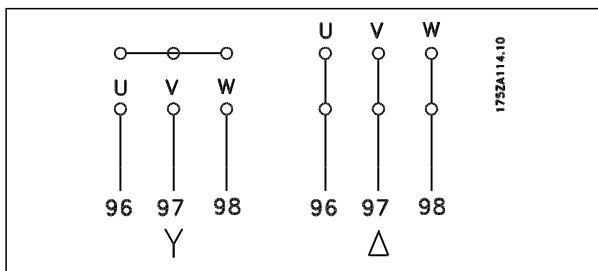
All types of three-phase asynchronous standard motors can be connected to the FC 300. Normally, small motors are star-connected (230/400 V, Y). Large motors are normally delta-connected (400/690 V Δ). Refer to the motor nameplate for correct connection mode and voltage.



Motor connection C1 and C2 (IP 21/ NEMA Type 1 and IP 55/66/ NEMA Type 12) enclosure

Term. no.	96	97	98	99	
	U	V	W	PE ¹⁾	Motor voltage 0-100% of line voltage. 3 wires out of motor
	U1	V1	W1	PE ¹⁾	Delta-connected
	W2	U2	V2		6 wires out of motor
	U1	V1	W1	PE ¹⁾	Star-connected U2, V2, W2 U2, V2 and W2 to be interconnected separately.

¹⁾Protected Ground Connection



NOTE

In motors without phase insulation paper or other insulation reinforcement suitable for operation with voltage supply (such as an adjustable frequency drive), fit an LC filter on the FC 300 output.

Fuses

Branch circuit protection:

In order to protect the installation against electrical and fire hazards, all branch circuits in an installation, switch gear, machines, etc. must be short-circuited and overcurrent protected according to national/international regulations.

Short-circuit protection:

The adjustable frequency drive must be protected against short-circuit to avoid electrical or fire hazard. Danfoss recommends using the fuses mentioned below to protect service personnel and equipment in case of an internal failure in the drive. The adjustable frequency drive provides full short-circuit protection in case of a short-circuit on the motor output.

Overcurrent protection:

Provide overload protection to avoid fire hazard due to overheating of the cables in the installation. The adjustable frequency drive is equipped with an internal overcurrent protection that can be used for upstream overload protection (UL applications excluded). See par. 4-18. Moreover, fuses or circuit breakers can be used to provide the overcurrent protection in the installation. Overcurrent protection must always be carried out according to national regulations.

Fuses must be designed for protection in a circuit capable of supplying a maximum of 100,000 A_{rms} (symmetrical), 500 V maximum.

Non-UL compliance

If UL/cUL is not to be complied with, we recommend using the following fuses, which will ensure compliance with EN50178:

In case of malfunction, not following the recommendation may result in unnecessary damage to the adjustable frequency drive.

FC 300	Max. fuse size ¹⁾	Voltage	Type
K25-K75	10A	200-240 V	type gG
1K1-2K2	20A	200-240 V	type gG
3K0-3K7	32A	200-240 V	type gG
5K5-7K5	63A	380-500 V	type gG
11K	80A	380-500 V	type gG
15K-18K	125A	380-500 V	type gG
5			
22K	160A	380-500 V	type aR
30K	200A	380-500 V	type aR
37K	250A	380-500 V	type aR

FC 300	Max. fuse size ¹⁾	Voltage	Type
K37-1K5	10A	380-500 V	type gG
2K2-4K0	20A	380-500 V	type gG
5K5-7K5	32A	380-500 V	type gG
11K-18K	63A	380-500 V	type gG
22K	80A	380-500 V	type gG
30K	100A	380-500 V	type gG
37K	125A	380-500 V	type gG
45K	160A	380-500 V	type aR
55K-75K	250A	380-500 V	type aR

1) Max. fuses - see national/international regulations to select an appropriate fuse size.

UL Compliance

200-240 V

FC 300	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K25-K75	KTN-R10	JKS-10	JJN-10	5017906-010	KLN-R10	ATM-R10	A2K-10R
1K1-2K2	KTN-R20	JKS-20	JJN-20	5017906-020	KLN-R20	ATM-R20	A2K-20R
3K0-3K7	KTN-R30	JKS-30	JJN-30	5012406-032	KLN-R30	ATM-R30	A2K-30R
5K5	KTN-R50	KS-50	JJN-50	5014006-050	KLN-R50		A2K-50R
7K5	KTN-R60	JKS-60	JJN-60	5014006-063	KLN-R60		A2K-60R
11K	KTN-R80	JKS-80	JJN-80	5014006-080	KLN-R80		A2K-80R
15K-18K5	KTN-R125	JKS-150	JJN-125	2028220-125	KLN-R125		A2K-125R
22K	FWX-150	---	---	2028220-150	L25S-150		A25X-150
30K	FWX-200	---	---	2028220-200	L25S-200		A25X-200
37K	FWX-250	---	---	2028220-250	L25S-250		A25X-250

380-500 V, 525-600 V

FC 300	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K37-1K5	KTS-R10	JKS-10	JJS-10	5017906-010	KLS-R10	ATM-R10	A6K-10R
2K2-4K0	KTS-R20	JKS-20	JJS-20	5017906-020	KLS-R20	ATM-R20	A6K-20R
5K5-7K5	KTS-R30	JKS-30	JJS-30	5012406-032	KLS-R30	ATM-R30	A6K-30R
11K	KTS-R40	JKS-40	JJS-40	5014006-040	KLS-R40		A6K-40R
15K	KTS-R50	JKS-50	JJS-50	5014006-050	KLS-R50		A6K-50R
18K	KTS-R60	JKS-60	JJS-60	5014006-063	KLS-R60		A6K-60R
22K	KTS-R80	JKS-80	JJS-80	2028220-100	KLS-R80		A6K-80R
30K	KTS-R100	JKS-100	JJS-100	2028220-125	KLS-R100		A6K-100R
37K	KTS-R125	JKS-150	JJS-150	2028220-125	KLS-R125		A6K-125R
45K	KTS-R150	JKS-150	JJS-150	2028220-150	KLS-R150		A6K-150R
55K	FWH-220	-	-	2028220-200	L50S-225		A50-P225
75K	FWH-250	-	-	2028220-250	L50S-250		A50-P250

KTS fuses from Bussmann may substitute for KTN for 240 V adjustable frequency drives.

FWH fuses from Bussmann may substitute for FWX for 240 V adjustable frequency drives.

KLSR fuses from LITTEL FUSE may substitute for KLN-R fuses for 240 V adjustable frequency drives.

L50S fuses from LITTEL FUSE may substitute for L50S fuses for 240 V adjustable frequency drives.

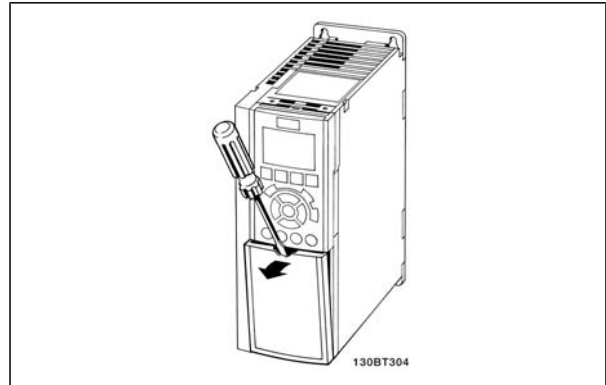
A6KR fuses from FERRAZ SHAWMUT may substitute for A2KR for 240 V adjustable frequency drives.

A50X fuses from FERRAZ SHAWMUT may substitute for A25X for 240 V adjustable frequency drives.



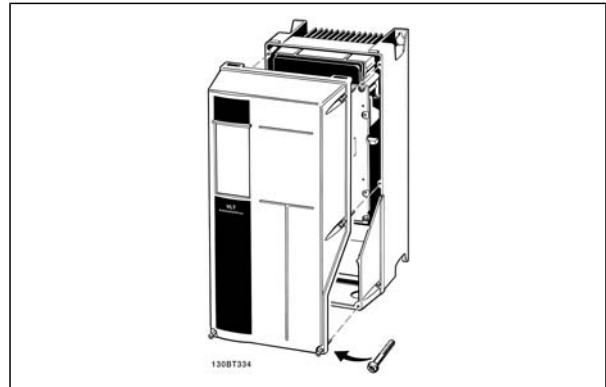
□ **Access to Control Terminals**

All terminals to the control cables are located underneath the terminal cover on the front of the adjustable frequency drive. Remove the terminal cover with a screwdriver.



A2 and A3 enclosures

Remove front cover to access control terminals. When replacing the front cover, ensure proper fastening by applying a torque of 2 Nm.



A5, B1, B2, C1 and C2 enclosures

□ **Electrical Installation, Control Terminals**

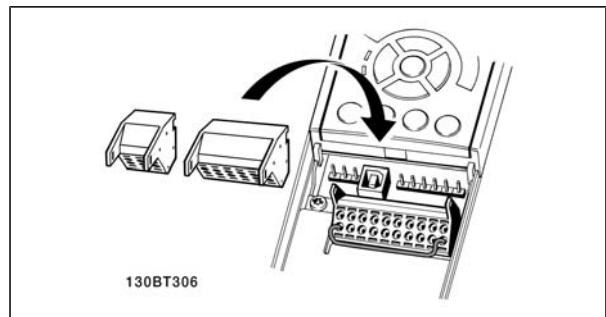
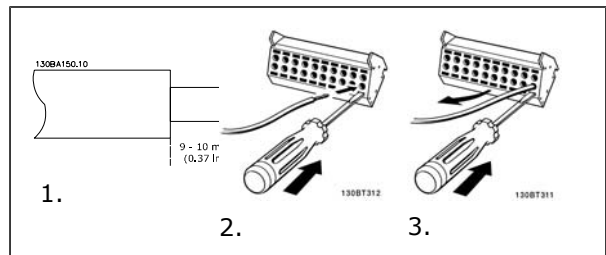
To mount the cable to the terminal:

1. Strip isolation of 0.34-0.39 in [9-10 mm]
2. Insert a screw driver¹⁾ in the square hole.
3. Insert the cable in the adjacent circular hole.
4. Remove the screwdriver. The cable is now mounted to the terminal.

To remove the cable from the terminal:

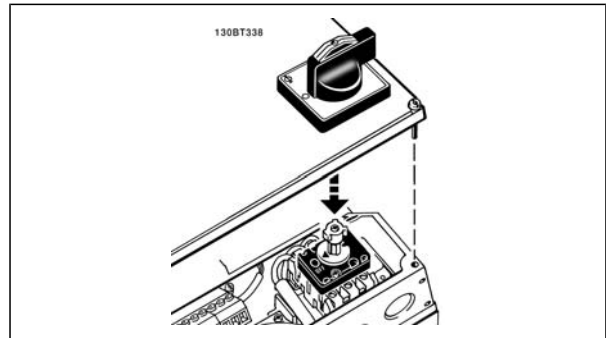
1. Insert a screw driver¹⁾ in the square hole.
2. Pull out the cable.

¹⁾ Max. 0.015 x 0.1 in. [0.4 x 2.5 mm]



Assembling of IP55 / NEMA Type 12 (A5 housing) with line supply disconnector

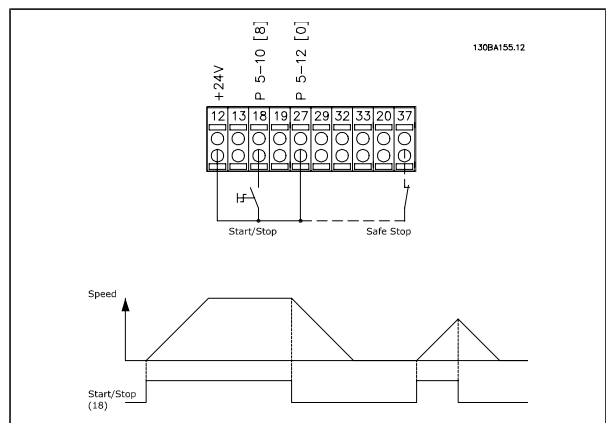
The line power switch is placed on the left side on the B1, B2, C1 and C2 enclosures. The line power switch on the A5 enclosure is placed on the right side



□ Connection Examples

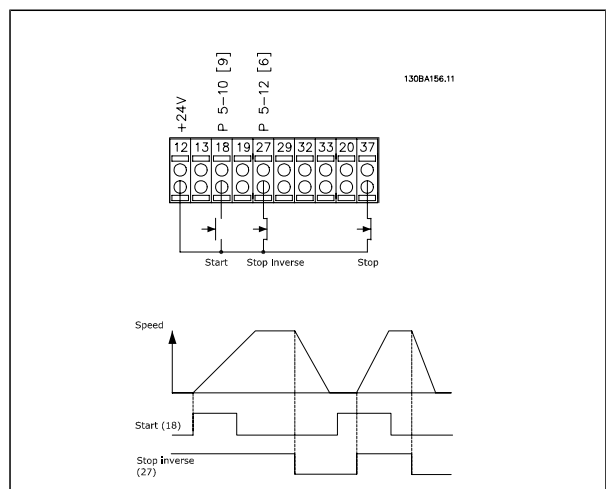
□ Start/Stop

- Terminal 18 = Par. 5-10 [8] *Start*
- Terminal 27 = Par. 5-12 [0] *No operation (Default coast inverse)*
- Terminal 37 = Safe stop (FC 302 and FC 301 A1 only)



□ Pulse Start/Stop

- Terminal 18 = Par. 5-10 [9] *Latched start*
- Terminal 27 = Par. 5-12 [6] *Stop inverse*
- Terminal 37 = Safe stop (FC 302 and FC 301 A1 only)



□ **Speed up/slow down**

Terminals 29/32 = Speed up/slow down.

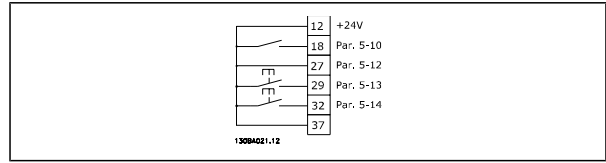
Par. 5 *Digital input* = *Pulse start* -10

Par. 5 *Digital input* = *Freeze reference* -12

Par. 5 *Digital input* = *Speed up* -13

Par. 5-14 *Digital input* = *Slow down*

Note: Terminal 29 only in FC 302.



□ **Potentiometer Reference**

Voltage reference via a potentiometer.

Reference Source 1 = [1] *Analog input*
 53 (default)

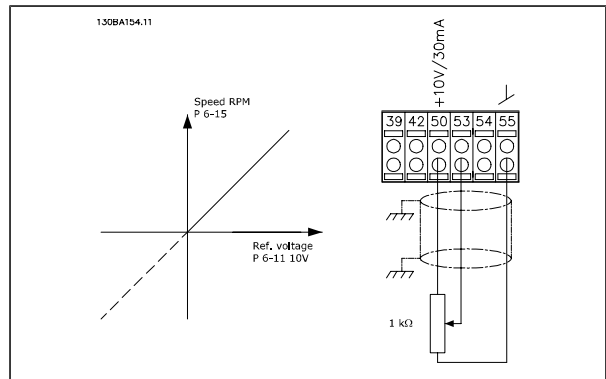
Terminal 53, Low Voltage = 0 Volt

Terminal 53, High Voltage = 10 Volt

Terminal 53, Low Ref./Feedback = 0 RPM

Terminal 53, High Ref./Feedback = 1500 RPM

Switch S201 = OFF (U)



□ Electrical Installation, Control Cables

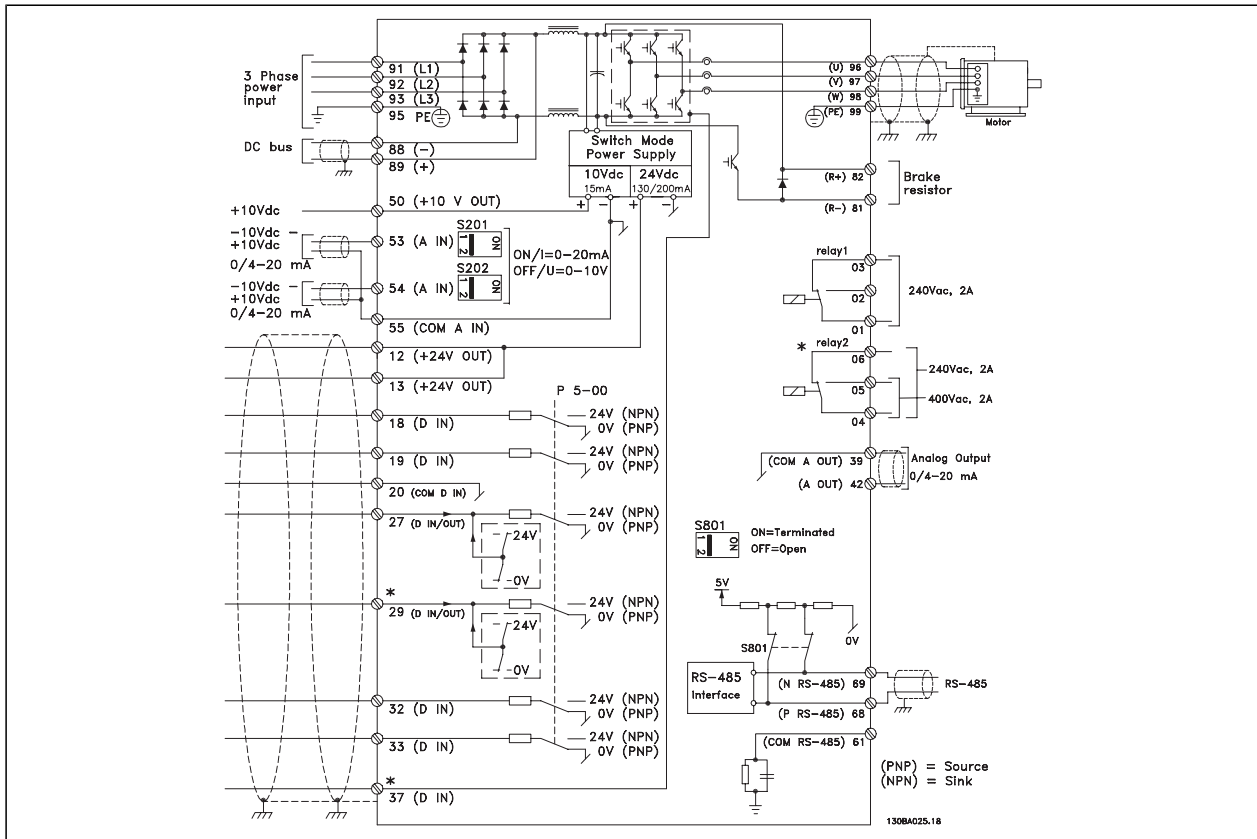


Diagram showing all electrical terminals without options.
 Terminal 37 is the input to be used for Safe Stop. For instructions on Safe Stop installation, please refer to the section *Safe Stop Installation* in the FC 300 Design Guide.

* Terminal 37 is not included in the FC 301 (Except the FC 301 A1, which includes Safe Stop).
 Terminal 29, Relay 2, is not included in the FC 301.

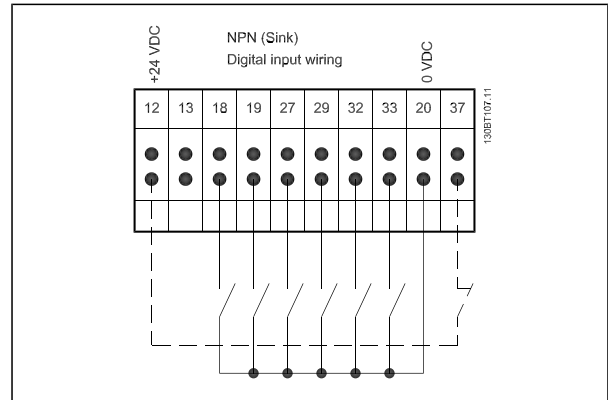
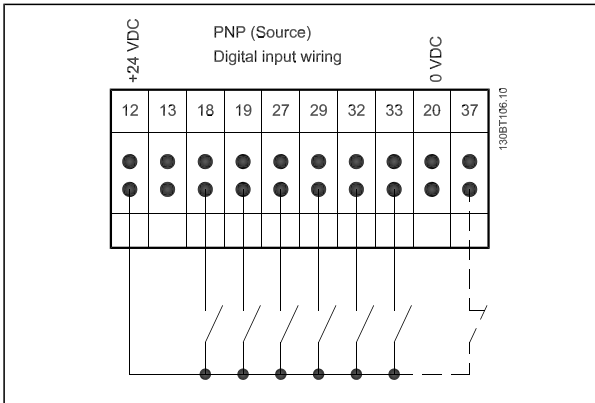
In rare cases, very long control cables and analog signals may, depending on installation, result in 50/60 Hz ground loops due to noise from line supply cables.

If this occurs, it may be necessary to break the shield or insert a 100 nF capacitor between shield and chassis.

The digital and analog inputs and outputs must be connected separately to the FC 300 common inputs (terminal 20, 55, 39) to avoid letting ground currents from both groups affect other groups. For example, switching on the digital input may disturb the analog input signal.

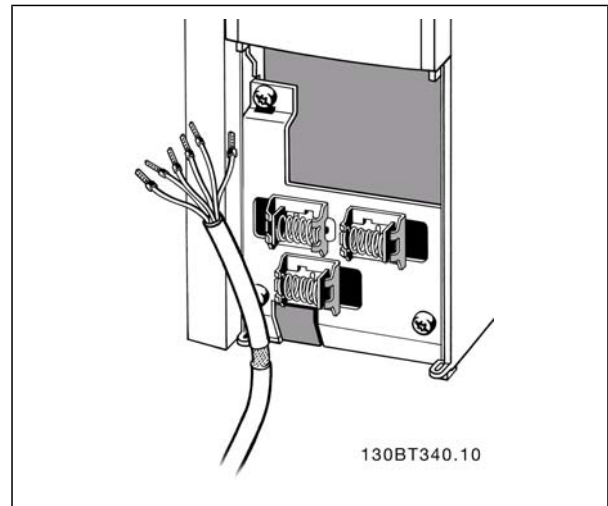


Input polarity of control terminals



NOTE
 Control cables must be shielded/armored.

See the section entitled *Grounding of Shielded/Armored Control Cables* for the correct termination of control cables.



□ **Switches S201, S202, and S801**

Switches S201 (A53) and S202 (A54) are used to select a current (0-20 mA) or a voltage (-10 to 10 V) configuration for the analog input terminals 53 and 54, respectively.

Switch S801 (BUS TER.) can be used to enable termination on the RS-485 port (terminals 68 and 69).

See drawing *Diagram showing all electrical terminals* in the *Electrical Installation* section.

Default settings:

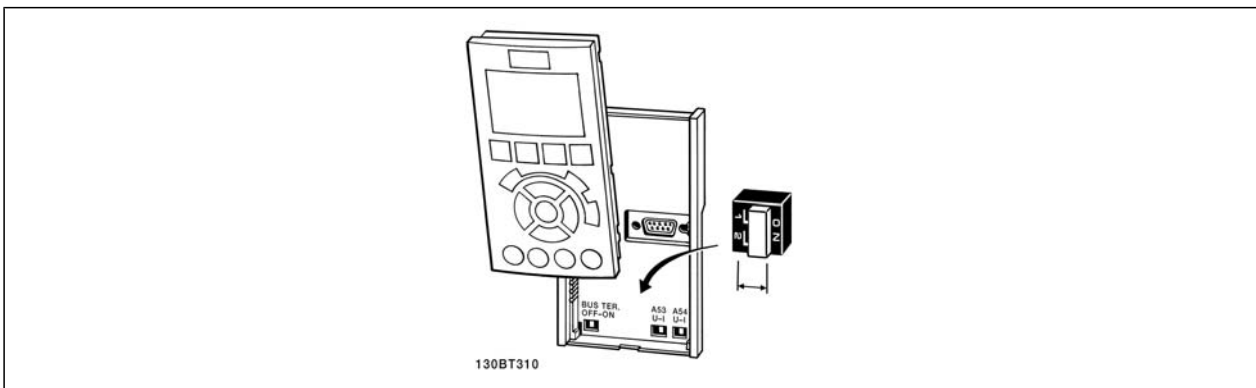
S201 (A53) = OFF (voltage input)

S202 (A54) = OFF (voltage input)

S801 (Bus termination) = OFF



When changing the function of S201, S202 or S801, be careful not to force the switch over. Removing the LCP fixture (cradle) when operating the switches is recommended. The switches must not be operated while the adjustable frequency drive is powered.



□ Final Set-Up and Test

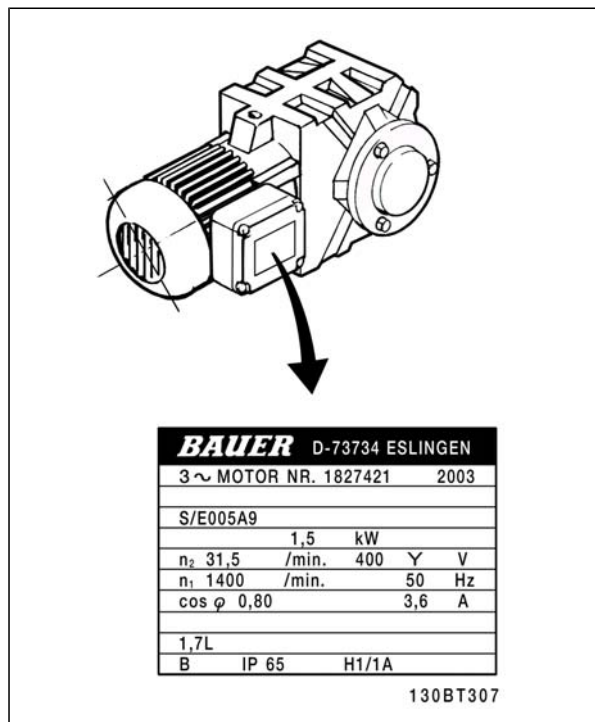
To test the set-up and ensure that the adjustable frequency drive is running, follow these steps.

Step 1. Locate the motor nameplate.



NOTE

The motor is either star (Y) or delta-connected (Δ). This information is located on the motor nameplate data.



Step 2. Enter the motor nameplate data in this parameter list.

To access this list first press the [QUICK MENU] key, then select "Q2 Quick Setup".

1.	Motor Power [kW] or Motor Power [HP]	par. 1-20 par. 1-21
2.	Motor Voltage	par. 1-22
3.	Motor Frequency	par. 1-23
4.	Motor Current	par. 1-24
5.	Motor Nominal Speed	par. 1-25

Step 3. Activate the Automatic Motor Adaptation (AMA)

Performing an AMA will ensure optimum performance. The AMA measures the values from the motor model equivalent diagram.

1. Connect terminal 37 to terminal 12 (if terminal 37 is available).
2. Connect terminal 27 to terminal 12 or set par. 5-12 to 'No function' (par. 5-12 [0]).
3. Activate the AMA par. 1-29.
4. Choose between complete or reduced AMA. If an LC filter is mounted, run only the reduced AMA, or remove the LC filter during the AMA procedure.
5. Press the [OK] key. The display shows "Press [Hand on] to start".
6. Press the [Hand on] key. A progress bar indicates if the AMA is in progress.

Stop the AMA during operation.

1. Press the [OFF] key. The adjustable frequency drive enters into alarm mode and the display shows that the AMA was terminated by the user.

Successful AMA

1. The display shows "Press [OK] to finish AMA".
2. Press the [OK] key to exit the AMA state.

Unsuccessful AMA

1. The adjustable frequency drive enters into alarm mode. A description of the alarm can be found in the *Troubleshooting* section.
2. "Report Value" in the [Alarm Log] shows the last measuring sequence carried out by the AMA, before the adjustable frequency drive entered alarm mode. This number, along with the description of the alarm, will assist you in troubleshooting. If you contact Danfoss for service, make sure to mention the number and alarm description.



NOTE

Unsuccessful AMA is often caused by incorrectly-registered motor nameplate data or too big of a difference between the motor power size and the FC 300 power size.

Step 4. Set speed limit and ramp time

Set up the desired limits for speed and ramp time.

Minimum Reference	par. 3-02
Maximum Reference	par. 3-03
Motor Speed Low Limit	par. 4-11 or 4-12
Motor Speed High Limit	par. 4-13 or 4-14
Ramp-up Time 1 [s]	par. 3-41
Ramp-down Time 1 [s]	par. 3-42



□ Additional Connections

□ Mechanical Brake Control

In hoisting/lowering applications, it is necessary to be able to control an electro-mechanical brake.

- Control the brake using any relay output or digital output (terminal 27 or 29).
- Keep the output closed (voltage-free) as long as the adjustable frequency drive is unable to 'support' the motor, such as when the load is too heavy, for example.
- Select *Mechanical brake control* [32] in par. 5-4* for applications with an electro-mechanical brake.
- The brake is released when the motor current exceeds the preset value found in par. 2-20.
- The brake is engaged when the output frequency is less than the frequency found in par. 2-21 or 2-22, and only if the adjustable frequency drive carries out a stop command.

If the adjustable frequency drive is in alarm mode or in an overvoltage situation, the mechanical brake immediately cuts in.

□ Parallel Connection of Motors

The adjustable frequency drive can control several parallel-connected motors. The total current consumption of the motors must not exceed the rated output current $I_{M,N}$ for the adjustable frequency drive.

Parallel motor connection is only recommended when U/f is selected in par. 1-01.



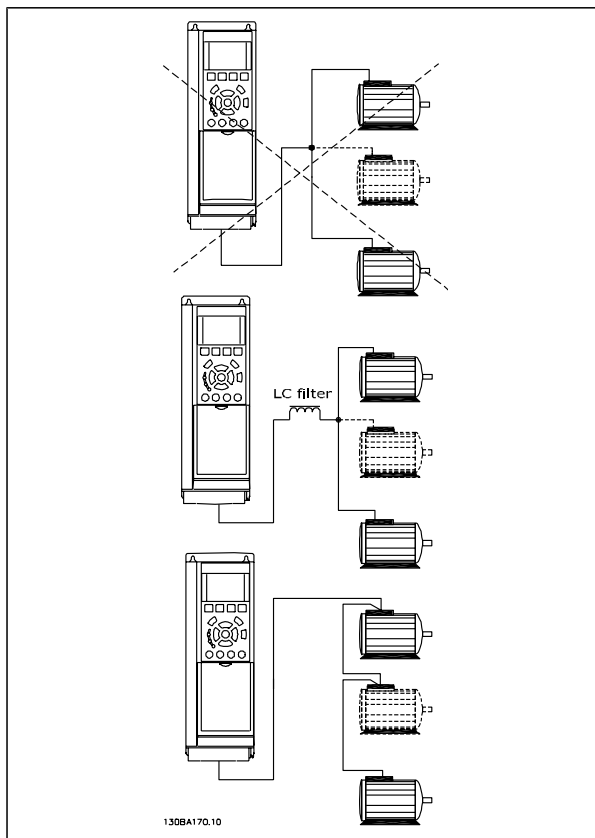
NOTE

Installation with cables connected in a common joint as in illustration 1 is only recommended for short cable lengths.



NOTE

When motors are connected in parallel, par. 1-02 *Automatic Motor Adaptation (AMA)* cannot be used, and par. 1-01 *Motor Control Principle* must be set to *Special motor characteristics (U/f)*.



Problems may arise at start and at low RPM values if motor sizes are widely different, because small motors' relatively high ohmic resistance in the stator calls for a higher voltage at start and at low RPM values.

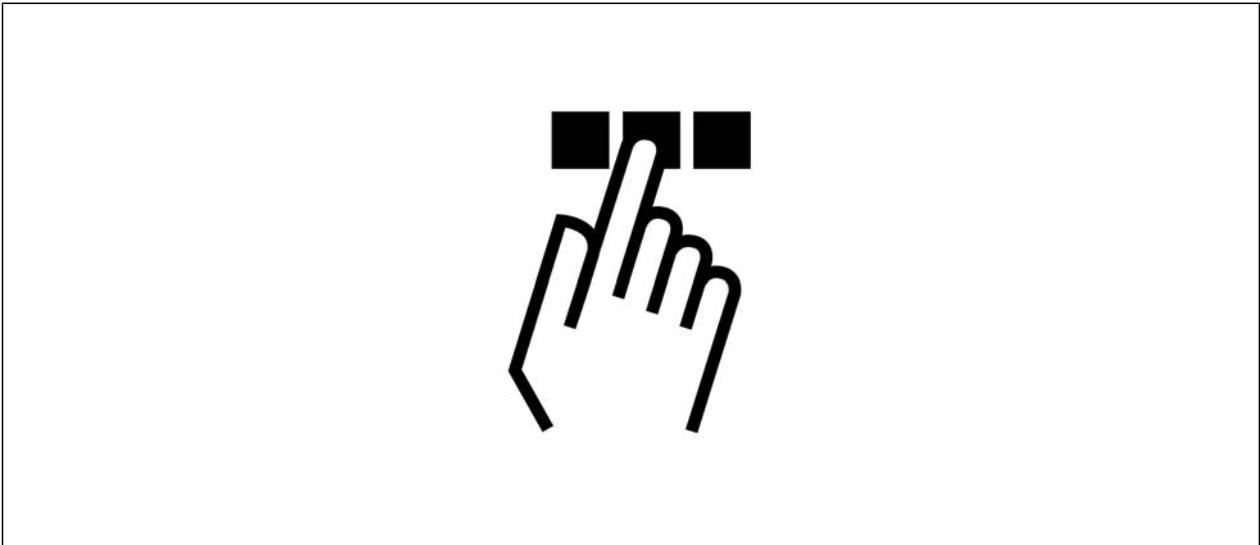
□ **Motor Thermal Protection**

The electronic thermal relay in FC 300 has received the UL-approval for single motor protection, when par. 1-90 *Motor Thermal Protection* is set for *ETR Trip* and par. 1-24 *Motor current, $I_{M,N}$* is set to the rated motor current (see motor nameplate).





How to Program



▣ The FC 300 Graphical and Numerical LCP

The easiest way to program FC 300 adjustable frequency drives is by using the Graphical Local Control Panel (G-LCP). It is necessary to consult the FC 300 Design Guide when using the Numerical Local Control Panel (N-LCP).

▣ How to Program on the Graphical LCP

The following instructions are valid for the Graphical LCP (LCP 102):

The control panel is divided into four functional groups:

1. Graphical display with Status lines.
2. Menu keys and LEDs - changing parameters and switching between display functions.
3. Navigation keys and lights (LEDs).
4. Operation keys and LEDs.

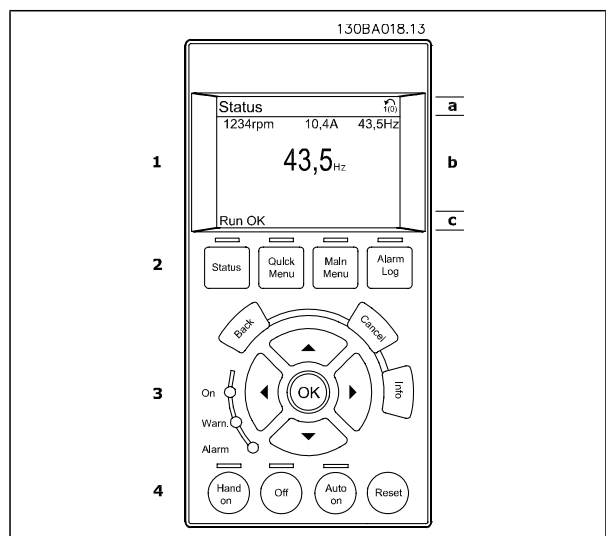
All data is displayed in a graphical LCP display, which can show up to five items of operating data while displaying [Status].

Display lines:

- a. **Status line:** Status messages displaying icons and graphic.
- b. **Line 1-2:** Operator data lines displaying data defined or chosen by the user. By

pressing the [Status] key, up to one extra line can be added.

- c. **Status line:** Status messages displaying text.

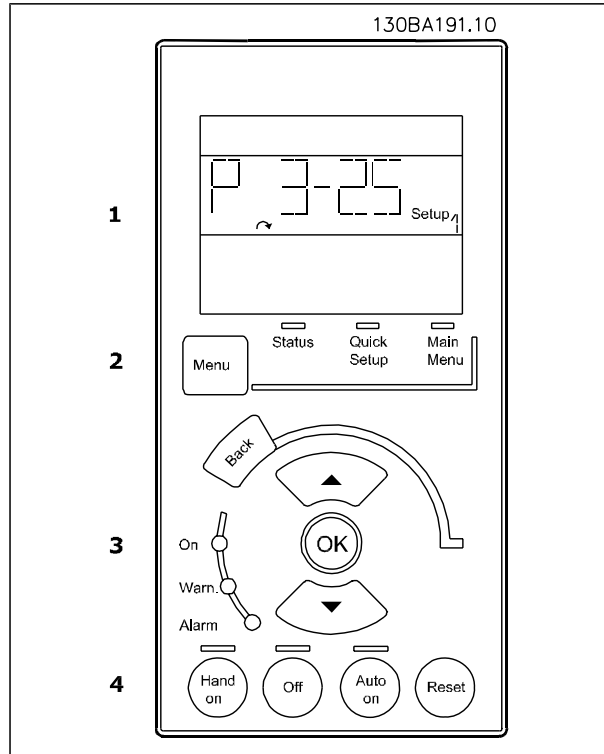


□ **How to Program using the Numerical Local Control Panel**

The following instructions are valid for the Numerical LCP (LCP 101):

The control panel is divided into four functional groups:

1. Numerical display.
2. Menu keys and LEDs - changing parameters and switching between display functions.
3. Navigation keys and lights (LEDs).
4. Operation keys and LEDs.



□ **Initial Commissioning**

The easiest way of doing the initial commissioning is to use the Quick Menu button and follow the quick set-up procedure using G-LCP (read table from left to right):

Press

0-01 Language		Set language		
1-20 Motor power		Set motor nameplate power		
1-22 Motor voltage		Set nameplate voltage		
1-23 Motor frequency		Set nameplate frequency		
1-24 Motor current		Set nameplate current		
1-25 Motor nominal speed		Set nameplate speed in RPM		
5-12 Terminal 27 Digital Input		If the terminal default is <i>Coast inverse</i> , it is possible to change this setting to <i>No function</i> . No connection to terminal 27 is then needed for running AMA		
1-29 Automatic Motor Adaptation		Set desired AMA function. Enabling complete AMA is recommended		
3-02 Minimum Reference		Set the minimum speed of the motor shaft		
3-03 Maximum Reference		Set the maximum speed of the motor shaft		
3-41 Ramp1 up time		Set the ramping-up time with reference to the nominal motor speed (set in par. 1-25)		
3-42 Ramp1 down time		Set the ramping-down time with reference to the nominal motor speed (set in par. 1-25)		
3-13 Reference site		Set the site from where the reference must work		



□ Quick Setup

0-01 Language	
Value:	
* English UK (English UK)	[0]
German (Deutsch)	[1]
French (Français)	[2]
Danish (Dansk)	[3]
Spanish (Español)	[4]
Italian (Italiano)	[5]
Swedish (Svenska)	[6]
Dutch (Nederlands)	[7]
Chinese (中文)	[10]
Finnish (Suomi)	[20]
English US (English US)	[22]
Greek (ελληνικά)	[27]
Portuguese (Português)	[28]
Slovenian (Slovenščina)	[36]
Korean (한국어)	[39]
Japanese (日本語)	[40]
Turkish (Türkçe)	[41]
Traditional Chinese (國語)	[42]
Bulgarian (Български)	[43]
Serbian (Srpski)	[44]
Romanian (Română)	[45]
Hungarian (Magyar)	[46]
Czech (Česky)	[47]
Polish (Polski)	[48]
Russian (Русский)	[49]
Thai (ไทย)	[50]
Bahasa Indonesian (Bahasa Indonesia)	[51]

Function:

Defines the language to be used in display.

The adjustable frequency drive can be delivered with 4 various language packages. English and German are included in all packages. English cannot be erased or manipulated.

Language package 1 consists of: English, German, French, Danish, Spanish, Italian and Finnish.

Language package 2 consists of: English, German, Chinese, Korean, Japanese, Thai and Bahasa Indonesian.

Language package 3 consists of: English, German, Slovenian, Bulgarian, Serbian, Romanian, Hungarian, Czech and Russian.

Language package 4 consists of: English, German, Spanish, English US, Greek, Brazilian Portuguese, Turkish and Polish.

1-20 Motor Power

Value:

1.2-675 hp [0.09 - 500 kW] [Size related]

Function:

Enter the nominal motor power in kW according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit. This parameter cannot be adjusted while the motor is running.

1-22 Motor Voltage

Value:

200-600 V [M-TYPE]

Function:

Enter the nominal motor voltage according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit. This parameter cannot be adjusted while the motor is running.

1-23 Motor Frequency

Value:

- * 50 Hz when parameter 0-03 = international (50 HZ) [50]
- 60 Hz when parameter 0-03 = US (60 HZ) [60]
- Min - Max motor frequency: 20-1000 Hz

* factory setting () display text [] value for use in communication via serial communication port

Function:

Select the motor frequency value from the motor nameplate data. If a value different from 50 Hz or 60 Hz is selected, it is necessary to adapt the load independent settings in par. 1-50 to 1-53. For 87 Hz operation with 230/400 V motors, set the nameplate data for 230 V/50 Hz. Adapt par. 4-13 *Motor Speed High Limit [RPM]* and par. 3-03 *Maximum Reference* to the 87 Hz application.

1-24 Motor Current

Value:

Motor type dependent.

Function:

Enter the nominal motor current value from the motor nameplate data. This data is used for calculating motor torque, motor thermal protection, etc.
 This parameter cannot be adjusted while the motor is running.

1-25 Motor Nominal Speed

Value:

100 - 60000 RPM * RPM

Function:

Enter the nominal motor speed value from the motor nameplate data. This data is used for calculating automatic motor compensations.
 This parameter cannot be adjusted while the motor is running.

1-29 Automatic Motor Adaptation (AMA)

Value:

- * OFF [0]
- Enable complete AMA [1]
- Enable reduced AMA [2]

Function:

The AMA function optimizes dynamic motor performance by automatically optimizing the advanced motor parameters (par. 1-30 to par. 1-35) while the motor is at a standstill.

Select the type of AMA. *Enable complete AMA* [1] performs AMA of the stator resistance R_s , the rotor resistance R_r , the stator leakage reactance X_1 , the rotor leakage reactance X_2 and the main reactance X_h . Select this option if an LC filter is used between the drive and the motor.

FC 301: The Complete AMA does not include X_h measurements for the FC 301. Instead, the X_h value is determined from the motor database. Par. 1-35 *Main Reactance (X_h)* may be adjusted to obtain optimal start performance.

Select *Reduced AMA* [2] for a reduced AMA of the stator resistance R_s in the system only. Activate the AMA function by pressing [Hand on] after selecting [1] or [2]. See also the section *Automatic Motor Adaptation*. After a normal sequence, the display will read: "Press [OK] to finish AMA". After pressing the [OK] key, the adjustable frequency drive is ready for operation. This parameter cannot be adjusted while the motor is running.

Note:

- To best adapt the adjustable frequency drive, run AMA on a cold motor.
- AMA cannot be performed while the motor is running.
- AMA cannot be performed on permanent magnet motors.



NOTE

It is important to set motor par. 1-2* Motor Data correctly, since these form part of the AMA algorithm. An AMA must be performed to achieve optimum dynamic motor performance. It may take up to 10 min, depending on the power rating of the motor.



NOTE

Avoid generating external torque during AMA.



NOTE

If one of the settings in par. 1-2* Motor Data is changed, par. 1-30 to 1-39, the advanced motor parameters, will return to default setting.



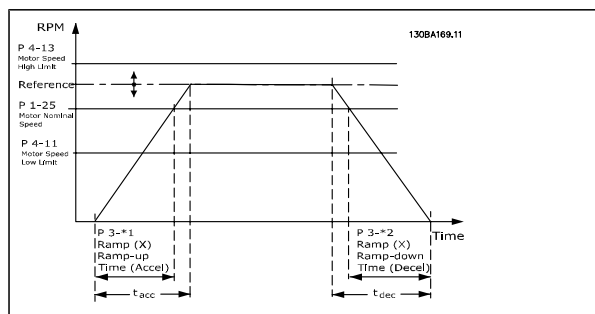
3-02 Minimum Reference

Value:

-100000.000 - par. 3-03 * 0.000 Unit

Function:

The *Minimum reference* is the minimum value obtained by the sum of all references. *Minimum reference* is only active if *Min - Max [0]* is set in par. 3-00.



3-03 Maximum Reference

Value:

Par. 3-02 - 100000.000 * 1500.000

Function:

Enter the maximum reference. The Maximum Reference is the highest sum of all references. The Maximum Reference unit matches:

- The choice of configuration in par. 1-00 *Configuration Mode*: for *Speed closed-loop [1]*, RPM; for *Torque [2]*, Nm.
- The unit selected in par. 3-01 *Reference/Feedback Unit*.

3-41 Ramp 1 Ramp-up Time

Value:

0.01-3600.00 s * s

Function:

Enter the ramp-up time, i.e., the acceleration time from 0 RPM to the rated motor speed $n_{M,N}$ (par. 1-25). Enter the ramp-up time, i.e., the acceleration time from 0 RPM to the rated motor speed $n_{M,N}$ (par. 1-25). Enter the ramp-up time, i.e., the acceleration time from 0 RPM to the rated motor speed $n_{M,N}$ (par. 1-25). Enter the ramp-up time, i.e., the acceleration time from 0 RPM to the rated motor speed $n_{M,N}$ (par. 1-25).

$$Par. 3-41 = \frac{t_{acc} [s] \times n_{M,N} (par. 1-25) [RPM]}{\Delta ref [RPM]}$$

3-42 Ramp 1 Ramp-down Time

Value:

0.01-3600.00 s * s

Function:

Enter the ramp-down time, i.e., the deceleration time from the rated motor speed $n_{M,N}$ (par. 1-25) to 0 RPM. Choose a ramp-down time such that no overvoltage arises in the inverter due to the regenerative operation of the motor, and such that the generated current does not exceed the current limit set in par. 4-18. The value 0.00 corresponds to 0.01 s in speed mode. See ramp-up time in par. 3-41.

$$Par. 3-42 = \frac{t_{acc} [s] \times n_{M,N} (par. 1-25) [RPM]}{\Delta ref [RPM]}$$

5-12 Terminal 27 Digital Input

Function:

Select the function from the available digital input range.

No operation	[0]
Reset	[1]
Coast inverse	[2]
Coast and reset inv.	[3]
Quick stop inverse	[4]
DC brake inverse	[5]
Stop inverse	[6]
Start	[8]
Latched start	[9]
Reversing	[10]
Start reverse	[11]
Enable start forward	[12]
Enable start reverse	[13]
Jog	[14]
Preset ref bit 0	[16]
Preset ref bit 1	[17]

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Preset ref bit 2	[18]
Freeze reference	[19]
Freeze output	[20]
Speed up	[21]
Slow	[22]
Set-up select bit 0	[23]
Set-up select bit 1	[24]
Catch up	[28]
Slow-down	[29]
Pulse input	[32]
Ramp bit 0	[34]
Ramp bit 1	[35]
Line failure inverse	[36]
DigiPot increase	[55]
DigiPot decrease	[56]
DigiPot clear	[57]
Reset Counter A	[62]
Reset Counter B	[65]



Parameter Lists

Changes during operation

“TRUE” means that the parameter can be changed while the adjustable frequency drive is in operation, and “FALSE” means that it must be stopped before a change can be made.

4-Set-up

'All set-up': the parameters can be set individually in each of the four set-ups, i.e., one single parameter can have four different data values.

'1 set-up': the data value will be the same in all set-ups.

Conversion index

This number refers to a conversion figure used when writing or reading to and from the adjustable frequency drive.

Conv. index	100	67	6	5	4	3	2	1	0	-1	-2	-3	-4	-5	-6
Conv. factor	1	1/60	1000000	100000	10000	1000	100	10	1	0.1	0.01	0.001	0.0001	0.00001	0.000001

Data type	Description	Type
2	Integer 8	Int8
3	Integer 16	Int16
4	Integer 32	Int32
5	Unsigned 8	UInt8
6	Unsigned 16	UInt16
7	Unsigned 32	UInt32
9	Visible String	VisStr
33	Normalized value 2 bytes	N2
35	Bit sequence of 16 boolean variables	V2
54	Time difference w/o date	TimD

See the *FC 300 Design Guide* for further information about data types 33, 35 and 54.



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Parameters for the FC 300 are grouped into various parameter groups for easy selection of the correct parameters for optimized operation of the adjustable frequency drive.

- 0-xx Operation and display parameters for basic adjustable frequency drive settings
- 1-xx Load and motor parameters, includes all load and motor-related parameters
- 2-xx Brake parameters
- 3-xx References and ramping parameters, includes DigiPot function
- 4-xx Limits warnings, setting of limits and warning parameters
- 5-xx Digital inputs and outputs, includes relay controls
- 6-xx Analog inputs and outputs
- 7-xx Controls, setting parameters for speed and process controls
- 8-xx Communication and option parameters, setting of FC RS485 and FC USB port parameters.
- 9-xx Profibus parameters
- 10-xx DeviceNet and CAN Serial Communication parameters
- 13-xx Smart Logic Control parameters
- 14-xx Special function parameters
- 15-xx Drive information parameters
- 16-xx Readout parameters
- 17-xx Encoder option parameters
- 32-xx MCO 305 Basic parameters
- 33-xx MCO 305 Advanced parameters
- 34-xx MCO Data Readout parameters



□ 0- ** Operation/Display

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
0-0* Basic Settings						
0-01	Language	[0] English	1 set-up	TRUE	-	Uint8
0-02	Motor Speed Unit	[0] RPM	2 set-ups	FALSE	-	Uint8
0-03	Regional Settings	[0] International	2 set-ups	FALSE	-	Uint8
0-04	Operating State at Power-up (Hand)	[1] Forced stop, ref=old	All set-ups	TRUE	-	Uint8
0-1* Set-up Operations						
0-10	Active Set-up	[1] Set-up 1	1 set-up	TRUE	-	Uint8
0-11	Edit Set-up	[1] Set-up 1	All set-ups	TRUE	-	Uint8
0-12	This Set-up Linked to	[0] Not linked	All set-ups	FALSE	-	Uint8
0-13	Readout: Linked Set-ups	0 N/A	All set-ups	FALSE	0	Uint16
0-14	Readout: Edit Set-ups / Channel	0 N/A	All set-ups	TRUE	0	Int32
0-2* LCP Display						
0-20	Display Line 1.1 Small	1617	All set-ups	TRUE	-	Uint16
0-21	Display Line 1.2 Small	1614	All set-ups	TRUE	-	Uint16
0-22	Display Line 1.3 Small	1610	All set-ups	TRUE	-	Uint16
0-23	Display Line 2 Large	1613	All set-ups	TRUE	-	Uint16
0-24	Display Line 3 Large	1602	All set-ups	TRUE	-	Uint16
0-25	My Personal Menu	ExpressionLimit	1 set-up	TRUE	0	Uint16
0-3* LCP Cust. Readout						
0-30	Unit for User-defined Readout	[0] None	All set-ups	TRUE	-	Uint8
0-31	Min Value of User-defined Readout	0.00 CustomReadoutUnit	All set-ups	TRUE	-2	Int32
0-32	Max Value of User-defined Readout	100.00 CustomReadoutUnit	All set-ups	TRUE	-2	Int32
0-4* LCP Keypad						
0-40	[Hand on] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-41	[Off] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-42	[Auto on] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-43	[Reset] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-5* Copy/Save						
0-50	LCP Copy	[0] No copy	All set-ups	FALSE	-	Uint8
0-51	Set-up Copy	[0] No copy	All set-ups	FALSE	-	Uint8
0-6* Password						
0-60	Main Menu Password	100 N/A	1 set-up	TRUE	0	Int16
0-61	Access to Main Menu w/o Password	[0] Full access	1 set-up	TRUE	-	Uint8
0-65	Quick Menu Password	200 N/A	1 set-up	TRUE	0	Int16
0-66	Access to Quick Menu w/o Password	[0] Full access	1 set-up	TRUE	-	Uint8
0-67	Bus Password Access	0 N/A	All set-ups	TRUE	0	Uint16

□ 1 - * * Load/Motor

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
1-0* General Settings							
1-00	Configuration Mode	null	All set-ups		TRUE	-	Uint8
1-01	Motor Control Principle	null	All set-ups		FALSE	-	Uint8
1-02	Flux Motor Feedback Source	[1] 24V encoder	All set-ups	x	FALSE	-	Uint8
1-03	Torque Characteristics	[0] Constant torque	All set-ups		TRUE	-	Uint8
1-04	Overload Mode	[0] High torque	All set-ups		FALSE	-	Uint8
1-05	Local Mode Configuration	[2] As mode par 1-00	All set-ups		TRUE	-	Uint8
1-1* Motor Selection							
1-10	Motor Construction	[0] Asynchron	All set-ups		FALSE	-	Uint8
1-2* Motor Data							
1-20	Motor Power [kW]	ExpressionLimit	All set-ups		FALSE	1	Uint32
1-21	Motor Power [HP]	ExpressionLimit	All set-ups		FALSE	-2	Uint32
1-22	Motor Voltage	ExpressionLimit	All set-ups		FALSE	0	Uint16
1-23	Motor Frequency	ExpressionLimit	All set-ups		FALSE	0	Uint16
1-24	Motor Current	ExpressionLimit	All set-ups		FALSE	-2	Uint32
1-25	Motor Nominal Speed	ExpressionLimit	All set-ups		FALSE	67	Uint16
1-26	Motor Cont. Rated Torque	ExpressionLimit	All set-ups		FALSE	-1	Uint32
1-29	Automatic Motor Adaptation (AMA)	[0] Off	All set-ups		FALSE	-	Uint8
1-3* Addl. Motor Data							
1-30	Stator Resistance (Rs)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-31	Rotor Resistance (Rr)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-33	Stator Leakage Reactance (X1)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-34	Rotor Leakage Reactance (X2)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-35	Main Reactance (Xh)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-36	Iron Loss Resistance (Rfe)	ExpressionLimit	All set-ups	x	FALSE	-3	Uint32
1-37	d-axis Inductance (Ld)	ExpressionLimit	All set-ups		FALSE	-4	Uint32
1-39	Motor Poles	ExpressionLimit	All set-ups		FALSE	0	Uint8
1-40	Back EMF at 1000 RPM	ExpressionLimit	All set-ups	x	FALSE	0	Uint16
1-41	Motor Angle Offset	0 N/A	All set-ups		FALSE	0	Uint16
1-5* Load-Indep. Setting							
1-50	Motor Magnetization at Zero Speed	100 %	All set-ups		TRUE	0	Uint16
1-51	Min Speed Normal Magnetizing [RPM]	ExpressionLimit	All set-ups		TRUE	67	Uint16
1-52	Min Speed Normal Magnetizing [Hz]	ExpressionLimit	All set-ups		TRUE	-1	Uint16
1-53	Model Shift Frequency	ExpressionLimit	All set-ups	x	FALSE	-1	Uint16
1-55	U/f Characteristic - U	ExpressionLimit	All set-ups		TRUE	-1	Uint16
1-56	U/f Characteristic - F	ExpressionLimit	All set-ups		TRUE	-1	Uint16
1-6* Load-Depend. Settg.							
1-60	Low Speed Load Compensation	100 %	All set-ups		TRUE	0	Uint16
1-61	High Speed Load Compensation	100 %	All set-ups		TRUE	0	Uint16
1-62	Slip Compensation	ExpressionLimit	All set-ups		TRUE	0	Uint16
1-63	Slip Compensation Time Constant	0.10 s	All set-ups		TRUE	-2	Uint16
1-64	Resonance Dampening	100 %	All set-ups		TRUE	0	Uint16
1-65	Resonance Dampening Time Constant	5 ms	All set-ups		TRUE	-3	Uint8
1-66	Min. Current at Low Speed	100 %	All set-ups	x	TRUE	0	Uint8
1-67	Load Type	[0] Passive load	All set-ups	x	TRUE	-	Uint8
1-68	Minimum Inertia	ExpressionLimit	All set-ups	x	FALSE	-4	Uint32
1-69	Maximum Inertia	ExpressionLimit	All set-ups	x	FALSE	-4	Uint32



Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
1-7* Start Adjustments						
1-71	Start Delay	0.0 s	All set-ups	TRUE	-1	Uint8
1-72	Start Function	[2] Coast/delay time	All set-ups	TRUE	-	Uint8
1-73	Flying Start	[0] Disabled	All set-ups	FALSE	-	Uint8
1-74	Start Speed [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
1-75	Start Speed [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
1-76	Start Current	0.00 A	All set-ups	TRUE	-2	Uint32
1-8* Stop Adjustments						
1-80	Function at Stop	[0] Coast	All set-ups	TRUE	-	Uint8
1-81	Min Speed for Function at Stop [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
1-82	Min Speed for Function at Stop [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
1-83	Precise Stop Function	[0] Precise ramp stop	All set-ups	FALSE	-	Uint8
1-84	Precise Stop Counter Value	100000 N/A	All set-ups	TRUE	0	Uint32
1-85	Precise Stop Speed Compensation Delay	10 ms	All set-ups	TRUE	-3	Uint8
1-9* Motor Temperature						
1-90	Motor Thermal Protection	[0] No protection	All set-ups	TRUE	-	Uint8
1-91	Motor External Fan	[0] No	All set-ups	TRUE	-	Uint16
1-93	Thermistor Resource	[0] None	All set-ups	TRUE	-	Uint8
1-95	KTY Sensor Type	[0] KTY Sensor 1	All set-ups	TRUE	-	Uint8
1-96	Thermistor Resource	[0] None	All set-ups	TRUE	-	Uint8
1-97	KTY Threshold level	80 °C	1 set-up	TRUE	100	Int16

□ 2- ** Brakes

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
2-0* DC Brake							
2-00	DC Hold Current	50 %	All set-ups		TRUE	0	Uint8
2-01	DC Brake Current	50 %	All set-ups		TRUE	0	Uint16
2-02	DC Braking Time	10.0 s	All set-ups		TRUE	-1	Uint16
2-03	DC Brake Cut-in Speed [RPM]	ExpressionLimit	All set-ups		TRUE	67	Uint16
2-04	DC Brake Cut-in Speed [Hz]	ExpressionLimit	All set-ups		TRUE	-1	Uint16
2-1* Brake Energy Funct.							
2-10	Brake Function	null	All set-ups		TRUE	-	Uint8
2-11	Brake Resistor (ohm)	ExpressionLimit	All set-ups		TRUE	0	Uint16
2-12	Brake Power Limit (kW)	ExpressionLimit	All set-ups		TRUE	0	Uint32
2-13	Brake Power Monitoring	[0] Off	All set-ups		TRUE	-	Uint8
2-15	Brake Check	[0] Off	All set-ups		TRUE	-	Uint8
2-16	AC Brake Max. Current	100.0 %	All set-ups		TRUE	-1	Uint32
2-17	Over-voltage Control	[0] Disabled	All set-ups		TRUE	-	Uint8
2-2* Mechanical Brake							
2-20	Release Brake Current	ExpressionLimit	All set-ups		TRUE	-2	Uint32
2-21	Activate Brake Speed [RPM]	ExpressionLimit	All set-ups		TRUE	67	Uint16
2-22	Activate Brake Speed [Hz]	ExpressionLimit	All set-ups		TRUE	-1	Uint16
2-23	Activate Brake Delay	0.0 s	All set-ups		TRUE	-1	Uint8
2-24	Stop Delay	0.0 s	All set-ups		TRUE	-1	Uint8
2-25	Brake Release Time	0.20 s	All set-ups		TRUE	-2	Uint16
2-26	Torque Ref	0.00 %	All set-ups		TRUE	-2	Uint16
2-27	Torque Ramp Time	0.2 s	All set-ups		TRUE	-1	Uint8
2-28	Gain Boost Factor	1.00 N/A	All set-ups		TRUE	-2	Uint16



□ 3- ** Reference / Ramps

Par. No. #	Parameter description	Default value	4-set-up only	FC 302 Change during operation only	Conversion index	Type
3-0* Reference Limits						
3-00	Reference Range	null	All set-ups	TRUE	-	Uint8
3-01	Reference/Feedback Unit	null	All set-ups	TRUE	-	Uint8
3-02	Minimum Reference	ExpressionLimit	All set-ups	TRUE	-3	Int32
3-03	Maximum Reference	ExpressionLimit	All set-ups	TRUE	-3	Int32
3-04	Reference Function	[0] Sum	All set-ups	TRUE	-	Uint8
3-1* References						
3-10	Preset Reference	0.00 %	All set-ups	TRUE	-2	Int16
3-11	Jog Speed [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
3-12	Catch up/slow-down Value	0.00 %	All set-ups	TRUE	-2	Int16
3-13	Reference Site	[0] Linked to Hand / Auto	All set-ups	TRUE	-	Uint8
3-14	Preset Relative Reference	0.00 %	All set-ups	TRUE	-2	Int32
3-15	Reference Resource 1	null	All set-ups	TRUE	-	Uint8
3-16	Reference Resource 2	null	All set-ups	TRUE	-	Uint8
3-17	Reference Resource 3	null	All set-ups	TRUE	-	Uint8
3-18	Relative Scaling Reference Resource	[0] No function	All set-ups	TRUE	-	Uint8
3-19	Jog Speed [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
3-4* Ramp 1						
3-40	Ramp 1 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-41	Ramp 1 Ramp-up Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-42	Ramp 1 Ramp-down Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-43	Ramp 1 S-ramp Ratio at Accel. Start	50 %	All set-ups	TRUE	0	Uint8
3-44	Ramp 1 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-45	Ramp 1 S-ramp Ratio at Accel. End	50 %	All set-ups	TRUE	0	Uint8
3-46	Ramp 1 S-ramp Ratio at Decel. Start	50 %	All set-ups	TRUE	0	Uint8
3-47	Ramp 1 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-5* Ramp 2						
3-50	Ramp 2 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-51	Ramp 2 Ramp-up Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-52	Ramp 2 Ramp-down Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-53	Ramp 2 S-ramp Ratio at Accel. Start	50 %	All set-ups	TRUE	0	Uint8
3-54	Ramp 2 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-55	Ramp 2 S-ramp Ratio at Accel. End	50 %	All set-ups	TRUE	0	Uint8
3-56	Ramp 2 S-ramp Ratio at Decel. Start	50 %	All set-ups	TRUE	0	Uint8
3-57	Ramp 2 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-6* Ramp 3						
3-60	Ramp 3 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-61	Ramp 3 Ramp-up Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-62	Ramp 3 Ramp-down Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-63	Ramp 3 S-ramp Ratio at Accel. Start	50 %	All set-ups	TRUE	0	Uint8
3-64	Ramp 3 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-65	Ramp 3 S-ramp Ratio at Accel. End	50 %	All set-ups	TRUE	0	Uint8
3-66	Ramp 3 S-ramp Ratio at Decel. Start	50 %	All set-ups	TRUE	0	Uint8
3-67	Ramp 3 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-7* Ramp 4						
3-70	Ramp 4 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-71	Ramp 4 Ramp-up Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-72	Ramp 4 Ramp-down Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-73	Ramp 4 S-ramp Ratio at Accel. Start	50 %	All set-ups	TRUE	0	Uint8
3-74	Ramp 4 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-75	Ramp 4 S-ramp Ratio at Accel. End	50 %	All set-ups	TRUE	0	Uint8
3-76	Ramp 4 S-ramp Ratio at Decel. Start	50 %	All set-ups	TRUE	0	Uint8
3-77	Ramp 4 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8
3-78	Ramp 4 S-ramp Ratio at Decel. End	50 %	All set-ups	TRUE	0	Uint8

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
3-8* Other Ramps						
3-80	Jog Ramp Time	ExpressionLimit	All set-ups	TRUE	-2	Uint32
3-81	Quick Stop Ramp Time	ExpressionLimit	2 set-ups	TRUE	-2	Uint32
3-9* Digital Pot. meter						
3-90	Step Size	0.10 %	All set-ups	TRUE	-2	Uint16
3-91	Ramp Time	1.00 s	All set-ups	TRUE	-2	Uint32
3-92	Power Restore	[0] Off	All set-ups	TRUE	-	Uint8
3-93	Maximum Limit	100 %	All set-ups	TRUE	0	Int16
3-94	Minimum Limit	-100 %	All set-ups	TRUE	0	Int16
3-95	Ramp Delay	1.000 N/A	All set-ups	TRUE	-3	TimD



□ 4- ** Limits / Warnings

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
4-1* Motor Limits						
4-10	Motor Speed Direction	null	All set-ups	FALSE	-	Uint8
4-11	Motor Speed Low Limit [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
4-12	Motor Speed Low Limit [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
4-13	Motor Speed High Limit [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
4-14	Motor Speed High Limit [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
4-16	Torque Limit Motor Mode	ExpressionLimit	All set-ups	TRUE	-1	Uint16
4-17	Torque Limit Generator Mode	100.0 %	All set-ups	TRUE	-1	Uint16
4-18	Current Limit	ExpressionLimit	All set-ups	TRUE	-1	Uint32
4-19	Max Output Frequency	132.0 Hz	All set-ups	FALSE	-1	Uint16
4-2* Limit Factors						
4-20	Torque Limit Factor Source	[0] No function	All set-ups	TRUE	-	Uint8
4-21	Speed Limit Factor Source	[0] No function	All set-ups	TRUE	-	Uint8
4-3* Motor Fb Monitor						
4-30	Motor Feedback Loss Function	[2] Trip	All set-ups	TRUE	-	Uint8
4-31	Motor Feedback Speed Error	300 RPM	All set-ups	TRUE	67	Uint16
4-32	Motor Feedback Loss Timeout	0.05 s	All set-ups	TRUE	-2	Uint16
4-5* Adj. Warnings						
4-50	Warning Current Low	0.00 A	All set-ups	TRUE	-2	Uint32
4-51	Warning Current High	ImaxVLT (P1637)	All set-ups	TRUE	-2	Uint32
4-52	Warning Speed Low	0 RPM	All set-ups	TRUE	67	Uint16
4-53	Warning Speed High	outputSpeedHighLimit (P413)	All set-ups	TRUE	67	Uint16
4-54	Warning Reference Low	-999999.999 N/A	All set-ups	TRUE	-3	Int32
4-55	Warning Reference High	999999.999 N/A	All set-ups	TRUE	-3	Int32
4-56	Warning Feedback Low	-999999.999 ReferenceFeedbackUnit	All set-ups	TRUE	-3	Int32
4-57	Warning Feedback High	999999.999 ReferenceFeedbackUnit	All set-ups	TRUE	-3	Int32
4-58	Missing Motor Phase Function	[1] On	All set-ups	TRUE	-	Uint8
4-6* Speed Bypass						
4-60	Bypass Speed From [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
4-61	Bypass Speed From [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16
4-62	Bypass Speed to [RPM]	ExpressionLimit	All set-ups	TRUE	67	Uint16
4-63	Bypass Speed To [Hz]	ExpressionLimit	All set-ups	TRUE	-1	Uint16

□ 5- ** Digital In/Out

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
5-0* Digital I/O mode							
5-00	Digital I/O Mode	[0] PNP	All set-ups		FALSE	-	Uint8
5-01	Terminal 27 Mode	[0] Input	All set-ups		TRUE	-	Uint8
5-02	Terminal 29 Mode	[0] Input	All set-ups	x	TRUE	-	Uint8
5-1* Digital Inputs							
5-10	Terminal 18 Digital Input	null	All set-ups		TRUE	-	Uint8
5-11	Terminal 19 Digital Input	null	All set-ups		TRUE	-	Uint8
5-12	Terminal 27 Digital Input	null	All set-ups		TRUE	-	Uint8
5-13	Terminal 29 Digital Input	null	All set-ups	x	TRUE	-	Uint8
5-14	Terminal 32 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-15	Terminal 33 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-16	Terminal X30/2 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-17	Terminal X30/3 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-18	Terminal X30/4 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-19	Terminal 37 Safe Stop	[1] Safe Stop Alarm	1 set-up	x	TRUE	-	Uint8
5-3* Digital Outputs							
5-30	Terminal 27 Digital Output	null	All set-ups		TRUE	-	Uint8
5-31	Terminal 29 digital Output	null	All set-ups	x	TRUE	-	Uint8
5-32	Term X30/6 Digi Out (MCB 101)	null	All set-ups		TRUE	-	Uint8
5-33	Term X30/7 Digi Out (MCB 101)	null	All set-ups		TRUE	-	Uint8
5-4* Relays							
5-40	Function Relay	null	All set-ups		TRUE	-	Uint8
5-41	On Delay, Relay	0.01 s	All set-ups		TRUE	-2	Uint16
5-42	Off Delay, Relay	0.01 s	All set-ups		TRUE	-2	Uint16
5-5* Pulse Input							
5-50	Term. 29 Low Frequency	100 Hz	All set-ups	x	TRUE	0	Uint32
5-51	Term. 29 High Frequency	100 Hz	All set-ups	x	TRUE	0	Uint32
5-52	Term. 29 Low Ref./Feedb. Value	0.000 ReferenceFeedbackUnit	All set-ups	x	TRUE	-3	Int32
5-53	Term. 29 High Ref./Feedb. Value	ExpressionLimit	All set-ups	x	TRUE	-3	Int32
5-54	Pulse Filter Time Constant #29	100 ms	All set-ups	x	FALSE	-3	Uint16
5-55	Term. 33 Low Frequency	100 Hz	All set-ups		TRUE	0	Uint32
5-56	Term. 33 High Frequency	100 Hz	All set-ups		TRUE	0	Uint32
5-57	Term. 33 Low Ref./Feedb. Value	0.000 ReferenceFeedbackUnit	All set-ups		TRUE	-3	Int32
5-58	Term. 33 High Ref./Feedb. Value	ExpressionLimit	All set-ups		TRUE	-3	Int32
5-59	Pulse Filter Time Constant #33	100 ms	All set-ups		FALSE	-3	Uint16
5-6* Pulse Output							
5-60	Terminal 27 Pulse Output Variable	null	All set-ups		TRUE	-	Uint8
5-62	Pulse Output Max Freq #27	ExpressionLimit	All set-ups		TRUE	0	Uint32
5-63	Terminal 29 Pulse Output Variable	null	All set-ups	x	TRUE	-	Uint8
5-65	Pulse Output Max Freq #29	ExpressionLimit	All set-ups	x	TRUE	0	Uint32
5-66	Terminal X30/6 Pulse Output Variable	null	All set-ups		TRUE	-	Uint8
5-68	Pulse Output Max Freq #X30/6	ExpressionLimit	All set-ups		TRUE	0	Uint32



Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
5-7* 24V Encoder Input							
5-70	Term 32/33 Pulses per Revolution	1024 N/A	All set-ups		FALSE	0	Uint16
5-71	Term 32/33 Encoder Direction	[0] Clockwise	All set-ups		FALSE	-	Uint8
5-9* Bus Controlled							
5-90	Digital & Relay Bus Control	0 N/A	All set-ups		TRUE	0	Uint32
5-93	Pulse Out #27 Bus Control	0.00 %	All set-ups		TRUE	-2	N2
5-94	Pulse Out #27 Timeout Preset	0.00 %	1 set-up		TRUE	-2	Uint16
5-95	Pulse Out #29 Bus Control	0.00 %	All set-ups	x	TRUE	-2	N2
5-96	Pulse Out #29 Timeout Preset	0.00 %	1 set-up	x	TRUE	-2	Uint16

□ 6- ** Analog In/Out

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
6-0* Analog I/O Mode						
6-00	Live Zero Timeout Time	10 s	All set-ups	TRUE	0	Uint8
6-01	Live Zero Timeout Function	[0] Off	All set-ups	TRUE	-	Uint8
6-1* Analog Input 1						
6-10	Terminal 53 Low Voltage	0.07 V	All set-ups	TRUE	-2	Int16
6-11	Terminal 53 High Voltage	10.00 V	All set-ups	TRUE	-2	Int16
6-12	Terminal 53 Low Current	0.14 mA	All set-ups	TRUE	-5	Int16
6-13	Terminal 53 High Current	20.00 mA	All set-ups	TRUE	-5	Int16
6-14	Terminal 53 Low Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-15	Terminal 53 High Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-16	Terminal 53 Filter Time Constant	0.001 s	All set-ups	TRUE	-3	Uint16
6-2* Analog Input 2						
6-20	Terminal 54 Low Voltage	0.07 V	All set-ups	TRUE	-2	Int16
6-21	Terminal 54 High Voltage	10.00 V	All set-ups	TRUE	-2	Int16
6-22	Terminal 54 Low Current	0.14 mA	All set-ups	TRUE	-5	Int16
6-23	Terminal 54 High Current	20.00 mA	All set-ups	TRUE	-5	Int16
6-24	Terminal 54 Low Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-25	Terminal 54 High Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-26	Terminal 54 Filter Time Constant	0.001 s	All set-ups	TRUE	-3	Uint16
6-3* Analog Input 3						
6-30	Terminal X30/11 Low Voltage	0.07 V	All set-ups	TRUE	-2	Int16
6-31	Terminal X30/11 High Voltage	10.00 V	All set-ups	TRUE	-2	Int16
6-34	Term. X30/11 Low Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-35	Term. X30/11 High Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-36	Term. X30/11 Filter Time Constant	0.001 s	All set-ups	TRUE	-3	Uint16
6-4* Analog Input 4						
6-40	Terminal X30/12 Low Voltage	0.07 V	All set-ups	TRUE	-2	Int16
6-41	Terminal X30/12 High Voltage	10.00 V	All set-ups	TRUE	-2	Int16
6-44	Term. X30/12 Low Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-45	Term. X30/12 High Ref./Feedb. Value	ExpressionLimit	All set-ups	TRUE	-3	Int32
6-46	Term. X30/12 Filter Time Constant	0.001 s	All set-ups	TRUE	-3	Uint16
6-5* Analog Output 1						
6-50	Terminal 42 Output	null	All set-ups	TRUE	-	Uint8
6-51	Terminal 42 Output Min Scale	0.00 %	All set-ups	TRUE	-2	Int16
6-52	Terminal 42 Output Max Scale	100.00 %	All set-ups	TRUE	-2	Int16
6-53	Terminal 42 Output Bus Control	0.00 %	All set-ups	TRUE	-2	N2
6-54	Terminal 42 Output Timeout Preset	0.00 %	1 set-up	TRUE	-2	Uint16
6-6* Analog Output 2						
6-60	Terminal X30/8 Output	null	All set-ups	TRUE	-	Uint8
6-61	Terminal X30/8 Min. Scale	0.00 %	All set-ups	TRUE	-2	Int16
6-62	Terminal X30/8 Max. Scale	100.00 %	All set-ups	TRUE	-2	Int16





□ 7- ** Controllers

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
7-0* Speed PID Ctrl.						
7-00	Speed PID Feedback Source	null	All set-ups	FALSE	-	Uint8
7-02	Speed PID Proportional Gain	ExpressionLimit	All set-ups	TRUE	-3	Uint16
7-03	Speed PID Integral Time	ExpressionLimit	All set-ups	TRUE	-4	Uint32
7-04	Speed PID Differentiation Time	ExpressionLimit	All set-ups	TRUE	-4	Uint16
7-05	Speed PID Diff. Gain Limit	5.0 N/A	All set-ups	TRUE	-1	Uint16
7-06	Speed PID Lowpass Filter Time	10.0 ms	All set-ups	TRUE	-4	Uint16
7-08	Speed PID Feed Forward Factor	0 %	All set-ups	FALSE	0	Uint16
7-2* Process Ctrl. Feedb						
7-20	Process CL Feedback 1 Resource	[0] No function	All set-ups	TRUE	-	Uint8
7-22	Process CL Feedback 2 Resource	[0] No function	All set-ups	TRUE	-	Uint8
7-3* Process PID Ctrl.						
7-30	Process PID Normal/Inverse Control	[0] Normal	All set-ups	TRUE	-	Uint8
7-31	Process PID Anti Windup	[1] On	All set-ups	TRUE	-	Uint8
7-32	Process PID Controller Start Value	0 RPM	All set-ups	TRUE	67	Uint16
7-33	Process PID Proportional Gain	0.01 N/A	All set-ups	TRUE	-2	Uint16
7-34	Process PID Integral Time	10000.00 s	All set-ups	TRUE	-2	Uint32
7-35	Process PID Differentiation Time	0.00 s	All set-ups	TRUE	-2	Uint16
7-36	Process PID Differentiation Gain Limit	5.0 N/A	All set-ups	TRUE	-1	Uint16
7-38	Process PID Feed Forward Factor	0 %	All set-ups	TRUE	0	Uint16
7-39	On Reference Bandwidth	5 %	All set-ups	TRUE	0	Uint8

□ 8- * * Comm. and options

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
8-0* General Settings						
8-01	Control Site	[0] Digital and ctrl. word	All set-ups	TRUE	-	Uint8
8-02	Control Word Source	null	All set-ups	TRUE	-	Uint8
8-03	Control Word Timeout Time	1.0 s	1 set-up	TRUE	-1	Uint32
8-04	Control Word Timeout Function	[0] Off	1 set-up	TRUE	-	Uint8
8-05	End-of-Timeout Function	[1] Resume set-up	1 set-up	TRUE	-	Uint8
8-06	Reset Control Word Timeout	[0] Do not reset	All set-ups	TRUE	-	Uint8
8-07	Diagnosis Trigger	[0] Disable	2 set-ups	TRUE	-	Uint8
8-1* Ctrl. Word Settings						
8-10	Control Word Profile	[0] FC profile	All set-ups	TRUE	-	Uint8
8-13	Configurable Status Word STW	[1] Profile Default	All set-ups	TRUE	-	Uint8
8-3* FC Port Settings						
8-30	Protocol	[0] FC	1 set-up	TRUE	-	Uint8
8-31	Address	1 N/A	1 set-up	TRUE	0	Uint8
8-32	FC Port Baud Rate	[2] 9600 Baud	1 set-up	TRUE	-	Uint8
8-35	Minimum Response Delay	10 ms	All set-ups	TRUE	-3	Uint16
8-36	Max Response Delay	5000 ms	1 set-up	TRUE	-3	Uint16
8-37	Max Inter-Char Delay	25 ms	1 set-up	TRUE	-3	Uint16
8-4* FC MC protocol set						
8-40	Telegram selection	[1] Standard telegram	1 2 set-ups	TRUE	-	Uint8
8-5* Digital/Bus						
8-50	Coasting Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-51	Quick Stop Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-52	DC Brake Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-53	Start Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-54	Reverse Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-55	Set-up Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-56	Preset Reference Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-9* Bus Jog						
8-90	Bus Jog 1 Speed	100 RPM	All set-ups	TRUE	67	Uint16
8-91	Bus Jog 2 Speed	200 RPM	All set-ups	TRUE	67	Uint16



□ 9- ** Profibus

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
9-00	Setpoint	0 N/A	All set-ups		TRUE	0	Uint16
9-07	Actual Value	0 N/A	All set-ups		FALSE	0	Uint16
9-15	PCD Write Configuration	ExpressionLimit	2 set-ups		TRUE	-	Uint16
9-16	PCD Read Configuration	ExpressionLimit	2 set-ups		TRUE	-	Uint16
9-18	Node Address	126 N/A	1 set-up		TRUE	0	Uint8
9-22	Telegram Selection	[108] PPO 8	1 set-up		TRUE	-	Uint8
9-23	Parameters for Signals	0	All set-ups		TRUE	-	Uint16
9-27	Parameter Edit	[1] Enabled	2 set-ups		FALSE	-	Uint16
9-28	Process Control	[1] Enable cyclic master	2 set-ups		FALSE	-	Uint8
9-31	Safe Address	0 N/A	1 set-up		TRUE	0	Uint16
9-44	Fault Message Counter	0 N/A	All set-ups		TRUE	0	Uint16
9-45	Fault Code	0 N/A	All set-ups		TRUE	0	Uint16
9-47	Fault Number	0 N/A	All set-ups		TRUE	0	Uint16
9-52	Fault Situation Counter	0 N/A	All set-ups		TRUE	0	Uint16
9-53	Profibus Warning Word	0 N/A	All set-ups		TRUE	0	V2
9-63	Actual Baud Rate	[255] No baud rate found	All set-ups		TRUE	-	Uint8
9-64	Device Identification	0 N/A	All set-ups		TRUE	0	Uint16
9-65	Profile Number	0 N/A	All set-ups		TRUE	0	OctStr[2]
9-67	Control Word 1	0 N/A	All set-ups		TRUE	0	V2
9-68	Status Word 1	0 N/A	All set-ups		TRUE	0	V2
9-71	Profibus Save Data Values	[0] Off	All set-ups		TRUE	-	Uint8
9-72	ProfibusDriveReset	[0] No action	1 set-up		FALSE	-	Uint8
9-80	Defined Parameters (1)	0 N/A	All set-ups		FALSE	0	Uint16
9-81	Defined Parameters (2)	0 N/A	All set-ups		FALSE	0	Uint16
9-82	Defined Parameters (3)	0 N/A	All set-ups		FALSE	0	Uint16
9-83	Defined Parameters (4)	0 N/A	All set-ups		FALSE	0	Uint16
9-84	Defined Parameters (5)	0 N/A	All set-ups		FALSE	0	Uint16
9-90	Changed Parameters (1)	0 N/A	All set-ups		FALSE	0	Uint16
9-91	Changed Parameters (2)	0 N/A	All set-ups		FALSE	0	Uint16
9-92	Changed Parameters (3)	0 N/A	All set-ups		FALSE	0	Uint16
9-93	Changed Parameters (4)	0 N/A	All set-ups		FALSE	0	Uint16
9-94	Changed Parameters (5)	0 N/A	All set-ups		FALSE	0	Uint16
9-99	Profibus Revision Counter	0 N/A	All set-ups		TRUE	0	Uint16

□ 10-.* * CAN fieldbus

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
10-0* Common Settings						
10-00	CAN Protocol	null	2 set-ups	FALSE	-	Uint8
10-01	Baud Rate Select	null	2 set-ups	TRUE	-	Uint8
10-02	MAC ID	ExpressionLimit	2 set-ups	TRUE	0	Uint8
10-05	Readout Transmit Error Counter	0 N/A	All set-ups	TRUE	0	Uint8
10-06	Readout Receive Error Counter	0 N/A	All set-ups	TRUE	0	Uint8
10-07	Readout Bus Off Counter	0 N/A	All set-ups	TRUE	0	Uint8
10-1* DeviceNet						
10-10	Process Data Type Selection	null	All set-ups	TRUE	-	Uint8
10-11	Process Data Config Write	ExpressionLimit	2 set-ups	TRUE	-	Uint16
10-12	Process Data Config Read	ExpressionLimit	2 set-ups	TRUE	-	Uint16
10-13	Warning Parameter	0 N/A	All set-ups	TRUE	0	Uint16
10-14	Net Reference	[0] Off	2 set-ups	TRUE	-	Uint8
10-15	Net Control	[0] Off	2 set-ups	TRUE	-	Uint8
10-2* COS Filters						
10-20	COS Filter 1	0 N/A	All set-ups	FALSE	0	Uint16
10-21	COS Filter 2	0 N/A	All set-ups	FALSE	0	Uint16
10-22	COS Filter 3	0 N/A	All set-ups	FALSE	0	Uint16
10-23	COS Filter 4	0 N/A	All set-ups	FALSE	0	Uint16
10-3* Parameter Access						
10-30	Array Index	0 N/A	2 set-ups	TRUE	0	Uint8
10-31	Store Data Values	[0] Off	All set-ups	TRUE	-	Uint8
10-32	DeviceNet Revision	ExpressionLimit	All set-ups	TRUE	0	Uint16
10-33	Store Always	[0] Off	1 set-up	TRUE	-	Uint8
10-34	DeviceNet Product Code	ExpressionLimit	1 set-up	TRUE	0	Uint16
10-39	DeviceNet F Parameters	0 N/A	All set-ups	TRUE	0	Uint32
10-5* CANopen						
10-50	Process Data Config Write.	ExpressionLimit	2 set-ups	TRUE	-	Uint16
10-51	Process Data Config Read.	ExpressionLimit	2 set-ups	TRUE	-	Uint16



□ 13-.* Smart logic

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
13-0* SLC Settings						
13-00	SL Controller Mode	null	2 set-ups	TRUE	-	UInt8
13-01	Start Event	null	2 set-ups	TRUE	-	UInt8
13-02	Stop Event	null	2 set-ups	TRUE	-	UInt8
13-03	Reset SLC	[0] Do not reset SLC	All set-ups	TRUE	-	UInt8
13-1* Comparators						
13-10	Comparator Operand	null	2 set-ups	TRUE	-	UInt8
13-11	Comparator Operator	null	2 set-ups	TRUE	-	UInt8
13-12	Comparator Value	ExpressionLimit	2 set-ups	TRUE	-3	Int32
13-2* Timers						
13-20	SL Controller Timer	ExpressionLimit	1 set-up	TRUE	-3	TimD
13-4* Logic Rules						
13-40	Logic Rule Boolean 1	null	2 set-ups	TRUE	-	UInt8
13-41	Logic Rule Operator 1	null	2 set-ups	TRUE	-	UInt8
13-42	Logic Rule Boolean 2	null	2 set-ups	TRUE	-	UInt8
13-43	Logic Rule Operator 2	null	2 set-ups	TRUE	-	UInt8
13-44	Logic Rule Boolean 3	null	2 set-ups	TRUE	-	UInt8
13-5* States						
13-51	SL Controller Event	null	2 set-ups	TRUE	-	UInt8
13-52	SL Controller Action	null	2 set-ups	TRUE	-	UInt8

□ 14-.* * Special functions

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
14-0* Inverter Switching							
14-00	Switching Pattern	[1] SFAVM	All set-ups		TRUE	-	Uint8
14-01	Switching Frequency	null	All set-ups		TRUE	-	Uint8
14-03	Overmodulation	[1] On	All set-ups		FALSE	-	Uint8
14-04	PWM Random	[0] Off	All set-ups		TRUE	-	Uint8
14-1* Mains On/Off							
14-10	Line Failure	[0] No function	All set-ups		FALSE	-	Uint8
14-11	Line Voltage at Line Fault	ExpressionLimit	All set-ups		TRUE	0	Uint16
14-12	Function at Mains Imbalance	[0] Trip	All set-ups		TRUE	-	Uint8
14-2* Trip Reset							
14-20	Reset Mode	[0] Manual reset	All set-ups		TRUE	-	Uint8
14-21	Automatic Restart Time	10 s	All set-ups		TRUE	0	Uint16
14-22	Operation Mode	[0] Normal operation	All set-ups		TRUE	-	Uint8
14-23	Typecode Setting	null	2 set-ups		FALSE	-	Uint16
14-25	Trip Delay at Torque Limit	60 s	All set-ups		TRUE	0	Uint8
14-26	Trip Delay at Inverter Fault	ExpressionLimit	All set-ups		TRUE	0	Uint8
14-28	Production Settings	[0] No action	All set-ups		TRUE	-	Uint8
14-29	Service Code	0 N/A	All set-ups		TRUE	0	Int32
14-3* Current Limit Ctrl.							
14-30	Current Lim Contr, Proportional Gain	100 %	All set-ups		FALSE	0	Uint16
14-31	Current Lim Contr, Integration Time	0.020 s	All set-ups		FALSE	-3	Uint16
14-4* Energy Optimizing							
14-40	VT Level	66 %	All set-ups		FALSE	0	Uint8
14-41	AEO Minimum Magnetization	40 %	All set-ups		TRUE	0	Uint8
14-42	Minimum AEO Frequency	10 Hz	All set-ups		TRUE	0	Uint8
14-43	Motor Cos-Phi	ExpressionLimit	All set-ups		TRUE	-2	Uint16
14-5* Environment							
14-50	RFL 1	[1] On	1 set-up	x	FALSE	-	Uint8
14-52	Fan Control	[0] Auto	All set-ups		TRUE	-	Uint8
14-53	Fan Monitor	[1] Warning	All set-ups		TRUE	-	Uint8
14-55	Output Filter	[0] No Filter	1 set-up		FALSE	-	Uint8
14-56	Capacitance Output Filter	2.0 uF	1 set-up		FALSE	-7	Uint16
14-57	Inductance Output Filter	7.000 mH	1 set-up		FALSE	-6	Uint16
14-7* Compatibility							
14-72	VLT Alarm Word	0 N/A	All set-ups		FALSE	0	Uint32
14-73	VLT Warning Word	0 N/A	All set-ups		FALSE	0	Uint32
14-74	VLT Ext. Status Word	0 N/A	All set-ups		FALSE	0	Uint32



□ 15-.* Drive information

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
15-0* Operating Data						
15-00	Operating Hours	0 h	All set-ups	FALSE	74	Uint32
15-01	Running Hours	0 h	All set-ups	FALSE	74	Uint32
15-02	kWh Counter	0 kWh	All set-ups	FALSE	75	Uint32
15-03	Power-ups	0 N/A	All set-ups	FALSE	0	Uint32
15-04	Over Temps	0 N/A	All set-ups	FALSE	0	Uint16
15-05	Over Volts	0 N/A	All set-ups	FALSE	0	Uint16
15-06	Reset kWh Counter	[0] Do not reset	All set-ups	TRUE	-	Uint8
15-07	Reset Running Hours Counter	[0] Do not reset	All set-ups	TRUE	-	Uint8
15-1* Data Log Settings						
15-10	Logging Source	0	2 set-ups	TRUE	-	Uint16
15-11	Logging Interval	ExpressionLimit	2 set-ups	TRUE	-3	TimD
15-12	Trigger Event	[0] FALSE	1 set-up	TRUE	-	Uint8
15-13	Logging Mode	[0] Log always	2 set-ups	TRUE	-	Uint8
15-14	Samples Before Trigger	50 N/A	2 set-ups	TRUE	0	Uint8
15-2* Historic Log						
15-20	Historic Log: Event	0 N/A	All set-ups	FALSE	0	Uint8
15-21	Historic Log: Value	0 N/A	All set-ups	FALSE	0	Uint32
15-22	Historic Log: Time	0 ms	All set-ups	FALSE	-3	Uint32
15-3* Fault Log						
15-30	Fault Log: Error Code	0 N/A	All set-ups	FALSE	0	Uint8
15-31	Fault Log: Value	0 N/A	All set-ups	FALSE	0	Int16
15-32	Fault Log: Time	0 s	All set-ups	FALSE	0	Uint32
15-4* Drive Identification						
15-40	FC Type	0 N/A	All set-ups	FALSE	0	VisStr[6]
15-41	Power Section	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-42	Voltage	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-43	Software Version	0 N/A	All set-ups	FALSE	0	VisStr[5]
15-44	Ordered Typecode String	0 N/A	All set-ups	FALSE	0	VisStr[40]
15-45	Actual Typecode String	0 N/A	All set-ups	FALSE	0	VisStr[40]
15-46	Adj Freq Dr Ordering No.	0 N/A	All set-ups	FALSE	0	VisStr[8]
15-47	Power Card Ordering No.	0 N/A	All set-ups	FALSE	0	VisStr[8]
15-48	LCP ID Num.	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-49	SW ID Control Card	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-50	SW ID Power Card	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-51	Adj Freq Dr Serial No.	0 N/A	All set-ups	FALSE	0	VisStr[10]
15-53	Power Card Serial Number	0 N/A	All set-ups	FALSE	0	VisStr[19]

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
15-6* Option Ident						
15-60	Option Mounted	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-61	Option SW Version	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-62	Option Ordering No	0 N/A	All set-ups	FALSE	0	VisStr[8]
15-63	Option Serial No	0 N/A	All set-ups	FALSE	0	VisStr[18]
15-70	Option in Slot A	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-71	Slot A Option SW Version	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-72	Option in Slot B	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-73	Slot B Option SW Version	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-74	Option in Slot C0	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-75	Slot C0 Option SW Version	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-76	Option in Slot C1	0 N/A	All set-ups	FALSE	0	VisStr[30]
15-77	Slot C1 Option SW Version	0 N/A	All set-ups	FALSE	0	VisStr[20]
15-9* Parameter Info						
15-92	Defined Parameters	0 N/A	All set-ups	FALSE	0	Uint16
15-93	Modified Parameters	0 N/A	All set-ups	FALSE	0	Uint16
15-99	Parameter Metadata	0 N/A	All set-ups	FALSE	0	Uint16



□ 16-.* Data readouts

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
16-0* General Status						
16-00	Control Word	0 N/A	All set-ups	FALSE	0	V2
16-01	Reference [Unit]	0.000 ReferenceFeedbackUnit	All set-ups	FALSE	-3	Int32
16-02	Reference %	0.0 %	All set-ups	FALSE	-1	Int16
16-03	Status Word	0 N/A	All set-ups	FALSE	0	V2
16-05	Main Actual Value [%]	0.00 %	All set-ups	FALSE	-2	N2
16-09	Custom Readout	0.00 CustomReadoutUnit	All set-ups	FALSE	-2	Int32
16-1* Motor Status						
16-10	Power [kW]	0.00 kW	All set-ups	FALSE	1	Int32
16-11	Power [hp]	0.00 hp	All set-ups	FALSE	-2	Int32
16-12	Motor voltage	0.0 V	All set-ups	FALSE	-1	Uint16
16-13	Frequency	0.0 Hz	All set-ups	FALSE	-1	Uint16
16-14	Motor Current	0.00 A	All set-ups	FALSE	-2	Int32
16-15	Frequency [%]	0.00 %	All set-ups	FALSE	-2	N2
16-16	Torque [Nm]	0.0 Nm	All set-ups	FALSE	-1	Int16
16-17	Speed [RPM]	0 RPM	All set-ups	FALSE	67	Int32
16-18	Motor Thermal	0 %	All set-ups	FALSE	0	Uint8
16-19	KTY sensor temperature	0 °C	All set-ups	FALSE	100	Int16
16-20	Motor Angle	0 N/A	All set-ups	TRUE	0	Uint16
16-22	Torque [%]	0 %	All set-ups	FALSE	0	Int16
16-3* Drive Status						
16-30	DC Link Voltage	0 V	All set-ups	FALSE	0	Uint16
16-32	Brake Energy /s	0.000 kW	All set-ups	FALSE	0	Uint32
16-33	Brake Energy /2 min	0.000 kW	All set-ups	FALSE	0	Uint32
16-34	Heatsink Temp.	0 °C	All set-ups	FALSE	100	Uint8
16-35	Inverter Thermal	0 %	All set-ups	FALSE	0	Uint8
16-36	Inv. Nom. Current	ExpressionLimit	All set-ups	FALSE	-2	Uint32
16-37	Inv. Max. Current	ExpressionLimit	All set-ups	FALSE	-2	Uint32
16-38	SL Controller State	0 N/A	All set-ups	FALSE	0	Uint8
16-39	Control Card Temp.	0 °C	All set-ups	FALSE	100	Uint8
16-40	Logging Buffer Full	[0] No	All set-ups	TRUE	-	Uint8
16-5* Ref. & Feedb.						
16-50	External Reference	0.0 N/A	All set-ups	FALSE	-1	Int16
16-51	Pulse Reference	0.0 N/A	All set-ups	FALSE	-1	Int16
16-52	Feedback [Unit]	0.000 ReferenceFeedbackUnit	All set-ups	FALSE	-3	Int32
16-53	Digi Pot Reference	0.00 N/A	All set-ups	FALSE	-2	Int16

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
16-6* Inputs & Outputs						
16-60	Digital Input	0 N/A	All set-ups	FALSE	0	Uint16
16-61	Terminal 53 Switch Setting	[0] Current	All set-ups	FALSE	-	Uint8
16-62	Analog Input 53	0.000 N/A	All set-ups	FALSE	-3	Int32
16-63	Terminal 54 Switch Setting	[0] Current	All set-ups	FALSE	-	Uint8
16-64	Analog Input 54	0.000 N/A	All set-ups	FALSE	-3	Int32
16-65	Analog Output 42 [mA]	0.000 N/A	All set-ups	FALSE	-3	Int16
16-66	Digital Output [bin]	0 N/A	All set-ups	FALSE	0	Int16
16-67	Freq. Input #29 [Hz]	0 N/A	All set-ups	FALSE	0	Int32
16-68	Freq. Input #33 [Hz]	0 N/A	All set-ups	FALSE	0	Int32
16-69	Pulse Output #27 [Hz]	0 N/A	All set-ups	FALSE	0	Int32
16-70	Pulse Output #29 [Hz]	0 N/A	All set-ups	FALSE	0	Int32
16-71	Relay Output [bin]	0 N/A	All set-ups	FALSE	0	Int16
16-72	Counter A	0 N/A	All set-ups	TRUE	0	Int32
16-73	Counter B	0 N/A	All set-ups	TRUE	0	Int32
16-74	Prec. Stop Counter	0 N/A	All set-ups	TRUE	0	Uint32
16-75	Analog In X30/11	0.000 N/A	All set-ups	FALSE	-3	Int32
16-76	Analog In X30/12	0.000 N/A	All set-ups	FALSE	-3	Int32
16-77	Analog Out X30/8 [mA]	0.000 N/A	All set-ups	FALSE	-3	Int16
16-8* Fieldbus & FC Port						
16-80	Fieldbus CTW 1	0 N/A	All set-ups	FALSE	0	V2
16-82	Fieldbus REF 1	0 N/A	All set-ups	FALSE	0	N2
16-84	Comm. Option Status	0 N/A	All set-ups	FALSE	0	V2
16-85	FC Port CTW 1	0 N/A	All set-ups	FALSE	0	V2
16-86	FC Port REF 1	0 N/A	All set-ups	FALSE	0	N2
16-9* Diagnosis Readouts						
16-90	Alarm Word	0 N/A	All set-ups	FALSE	0	Uint32
16-91	Alarm word 2	0 N/A	All set-ups	FALSE	0	Uint32
16-92	Warning Word	0 N/A	All set-ups	FALSE	0	Uint32
16-93	Warning word 2	0 N/A	All set-ups	FALSE	0	Uint32
16-94	Ext. Status Word	0 N/A	All set-ups	FALSE	0	Uint32



□ 17-.* * Motor Feedb.Option

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
17-1* Inc. Enc. Interface						
17-10	Signal Type	[1] TTL (5V, RS422)	All set-ups	FALSE	-	Uint8
17-11	Resolution (PPR)	1024 N/A	All set-ups	FALSE	0	Uint16
17-2* Abs. Enc. Interface						
17-20	Protocol Selection	[0] None	All set-ups	FALSE	-	Uint8
17-21	Resolution (Positions/Rev)	ExpressionLimit	All set-ups	FALSE	0	Uint32
17-24	SSI Data Length	13 N/A	All set-ups	FALSE	0	Uint8
17-25	Clock Rate	ExpressionLimit	All set-ups	FALSE	3	Uint16
17-26	SSI Data Format	[0] Gray code	All set-ups	FALSE	-	Uint8
17-34	HIPERFACE Baud rate	[4] 9600	All set-ups	FALSE	-	Uint8
17-5* Resolver Interface						
17-50	Poles	2 N/A	1 set-up	FALSE	0	Uint8
17-51	Input Voltage	7.0 V	1 set-up	FALSE	-1	Uint8
17-52	Input Frequency	10.0 kHz	1 set-up	FALSE	2	Uint8
17-53	Transformation Ratio	0.5 N/A	1 set-up	FALSE	-1	Uint8
17-59	Resolver Interface	[0] Disabled	All set-ups	FALSE	-	Uint8
17-6* Monitoring and App.						
17-60	Feedback Direction	[0] Clockwise	All set-ups	FALSE	-	Uint8
17-61	Feedback Signal Monitoring	[1] Warning	All set-ups	TRUE	-	Uint8

□ 32- ** MCO Basic Settings

Par. No. #	Parameter description	Default value	4-set-up only	FC 302 Change during operation	Conversion index	Type
32-0* Encoder 2						
32-00	Incremental Signal Type	[1] TTL (5V, RS4222)	2 set-ups	TRUE	-	Uint8
32-01	Incremental Resolution	1024 N/A	2 set-ups	TRUE	0	Uint32
32-02	Absolute Protocol	[0] None	2 set-ups	TRUE	-	Uint8
32-03	Absolute Resolution	8192 N/A	2 set-ups	TRUE	0	Uint32
32-05	Absolute Encoder Data Length	25 N/A	2 set-ups	TRUE	0	Uint8
32-06	Absolute Encoder Clock Frequency	262.000 kHz	2 set-ups	TRUE	0	Uint32
32-07	Absolute Encoder Cable Length	[1] On 0 m	2 set-ups	TRUE	-	Uint8
32-08	Absolute Encoder Cable Length	0 m	2 set-ups	TRUE	0	Uint16
32-09	Encoder Monitoring	[0] Off	2 set-ups	TRUE	-	Uint8
32-10	Rotational Direction	[1] No action	2 set-ups	TRUE	-	Uint8
32-11	User Unit Denominator	1 N/A	2 set-ups	TRUE	0	Uint32
32-12	User Unit Numerator	1 N/A	2 set-ups	TRUE	0	Uint32
32-3* Encoder 1						
32-30	Incremental Signal Type	[1] TTL (5V, RS4222)	2 set-ups	TRUE	-	Uint8
32-31	Incremental Resolution	1024 N/A	2 set-ups	TRUE	0	Uint32
32-32	Absolute Protocol	[0] None	2 set-ups	TRUE	-	Uint8
32-33	Absolute Resolution	8192 N/A	2 set-ups	TRUE	0	Uint32
32-35	Absolute Encoder Data Length	25 N/A	2 set-ups	TRUE	0	Uint8
32-36	Absolute Encoder Clock Frequency	262.000 kHz	2 set-ups	TRUE	0	Uint32
32-37	Absolute Encoder Cable Length	[1] On 0 m	2 set-ups	TRUE	-	Uint8
32-38	Absolute Encoder Cable Length	0 m	2 set-ups	TRUE	0	Uint16
32-39	Encoder Monitoring	[0] Off	2 set-ups	TRUE	-	Uint8
32-40	Encoder Termination	[1] On	2 set-ups	TRUE	-	Uint8
32-5* Feedback Source						
32-50	Source Slave	[2] Encoder 2	2 set-ups	TRUE	-	Uint8
32-6* PID Controller						
32-60	Proportional factor	30 N/A	2 set-ups	TRUE	0	Uint32
32-61	Derivative factor	0 N/A	2 set-ups	TRUE	0	Uint32
32-62	Integral factor	0 N/A	2 set-ups	TRUE	0	Uint32
32-63	Limit Value for Integral Sum	1000 N/A	2 set-ups	TRUE	0	Uint16
32-64	PID Bandwidth	1000 N/A	2 set-ups	TRUE	0	Uint16
32-65	Velocity Feed-Forward	0 N/A	2 set-ups	TRUE	0	Uint32
32-66	Acceleration Feed-Forward	0 N/A	2 set-ups	TRUE	0	Uint32
32-67	Max. Tolerated Position Error	20000 N/A	2 set-ups	TRUE	0	Uint32
32-68	Reverse Behavior for Slave	[0] Reversing allowed	2 set-ups	TRUE	-	Uint8
32-69	Sampling Time for PID Control	1 ms	2 set-ups	TRUE	-3	Uint16
32-70	Scan Time for Profile Generator	1 ms	2 set-ups	TRUE	-3	Uint8
32-71	Size of the Control Window (Activation)	0 N/A	2 set-ups	TRUE	0	Uint32
32-72	Size of the Control Window (Deactiv.)	0 N/A	2 set-ups	TRUE	0	Uint32
32-8* Velocity & Accel.						
32-80	Maximum Velocity (Encoder)	1500 RPM	2 set-ups	TRUE	67	Uint32
32-81	Shortest Ramp	1.000 s	2 set-ups	TRUE	-3	Uint32
32-82	Ramp Type	[0] Linear	2 set-ups	TRUE	-	Uint8
32-83	Velocity Resolution	100 N/A	2 set-ups	TRUE	0	Uint32
32-84	Default Velocity	50 N/A	2 set-ups	TRUE	0	Uint32
32-85	Default Acceleration	50 N/A	2 set-ups	TRUE	0	Uint32



□ 33- * * MCO Adv. Settings

Par. No. #	Parameter description	Default value	4-set-up FC 302 only	Change during operation	Conversion index	Type
33-0* Home Motion						
33-00	Force HOME	[0] Home not forced	2 set-ups	TRUE	-	Uint8
33-01	Zero Point Offset from Home Pos.	0 N/A	2 set-ups	TRUE	0	Int32
33-02	Ramp for Home Motion	10 N/A	2 set-ups	TRUE	0	Uint32
33-03	Velocity of Home Motion	10 N/A	2 set-ups	TRUE	0	Uint32
33-04	Behavior during Home Motion	[0] Reverse and index	2 set-ups	TRUE	-	Uint8
33-1* Synchronization						
33-10	Synchronization Factor Master (M:S)	1 N/A	2 set-ups	TRUE	0	Int32
33-11	Synchronization Factor Slave (M:S)	1 N/A	2 set-ups	TRUE	0	Int32
33-12	Position Offset for Synchronization	0 N/A	2 set-ups	TRUE	0	Int32
33-13	Accuracy Window for Position Sync.	1000 N/A	2 set-ups	TRUE	0	Int32
33-14	Relative Slave Velocity Limit	0 %	2 set-ups	TRUE	0	Uint8
33-15	Marker Number for Master	1 N/A	2 set-ups	TRUE	0	Uint16
33-16	Marker Number for Slave	1 N/A	2 set-ups	TRUE	0	Uint16
33-17	Master Marker Distance	4096 N/A	2 set-ups	TRUE	0	Uint32
33-18	Slave Marker Distance	4096 N/A	2 set-ups	TRUE	0	Uint32
33-19	Master Marker Type	[0] Encoder Z positive	2 set-ups	TRUE	-	Uint8
33-20	Slave Marker Type	[0] Encoder Z positive	2 set-ups	TRUE	-	Uint8
33-21	Master Marker Tolerance Window	0 N/A	2 set-ups	TRUE	0	Uint32
33-22	Slave Marker Tolerance Window	0 N/A	2 set-ups	TRUE	0	Uint32
33-23	Start Behavior for Marker Sync	[0] Start Function 1	2 set-ups	TRUE	-	Uint16
33-24	Marker Number for Fault	10 N/A	2 set-ups	TRUE	0	Uint16
33-25	Marker Number for Ready	1 N/A	2 set-ups	TRUE	0	Uint16
33-26	Velocity Filter	0 us	2 set-ups	TRUE	-6	Int32
33-27	Offset Filter Time	0 ms	2 set-ups	TRUE	-3	Uint32
33-28	Marker Filter Configuration	[0] Marker filter 1	2 set-ups	TRUE	-	Uint8
33-29	Filter Time for Marker Filter	0 ms	2 set-ups	TRUE	-3	Int32
33-30	Maximum Marker Correction	0 N/A	2 set-ups	TRUE	0	Uint32
33-31	Synchronization Type	[0] Standard	2 set-ups	TRUE	-	Uint8
33-4* Limit Handling						
33-40	Behavior at End Limit Switch	[0] Call error handler	2 set-ups	TRUE	-	Uint8
33-41	Negative Software End Limit	-500000 N/A	2 set-ups	TRUE	0	Int32
33-42	Positive Software End Limit	500000 N/A	2 set-ups	TRUE	0	Int32
33-43	Negative Software End Limit Active	[0] Inactive	2 set-ups	TRUE	-	Uint8
33-44	Positive Software End Limit Active	[0] Inactive	2 set-ups	TRUE	-	Uint8
33-45	Time in Target Window	0 ms	2 set-ups	TRUE	-3	Uint8
33-46	Target Window LimitValue	1 N/A	2 set-ups	TRUE	0	Uint16
33-47	Size of Target Window	0 N/A	2 set-ups	TRUE	0	Uint16

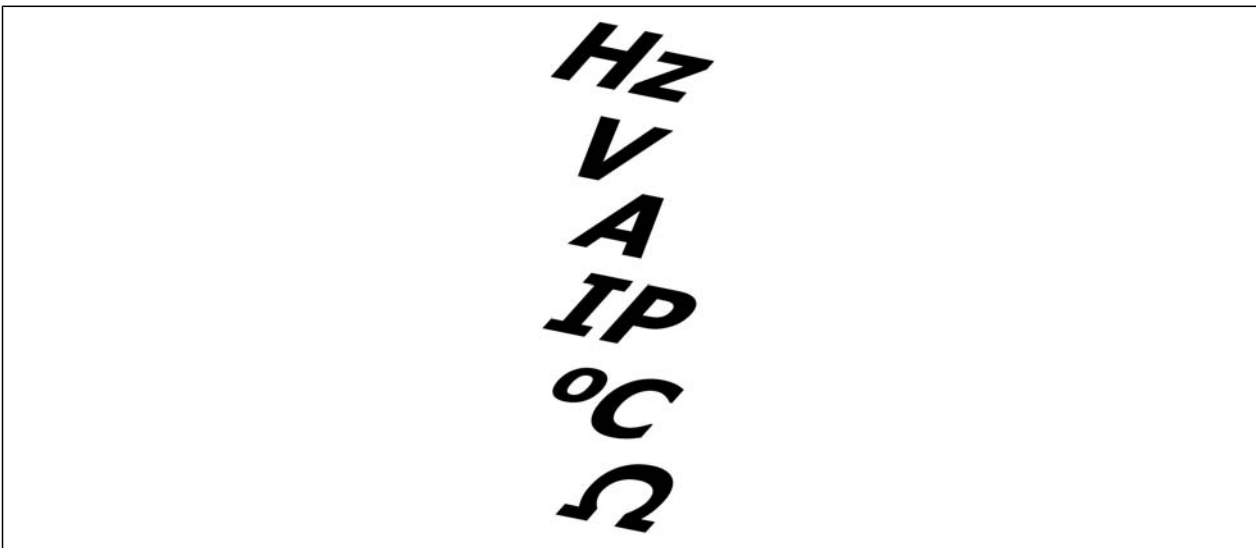
Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
33-5* I/O Configuration						
33-50	Terminal X57/1 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-51	Terminal X57/2 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-52	Terminal X57/3 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-53	Terminal X57/4 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-54	Terminal X57/5 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-55	Terminal X57/6 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-56	Terminal X57/7 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-57	Terminal X57/8 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-58	Terminal X57/9 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-59	Terminal X57/10 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-60	Terminal X59/1 and X59/2 Mode	[1] Output	2 set-ups	FALSE	-	UInt8
33-61	Terminal X59/1 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-62	Terminal X59/2 Digital Input	[0] No function	2 set-ups	TRUE	-	UInt8
33-63	Terminal X59/1 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-64	Terminal X59/2 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-65	Terminal X59/3 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-66	Terminal X59/4 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-67	Terminal X59/5 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-68	Terminal X59/6 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-69	Terminal X59/7 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-70	Terminal X59/8 Digital Output	[0] No function	2 set-ups	TRUE	-	UInt8
33-8* Global Parameters						
33-80	Activated Program Number	-1 N/A	2 set-ups	TRUE	0	Int8
33-81	Power-up State	[1] Motor ON	2 set-ups	TRUE	-	UInt8
33-82	Drive Status Monitoring	[1] On	2 set-ups	TRUE	-	UInt8
33-83	Behavior After Error	[0] Coast	2 set-ups	TRUE	-	UInt8
33-84	Behavior after Esc.	[0] Controlled stop	2 set-ups	TRUE	-	UInt8
33-85	MCO Supplied by External 24VDC	[0] No	2 set-ups	TRUE	-	UInt8



□ 34- ** MCO Data Readouts

Par. No. #	Parameter description	Default value	4-set-up	FC 302 Change during operation only	Conversion index	Type
34-0* PCD Write Par.						
34-01	PCD 1 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-02	PCD 2 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-03	PCD 3 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-04	PCD 4 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-05	PCD 5 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-06	PCD 6 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-07	PCD 7 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-08	PCD 8 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-09	PCD 9 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-10	PCD 10 Write to MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-2* PCD Read Par.						
34-21	PCD 1 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-22	PCD 2 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-23	PCD 3 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-24	PCD 4 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-25	PCD 5 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-26	PCD 6 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-27	PCD 7 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-28	PCD 8 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-29	PCD 9 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-30	PCD 10 Read from MCO	0 N/A	All set-ups	TRUE	0	Uint16
34-4* Inputs & Outputs						
34-40	Digital Inputs	0 N/A	All set-ups	TRUE	0	Uint16
34-41	Digital Outputs	0 N/A	All set-ups	TRUE	0	Uint16
34-5* Process Data						
34-50	Actual Position	0 N/A	All set-ups	TRUE	0	Int32
34-51	Commanded Position	0 N/A	All set-ups	TRUE	0	Int32
34-52	Actual Master Position	0 N/A	All set-ups	TRUE	0	Int32
34-53	Slave Index Position	0 N/A	All set-ups	TRUE	0	Int32
34-54	Master Index Position	0 N/A	All set-ups	TRUE	0	Int32
34-55	Curve Position	0 N/A	All set-ups	TRUE	0	Int32
34-56	Track Error	0 N/A	All set-ups	TRUE	0	Int32
34-57	Synchronizing Error	0 N/A	All set-ups	TRUE	0	Int32
34-58	Actual Velocity	0 N/A	All set-ups	TRUE	0	Int32
34-59	Actual Master Velocity	0 N/A	All set-ups	TRUE	0	Int32
34-60	Synchronizing Status	0 N/A	All set-ups	TRUE	0	Int32
34-61	Axis Status	0 N/A	All set-ups	TRUE	0	Int32
34-62	Program Status	0 N/A	All set-ups	TRUE	0	Int32
34-7* Diagnosis readouts						
34-70	MCO Alarm Word 1	0 N/A	All set-ups	FALSE	0	Uint32
34-71	MCO Alarm Word 2	0 N/A	All set-ups	FALSE	0	Uint32

General Specifications



AC line supply (L1, L2, L3):

Supply voltage	200-240 V ±10%
Supply voltage	FC 301: 380-480 V / FC 302: 380-500 V ±10%
Supply voltage	FC 302: 525-600 V ±10%
Supply frequency	50/60 Hz
Max. imbalance temporary between line phases	3.0% of rated supply voltage
True Power Factor (λ)	≥ 0.9 nominal at rated load
Displacement Power Factor ($\cos \phi$) near unity	(> 0.98)
Switching on input supply L1, L2, L3 (power-ups) ≤10 hp [7.5 kW]	maximum 2 times/min.
Switching on input supply L1, L2, L3 (power-ups) ≥ 15 hp [11 kW]	maximum 1 time/min.
Environment according to EN60664-1	overvoltage category III/pollution degree 2

The unit is suitable for use on a circuit capable of delivering no more than 100,000 RMS symmetrical Amperes, 240/500/600 V maximum.

Motor output (U, V, W):

Output voltage	0 - 100% of supply voltage
Output frequency	FC 301: 0.2 - 1000 Hz / FC 302: 0 - 1000 Hz
Switching on output	Unlimited
Ramp times	0.01 - 3600 sec.

Torque characteristics:

Starting torque (Constant torque)	maximum 160% for 60 sec.*
Starting torque	maximum 180% up to 0.5 sec.*
Overload torque (Constant torque)	maximum 160% for 60 sec.*
Starting torque (Variable torque)	maximum 110% for 60 sec.*
Overload torque (Variable torque)	maximum 110% for 60 sec.

**Percentage relates to FC 300 nominal torque.*



Digital inputs:

Programmable digital inputs	FC 301: 4 (5) / FC 302: 4 (6)
Terminal number	18, 19, 27 ¹⁾ , 29 ⁴⁾ , 32, 33,
Logic	PNP or NPN
Voltage level	0 - 24 V DC
Voltage level, logic '0' PNP	< 5 V DC
Voltage level, logic '1' PNP	> 10 V DC
Voltage level, logic '0' NPN ²⁾	> 19 V DC
Voltage level, logic '1' NPN ²⁾	< 14 V DC
Maximum voltage on input	28 V DC
Input resistance, R _i	approx. 4 kΩ

Safe stop Terminal 37³⁾ (Terminal 37 is fixed PNP logic):

Voltage level	0 - 24 V DC
Voltage level, logic '0' PNP	< 4 V DC
Voltage level, logic '1' PNP	> 20 V DC
Nominal input current at 24 V	50 mA rms
Nominal input current at 20 V	60 mA rms
Input capacitance	400 nF

All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

1) Terminals 27 and 29 can also be programmed as output.

2) Except safe stop input Terminal 37.

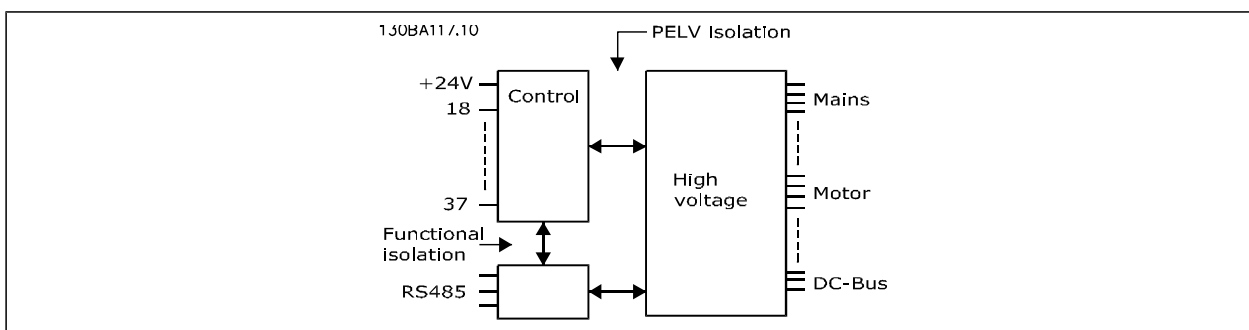
3) Terminal 37 is only available in FC 302 and FC 301 A1 with Safe Stop. It can only be used as safe stop input. Terminal 37 is suitable for category 3 installations according to EN 954-1 (safe stop according to category 0 EN 60204-1), and as required by the EU Machinery Directive 98/37/EC. Terminal 37 and the Safe Stop function are designed in accordance with EN 60204-1, EN 50178, EN 61800-2, EN 61800-3 and EN 954-1. For correct and safe use of the Safe Stop function, follow the related information and instructions in the Design Guide.



Analog inputs:

Number of analog inputs	2
Terminal number	53, 54
Modes	Voltage or current
Mode select	Switch S201 and switch S202
Voltage mode	Switch S201/switch S202 = OFF (U)
Voltage level	FC 301: 0 to + 10/ FC 302: -10 to +10 V (scalable)
Input resistance, R _i	approx. 10 kΩ
Max. voltage	± 20 V
Current mode	Switch S201/switch S202 = ON (I)
Current level	0/4 to 20 mA (scalable)
Input resistance, R _i	approx. 200 Ω
Max. current	30 mA
Resolution for analog inputs	10 bit (+ sign)
Accuracy of analog inputs	Max. error 0.5% of full scale
Bandwidth	FC 301: 20 Hz/ FC 302: 100 Hz

The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.



Pulse/encoder inputs:

Programmable pulse/encoder inputs	2/1
Terminal number pulse/encoder	29 ³ , 33 ¹⁾ / 32 ² , 33 ²⁾ 3)
Max. frequency at terminal 29, 32, 33 ³⁾	110 kHz (push-pull driven)
Max. frequency at terminal 29, 32, 33 ³⁾	5 kHz (open collector)
Min. frequency at terminal 29, 32, 33 ³⁾	4 Hz
Voltage level	see section on Digital input
Maximum voltage on input	28 V DC
Input resistance, R _i	approx. 4 kΩ
Pulse input accuracy (0.1 - 1 kHz)	Max. error: 0.1% of full scale
Encoder input accuracy (1 - 110 kHz)	Max. error: 0.05 % of full scale

The pulse and encoder inputs (terminals 29, 32, 33) are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

- 1) Pulse inputs are 29 and 33
- 2) Encoder inputs: 32 = A, and 33 = B
- 3) Terminal 29: Only FC 302



Digital output:

Programmable digital/pulse outputs	2
Terminal number	27, 29 ^{1) 2)}
Voltage level at digital/frequency output	0 - 24 V
Max. output current (sink or source)	40 mA
Max. load at frequency output	1 kΩ
Max. capacitive load at frequency output	10 nF
Minimum output frequency at frequency output	0 Hz
Maximum output frequency at frequency output	32 kHz
Accuracy of frequency output	Max. error: 0.1% of full scale
Resolution of output frequency	12 bit

1) Terminal 27 and 29 can also be programmed as input.

2) Terminal 29: Only FC 302.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Analog output:

Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4 - 20 mA
Max. load to common at analog output	500 Ω
Accuracy on analog output	Max. error: 0.5% of full scale
Resolution on analog output	12 bit

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, 24 V DC output:

Terminal number	12, 13
Output voltage	24 V +1, -3 V
Max. load	FC 301: 130 mA/ FC 302: 200 mA

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same potential as the analog and digital inputs and outputs.

Control card, 10 V DC output:

Terminal number	50
Output voltage	10.5 V ±0.5 V
Max. load	15 mA

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.



Control card, RS-485 serial communication:

Terminal number	68 (P,TX+, RX+), 69 (N,TX-, RX-)
Terminal number 61	Common for terminals 68 and 69

The RS-485 serial communication circuit is functionally separated from other central circuits and galvanically isolated from the supply voltage (PELV).

Control card, USB serial communication:

USB standard	1.1 (Full speed)
USB plug	USB type B "device" plug

Connection to PC is carried out via a standard host/device USB cable.

The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

The USB ground connection is not galvanically isolated from protection ground. Only use an isolated laptop as a PC connection to the USB connector on the FC 300 drive.

Relay outputs:

Programmable relay outputs	FC 301 ≤ 10 hp [7.5 kW]: 1 / FC 302 all hp [kW]: 2
Relay 01 Terminal number	1-3 (break), 1-2 (make)
Max. terminal load (AC-1) ¹⁾ on 1-3 (NC), 1-2 (NO) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15) ¹⁾ (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1) ¹⁾ on 1-2 (NO), 1-3 (NC) (Resistive load)	60 V DC, 1A
Max. terminal load (DC-13) ¹⁾ (Inductive load)	24 V DC, 0.1A
Relay 02 (FC 302 only) Terminal number	4-6 (break), 4-5 (make)
Max. terminal load (AC-1) ¹⁾ on 4-5 (NO) (Resistive load)	400 V AC, 2 A
Max. terminal load (AC-15) ¹⁾ on 4-5 (NO) (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1) ¹⁾ on 4-5 (NO) (Resistive load)	80 V DC, 2 A
Max. terminal load (DC-13) ¹⁾ on 4-5 (NO) (Inductive load)	24 V DC, 0.1A
Max. terminal load (AC-1) ¹⁾ on 4-6 (NC) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15) ¹⁾ on 4-6 (NC) (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1) ¹⁾ on 4-6 (NC) (Resistive load)	50 V DC, 2 A
Max. terminal load (DC-13) ¹⁾ on 4-6 (NC) (Inductive load)	24 V DC, 0.1 A
Min. terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO)	24 V DC 10 mA, 24 V AC 20 mA
Environment according to EN 60664-1	overvoltage category III/pollution degree 2

1) IEC 60947 part 4 and 5

The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).



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— General Specifications —

Cable lengths and cross-sections:

	FC 301: 164 ft. [50 m] / FC 301 (A1-encl.): 82 ft. [25 m] /
Max. motor cable length, shielded/armored	FC 302: 492 ft. [150 m]
	FC 301: 246 ft. [75 m] / FC 301 (A1-encl.): 164 ft. [50
Max. motor cable length, unshielded/unarmored	m] / FC 302: 984 ft [300 m]
Max. cross-section to motor, line power, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (0.34-10 hp [0.25 kW - 7.5 kW])	0.0062 in. ² [4 mm ²] / 10 AWG
Max. cross-section to motor, line power, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (15-20 hp [11-15 kW])	0.025 in. ² [16 mm ²] / 6 AWG
Max. cross-section to motor, line power, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (25-30 hp [18-22 kW])	0.054 in. ² [35 mm ²] / 2 AWG
Maximum cross-section to control terminals, rigid wire	0.0023 in. ² [1.5 mm ²]/16 AWG (2 x 0.0012 in. ² [2 x 0.75 mm ²])
Maximum cross-section to control terminals, flexible cable	0.0016 in. ² [1 mm ²]/18 AWG
Maximum cross-section to control terminals, cable with enclosed core	0.00078 in. ² [0.5 mm ²]/20 AWG
Minimum cross-section to control terminals	0.0039 in. ² [0.25 mm ²]/AWG

Control card performance:

Scan interval	FC 301: 5 ms / FC 302: 1 ms
---------------	-----------------------------

Control characteristics:

Resolution of output frequency at 0 - 1000 Hz	FC 301: +/- 0.013 Hz / FC 302: +/- 0.003 Hz
Repeat accuracy of <i>Precise start/stop</i> (terminals 18, 19)	FC 301: ≤± 1ms / FC 302: ≤± 0.1 msec
System response time (terminals 18, 19, 27, 29, 32, 33)	FC 301: ≤ 10 ms / FC 302: ≤ 2 ms
Speed control range (open-loop)	1:100 of synchronous speed
Speed control range (closed-loop)	1:1000 of synchronous speed
Speed accuracy (open-loop)	30 - 4000 rpm: error ±8 rpm
Speed accuracy (closed-loop), depending on resolution of feedback device	0 - 6000 rpm: error ±0.15 rpm

All control characteristics are based on a 4-pole asynchronous motor

Surroundings:

Enclosure	IP 20 ¹⁾ / Type 1, IP 21 ²⁾ / Type 1, IP 55/ Type 12, IP 66
Vibration test	1.0 g
Max. relative humidity	5% - 95%(IEC 721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 60068-2-43	class H25
Ambient temperature ³⁾	Max. 122°F [50°C] (24-hour average maximum 113°F [45°C])

- 1) Only for ≤ 5 hp [3.7 kW] (200-240 V), ≤ 10 hp [7.5 kW] (400-480/ 500 V)
- 2) As enclosure kit for ≤ 5 hp [3.7 kW] (200-240 V), ≤ 10 hp [7.5 kW] (400-480/ 500 V)
- 3) Derating for high ambient temperature, see special conditions in the Design Guide.

Minimum ambient temperature during full-scale operation	32°F [0°C]
Minimum ambient temperature at reduced performance	14°F [-10°C]
Temperature during storage/transport	-13° - +149/158°F [-25° - +65/70°C]

Maximum altitude above sea level without derating 3,280 ft./1,000 m.

Derating for high altitude, see special conditions in the Design Guide.

EMC standards, Emission EN 61800-3, EN 61000-6-3/4, EN 55011

EN 61800-3, EN 61000-6-1/2,

EMC standards, Immunity EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6

See section on special conditions in the Design Guide

Protection and Features:

- Electronic thermal motor protection against overload.
- Temperature monitoring of the heatsink ensures that the adjustable frequency drive trips if the temperature reaches $203^{\circ}\text{F} \pm 9^{\circ}\text{F}$ [$95^{\circ}\text{C} \pm 5^{\circ}\text{C}$]. An overload temperature cannot be reset until the temperature of the heatsink is below $158^{\circ}\text{F} \pm 9^{\circ}\text{F}$ [$70^{\circ}\text{C} \pm 5^{\circ}\text{C}$] (Guideline - these temperatures may vary for different power sizes, enclosures, etc.).
- The adjustable frequency drive is protected against short-circuits in motor terminals U, V, W.
- If a line phase is missing, the adjustable frequency drive trips or issues a warning (depending on the load).
- Monitoring of the intermediate circuit voltage ensures that the adjustable frequency drive trips if the intermediate circuit voltage is too low or too high.
- The adjustable frequency drive constantly checks for critical internal temperature levels, load current, high voltage on the intermediate circuit and low motor speeds. As a response to a critical level, the adjustable frequency drive can adjust the switching frequency and/ or change the switching pattern in order to ensure the performance of the drive.





Warnings and Alarms



□ Warnings/Alarm Messages

A warning or an alarm is signaled by the relevant LED on the front of the adjustable frequency drive and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances, operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the adjustable frequency drive will have tripped. Alarms must be reset to restart operation once their cause has been rectified. This may be done in three ways:

1. By using the [RESET] control button on the LCP control panel.
2. Via a digital input with the "Reset" function.
3. Via serial communication/optional serial communication bus.



NOTE

After a manual reset using the [RESET] button on the LCP, the [AUTO ON] button must be pressed to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also table on following page).

Alarms that are trip-locked offer additional protection, meaning that the line supply must be switched off before the alarm can be reset. Once the cause of the alarm has been rectified and the device has been switched back on, the FC 300 is no longer blocked and may be reset as described above.

Alarms that are not trip-locked can also be reset using the automatic reset function in parameters 14-20 (Warning: automatic wake-up is possible!)

If a warning and alarm is marked against a code in the table on the following page, this means that either a warning occurs before an alarm, or that you can specify whether it is a warning or an alarm that is to be displayed for a given fault.



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— Warnings and Alarms —

This is possible, for instance, in parameters 1-90 *Motor Thermal Protection*. After an alarm or trip, the motor carries on coasting, and the alarm and warning flash. Once the problem has been rectified, only the alarm continues flashing until the FC 300 is reset.

Alarm/Warning code list					
No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
1	10 Volts low	X			
2	Live zero error	(X)	(X)		6-01
3	No motor	(X)			1-80
4	Line phase loss	(X)	(X)	(X)	14-12
5	DC link voltage high	X			
6	DC link voltage low	X			
7	DC overvoltage	X	X		
8	DC undervoltage	X	X		
9	Inverter overloaded	X	X		
10	Motor ETR overtemperature	(X)	(X)		1-90
11	Motor thermistor overtemperature	(X)	(X)		1-90
12	Torque limit	X	X		
13	Overcurrent	X	X	X	
14	Ground Fault	X	X	X	
15	Hardware mismatch		X	X	
16	Short Circuit		X	X	
17	Control word timeout	(X)	(X)		8-04
23	Internal Fan Fault	X			
24	External Fan Fault	X			14-53
25	Brake resistor short-circuited	X			
26	Brake resistor power limit	(X)	(X)		2-13
27	Brake chopper short-circuited	X	X		
28	Brake check	(X)	(X)		2-15
29	Power board overtemp	X	X	X	
30	Motor phase U missing	(X)	(X)	(X)	4-58
31	Motor phase V missing	(X)	(X)	(X)	4-58
32	Motor phase W missing	(X)	(X)	(X)	4-58
33	Soft-charge fault		X	X	
34	Serial communication bus fault	X	X		
36	Line failure	X	X		
38	Internal Fault		X	X	
40	Overload of Digital Output Terminal 27	(X)			5-00, 5-01
41	Overload of Digital Output Terminal 29	(X)			5-00, 5-02
42	Overload of Digital Output On X30/6	(X)			5-32
42	Overload of Digital Output On X30/7	(X)			5-33
47	24 V supply low	X	X	X	
48	1.8 V supply low		X	X	
49	Speed limit	X			
50	AMA calibration failed		X		
51	AMA check U_{nom} and I_{nom}		X		
52	AMA low I_{nom}		X		
53	AMA motor too big		X		
54	AMA motor too small		X		
55	AMA parameter out of range		X		
56	AMA interrupted by user		X		
57	AMA timeout		X		
58	AMA internal fault	X	X		
59	Current limit	X			



Alarm/Warning code list					
No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
61	Tracking Error	(X)	(X)		4-30
62	Output Frequency at Maximum Limit	X			
63	Mechanical Brake Low		(X)		2-20
64	Voltage Limit	X			
65	Control Board Overtemperature	X	X	X	
66	Heatsink Temperature Low	X			
67	Option Configuration Has Changed		X		
68	Safe Stop Activated		X		
70	Illegal FC configuration			X	
80	Drive Initialized to Default Value		X		
90	Encoder Loss	(X)	(X)		17-61
91	Analog input 54 wrong settings			X	S202
100-199	See Instruction Manual for MCO 305				
250	New spare part			X	14-23
251	New Type Code		X	X	

(X) Dependent on parameter

LED indication	
Warning	yellow
Alarm	flashing red
Trip-locked	yellow and red

Description of Alarm Word, Warning Word, and extended Status Word					
Alarm Word	Extended Status Word				
Bit	Hex	Dec	AlarmWord	WarningWord	ExtendedStatusWord
0	00000001	1	Brake Check	Brake Check	Ramping
1	00000002	2	Pwr. Card Temp	Pwr. Card Temp	AMA Running
2	00000004	4	Ground Fault	Ground Fault	Start CW/CCW
3	00000008	8	Ctrl.Card Temp	Ctrl.Card Temp	Slow Down
4	00000010	16	Ctrl. Word TO	Ctrl. Word TO	Catch Up
5	00000020	32	Overcurrent	Overcurrent	Feedback High
6	00000040	64	Torque Limit	Torque Limit	Feedback Low
7	00000080	128	Thrmstr overld	Thrmstr overld	Output Current High
8	00000100	256	Motor ETR Over	Motor ETR Over	Output Current Low
9	00000200	512	Inverter Overld.	Inverter Overld.	Output Freq High
10	00000400	1024	DC undervolt	DC undervolt	Output Freq Low
11	00000800	2048	DC overvolt	DC overvolt	Brake Check OK
12	00001000	4096	Short Circuit	DC Voltage Low	Braking Max
13	00002000	8192	Soft-charge fault	DC Voltage High	Braking
14	00004000	16384	Line ph. Loss	Line ph. Loss	Out of Speed Range
15	00008000	32768	AMA Not OK	No Motor	OVC Active
16	00010000	65536	Live Zero Error	Live Zero Error	
17	00020000	131072	Internal Fault	10 V Low	
18	00040000	262144	Brake Overload	Brake Overload	
19	00080000	524288	U phase loss	Brake Resistor	
20	00100000	1048576	V-phase Loss	Brake IGBT	
21	00200000	2097152	W-phase Loss	Speed Limit	
22	00400000	4194304	Ser. com. bus fault	Ser. com. bus fault	
23	00800000	8388608	24 V Supply Low	24 V Supply Low	
24	01000000	16777216	Line Failure	Line Failure	
25	02000000	33554432	1.8 V Supply Low	Current Limit	
26	04000000	67108864	Brake Resistor	Low Temp	
27	08000000	134217728	Brake IGBT	Voltage Limit	
28	10000000	268435456	Option Change	Unused	
29	20000000	536870912	Drive Initialized	Unused	
30	40000000	1073741824	Safe Stop	Unused	
31	80000000	2147483648	Mech. brake low	Extended Status Word	

The alarm words, warning words and extended status words can be read out via serial bus or optional serial communication bus for diagnosis. See also par. 16-90, 16-92, and 16-94.



WARNING 1

10 Volts low:

The 10 V voltage from terminal 50 on the control card is below 10 V.

Remove some of the load from terminal 50, as the 10 V supply is overloaded. Max. 15 mA or minimum 590 Ω

WARNING/ALARM 2

Live zero error:

The signal on terminal 53 or 54 is less than 50% of the value set in par. 6-10, 6-12, 6-20, or 6-22, respectively.

WARNING/ALARM 3

No motor:

No motor has been connected to the output of the adjustable frequency drive.

WARNING/ALARM 4

Line phase loss:

A phase is missing on the supply side, or the line voltage imbalance is too high.

This message also appears in case of a fault in the input rectifier on the adjustable frequency drive.

Check the supply voltage and supply currents to the adjustable frequency drive.

WARNING 5

DC link voltage high:

The intermediate circuit voltage (DC) is higher than the overvoltage limit of the control system. The adjustable frequency drive is still active.

WARNING 6

DC link voltage low

The intermediate circuit voltage (DC) is below the undervoltage limit of the control system. The adjustable frequency drive is still active.

WARNING/ALARM 7

DC overvoltage:

If the intermediate circuit voltage exceeds the limit, the adjustable frequency drive trips after a time.

Possible corrections:

- Connect a brake resistor
- Extend the ramp time
- Activate functions in par. 2-10
- Increase par. 14-26

Alarm/warning limits:			
FC 300 Series	3 x 200 - 240 V [VDC]	3 x 380 - 500 V [VDC]	3 x 525 - 600 V [VDC]
Undervoltage	185	373	532
Voltage warning low	205	410	585
Voltage warning high (w/o brake - w/ brake)	390/405	810/840	943/965
Overvoltage	410	855	975

The voltages stated are the intermediate circuit voltages of the FC 300 with a tolerance of ± 5 %. The corresponding line voltage is the intermediate circuit voltage (DC link) divided by 1.35.

WARNING/ALARM 8

DC undervoltage:

If the intermediate circuit voltage (DC) drops below the "voltage warning low" limit (see table above), the adjustable frequency drive checks if 24 V backup supply is connected.

If no 24 V backup supply is connected, the adjustable frequency drive trips after a given time depending on the unit.

To check whether the supply voltage matches the adjustable frequency drive, see *General Specifications*.

WARNING/ALARM 9

Inverter overloaded:

The adjustable frequency drive is about to cut out because of an overload (too high current for too long). The counter for electronic, thermal inverter protection gives a warning at 98% and trips at 100%, while sounding an alarm. You cannot reset the adjustable frequency drive until the counter is below 90%.

The fault is that the adjustable frequency drive has been overloaded by more than 100% for too long.

WARNING/ALARM 10

Motor ETR overtemperature:

According to the electronic thermal protection (ETR), the motor is too hot. You can choose if you want the adjustable frequency drive to give a warning or an alarm when the counter reaches 100% in par. 1-90. The fault is that the motor is overloaded by more than 100% for too long. Check that the motor par. 1-24 is set correctly.



WARNING/ALARM 11

Motor thermistor overtemp:

The thermistor or the thermistor connection is disconnected. You can choose if you want the adjustable frequency drive to give a warning or an alarm when the counter reaches 100% in par. 1-90. Make sure that the thermistor is connected correctly between terminal 53 or 54 (analog voltage input) and terminal 50 (+ 10 V supply), or between terminal 18 or 19 (digital input PNP only) and terminal 50. If aKTY sensor is used, check for correct connection between terminal 54 and 55.

WARNING/ALARM 12

Torque limit:

The torque is higher than the value in par. 4-16 (in motor operation) or the torque is higher than the value in par. 4-17 (in regenerative operation).

WARNING/ALARM 13

Overcurrent:

The inverter peak current limit (approx. 200% of the rated current) is exceeded. The warning will last approx. 8-12 sec., then the adjustable frequency drive trips and issues an alarm. Turn off the adjustable frequency drive and check if the motor shaft can be turned and if the motor size matches the adjustable frequency drive. If extended mechanical brake control is selected, the trip can be reset externally.

ALARM 14

Ground fault:

There is a discharge from the output phases to ground, either in the cable between the adjustable frequency drive and the motor or in the motor itself.

Turn off the adjustable frequency drive and remove the ground fault.

ALARM 15

Incomplete hardware:

A fitted option is not handled by the present control board (hardware or software).

ALARM 16

Short-circuit

There is a short-circuit in the motor or on the motor terminals.

Turn off the adjustable frequency drive and remove the short-circuit.

WARNING/ALARM 17

Control word timeout:

There is no communication to the adjustable frequency drive.

The warning will only be active when par. 8-04 is NOT set to OFF.

If par. 8-04 is set to *Stop* and *Trip*, a warning appears and the adjustable frequency drive ramps down until it trips, while sounding an alarm.

par. 8-03 *Control word Timeout Time* could possibly be increased.

WARNING 23

Internal fan fault:

The fan warning function is an extra protection function that checks if the fan is running / mounted. The fan warning can be disabled in *Fan Monitor*, par. 14-53, (set to [0] Disabled).

WARNING 24

External fan fault:

The fan warning function is an extra protection function that checks if the fan is running / mounted. The fan warning can be disabled in *Fan Monitor*, par. 14-53, (set to [0] Disabled).

WARNING 25

Brake resistor short-circuited:

The brake resistor is monitored during operation. If it short-circuits, the brake function is disconnected and the warning appears. The adjustable frequency drive still works, but without the brake function. Turn off the adjustable frequency drive and replace the brake resistor (see par. 2-15 *Brake Check*).

ALARM/WARNING 26

Brake resistor power limit:

The power transmitted to the brake resistor is calculated as a percentage, as a mean value over the last 120 s, on the basis of the resistance value of the brake resistor (par. 2-11) and the intermediate circuit voltage. The warning is active when the dissipated braking energy is higher than 90%. If *Trip* [2] has been selected in par. 2-13, the adjustable frequency drive cuts out and issues this alarm, when the dissipated braking energy is higher than 100%.



WARNING 27

Brake chopper fault:

The brake transistor is monitored during operation and if it short-circuits, the brake function disconnects and the warning comes up. The adjustable frequency drive is still able to run, but since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive.

Turn off the adjustable frequency drive and remove the brake resistor.



Warning: There is a risk of substantial power being transmitted to the brake resistor if the brake transistor is short-circuited.

ALARM/WARNING 28

Brake check failed:

Brake resistor fault: the brake resistor is not connected/working.

ALARM 29

Drive overtemperature:

If the enclosure is IP 20 or IP 21/Type 1, the cut-out temperature of the heatsink is 203 °F \pm 10 °F [95 °C \pm 5 °C]. The temperature fault cannot be reset until the temperature of the heatsink is below 158 °F \pm 10 °F [70 °C \pm 5 °C].

The fault could be:

- Ambient temperature too high
- Motor cable too long

ALARM 30

Motor phase U missing:

Motor phase U between the adjustable frequency drive and the motor is missing.

Turn off the adjustable frequency drive and check motor phase U.

ALARM 31

Motor phase V missing:

Motor phase V between the adjustable frequency drive and the motor is missing.

Turn off the adjustable frequency drive and check motor phase V.

ALARM 32

Motor phase W missing:

Motor phase W between the adjustable frequency drive and the motor is missing.

Turn off the adjustable frequency drive and check motor phase W.

ALARM 33

Soft-charge fault:

Too many powerups have occurred within a short period of time. See the chapter *General Specifications* for the allowed number of power-ups within one minute.

WARNING/ALARM 34

Ser. com. bus fault:

The serial communication bus on the communication option card is not working.

WARNING/ALARM 36

Line failure:

This warning/alarm is only active if the supply voltage to the adjustable frequency drive is lost and parameter 14-10 is NOT set to OFF. Possible correction: check the fuses to the adjustable frequency drive

ALARM 38

Internal fault:

When this alarm sounds, it may be necessary to contact your Danfoss supplier. Some typical alarm messages:

- 0 The serial port cannot be initialized. Serious hardware failure
- 256 The power EEPROM data is defective or too old.
- 512 The control board EEPROM data is defective or too old.
- 513 Communication timeout Reading EEPROM data
- 514 Communication timeout Reading EEPROM data
- 515 The Application Orientated Control cannot recognize the EEPROM data.
- 516 Cannot write to the EEPROM because a write command is in progress.
- 517 The write command has timed out.
- 518 Failure in the EEPROM
- 519 Missing or invalid BarCode data in EEPROM 1024 – 1279 CAN telegram cannot be sent. (1027 indicates a possible hardware failure)
- 1281 Digital Signal Processor flash timeout
- 1282 Power micro software version mismatch



- 1283 Power EEPROM data version mismatch
- 1284 Cannot read Digital Signal Processor software version
- 1299 Option SW in slot A is too old.
- 1300 Option SW in slot B is too old.
- 1301 Option SW in slot C0 is too old.
- 1302 Option SW in slot C1 is too old.
- 1315 Option SW in slot A is not supported (not allowed).
- 1316 Option SW in slot B is not supported (not allowed).
- 1317 Option SW in slot C0 is not supported (not allowed).
- 1318 Option SW in slot C1 is not supported (not allowed).
- 1536 An exception in the Application Orientated Control is registered. Debug information written in LCP
- 1792 DSP watchdog is active. Debugging of power part data Motor Orientated Control data not transferred correctly
- 2049 Power data restarted
- 2315 Missing SW version from power unit
- 2816 Stack overflow Control board module
- 2817 Scheduler slow tasks
- 2818 Fast tasks
- 2819 Parameter thread
- 2820 LCP stack overflow
- 2821 Serial port overflow
- 2822 USB port overflow
- 3072-5 Parameter value is outside its limits.
- 122 Perform an initialization. Parameter number causing the alarm: Subtract the code from 3072. Ex Error code 3238: 3238-3072 = 166 is outside the limit
- 5123 Option in slot A: Hardware incompatible with Control board hardware
- 5124 Option in slot B: Hardware incompatible with Control board hardware
- 5125 Option in slot C0: Hardware incompatible with Control board hardware
- 5126 Option in slot C1: Hardware incompatible with Control board hardware
- 5376-6 Out of memory
- 231

WARNING 40

Overload of Digital Output Terminal 27:

Check the load connected to terminal 27 or remove short-circuit connection. Check parameters 5-00 and 5-01.

WARNING 41

Overload of Digital Output Terminal 29:

Check the load connected to terminal 29 or remove short-circuit connection. Check parameters 5-00 and 5-02.

WARNING 42

Overload of Digital Output On X30/6 :

Check the load connected to X30/6 or remove short-circuit connection. Check parameter 5-32.

WARNING 42

Overload of Digital Output On X30/7 :

Check the load connected to X30/7 or remove short-circuit connection. Check parameter 5-33.

WARNING 47

24 V supply low:

The external 24 V DC backup power supply may be overloaded, otherwise contact your Danfoss supplier.

WARNING 48

1.8 V supply low:

Contact your Danfoss supplier.

WARNING 49

Speed limit:

The speed is not within the range specified in par. 4-11 and par. 4-13.

ALARM 50

AMA calibration failed:

Contact your Danfoss supplier.

ALARM 51

AMA check Unom and Inom:

The setting of motor voltage, motor current, and motor power is presumably wrong. Check the settings.

ALARM 52

AMA low Inom:

The motor current is too low. Check the settings.

ALARM 53

AMA motor too big:

The motor is too big for the AMA to be carried out.



ALARM 54

AMA motor too small:

The motor is too big for the AMA to be carried out.

ALARM 55

AMA par. out of range:

The par. values found from the motor are outside the acceptable range.

ALARM 56

AMA interrupted by user:

The AMA has been interrupted by the user.

ALARM 57

AMA timeout:

Try to start the AMA again a number of times, until the AMA is carried out. Please note that repeated runs may heat the motor to a level where the resistances R_s and R_r are increased. In most cases, however, this is not critical.

ALARM 58

AMA internal fault:

Contact your Danfoss supplier.

WARNING 59

Current limit:

Contact your Danfoss supplier.

WARNING 61

Encoder loss:

Contact your Danfoss supplier.

WARNING 62

Output Frequency at Maximum Limit:

The output frequency is higher than the value set in par. 4-19.

ALARM 63

Mechanical Brake Low:

The actual motor current has not exceeded the "release brake" current within the "Start delay" time window.

WARNING 64

Voltage Limit:

The load and speed combination demands a motor voltage higher than the actual DC link voltage.

WARNING/ALARM/TRIP 65

Control Card Overtemperature:

Control card overtemperature: The cut-out temperature of the control card is 176°F [80°C].

WARNING 66

Heatsink Temperature Low:

The heatsink temperature is measured as 32° F (0° C). This could indicate that the temperature sensor is defect and that the fan speed has thus increased to the maximum in case the power part or control card is very hot.

ALARM 67

Option Configuration has Changed:

One or more options has either been added or removed since the last power-down.

ALARM 68

Safe Stop Activated:

Safe Stop has been activated. To resume normal operation, apply 24 V DC to terminal 37, then send a reset signal (via bus, digital I/O, or by pressing [RESET]). For correct and safe use of the Safe Stop function, follow the related information and instructions in the Design Guide

ALARM 70

Illegal FC Configuration:

Current combination of control board and power board is illegal.

ALARM 80

Drive Initialized to Default Value:

Parameter settings are initialized to default setting after a manual (three-finger) reset.

ALARM 91

Analog Input 54 Wrong Settings:

Switch S202 has to be set in position OFF (voltage input) when a KTY sensor is connected to analog input terminal 54.

ALARM 250

New Spare Part:

The power or Switch Mode Power Supply has been exchanged. The adjustable frequency drive type code must be restored in the EEPROM. Select the correct type code in Par 14-23 according to the label on unit. Remember to select 'Save to EEPROM' to complete.

ALARM 251

New Type Code:

The adjustable frequency drive has a new type code.



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